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A Nonlinear Lattice and Volterra’s System

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A new kind of nonlinear lattice is presented. This is not the usual dynamical system. It is asymmetric with respect to momentum, and consequently the motion is asymmetric in space. The equations of motion can be interpreted as a special case of Lotka-Volterra’s equation of competing species forming a chain of preys and predators.

§1. Hamiltonian

The Hamiltonian of the exponential lattice is written as

\[ H(x, p) = \sum_n \frac{p_n^2}{2} + \sum_n \left\{ e^{-(x_n-x_{n-1})} - 1 + (x_n - x_{n-1}) \right\}. \]

The potential \( \phi(r) = e^{-r} - 1 + r \) reduces to quadratic \( r^2/2 \) when \( r \) is small.

Similarly for small \( p \), the kinetic term can be approximated by \( e^{-p} - 1 + p \).
We may rather consider a system with the Hamiltonian

\[ H(z, p) = \alpha^2 \sum_n \left( e^{-p_n} - 1 + p_n \right) + \sum_n \left( e^{-(z_n - z_{n-1})} - 1 + (z_n - z_{n-1}) \right), \]

(1)

where \( z_n \) and \( p_n \) are canonical conjugate variables, coordinate and momentum, and \( \alpha \) is a constant. We may introduce some constants to change the potential term \( e^{-r} - 1 + r \) to \( \frac{\alpha}{b} (e^{-b r} - 1 + br) \) and to modify similarly the kinetic term \( e^{-p} - 1 + p \). However by rescaling of coordinate, momentum and energy we can reduce the Hamiltonian to the above form, with a single parameter \( \alpha \).

Let us suppose (1) to hold for the infinite range of \( p_n \) and \( z_n \) (-\( \infty < p_n < \infty \), -\( \infty < z_n < \infty \)). Then the canonical equations of motion are given as

\[ \dot{z}_n = \frac{\partial H}{\partial p_n} = \alpha^2 \left( 1 - e^{-p_n} \right), \]

(2)

\[ \dot{p}_n = -\frac{\partial H}{\partial z_n} = e^{-(z_n - z_{n-1})} - e^{-(z_{n+1} - z_{n})}. \]

(2')

If we introduce

\[ r_n = z_n - z_{n-1}, \]

(3)

we obtain the equations of motion in the form

\[ \dot{r}_n = \alpha^2 \left( e^{-p_{n-1}} - e^{-p_n} \right), \]

(4)

\[ \dot{p}_n = e^{-r_n} - e^{-r_{n+1}}, \]

(4')

which are nearly symmetric with respect to \( r_n \) and \( p_n \).

If we further write

\[ \alpha \left( e^{-p_n} - 1 \right) = I_n, \]

(5)

\[ \alpha^{-1} \left( e^{-r_n} - 1 \right) = V_n, \]

(5')
or

\[ p_n = - \log \left( 1 + \frac{I_n}{\alpha} \right), \quad (6) \]

\[ r_n = - \log (1 + \alpha V_n) \quad (6') \]

and

\[ \alpha t = \tau, \quad (7) \]

we obtain

\[ -\frac{d}{d\tau} \log(\alpha^{-1} + V_n) = I_{n-1} - I_n \quad (8) \]

\[ -\frac{d}{d\tau} \log(\alpha + I_n) = V_n - V_{n+1} \quad (8') \]

The set of equations (8) was already studied by Hirota and Satsuma.\(^1\)\(^2\)

Soliton solutions and periodic solutions revealed interesting properties, especially its non-reciprocal property in the sense that forward propagation and backward propagation are different.

When \( \alpha \gg 1 \), \( p_n \) values are limited small, and the system reduces to the usual exponential lattice. When \( \alpha = 1 \), solitons can propagate only to the left.

§2. Lagrangean

The time rate of change of \( x_n \), or the "velocity" \( v_n \) is given from (2) as

\[ v_n = \dot{x}_n = \alpha^2 (1 - e^{-p_n}), \quad (9) \]

Therefore we see that upper bound of \( v_n \) is limited \(( -\infty < v_n < \alpha^2 )\). We have from (9)

\[ p_n = \log \frac{\alpha^2}{\alpha^2 - \dot{x}_n}. \quad (10) \]
The Lagrangean of the system is given as
\[ L(x, \dot{x}) = \sum_n \dot{x}_n p_n(\dot{x}_n) - H(x, p(\dot{x})), \quad (11) \]
which is
\[ L(x, \dot{x}) = \sum_n \left\{ -(\alpha^2 - \dot{x}_n) \log \frac{\alpha^2}{\alpha^2 - \dot{x}_n} + \dot{x}_n \right\} 
- \sum_n \left\{ e^{-(x_n - x_{n-1})} - 1 + (x_n - x_{n-1}) \right\}. \quad (12) \]
From this Lagrangean we have the momentum
\[ p_n = \frac{\partial L}{\partial \dot{x}_n} = \log \frac{\alpha^2}{\alpha^2 - \dot{x}_n}, \quad (13) \]
which is the same to (10). The Lagrange equations of motion\[ \frac{d}{dt} \frac{\partial L}{\partial \dot{x}_n} - \frac{\partial L}{\partial x_n} = 0 \quad (14) \]
gives\[ \frac{d}{dt} \log \frac{\alpha^2}{\alpha^2 - \dot{x}_n} - \left\{ e^{-(x_n - x_{n-1})} - e^{-(x_{n+1} - x_n)} \right\} = 0. \quad (15) \]
In view of (13), we see that (15) is the same to (2') as it should be.

§3. Lotka-Volterra’s System

The system under consideration has intimate connection to the Lotka-Volterra system of competing species,
\[ \frac{dN_i}{dt} = \epsilon_i N_i + \frac{1}{\beta_i} \sum_j \alpha_{ji} N_j N_i \quad (16) \]
where \( N_i \) is the population of the \( i \)-th species, and \( \epsilon_i, \beta_i \) and \( \alpha_{ji} \) are parameters specifying the system. \( \epsilon_i \) and \( \alpha_{ji} \) are plus or negative, or zero. It is assumed that \( N_i \) has certain equilibrium value \( q_i \), so that
\[ \epsilon_i + \frac{1}{\beta_i} \sum_j \alpha_{ji} q_j = 0. \quad (17) \]
Further, we assume that \((\alpha_{ji})\) is skew symmetric,

\[ \alpha_{ji} = -\alpha_{ij}, \]

then it is known that the system has a conserved quantity \(\left( \frac{dG}{dt} = 0 \right)\)

\[ G = \sum_{i} q_i \beta_i \left( e^{-v_i} - 1 + v_i \right), \quad (18) \]

where \(v_i\) is defined by

\[ N_i = q_i e^{-v_i}. \quad (19) \]

It is to be noted that (18) consists of the familiar functions of the form \(e^{-v} - 1 + v\), used in (2) for momentum and interaction terms.

Lotka-Volterra's equation (16) can be written as

\[ \frac{dv_i}{dt} = \frac{1}{\beta_i} \sum_j \alpha_{ji} q_j (1 - e^{-v_j}). \quad (20) \]

We may put

\[ v_{2n} = p_{n-1} \]
\[ v_{2n+1} = \tau_n. \quad (21) \]

If \(\alpha_{ji} = 0\) except that

\[ \frac{1}{\beta_{2n+1}} \alpha_{2n,2n+1} q_{2n} = -\alpha^2 \]
\[ \frac{1}{\beta_{2n+1}} \alpha_{2n+1,2n+1} q_{2n+2} = \alpha^2 \]
\[ \frac{1}{\beta_{2n}} \alpha_{2n-1,2n} q_{2n-1} = -1 \]
\[ \frac{1}{\beta_{2n}} \alpha_{2n+1,2n} q_{2n+1} = 1, \quad (22) \]

then Lotka-Volterra's equation (20) reduces to our equations (4) and (4'), and therefore to (8) and (8').

References