Displacement convexity of generalized relative entropies

Shin-ichi Ohta*and Asuka Takatsu[†]

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Abstract

We investigate the *m*-relative entropy, which stems from the Bregman divergence, on weighted Riemannian and Finsler manifolds. We prove that the displacement K-convexity of the *m*-relative entropy is equivalent to the combination of the nonnegativity of the weighted Ricci curvature and the K-convexity of the weight function. We use this to show appropriate variants of the Talagrand, HWI and the logarithmic Sobolev inequalities, as well as the concentration of measures. We also prove that the gradient flow of the *m*-relative entropy produces a solution to the porous medium equation or the fast diffusion equation.

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^{*}Department of Mathematics, Kyoto University, Kyoto 606-8502, Japan (sohta@math.kyoto-u.ac.jp) & Max-Planck-Institut für Mathematik, Vivatsgasse 7, 53111 Bonn, Germany; Supported in part by the Grant-in-Aid for Young Scientists (B) 20740036.

[†]Graduate School of Mathematics, Nagoya University, Nagoya 464-8602, Japan (takatsu@math.nagoyau.ac.jp) & Institut des Hautes Études Scientifiques, Bures-sur-Yvette 91440, France; Supported in part by Research Fellowships of the JSPS for Young Scientists & by JSPS-IHÉS (EPDI) Fellowship.

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1 Introduction

The displacement convexity of a functional on the space of probability measures was introduced in McCann's influential paper [Mc1] as the convexity along geodesics with respect to the L^2 -Wasserstein distance. Recent astonishing development of optimal transport theory reveals that the displacement convexity of entropy-type functionals plays important roles in the theory of partial differential equations, probability theory and differential geometry (see [AGS], [Vi1], [Vi2] and the references therein). For instance, on a compact Riemannian manifold (M, g) equipped with the Riemannian volume measure vol_g , the gradient flow of the relative entropy Ent_{vol_g} (see (3.3) for definition) in the L^2 -Wasserstein space $(\mathcal{P}(M), W_2)$ produces a weak solution to the heat equation ([Oh1], [GO], [Vi2, Chapter 23]). Then the displacement K-convexity of Ent_{vol_g} for some $K \in \mathbb{R}$ (denoted by Hess $Ent_{vol_g} \geq K$ for short) implies the K-contraction property

$$W_2(p(t, x, \cdot) \operatorname{vol}_g, p(t, y, \cdot) \operatorname{vol}_g) \le e^{-Kt} d(x, y), \qquad x, y \in M,$$

of the heat kernel $p: (0,\infty) \times M \times M \longrightarrow (0,\infty)$ (and vice versa, [vRS]), where d is the Riemannian distance. The condition $\text{Hess Ent}_{\text{vol}_g} \geq K$ is called the *curvature-dimension condition* $\mathsf{CD}(K,\infty)$ and known to be equivalent to the lower Ricci curvature bound Ric $\geq K$ ([vRS]). There is a rich theory on general metric measure spaces satisfying $\mathsf{CD}(K,\infty)$ ([St2], [LV2], [Vi2, Part III]). Especially, $\mathsf{CD}(K,\infty)$ with K > 0 is an important condition which yields, among others, the logarithmic Sobolev inequality and the normal concentration of measures (a kind of large deviation principle).

The curvature-dimension condition is generalized to $\mathsf{CD}(K, N)$ for each $K \in \mathbb{R}$ and $N \in (1, \infty]$, and then $\mathsf{CD}(K, N)$ is equivalent to the lower bound of the weighted Ricci curvature $\operatorname{Ric}_N \geq K$ of a weighted Riemannian manifold (M, ω) , where ω is a conformal deformation of vol_g ([St3], [LV1], see (2.1) for the definition of Ric_N). However, $\mathsf{CD}(K, N)$ with $N < \infty$ is written as a simple convexity condition only when K = 0 (and it causes some difficulties when $K \neq 0$, see [BS]). Precisely, $\mathsf{CD}(0, N)$ is defined as the convexity of the Rényi entropy S_N (see (3.2) for definition), while $\mathsf{CD}(K, N)$ with $K \neq 0$ is a more subtle inequality involving the integrand of S_N . Sturm has shown in [St1, Theorem 1.7] that there are (by no means unique) functionals whose displacement K-convexity is equivalent to the combination of Ric $\geq K$ and dim $\leq N$ for unweighted Riemannian manifolds, but it is unclear how this observation relates to $\mathsf{CD}(K, N)$.

In this article, we introduce and consider a different kind of relative entropy $H_m(\cdot|\nu)$ for $m \in [(n-1)/n, 1) \cup (1, \infty)$ —we call this the *m*-relative entropy—which is related to, but different from S_N . Here $\nu = \exp_m(-\Psi)\omega$ is a fixed conformal deformation of ω , and exp_m is the *m*-exponential function (see Subsection 2.2). Our definition of $H_m(\cdot|\nu)$ stems from the Bregman divergence in information theory/geometry which is closely related to the Tsallis and Rényi entropies (see Subsection 3.1). Roughly speaking, $H_m(\mu|\nu)$ is defined as

$$H_m(\mu|\nu) = \frac{1}{m(m-1)} \int_M \{\rho^m - m\rho\sigma^{m-1} + (m-1)\sigma^m\} \, d\omega,$$

for $\mu = \rho \omega$ and $\nu = \sigma \omega$ (see Definition 3.1 for the precise definition). We can regard $H_m(\mu|\nu)$ as representing the difference between μ and ν . Taking the limit as m tends to 1 recovers the usual relative entropy Ent_{ν} (or the Kullback-Leibler divergence $H(\cdot|\nu)$). Our results will guarantee that $H_m(\cdot|\nu)$ is a natural and important object.

Our first main theorem asserts that $\operatorname{Hess} H_m(\cdot|\nu) \geq K$ in $(\mathcal{P}^2(M), W_2)$ is equivalent to the combination of $\operatorname{Ric}_N \geq 0$ with N = 1/(1 - m) and $\operatorname{Hess} \Psi \geq K$, where Ric_N is of (M, ω) (Theorem 4.1). We remark that N can be negative, such Ric_N is not previously studied and would be of independent interest. It is also interesting to obtain split curvature bound/convexity conditions from a single convexity condition of the entropy. Then, according to the technique similar to the curvature-dimension condition, we show that $\operatorname{Ric}_N \geq 0$ and $\operatorname{Hess} \Psi \geq K$ imply appropriate variants of the Talagrand, HWI, logarithmic Sobolev and the global Poincaré inequalities (Propositions 5.1, 5.4, Theorem 5.2), and also the concentration of measures (Theorem 6.1, Proposition 6.7). Furthermore, the gradient flow of $H_m(\cdot|\nu)$ produces a weak solution to the porous medium equation (for m > 1) or the fast diffusion equation (for m < 1) of the form

$$\frac{\partial \rho}{\partial t} = \frac{1}{m} \Delta^{\omega}(\rho^m) + \operatorname{div}_{\omega}(\rho \nabla \Psi),$$

where Δ^{ω} and $\operatorname{div}_{\omega}$ are the Laplacian and the divergence associated with the measure ω (Theorem 7.6). Among others, we shall follow the metric geometric way of interpreting this coincidence as in [Oh1], [GO]. Most results hold true also for Finsler manifolds thanks to the theory developed in [Oh2] and [OS1] (see Section 8).

We comment on former related work on this kind of entropy. On unweighted Riemannian manifolds, Sturm showed a similar characterization of the displacement K-convexity of a class of entropies (or free energies) including H_m ([St1, Theorem 1.3]). We generalize this to weighted Riemannian (and even Finsler) manifolds, and then Ric is replaced with Ric_N (this is natural but nonobvious). Also our treatment of singular measures is more precise than [St1]. Gradient flow from the view of Wasserstein geometry has been investigated by Otto [Ot] in the Euclidean case, and by Villani [Vi2, Chapters 23, 24] in the weighted Riemannian case in a different manner from ours. Functional inequalities related to the convexity of the weight Ψ were studied in [AGK], [CGH] and [Ta2] in Euclidean spaces (see also [St1, Remark 1.1] and [Vi2, Chapters 24, 25]). The concentration of measures seems new even in the Euclidean setting.

The organization of the article is as follows. After preliminaries, we introduce the *m*-relative entropy $H_m(\cdot|\nu)$ in Section 3, and show that Hess $H_m(\cdot|\nu) \ge K$ is equivalent to Hess $\Psi \ge K$ with $\operatorname{Ric}_N \ge 0$ in Section 4. Using this equivalence, we obtain several functional inequalities in Section 5, and the concentration of measures in Section 6. Section 7 is devoted to the study of the gradient flow of $H_m(\cdot|\nu)$. Finally, we treat the Finsler case in Section 8.

2 Preliminaries

Throughout the article except the last section, (M, g) will be a complete, connected *n*dimensional C^{∞} -Riemannian manifold and *d* stands for the Riemannian distance of *M*. For simplicity and since we are interested in the role of curvature bounds, we will always assume $n \ge 2$. Denote by B(x, r) the open ball of center $x \in M$ and radius r > 0, i.e., $B(x, r) = \{y \in M \mid d(x, y) < r\}$. See, e.g., [Ch] for the basics of Riemannian geometry.

2.1 Weighted Ricci curvature

We fix a conformal change $\omega = e^{-\psi} \operatorname{vol}_g$, with $\psi \in C^{\infty}(M)$, of the Riemannian volume measure vol_g as our base measure. Given a unit vector $v \in T_x M$ and $N \in (-\infty, 0) \cup (n, \infty)$, we define the *weighted Ricci curvature* by

$$\operatorname{Ric}_{N}(v) := \operatorname{Ric}(v) + \operatorname{Hess}\psi(v,v) - \frac{\langle \nabla\psi, v \rangle^{2}}{N-n}.$$
(2.1)

We also set

$$\operatorname{Ric}_{n}(v) := \begin{cases} \operatorname{Ric}(v) + \operatorname{Hess}\psi(v,v) & \text{if } \langle \nabla\psi,v\rangle = 0, \\ -\infty & \text{otherwise.} \end{cases}$$

Observe that, if ψ is constant, then $\operatorname{Ric}_N(v)$ coincides with $\operatorname{Ric}(v)$ for all N.

Remark 2.1 We usually consider Ric_N only for $N \in [n, \infty]$ (where $\operatorname{Ric}_\infty(v) = \operatorname{Ric}(v) + \operatorname{Hess} \psi(v, v)$ is the *Bakry-Émery tensor*, see [BE], [Qi], [Lo]), and then it enjoys the monotonicity: $\operatorname{Ric}_N(v) \leq \operatorname{Ric}_{N'}(v)$ for N < N'. Admitting N < 0 violates this monotonicity, but we abuse this notation for brevity. The reason why we consider this range of N will be seen in (2.2).

As we mentioned in the introduction, $\operatorname{Ric}_N \geq K$ for $K \in \mathbb{R}$ and $N \geq n$ is equivalent to Sturm's *curvature-dimension condition* $\operatorname{CD}(K, N)$. Spaces satisfying $\operatorname{CD}(K, N)$ behave like a space with "dimension $\leq N$ as well as Ricci curvature $\geq K$ " (see [St3], [LV1], [Vi2, Part III]).

2.2 Generalized exponential functions and Gaussian measures

We briefly recall the *m*-calculus, see [Ts2] for further discussion. We introduce a parameter m such that

$$m \in [(n-1)/n, 1) \cup (1, \infty).$$

We sometimes eliminate the special case m = 1/2 with n = 2 (Section 5) or restrict ourselves to $m \leq 2$ (Sections 6, 7). We set

$$N = N(m) := 1/(1-m) \in (-\infty, 0) \cup [n, \infty).$$
(2.2)

Define the m-logarithmic function by

$$\ln_m(t) := \frac{t^{m-1} - 1}{m - 1} \quad \text{for } \begin{cases} t > 0 & \text{if } m < 1, \\ t \ge 0 & \text{if } m > 1. \end{cases}$$

Note that \ln_m is monotone increasing and that the image of \ln_m is $(-\infty, 1/(1-m))$ if m < 1; $[-1/(m-1), \infty)$ if m > 1. We define the *m*-exponential function \exp_m as the inverse of \ln_m , namely

$$\exp_m(t) := \{1 + (m-1)t\}^{1/(m-1)} \quad \text{for } \begin{cases} t \in (-\infty, 1/(1-m)) & \text{if } m < 1, \\ t \in [-1/(m-1), \infty) & \text{if } m > 1. \end{cases}$$

For the sake of simplicity, we set $\exp_m(t) := 0$ for m > 1 and t < -1/(m-1). We also define

$$e_m(t) := t \ln_m(t) = \frac{t^m - t}{m - 1}$$
 for $t > 0$, $e_m(0) := 0$.

Observe that

$$\lim_{m \to 1} \ln_m(t) = \ln(t), \qquad \lim_{m \to 1} \exp_m(t) = e^t, \qquad \lim_{m \to 1} e_m(t) = t \ln(t).$$

Remark 2.2 (1) Taking m < 1 and m > 1 gives rise to qualitatively different phenomena (see Lemma 2.5, Example 2.6 for instances). Nonetheless, most of our results will cover both cases.

(2) In some notations, it is common to use the parameter q = 2 - m instead of m (e.g., \exp_q and q-Gaussian measures). In the present paper, however, we shall use only m for brevity.

Using \exp_m and the base measure $\omega = e^{-\psi} \operatorname{vol}_g$, we will fix another measure

$$\nu = \sigma\omega := \exp_m(-\Psi)\omega$$

as our reference measure, where $\Psi \in C(M)$ such that $\Psi > -1/(1-m)$ if m < 1. Note that the two weights $e^{-\psi}$ and $\exp_m(-\Psi)$ involve different kinds of exponential function, so that they can not be combined. For later convenience, we set

$$M_0 := \begin{cases} M & \text{for } m < 1, \\ \Psi^{-1} ((-\infty, 1/(m-1))) & \text{for } m > 1, \end{cases}$$
(2.3)

and assume that M_0 is nonempty. Note that $\operatorname{supp} \nu = \overline{M_0}$ holds in both cases. We shall study how the convexity of Ψ has an effect on the geometric and analytic structures of (M, ν) .

Definition 2.3 (K-convexity) Given $K \in \mathbb{R}$, we say that Ψ is *K-convex in the weak* sense, denoted by Hess $\Psi \geq K$ for short, if any two points $x, y \in M$ admit a minimal geodesic $\gamma : [0, 1] \longrightarrow M$ from x to y along which

$$\Psi(\gamma(t)) \le (1-t)\Psi(x) + t\Psi(y) - \frac{K}{2}(1-t)td(x,y)^2$$
(2.4)

holds for all $t \in [0, 1]$.

Note that this is equivalent to saying that (2.4) holds along any minimal geodesic γ between x and y, for $\gamma|_{[\varepsilon,1-\varepsilon]}$ is a unique minimal geodesic for all $\varepsilon > 0$ and Ψ is continuous.

Remark 2.4 Consider a different presentation $\nu = (c\sigma)(c^{-1}\omega) =: \tilde{\sigma}\tilde{\omega}$ of ν for some constant c > 0. Then the weighted Ricci curvature Ric_N is unchanged, while

$$\tilde{\sigma} = c \exp_m(-\Psi) = \{c^{m-1} - (m-1)c^{m-1}\Psi\}^{1/(m-1)}$$
$$= \left\{1 - (m-1)\left(c^{m-1}\Psi - \frac{c^{m-1} - 1}{m-1}\right)\right\}^{1/(m-1)} =: \exp_m(-\widetilde{\Psi})$$

and hence $\operatorname{Hess} \widetilde{\Psi} = c^{m-1} \operatorname{Hess} \Psi$.

Sections 5, 6 will be concerned with the case where $\text{Hess } \Psi \geq K > 0$ as well as $\text{Ric}_N \geq 0$. In such a situation, it turns out that ν has finite total mass. Here we give explicit estimates for later use (in Section 6).

Lemma 2.5 Assume that $\text{Hess } \Psi \geq K$ holds for some K > 0, and take a unique minimizer $x_0 \in M$ of Ψ .

(i) If m < 1 and $\operatorname{Ric}_N \geq 0$, then $\sigma \in L^c(M, \omega)$ for all $c \in (1/2, 1]$, in particular, $\nu(M) < \infty$. Moreover, we have

$$\int_{M} \sigma^{c} d\omega \leq C_{1}^{1-c} \nu(M)^{c} + C_{2} K^{c/(m-1)}$$

for some $C_1 = C_1(\omega) > 0$ and $C_2 = C_2(m, c, \omega) > 0$.

- (ii) If m < 1 and $\operatorname{Ric}_N \ge 0$, then $\int_M d(x_0, x)^p \, d\nu < \infty$ for all $p \in [1, 1/(1-m))$.
- (iii) If m > 1, then M_0 and $\operatorname{supp} \nu$ are convex in the sense that any pair of points in M_0 or $\operatorname{supp} \nu$ is connected by a minimal geodesic contained in M_0 or $\operatorname{supp} \nu$, respectively. In addition, we have

$$\operatorname{supp} \nu \subset \overline{B\left(x_0, \left\{\frac{2}{K}\left(\frac{1}{m-1} - \Psi(x_0)\right)\right\}^{1/2}\right)}.$$

Proof. By our assumption $\text{Hess } \Psi \ge K > 0$, we find a unique point $x_0 \in M_0$ such that $\Psi(x_0) = \inf_M \Psi$. Then we deduce from (2.4) that

$$\Psi(\gamma(1)) \ge \Psi(x_0) + \frac{K}{2}d(x_0,\gamma(1))^2$$

holds for all minimal geodesics γ with $\gamma(0) = x_0$. Thus we have

$$\sigma(x) = \exp_m\left(-\Psi(x)\right) \le \exp_m\left(-\Psi(x_0) - \frac{K}{2}d(x_0, x)^2\right)$$
(2.5)

for all $x \in M_0$.

(i) Denote by $\operatorname{area}_{\omega}(S(x_0, r))$ the area of the sphere $S(x_0, r) := \{x \in M \mid d(x_0, x) = r\}$ with respect to ω . Then (2.5) implies

$$\int_{M} \sigma^{c} d\omega \leq \int_{B(x_{0},1)} \sigma^{c} d\omega + \int_{1}^{\infty} \exp_{m} \left(-\Psi(x_{0}) - \frac{K}{2}r^{2} \right)^{c} \operatorname{area}_{\omega} \left(S(x_{0},r) \right) dr.$$

On the one hand, it follows from $\operatorname{Ric}_N \geq 0$ that, for $r \geq 1$,

$$\operatorname{area}_{\omega} \left(S(x_0, r) \right) \le r^{N-1} \operatorname{area}_{\omega} \left(S(x_0, 1) \right) = r^{m/(1-m)} \operatorname{area}_{\omega} \left(S(x_0, 1) \right)$$

(cf. [St3, Theorem 2.3]). Therefore we obtain, putting $a := \exp_m(-\Psi(x_0))^{m-1} > 0$,

$$\int_{1}^{\infty} \exp_{m} \left(-\Psi(x_{0}) - \frac{K}{2}r^{2} \right)^{c} \operatorname{area}_{\omega} \left(S(x_{0}, r) \right) dr$$

$$\leq \operatorname{area}_{\omega} \left(S(x_{0}, 1) \right) \int_{1}^{\infty} \left\{ a + (1 - m) \frac{K}{2}r^{2} \right\}^{c/(m-1)} r^{m/(1-m)} dr$$

$$= \operatorname{area}_{\omega} \left(S(x_{0}, 1) \right) \int_{1}^{\infty} \left\{ ar^{-2} + (1 - m) \frac{K}{2} \right\}^{c/(m-1)} r^{(m-2c)/(1-m)} dr$$

$$\leq \operatorname{area}_{\omega} \left(S(x_{0}, 1) \right) \left\{ (1 - m) \frac{K}{2} \right\}^{c/(m-1)} \int_{1}^{\infty} r^{(m-2c)/(1-m)} dr.$$

As c > 1/2, the most right-hand side coincides with

$$\operatorname{area}_{\omega} \left(S(x_0, 1) \right) \frac{(1-m)^{c/(m-1)+1}}{2c-1} \left(\frac{K}{2} \right)^{c/(m-1)} =: C_2(m, c, \omega) K^{c/(m-1)} < \infty.$$

On the other hand, as $\nu(M) < \infty$ is already observed, the Hölder inequality and $c \leq 1$ yield

$$\int_{B(x_0,1)} \sigma^c d\omega \le \left(\int_{B(x_0,1)} \sigma d\omega\right)^c \omega \left(B(x_0,1)\right)^{1-c} \le \nu(M)^c \omega \left(B(x_0,1)\right)^{1-c}.$$

We set $C_1(\omega) = \omega(B(x_0, 1))$ and complete the proof.

(ii) We similarly deduce from (2.5) and $\operatorname{Ric}_N \geq 0$ that

$$\int_{M\setminus B(x_0,1)} d(x_0,x)^p \, d\nu(x)$$

$$\leq \int_1^\infty r^p \exp_m \left(-\Psi(x_0) - \frac{K}{2}r^2 \right) \operatorname{area}_\omega \left(S(x_0,r) \right) dr$$

$$\leq \operatorname{area}_\omega \left(S(x_0,1) \right) \left\{ (1-m)\frac{K}{2} \right\}^{1/(m-1)} \int_1^\infty r^{p+(m-2)/(1-m)} \, dr$$

$$= \operatorname{area}_\omega \left(S(x_0,1) \right) \frac{(1-m)^{m/(m-1)}}{1-(1-m)p} \left(\frac{K}{2} \right)^{1/(m-1)} < \infty.$$

We used p < 1/(1-m) to see p + (m-2)/(1-m) < -1.

(iii) Recall that $M_0 = \Psi^{-1}((-\infty, 1/(m-1)))$ and $\operatorname{supp} \nu = \overline{M_0}$. Therefore M_0 and $\operatorname{supp} \nu$ are convex and (2.5) shows the desired estimate.

Observe that the convexity of M_0 and $\operatorname{supp} \nu$ in Lemma 2.5(iii) holds true also for K = 0.

Example 2.6 (*m***-Gaussian measures)** One fundamental and important example to which Lemma 2.5 applies is the *m*-Gaussian measure on \mathbb{R}^n defined by

$$N_m(v,V) = \sigma dx := \frac{C_0}{(\det V)^{1/2}} \exp_m \left[-\frac{C_1}{2} \langle x - v, V^{-1}(x - v) \rangle \right] dx, \qquad (2.6)$$

where dx is the Lebesgue measure, a vector $v \in \mathbb{R}^n$ is the mean, a positive-definite symmetric matrix $V \in \text{Sym}^+(n, \mathbb{R})$ is the covariance matrix, and C_0, C_1 are positive constants depending only on n and m (see [Ta2]). Then clearly Hess $\Psi = C_0^{m-1} (\text{det}V)^{(1-m)/2} \cdot C_1 V^{-1}$ (by taking Remark 2.4 into account) and hence

Hess
$$\Psi \ge C_0^{m-1} C_1 (\det V)^{(1-m)/2} \Lambda^{-1} > 0$$
,

where Λ denotes the largest eigenvalue of V. Note that $N_m(v, V)$ has unbounded and bounded support for m < 1 and m > 1, respectively. The family of *m*-Gaussian measures will play interesting roles in Sections 3, 5, 7.

2.3 Wasserstein geometry

We very briefly recall some fundamental facts in optimal transport theory and Wasserstein geometry. We refer to [Vi1], [Vi2] for basics as well as recent diverse development of them.

Let (X, d) be a complete, separable metric space. A rectifiable curve $\gamma : [0, 1] \longrightarrow X$ is called a *geodesic* if it is locally minimizing and has a constant speed, we say that γ is *minimal* if it is globally minimizing (i.e., $d(\gamma(s), \gamma(t)) = |s - t| d(\gamma(0), \gamma(1))$) for all $s, t \in [0, 1]$). If any two points in X are connected by a minimal geodesic, then (X, d) is called a *geodesic space*.

We denote by $\mathcal{P}(X)$ the set of all Borel probability measures on X, and by $\mathcal{P}^p(X) \subset \mathcal{P}(X)$ with $p \geq 1$ the subset consisting of measures μ of finite p-th moment, that is, $\int_X d(x,y)^p d\mu(y) < \infty$ for some (and hence all) $x \in X$. Clearly $\mathcal{P}^p(X) = \mathcal{P}(X)$ if X is bounded. Given $\mu, \nu \in \mathcal{P}(X)$, a probability measure $\pi \in \mathcal{P}(X \times X)$ is called a *coupling* of μ and ν if its projections coincides with μ and ν , namely $\pi(A \times X) = \mu(A)$ and $\pi(X \times A) = \nu(A)$ hold for any Borel set $A \subset X$. We define the L^p -Wasserstein distance between $\mu, \nu \in \mathcal{P}^p(X)$ by

$$W_p(\mu,\nu) := \inf_{\pi} \left(\int_{X \times X} d(x,y)^p \, d\pi(x,y) \right)^{1/p},$$

where π runs over all couplings of μ and ν . We call π an *optimal coupling* if it attains the infimum above. We remark that $W_p(\mu, \nu)$ is finite since $\mu, \nu \in \mathcal{P}^p(X)$, and it is indeed a distance of $\mathcal{P}^p(X)$. The metric space $(\mathcal{P}^p(X), W_p)$ is called the L^p -Wasserstein space over X. If X is compact, then $(\mathcal{P}(X), W_p)$ is also compact and the topology induced from W_p coincides with the weak topology.

We will consider only the case of p = 2 that is suitable and important for applications in Riemannian geometry. A minimal geodesic between $\mu, \nu \in \mathcal{P}^2(X)$ amounts to an optimal way of transporting μ to ν with respect to the quadratic cost $d(x, y)^2$. Then it is natural to expect that such an optimal transport is performed along minimal geodesics in X, that is indeed the case as seen in the following proposition. We denote by $\Gamma(X)$ the set of all minimal geodesics $\gamma : [0, 1] \longrightarrow X$ endowed with the topology induced from the distance $d_{\Gamma(X)}(\gamma, \eta) := \sup_{t \in [0,1]} d(\gamma(t), \eta(t))$. For $t \in [0,1]$, define the evaluation map $e_t : \Gamma(X) \longrightarrow X$ as $e_t(\gamma) := \gamma(t)$, and observe that each e_t is 1-Lipschitz.

Proposition 2.7 ([Vi2, Corollary 7.22]) Let (X, d) be a locally compact geodesic space. Then, for any $\mu, \nu \in \mathcal{P}^2(X)$ and any minimal geodesic $\alpha : [0, 1] \longrightarrow \mathcal{P}^2(X)$ between them, there exists $\Pi \in \mathcal{P}(\Gamma(X))$ such that $(e_0 \times e_1)_{\sharp} \Pi$ is an optimal coupling of μ and ν and that $(e_t)_{\sharp} \Pi = \alpha(t)$ holds for all $t \in [0, 1]$.

We denoted by $(e_t)_{\sharp}\Pi$ the push-forward measure of Π by e_t . In Riemannian manifolds, a more precise description of an optimal transport using a gradient vector field of some kind of convex function is known. We first recall McCann's original work on compact Riemannian manifolds. Denote by $\mathcal{P}_{ac}(M, \operatorname{vol}_g) \subset \mathcal{P}(M)$ the subset of absolutely continuous measures with respect to the volume measure vol_g . We also set $\mathcal{P}^2_{ac}(M, \operatorname{vol}_g) := \mathcal{P}^2(M) \cap \mathcal{P}_{ac}(M, \operatorname{vol}_g)$.

Theorem 2.8 ([Mc2, Theorems 8, 9]) Let (M, g) be a compact Riemannian manifold. Then, for any $\mu \in \mathcal{P}_{ac}(M, \operatorname{vol}_g)$ and $\nu \in \mathcal{P}(M)$, there exists a $(d^2/2)$ -convex function $\varphi : M \longrightarrow \mathbb{R}$ such that the map $\mathcal{T}_t(x) := \exp_x(t\nabla\varphi(x)), t \in [0, 1]$, provides a unique minimal geodesic from μ to ν . Precisely, $(\mathcal{T}_0 \times \mathcal{T}_1)_{\sharp}\mu$ is an optimal coupling of μ and ν , and $\mu_t = (\mathcal{T}_t)_{\sharp}\mu$ is a minimal geodesic from $\mu_0 = \mu$ to $\mu_1 = \nu$ with respect to W_2 .

See [Vi2, Chapter 5] for the definition of the $(d^2/2)$ -convex function, here we only remark that it is semi-convex in compact spaces. Such convexity is important as it implies the almost everywhere twice differentiability (due to the Alexandrov-Bangert theorem), and is generalized to noncompact spaces in [FG].

Theorem 2.9 ([FG, Theorem 1]) Let (M, g) be a complete Riemannian manifold. Then, for any $\mu \in \mathcal{P}^2_{ac}(M, \operatorname{vol}_g)$ and $\nu \in \mathcal{P}^2(M)$, there exists a locally semi-convex function $\varphi :$ $\Omega \longrightarrow \mathbb{R}$ on an open set $\Omega \subset M$ with $\mu(\Omega) = 1$ such that the map $\mathcal{T}_t(x) := \exp_x(t\nabla\varphi(x))$, $t \in [0, 1]$, provides a unique minimal geodesic from μ to ν (in the sense of Theorem 2.8).

We will also use the following Jacobian (or Monge-Amperè) equation.

Theorem 2.10 ([Vi2, Theorems 8.7, 11.1]) Let (M, g) be complete and μ , ν , φ , Ω and \mathcal{T}_t be as in Theorem 2.9 above. Put

$$\mathbf{J}_{t}^{\omega}(x) := e^{\psi(x) - \psi(\mathcal{T}_{t}(x))} \det(D\mathcal{T}_{t}(x))$$

for $x \in \Omega$ and $t \in [0,1)$. Then it holds $\mu_t \in \mathcal{P}^2_{ac}(M, \operatorname{vol}_g)$ and $(\rho_t \circ \mathcal{T}_t)\mathbf{J}^{\omega}_t = \rho_0 \ \mu_0$ -a.e. for all $t \in [0,1)$, where we set $\mu_t = (\mathcal{T}_t)_{\sharp}\mu = \rho_t\omega$. In particular, $\mathbf{J}^{\omega}_t > 0 \ \mu_0$ -a.e. for each $t \in [0,1)$. If in addition $\nu \in \mathcal{P}^2_{ac}(M, \operatorname{vol}_g)$, then the above assertions hold also at t = 1.

Note that \mathbf{J}_t^{ω} is the combination of the Jacobian det $(D\mathcal{T}_t)$ of \mathcal{T}_t with respect to the metric g and the ratio $e^{\psi - \psi(\mathcal{T}_t)}$ of the weight $e^{-\psi}$ on vol_g .

3 Generalized relative entropies

Before discussing the *m*-relative entropy, we briefly review the Boltzmann and the Tsallis entropies (see [Ts1], [Ts2]), and explain the motivation related to information geometry (see [Am], [AN]).

3.1 Background: Tsallis entropy and information geometry

Entropy is a functional playing prominent roles in thermodynamics, information theory (sometimes with the opposite sign) and many other fields. It describes how particles diffuse in thermodynamics, and measures the uncertainty of an event in information theory. The most fundamental entropy is the *Boltzmann(-Gibbs-Shannon) entropy* given by

$$E(\mu) = -\int_{\mathbb{R}^n} \rho \ln \rho \, dx$$

for $\mu = \rho dx \in \mathcal{P}_{ac}(\mathbb{R}^n, dx)$, where dx is the Lebesgue measure.

Boltzmann entropy is thermodynamically *extensive* and probabilistically *additive*, so that it is suitable for the treatment of independent systems. Precisely, for two independent distributions $\mu_1, \mu_2 \in \mathcal{P}_{ac}(\mathbb{R}^n, dx)$ and their joint probability $\mu_1 \times \mu_2 \in \mathcal{P}_{ac}(\mathbb{R}^{2n}, dx)$, one easily observes $E(\mu_1 \times \mu_2) = E(\mu_1) + E(\mu_2)$. Recently, there is a growing interest in strongly correlated systems and non-additive entropies. Among them, we are interested in the *Tsallis entropy* defined by

$$E_m(\mu) := -\int_{\mathbb{R}^n} e_m(\rho) \, dx = -\int_{\mathbb{R}^n} \rho \ln_m \rho \, dx = -\int_{\mathbb{R}^n} \frac{\rho^m - \rho}{m - 1} \, dx \tag{3.1}$$

for $\mu = \rho dx \in \mathcal{P}_{ac}(\mathbb{R}^n, dx)$, where $m \in [(n-1)/n, 1) \cup (1, 2]$. Note that letting m tend to 1 recovers the Boltzmann entropy $E(\mu)$, and that $E_m(\mu)$ is closely related to the *Rényi* entropy

$$S_N(\mu) := -\int_{\mathbb{R}^n} \rho^{1-1/N} \, dx = (m-1)E_m(\mu) - 1. \tag{3.2}$$

One can connect E and E_m via Gaussian measures as follows. On the one hand, given $v \in \mathbb{R}^n$ and $V \in \text{Sym}^+(n, \mathbb{R})$, the (usual) Gaussian measure

$$N(v,V) = \frac{1}{(2\pi)^{n/2} (\det V)^{1/2}} \exp\left[-\frac{1}{2}\langle x-v, V^{-1}(x-v)\rangle\right] dx$$

maximizes E among $\mu \in \mathcal{P}_{ac}(\mathbb{R}^n, dx)$ with mean v and covariance matrix V. On the other hand, the *m*-Gaussian measure $N_m(v, V)$ defined in (2.6) similarly maximizes E_{2-m} under the same constraint (for $m \neq 1/2, 2$).

In the following sections, we shall verify that a number of further geometric and analytic properties of E have counterparts for E_m . Precisely, since E_m itself is not really interesting in our view (see Remark 4.3(2)), we modify E_m in the manner of information geometry.

We start from the family of Gaussian measures

$$\mathcal{N}(n) := \{ N(v, V) \, | \, v \in \mathbb{R}^n, \, V \in \mathrm{Sym}^+(n, \mathbb{R}) \}$$

as an $((n^2 + 3n)/2)$ -dimensional manifold. In information geometry, we equip $\mathcal{N}(n)$ with the Fisher information metric m_F which is different from the Wasserstein metric W_2 . In fact, $(\mathcal{N}(1), m_F)$ has the negative constant sectional curvature ([Am]), while $(\mathcal{N}(1), W_2)$ is flat (cf. [Ta1, Theorem 2.2] and the references therein). The Fisher metric admits a pair of dually flat connections (exponential and mixture connections) and the Kullback-Leibler divergence

$$H(\mu|\nu) = \int_{\mathbb{R}^n} \frac{\rho}{\sigma} \ln\left(\frac{\rho}{\sigma}\right) d\nu$$

for $\nu = \sigma dx \in \mathcal{P}_{ac}(\mathbb{R}^n, dx)$ and $\mu = \rho dx \in \mathcal{P}_{ac}(\mathbb{R}^n, \nu)$. Note that $H(\mu|\nu)$ is nonnegative by Jensen's inequality. The square root of the divergence $H(\mu|\nu)$ can be regarded as a kind of distance between μ and ν . It certainly satisfies a generalized Pythagorean theorem, though it does not satisfy symmetry nor the triangle inequality. The Kullback-Leibler divergence $H(\mu|\nu)$ coincides with the *relative entropy* $\operatorname{Ent}_{\nu}(\mu)$ of μ with respect to ν . Roughly speaking, $\operatorname{Ent}_{\nu}(\mu)$ is defined for $\mu \in \mathcal{P}(\mathbb{R}^n)$ and a Borel measure ν on \mathbb{R}^n by

$$\operatorname{Ent}_{\nu}(\mu) := \begin{cases} \int_{\mathbb{R}^n} \varsigma \ln \varsigma \, d\nu & \text{for } \mu = \varsigma \nu \in \mathcal{P}_{\operatorname{ac}}(\mathbb{R}^n, \nu), \\ \infty & \text{otherwise,} \end{cases}$$
(3.3)

and then $\operatorname{Ent}_{\nu}(\mu) \geq -\ln \nu(\mathbb{R}^n)$.

The family of m-Gaussian measures

$$\mathcal{N}(n,m) := \{ N_m(v,V) \, | \, v \in \mathbb{R}^n, \, V \in \mathrm{Sym}^+(n,\mathbb{R}) \}$$

similarly admits dually flat connections and the corresponding *Bregman divergence* (called the β -divergence, cf. [OW, §2.1]) is

$$H_m(\mu|\nu) = \frac{1}{m(m-1)} \int_{\mathbb{R}^n} \{\rho^m - m\rho\sigma^{m-1} + (m-1)\sigma^m\} dx$$
(3.4)

for $\nu = \sigma dx \in \mathcal{P}_{ac}(\mathbb{R}^n, dx)$ and $\mu = \rho dx \in \mathcal{P}_{ac}(\mathbb{R}^n, \nu)$. We can rewrite this by using e_m as

$$H_m(\mu|\nu) = \frac{1}{m} \int_{\mathbb{R}^n} \{e_m(\rho) - e_m(\sigma) - e'_m(\sigma)(\rho - \sigma)\} dx$$

and recover the Kullback-Leibler divergence as the limit:

$$\lim_{m \to 1} H_m(\mu|\nu) = \int_{\mathbb{R}^n} \{\rho \ln \rho - \sigma \ln \sigma - (\ln \sigma + 1)(\rho - \sigma)\} dx = H(\mu|\nu).$$

It will turn out that the entropy induced from (3.4) is appropriate for our purpose. We remark that the division by m in (3.4) is unessential, we prefer this form merely for aesthetic reasons of the presentation of Theorem 4.1.

3.2 *m*-relative entropy

Recall our weighted Riemannian manifold (M, ω) and reference measure $\nu = \sigma \omega$. The Bregman divergence (3.4) leads us to the following generalization of the relative entropy.

Definition 3.1 (*m***-relative entropy)** Assume $\sigma \in L^m(M, \omega)$. Given $\mu \in \mathcal{P}(M)$, let $\mu = \rho \omega + \mu^s$ be its Lebesgue decomposition into absolutely continuous and singular parts with respect to ω . Then we define the *m*-relative entropy as follows.

(1) For m < 1,

$$H_{m}(\mu|\nu) = \frac{1}{m} \int_{M} \{e_{m}(\rho) - e_{m}(\sigma) - e'_{m}(\sigma)(\rho - \sigma)\} d\omega - \frac{1}{m-1} \int_{M} \sigma^{m-1} d\mu^{s} + H_{m}(\infty)\mu^{s}(M) = \frac{1}{m(m-1)} \int_{M} \{\rho^{m} + (m-1)\sigma^{m}\} d\omega - \frac{1}{m-1} \int_{M} \sigma^{m-1} d\mu + H_{m}(\infty)\mu^{s}(M)$$
(3.5)

if $\sigma \in L^{m-1}(M,\mu)$, where $H_m(\infty) := 0$. We define $H_m(\mu|\nu) := \infty$ for $\mu \in \mathcal{P}(M)$ with $\sigma \notin L^{m-1}(M,\mu)$.

(2) For m > 1, $H_m(\mu|\nu)$ is defined by (3.5) if $\rho \in L^m(M, \omega)$, where $H_m(\infty) := \infty$ and $\infty \cdot 0 = 0$ as convention. We set $H_m(\mu|\nu) := \infty$ for $\mu \in \mathcal{P}(M)$ with $\rho \notin L^m(M, \omega)$.

For $\mu = \rho \omega \in \mathcal{P}_{ac}(M, \omega)$, (3.5) has the simplified form

$$H_m(\mu|\nu) = \frac{1}{m(m-1)} \int_M \{\rho^m - m\rho\sigma^{m-1} + (m-1)\sigma^m\} \, d\omega$$

as in (3.4). Note that the first two terms in the right hand side are regarded as the internal and external energies, and the last term (which is independent of μ) is added for the sake of nonnegativity (see Lemma 3.3).

Remark 3.2 (1) If Hess $\Psi \ge K > 0$, then the primal assumption $\sigma \in L^m(M, \omega)$ is clearly satisfied for m > 1 by Lemma 2.5(iii). We deduce from Lemma 2.5(i) that $\sigma \in L^m(M, \omega)$ also holds true if Hess $\Psi \ge K > 0$, Ric_N ≥ 0 and $m \in (1/2, 1)$.

(2-a) For m < 1, if $\sigma \in L^{m-1}(M, \mu)$, then the Hölder inequality implies

$$\int_{M} \rho^{m} d\omega = \int_{M} (\rho \sigma^{m-1})^{m} \sigma^{m(1-m)} d\omega \le \left(\int_{M} \rho \sigma^{m-1} d\omega\right)^{m} \left(\int_{M} \sigma^{m} d\omega\right)^{1-m}.$$

Thus we have $\rho \in L^m(M, \omega)$. Moreover, for $\mu = \rho \omega \in \mathcal{P}_{ac}(M, \omega)$, it holds

$$H_m(\mu|\nu) - \frac{1}{m} \int_M \sigma^m d\omega$$

$$\geq \frac{1}{m(m-1)} \left(\int_M \sigma^{m-1} d\mu \right)^m \left(\int_M \sigma^m d\omega \right)^{1-m} + \frac{1}{1-m} \int_M \sigma^{m-1} d\mu$$

$$= \frac{1}{m(1-m)} \left(\int_M \sigma^{m-1} d\mu \right)^m \left\{ m \left(\int_M \sigma^{m-1} d\mu \right)^{1-m} - \left(\int_M \sigma^m d\omega \right)^{1-m} \right\},$$

and hence it is natural to define $H_m(\mu|\nu) = \infty$ for μ with $\sigma \notin L^{m-1}(M,\mu)$.

(2-b) For m > 1 and $\rho \in L^m(M, \omega)$, the Hölder inequality

$$\int_{M} \rho \sigma^{m-1} d\omega \le \left(\int_{M} \rho^{m} d\omega \right)^{1/m} \left(\int_{M} \sigma^{m} d\omega \right)^{(m-1)/m}$$

similarly yields $\sigma \in L^{m-1}(M,\mu)$ and, for $\mu = \rho \omega \in \mathcal{P}_{\mathrm{ac}}(M,\omega)$,

$$H_{m}(\mu|\nu) - \frac{1}{m} \int_{M} \sigma^{m} d\omega$$

$$\geq \frac{1}{m(m-1)} \left(\int_{M} \rho^{m} d\omega \right)^{1/m} \left\{ \left(\int_{M} \rho^{m} d\omega \right)^{(m-1)/m} - m \left(\int_{M} \sigma^{m} d\omega \right)^{(m-1)/m} \right\}.$$
The product of the product

Hence it is again natural to set $H_m(\mu|\nu) = \infty$ for $\rho \notin L^m(M, \omega)$.

(3) The validity of the definition of $H_m(\infty)$ would be understood by the following observation (putting $\rho = \chi_{B(x,\varepsilon)}/\omega(B(x,\varepsilon))$ so that $\chi_{B(x,\varepsilon)}$ is the characteristic function of $B(x,\varepsilon)$):

$$\int_{B(x,\varepsilon)} \frac{1}{\omega(B(x,\varepsilon))^m} \, d\omega = \omega \big(B(x,\varepsilon) \big)^{1-m} \to \begin{cases} 0 & \text{if } m < 1, \\ \infty & \text{if } m > 1 \end{cases}$$

as ε tends to zero (see also Lemma 3.4 below).

Next we see that ν is a unique ground state of $H_m(\cdot|\nu)$ (provided $\nu(M) = 1$).

Lemma 3.3 We have $H_m(\mu|\nu) \ge 0$ for all $\mu \in \mathcal{P}(M)$, and equality holds if and only if $\nu \in \mathcal{P}_{ac}(M, \omega)$ and $\mu = \nu$.

Proof. Note that, if $\mu^s(M) > 0$, then the singular part

$$-\frac{1}{m-1}\int_M \sigma^{m-1} d\mu^s + H_m(\infty)\mu^s(M)$$

in (3.5) is positive for m < 1 (since $\sigma > 0$ on M) and infinity for m > 1, respectively. Hence it is sufficient to consider the absolutely continuous part. As the function $e_m(t) = (t^m - t)/(m - 1)$ is strictly convex on $(0, \infty)$, we have

$$e_m(\rho) - e_m(\sigma) - e'_m(\sigma)(\rho - \sigma) \ge 0$$

in (3.5) and equality holds if and only if $\rho = \sigma$. Therefore $H_m(\mu|\nu) \ge 0$ and equality holds if and only if $\mu^s(M) = 0$ and $\rho = \sigma \omega$ -a.e..

The following lemma will be used in Section 7 (Claim 7.7) where M is assumed to be compact. This also guarantees the validity of the definition of $H_m(\infty)$.

Lemma 3.4 Let (M, g) be compact. Then the entropy $H_m(\cdot|\nu)$ is lower semi-continuous with respect to the weak topology, that is to say, if a sequence $\{\mu_i\}_{i\in\mathbb{N}} \subset \mathcal{P}(M)$ weakly converges to $\mu \in \mathcal{P}(M)$, then we have

$$H_m(\mu|\nu) \leq \liminf_{i \to \infty} H_m(\mu_i|\nu).$$

Proof. We divide $H_m(\mu|\nu) - m^{-1} \int_M \sigma^m d\omega$ into two parts:

$$h_1(\mu) := \frac{1}{m(m-1)} \int_M \rho^m \, d\omega + H_m(\infty) \mu^s(M), \quad h_2(\mu) := -\frac{1}{m-1} \int_M \sigma^{m-1} \, d\mu.$$

Then $h_2(\mu)$ is clearly continuous in μ (since M is compact). In addition, the lower semi-continuity of $h_1(\mu)$ follows from [LV2, Theorem B.33] since the function $U_m(t) := t^m/m(m-1)$ is continuous, convex and satisfies $U_m(0) = 0$ as well as $\lim_{t\to\infty} U_m(t)/t = H_m(\infty)$.

4 Displacement convexity

In this section, we prove our first main theorem on a characterization of the displacement convexity of $H_m(\cdot|\nu)$ along the lines of [CMS], [vRS], [St1] and [St3].

In [St1], Sturm considered a more general class of entropies (or free energies) on unweighted Riemannian manifolds. Then his [St1, Theorem 1.3] includes the equivalence between (A) and (B) in Theorem 4.1 below (with $\omega = \text{vol}_g$, see also [St1, Remark 1.1]). To be precise, in his theorem, the condition (A) is written as

$$U'(r)\operatorname{Ric}(v) + \operatorname{Hess}\Psi(v,v) \ge K$$

for all $r \in \mathbb{R}$ and unit vectors $v \in TM$, where $U(r) = e^{(m-1)r}/m(m-1)$ (one more condition $U''(r) + U'(r)/n \geq 0$ corresponds to $m \geq (n-1)/n$, see Remark 4.3(1)). Thus Theorem 4.1 can be regarded as the combination of [St1, Theorem 1.3] and the equivalence between $\operatorname{Ric}_N \geq K$ and $\operatorname{CD}(K, N)$ (for (M, ω) , see [St3, Theorem 1.7], [LV1, Theorem 4.22]). Our proof is also in a sense the combination of them. Recall from (2.3) that $M_0 = M$ for m < 1, $M_0 = \Psi^{-1}((-\infty, 1/(m-1)))$ for m > 1, and that $\overline{M_0} = \operatorname{supp} \nu$ in both cases.

Theorem 4.1 Let (M, ω, ν) and $m \in [(n-1)/n, 1) \cup (1, \infty)$ with $\sigma \in L^m(M, \omega)$ be given. Then, for $K \in \mathbb{R}$, the following three conditions are mutually equivalent:

- (A) We have $\operatorname{Ric}_N \geq 0$ on $\overline{M_0}$ with N = 1/(1-m) as well as $\operatorname{Hess} \Psi \geq K$ on $\overline{M_0}$ in the sense of Definition 2.3.
- (B) For any $\mu_0, \mu_1 \in \mathcal{P}^2_{ac}(\overline{M_0}, \omega)$ such that any two points $x_0 \in \operatorname{supp} \mu_0, x_1 \in \operatorname{supp} \mu_1$ are joined by some geodesic contained in $\overline{M_0}$, there is a minimal geodesic $(\mu_t)_{t \in [0,1]} \subset \mathcal{P}^2_{ac}(\overline{M_0}, \omega)$ along which we have

$$H_m(\mu_t|\nu) \le (1-t)H_m(\mu_0|\nu) + tH_m(\mu_1|\nu) - \frac{K}{2}(1-t)tW_2(\mu_0,\mu_1)^2$$
(4.1)

for all $t \in [0, 1]$.

(C) For any $\mu_0, \mu_1 \in \mathcal{P}^2(\overline{M_0})$ such that any two points $x_0 \in \operatorname{supp} \mu_0, x_1 \in \operatorname{supp} \mu_1$ are joined by some geodesic contained in $\overline{M_0}$, there is a minimal geodesic $(\mu_t)_{t \in [0,1]} \subset \mathcal{P}^2(\overline{M_0})$ along which we have (4.1) for all $t \in [0,1]$.

Proof. Note that $(C) \Rightarrow (B)$ is clear. Thus it suffices to show $(A) \Rightarrow (C)$ and $(B) \Rightarrow (A)$. As the general case of the part $(A) \Rightarrow (C)$ is somewhat technical, let us begin with absolutely continuous measures, in other words, $(A) \Rightarrow (B)$.

(A) \Rightarrow (B): Since the assertion (4.1) is clear if $H_m(\mu_0|\nu) = \infty$ or $H_m(\mu_1|\nu) = \infty$, we assume that both $H_m(\mu_0|\nu)$ and $H_m(\mu_1|\nu)$ are finite. Theorem 2.9 ensures that there is an almost everywhere twice differentiable function $\varphi : M \longrightarrow \mathbb{R}$ such that the map $\mathcal{T}_t(x) := \exp_x(t\nabla\varphi(x))$ gives the unique minimal geodesic $\mu_t := (\mathcal{T}_t)_{\sharp}\mu_0$ from μ_0 to μ_1 . Due to [CMS, Proposition 4.1], $\mathcal{T}_1(x)$ is not a cut point of x for μ_0 -a.e. x, and hence the minimal geodesic $(\mathcal{T}_t(x))_{t \in [0,1]}$ is unique and contained in $\overline{M_0}$. Recall that, putting $\mu_t = \rho_t \omega$,

$$H_m(\mu_t|\nu) = \frac{1}{m(m-1)} \int_M (\rho_t^{m-1} - m\sigma^{m-1}) \, d\mu_t + \frac{1}{m} \int_M \sigma^m \, d\omega.$$

By the Jacobian equation (Theorem 2.10), we deduce that

$$\int_{M} (\rho_{t}^{m-1} - m\sigma^{m-1}) d\mu_{t} = \int_{M} \{\rho_{t}(\mathcal{T}_{t})^{m-1} - m\sigma(\mathcal{T}_{t})^{m-1}\} d\mu_{0}$$
$$= \int_{M} \left\{ \left(\frac{\mathbf{J}_{t}^{\omega}}{\rho_{0}}\right)^{1-m} - m\sigma(\mathcal{T}_{t})^{m-1} \right\} d\mu_{0},$$

where $\mathbf{J}_t^{\omega}(x) := e^{\psi(x) - \psi(\mathcal{T}_t(x))} \det(D\mathcal{T}_t(x)) > 0 \ \mu_0$ -a.e..

Claim 4.2 For μ_0 -a.e. $x \in M$, the function $\mathbf{J}_t^{\omega}(x)^{1-m}/(m-1) = -N\mathbf{J}_t^{\omega}(x)^{1/N}$ is convex in t.

Proof. For m < 1 (and hence $N \ge n$), this is proved in [St3, Theorem 1.7] (see also [Oh2, Section 8.2]). We can apply the same calculation to m > 1 (and N < 0). For completeness, we briefly explain how to modify calculations in [Oh2]. With the notations in [Oh2, Section 8.2], we observe that $\operatorname{Ric}_N \ge 0$ implies $(N-1)h''_3h_3^{-1} \le 0$. Thus h_3 is convex and e^{β} is concave, therefore

$$\{e^{-\psi(x)}\mathbf{J}_t^{\omega}(x)\}^{1/N} = h(t) = (e^{\beta(t)})^{1/N}h_3(t)^{(N-1)/N}$$

is convex in t (via the Hölder inequality

$$(a+b)^{1/N}(c+d)^{(N-1)/N} \le a^{1/N}c^{(N-1)/N} + b^{1/N}d^{(N-1)/N}$$

for a, b > 0 and $c, d \ge 0$).

In order to estimate the term $\sigma(\mathcal{T}_t)^{m-1}/(1-m)$, we observe from Hess $\Psi \geq K$ that

 \diamond

$$\frac{\sigma(\mathcal{T}_t)^{m-1}}{1-m} = \frac{1}{1-m} + \Psi(\mathcal{T}_t)$$

$$\leq \frac{1}{1-m} + (1-t)\Psi(\mathcal{T}_0) + t\Psi(\mathcal{T}_1) - \frac{K}{2}(1-t)td(\mathcal{T}_0,\mathcal{T}_1)^2$$

$$= (1-t)\frac{\sigma(\mathcal{T}_0)^{m-1}}{1-m} + t\frac{\sigma(\mathcal{T}_1)^{m-1}}{1-m} - \frac{K}{2}(1-t)td(\mathcal{T}_0,\mathcal{T}_1)^2.$$

Combining this with Claim 4.2 and integrating with μ_0 yield the desired inequality (4.1).

(A) \Rightarrow (C): We next consider the more technical case where μ_0 or μ_1 has nontrivial singular part. There is nothing to prove for m > 1. For m < 1, we decompose as $\mu_0 = \rho_0 \omega + \mu_0^s$ and $\mu_1 = \rho_1 \omega + \mu_1^s$, and take an optimal coupling π of μ_0 and μ_1 . Now, π is decomposed into four parts $\pi = \pi_{aa} + \pi_{as} + \pi_{sa} + \pi_{ss}$ such that $(p_1)_{\sharp}(\pi_{aa}), (p_1)_{\sharp}(\pi_{as}), (p_2)_{\sharp}(\pi_{aa})$ and $(p_2)_{\sharp}(\pi_{ss})$ are absolutely continuous, and that $(p_1)_{\sharp}(\pi_{sa}), (p_1)_{\sharp}(\pi_{ss}), (p_2)_{\sharp}(\pi_{as})$ and $(p_2)_{\sharp}(\pi_{ss})$ are singular (or null) measures. Here $p_1, p_2 : M \times M \longrightarrow M$ denote projections to the first and second elements.

We divide optimal transport between μ_0 and μ_1 into two parts, corresponding to $\pi - \pi_{ss}$ and π_{ss} . As for $\hat{\mu}_0 := (p_1)_{\sharp}(\pi - \pi_{ss})$ and $\hat{\mu}_1 := (p_2)_{\sharp}(\pi - \pi_{ss})$, Theorems 2.9, 2.10 are again applicable and give a minimal geodesic $\hat{\mu}_t = \hat{\rho}_t \omega \in (1 - \pi_{ss}(M \times M)) \cdot \mathcal{P}^2_{ac}(\overline{M_0}, \omega)$ (i.e., $\hat{\mu}_t(M) = 1 - \pi_{ss}(M \times M)$) satisfying

$$\int_{M} \hat{\rho}_{t}^{m} d\omega \geq (1-t) \int_{M} \rho_{0}^{m} d\omega + t \int_{M} \rho_{1}^{m} d\omega,$$

$$\int_{M} \sigma^{m-1} d\hat{\mu}_{t} \leq (1-t) \int_{M} \sigma^{m-1} d\hat{\mu}_{0} + t \int_{M} \sigma^{m-1} d\hat{\mu}_{1}$$

$$- \frac{(1-m)K}{2} (1-t)t \int_{M \times M} d(x,y)^{2} d(\pi - \pi_{ss})(x,y).$$

We then choose an arbitrary minimal geodesic $\tilde{\mu}_t = \tilde{\rho}_t \omega + \tilde{\mu}_t^s \in \pi_{ss}(M \times M) \cdot \mathcal{P}^2(\overline{M_0})$ from $\tilde{\mu}_0 := (p_1)_{\sharp}(\pi_{ss})$ to $\tilde{\mu}_1 := (p_2)_{\sharp}(\pi_{ss})$. Thanks to Proposition 2.7, $\tilde{\mu}_t$ is also realized through a family of geodesics in $\overline{M_0}$, and hence Hess $\Psi \geq K$ implies

$$\int_{M} \sigma^{m-1} d\tilde{\mu}_{t} \leq (1-t) \int_{M} \sigma^{m-1} d\tilde{\mu}_{0} + t \int_{M} \sigma^{m-1} d\tilde{\mu}_{1} - \frac{(1-m)K}{2} (1-t) t \int_{M \times M} d(x,y)^{2} d\pi_{ss}(x,y).$$

We put $\mu_t := \hat{\mu}_t + \tilde{\mu}_t$ and conclude that

$$H_m(\mu_t|\nu) = \frac{1}{m(m-1)} \int_M \{(\hat{\rho}_t + \tilde{\rho}_t)^m + (m-1)\sigma^m\} d\omega + \frac{1}{1-m} \int_M \sigma^{m-1} d\mu_t$$

$$\leq \frac{1}{m(m-1)} \int_M \{\hat{\rho}_t^m + (m-1)\sigma^m\} d\omega + \frac{1}{1-m} \int_M \sigma^{m-1} d(\hat{\mu}_t + \tilde{\mu}_t)$$

$$\leq (1-t)H_m(\mu_0|\nu) + tH_m(\mu_1|\nu) - \frac{K}{2}(1-t)tW_2(\mu_0,\mu_1)^2.$$

(B) \Rightarrow (A): By approximation, it suffices to show $\operatorname{Ric}_N \geq 0$ and $\operatorname{Hess} \Psi \geq K$ on M_0 . We first consider the case of m < 1. Fix a unit vector $v \in T_x M$ with $x \in M_0$ and put $\gamma(t) := \exp_x(tv), B_{\pm} := B(\gamma(\pm \delta), (1 \mp a\delta)\varepsilon)$ for $0 < \varepsilon \ll \delta \ll 1$ with a constant $a \in \mathbb{R}$ chosen later. Set

$$\mu_0 = \rho_0 \omega := \frac{\chi_{B_-}}{\omega(B_-)} \omega, \quad \mu_1 = \rho_1 \omega := \frac{\chi_{B_+}}{\omega(B_+)} \omega, \tag{4.2}$$

where χ_A stands for the characteristic function of a set A. Let $\mu_t = (\mathcal{T}_t)_{\sharp} \mu_0$ be the unique optimal transport from μ_0 to μ_1 . Recall that

$$H_m(\mu_t|\nu) - \frac{1}{m} \int_M \sigma^m \, d\omega = \frac{1}{m(m-1)} \int_M \{\rho_0^{m-1}(\mathbf{J}_t^{\omega})^{1-m} - m\sigma(\mathcal{T}_t)^{m-1}\} \, d\mu_0, \qquad (4.3)$$

where $\mathbf{J}_t^{\omega} = e^{\psi - \psi(\mathcal{T}_t)} \det(D\mathcal{T}_t)$. By definition, we find

$$\rho_0^{m-1} = \{c_n e^{-\psi(\gamma(-\delta))} (1+a\delta)^n \varepsilon^n + O(\varepsilon^{n+1})\}^{1-m} \chi_{B_-},$$

where c_n denotes the volume of the unit ball in \mathbb{R}^n . Note also that

$$\int_{M} (\mathbf{J}_{t}^{\omega})^{1-m} d\mu_{0} \leq \left(\int_{M} \mathbf{J}_{t}^{\omega} d\mu_{0} \right)^{1-m} = \left(\frac{\omega(\operatorname{supp} \mu_{t})}{\omega(B_{-})} \right)^{1-m}.$$
(4.4)

As the (second order) behavior of the distance function is controlled by the sectional curvature, we have

$$\sup \mu_{1/2} \subset \exp_x \left(\sum_{i=1}^n a_i \frac{\partial}{\partial x^i} \in T_x M \, \middle| \, \sqrt{\sum_{i=1}^n \left(\frac{a_i}{\varepsilon_i} \right)^2} \le 1 \right), \\ \varepsilon_i := \left(1 + \frac{k_i}{2} \delta^2 + O(\delta^3) \right) \varepsilon,$$

where we chose a coordinate $(x^i)_{i=1}^n$ around x such that $\{(\partial/\partial x^i)|_x\}_{i=1}^n$ is orthonormal and that $(\partial/\partial x^1)|_x = \dot{\gamma}(0)$, and denote by k_i the sectional curvature of the plane spanned by $\dot{\gamma}(0)$ and $(\partial/\partial x^i)|_x$ (so that $k_1 = 0$) (see the proof of [vRS, Theorem 1]). Thus we observe from $\operatorname{Ric}(v) = \sum_{i=1}^n k_i$ that

$$\limsup_{\varepsilon \to 0} \frac{\omega(\operatorname{supp} \mu_{1/2})}{c_n \varepsilon^n} = e^{-\psi(x)} \limsup_{\varepsilon \to 0} \frac{\operatorname{vol}_g(\operatorname{supp} \mu_{1/2})}{c_n \varepsilon^n} \le e^{-\psi(x)} \left\{ 1 + \frac{1}{2} \operatorname{Ric}(v) \delta^2 + O(\delta^3) \right\}.$$
(4.5)

We similarly observe that $\omega(\operatorname{supp} \mu_t)/c_n \varepsilon^n$ is uniformly bounded as $\varepsilon \to 0$. Hence, since 1-m > 0, the leading term of (4.3) (as $\varepsilon \to 0$) is

$$\frac{1}{1-m}\int_M \sigma(\mathcal{T}_t)^{m-1}\,d\mu_0.$$

Thus we obtain from (4.1) with t = 1/2 that, by letting ε go to zero,

$$\sigma(\gamma(0))^{m-1} \le \frac{\sigma(\gamma(-\delta))^{m-1} + \sigma(\gamma(\delta))^{m-1}}{2} - (1-m)\frac{K}{8}(2\delta)^2.$$

This means that

$$\operatorname{Hess} \Psi = \frac{1}{1-m} \operatorname{Hess}(\sigma^{m-1}) \ge K$$

in the weak sense.

In order to show $\operatorname{Ric}_N(v) \ge 0$, we choose a point y with $d(x, y) \gg \delta$ and modify μ_0 and μ_1 into

$$\tilde{\mu}_i := (1 - \varepsilon^{n+1}) \frac{\chi_{B(y,\delta)}}{\omega(B(y,\delta))} \omega + \varepsilon^{n+1} \mu_i$$
(4.6)

for i = 0, 1. Then $W_2(\tilde{\mu}_0, \tilde{\mu}_1) = \varepsilon^{(n+1)/2} \cdot W_2(\mu_0, \mu_1)$ and

$$\tilde{\mu}_t := (1 - \varepsilon^{n+1}) \frac{\chi_{B(y,\delta)}}{\omega(B(y,\delta))} \omega + \varepsilon^{n+1} \mu_t$$

is the unique minimal geodesic from $\tilde{\mu}_0$ to $\tilde{\mu}_1$, so that (4.3) is modified into

$$H_m(\tilde{\mu}_t|\nu) - \frac{1}{m} \int_M \sigma^m d\omega$$

= $\frac{\varepsilon^{n+1}}{m(m-1)} \int_M \{(\varepsilon^{n+1}\rho_0)^{m-1} (\mathbf{J}_t^{\omega})^{1-m} - m\sigma(\mathcal{T}_t)^{m-1}\} d\mu_0$
+ $\frac{1}{m(m-1)} \frac{1-\varepsilon^{n+1}}{\omega(B(y,\delta))} \int_{B(y,\delta)} \left\{ \left(\frac{1-\varepsilon^{n+1}}{\omega(B(y,\delta))}\right)^{m-1} - m\sigma^{m-1} \right\} d\omega.$

We rewrite this as

$$H_{m}(\tilde{\mu}_{t}|\nu) - \frac{1}{m} \int_{M} \sigma^{m} d\omega$$

$$- \frac{1 - \varepsilon^{n+1}}{m(m-1)} \left\{ \left(\frac{1 - \varepsilon^{n+1}}{\omega(B(y,\delta))} \right)^{m-1} - \frac{m}{\omega(B(y,\delta))} \int_{B(y,\delta)} \sigma^{m-1} d\omega \right\}$$

$$= \frac{\varepsilon^{n+1}}{m(m-1)} \int_{M} \left\{ (\varepsilon^{n+1}\rho_{0})^{m-1} (\mathbf{J}_{t}^{\omega})^{1-m} - m\sigma(\mathcal{T}_{t})^{m-1} \right\} d\mu_{0}.$$
(4.7)

Since $(\varepsilon^{n+1}\rho_0)^{m-1} = \{c_n e^{-\psi(\gamma(-\delta))}(1+a\delta)^n \varepsilon^{-1} + O(1)\}^{1-m} \chi_{B_-}$, the leading term of (4.7) (as $\varepsilon \to 0$) is

$$\frac{\varepsilon^{m(n+1)}}{m(m-1)} \int_M \rho_0^{m-1} (\mathbf{J}_t^{\omega})^{1-m} \, d\mu_0.$$

Therefore (4.1) with t = 1/2 and the Jacobian equation (Theorem 2.10) yield that

$$\begin{aligned} \liminf_{\varepsilon \to 0} \int_{M} (\mathbf{J}_{1/2}^{\omega})^{1-m} d\mu_{0} &\geq \frac{1}{2} \Big\{ \mathbf{J}_{0}^{\omega} \big(\gamma(-\delta) \big)^{1-m} + \mathbf{J}_{1}^{\omega} \big(\gamma(-\delta) \big)^{1-m} \Big\} \\ &= \frac{1}{2} \Big\{ 1 + \left(\frac{1-a\delta}{1+a\delta} \right)^{n/N} e^{\{\psi(\gamma(-\delta)) - \psi(\gamma(\delta))\}/N} \Big\}. \end{aligned}$$

Combining this with (4.4) and (4.5), we obtain

$$1 + \frac{1}{2}\operatorname{Ric}(v)\delta^{2}$$

$$\geq (1 + a\delta)^{n}e^{\psi(x) - \psi(\gamma(-\delta))} \left(\int_{M} (\mathbf{J}_{t}^{\omega})^{1-m} d\mu_{0}\right)^{1/(1-m)} + O(\delta^{3})$$

$$\geq \frac{1}{2^{N}} \left\{ (1 + a\delta)^{n/N} e^{\{\psi(x) - \psi(\gamma(-\delta))\}/N} + (1 - a\delta)^{n/N} e^{\{\psi(x) - \psi(\gamma(\delta))\}/N} \right\}^{N} + O(\delta^{3})$$

Hence we have, expanding the (1/N)-th power of both sides near $\delta = 0$,

$$\begin{split} &1 + \frac{1}{2N} \operatorname{Ric}(v) \delta^{2} \\ &\geq \frac{1}{2} \Big\{ (1 + a\delta)^{n/N} e^{\{\psi(x) - \psi(\gamma(-\delta))\}/N} + (1 - a\delta)^{n/N} e^{\{\psi(x) - \psi(\gamma(\delta))\}/N} \Big\} + O(\delta^{3}) \\ &= 1 + \frac{\delta^{2}}{2} \Big[\frac{n}{N} \bigg(\frac{n}{N} - 1 \bigg) a^{2} - \Big\{ \frac{(\psi \circ \gamma)''(0)}{N} - \frac{(\psi \circ \gamma)'(0)^{2}}{N^{2}} \Big\} + \frac{2na}{N} \frac{(\psi \circ \gamma)'(0)}{N} \Big] + O(\delta^{3}) \\ &= 1 + \frac{\delta^{2}}{2N} \Big\{ - (\psi \circ \gamma)''(0) + \frac{n(n-N)}{N} a^{2} + \frac{2n(\psi \circ \gamma)'(0)}{N} a + \frac{(\psi \circ \gamma)'(0)^{2}}{N} \Big\} + O(\delta^{3}). \end{split}$$

Therefore we obtain

$$\operatorname{Ric}(v) + (\psi \circ \gamma)''(0) - \frac{n(n-N)}{N}a^2 - \frac{2n(\psi \circ \gamma)'(0)}{N}a - \frac{(\psi \circ \gamma)'(0)^2}{N} \ge 0.$$
(4.8)

If N > n, then choosing the minimizer $a = (\psi \circ \gamma)'(0)/(N-n)$ gives the desired curvature bound

$$\operatorname{Ric}_N(v) = \operatorname{Ric}(v) + (\psi \circ \gamma)''(0) - \frac{(\psi \circ \gamma)'(0)^2}{N - n} \ge 0.$$

If N = n, then we consider a going to ∞ or $-\infty$ and find $(\psi \circ \gamma)'(0) = 0$ as well as $\operatorname{Ric}_n(v) \ge 0$.

In the case of m > 1, we use the same transport (4.2) and then the leading term of (4.3) changes into

$$\frac{1}{m(m-1)} \int_M \rho_0^{m-1} (\mathbf{J}_t^{\omega})^{1-m} \, d\mu_0$$

Thus calculations as above yield the reverse inequality of (4.4) and finally (4.8) with N < 0. We again choose the minimizer $a = (\psi \circ \gamma)'(0)/(N-n)$ and find $\operatorname{Ric}_N(v) \ge 0$. Similarly, for the transport (4.6), the leading term of (4.7) is

$$\frac{\varepsilon^{n+1}}{1-m}\int_M \sigma(\mathcal{T}_t)^{m-1}\,d\mu_0,$$

and then (4.1) yields $\text{Hess}\Psi = \text{Hess}(\sigma^{m-1}/(1-m)) \geq K$ (note that $W_2(\tilde{\mu}_0, \tilde{\mu}_1)^2 = \varepsilon^{n+1}W_2(\mu_0, \mu_1)^2$ has the same order). \Box

Remark 4.3 (1) If we admit $m \in (0, (n-1)/n)$ and generalize Ric_N in (2.1) to $N \in (1, n)$, then Claim 4.2 is false. Moreover, as the coefficient of a^2 in (4.8) is negative, (4.1) is never satisfied (let $a \to \infty$). Compare this with [St1, (1.7)] which means $m \ge (n-1)/n$ in our setting.

(2) Note that the special case $\nu = \omega$ (i.e., $\Psi \equiv 0$) in Theorem 4.1 makes sense only for K = 0. Then the assertion of Theorem 4.1 corresponds to the equivalence between $\operatorname{Ric}_N \geq 0$ and the convexity of the Rényi entropy S_N , i.e., the curvature-dimension condition $\mathsf{CD}(0, N)$ of (M, ω) .

(3) In the limit case of m = 1, two weights ψ and Ψ are synchronized as $\nu = e^{-\psi - \Psi} \operatorname{vol}_g$, and Hess $\operatorname{Ent}_{\nu} \geq K$ (i.e., $\operatorname{CD}(K, \infty)$ for (M, ν)) is equivalent to the single condition Ric + Hess $(\psi + \Psi) \geq K$ ([vRS, Theorem 1], [St2, Proposition 4.14]). For $m \neq 1$, however, ψ and Ψ keep separate and they measure different phases of (M, ω, ν) , as indicated in Theorem 4.1.

5 Functional inequalities

Since Otto and Villani's celebrated work [OV], the displacement convexity of entropy-type functionals has played a significant role in the study of functional inequalities (and the concentration of measures). In this section, we follow the argument in [LV2, Section 6] that the direct application of the displacement convexity of the entropy implies various functional inequalities. Our proofs use only fundamental properties of convex functions.

In more analytic context, related results for $m \neq 1$ in the Euclidean spaces $(M, \omega) = (\mathbb{R}^n, dx)$ can be found in [AGK], [CGH] and [Ta2]. See especially [AGK, Section 4] and [CGH, Section 3] for various generalizations of the Talagrand (transport) inequality, logarithmic Sobolev (entropy-information) inequality, HWI inequality and the Poincaré inequality. The relation among these inequalities are also discussed there.

Throughout the section, we suppose that m > 1/2, $\operatorname{Ric}_N \ge 0$ and that $\operatorname{Hess} \Psi \ge K$ holds for some K > 0. Note that m > 1/2 is clear if $n \ge 3$. Recall from Lemma 2.5(i), (iii) that $\nu(M) < \infty$ automatically follows from these hypotheses, so that the normalization gives

$$\bar{\nu} = \bar{\sigma}\omega = \exp_m(-\overline{\Psi})\omega := \nu(M)^{-1}\nu \in \mathcal{P}_{\mathrm{ac}}(M,\omega)$$

with Hess $\overline{\Psi} \geq \nu(M)^{1-m} K$ according to Remark 2.4. Lemma 2.5 moreover ensures that $\overline{\sigma} \in L^m(M, \omega), \ \overline{\nu} \in \mathcal{P}^2_{\mathrm{ac}}(M, \omega)$ and that $\overline{M_0}$ is convex. Keeping these in mind, we will consider ν with $\nu(M) = 1$ for simplicity.

Proposition 5.1 (Talagrand inequality) Assume that $m \in [(n-1)/n, \infty) \setminus \{1/2, 1\}$, $\nu(M) = 1$, $\operatorname{Ric}_N \geq 0$ and $\operatorname{Hess} \Psi \geq K > 0$. Then we have, for any $\mu \in \mathcal{P}^2(\overline{M_0})$,

$$W_2(\mu,\nu) \le \sqrt{\frac{2}{K}H_m(\mu|\nu)}.$$

Proof. There is nothing to prove if $H_m(\mu|\nu) = \infty$, so that we assume $H_m(\mu|\nu) < \infty$. Let $(\mu_t)_{t \in [0,1]} \subset \mathcal{P}^2(\overline{M_0})$ be the optimal transport from $\mu_0 = \mu$ to $\mu_1 = \nu$. It follows from (4.1) and $H_m(\nu|\nu) = 0$ that

$$H_m(\mu_t|\nu) \le (1-t)H_m(\mu|\nu) - \frac{K}{2}(1-t)tW_2(\mu,\nu)^2.$$
(5.1)

Since $H_m(\mu_t|\nu) \ge 0$ (Lemma 3.3), we obtain $H_m(\mu|\nu) \ge (K/2)W_2(\mu,\nu)^2$ by dividing (5.1) with 1-t and letting t go to 1.

The above Talagrand inequality is regarded as a comparison between distances in Wasserstein geometry and information geometry (recall Subsection 3.1).

In the remainder of the section, let Ψ be locally Lipschitz. For $\mu = \rho \omega \in \mathcal{P}^2_{ac}(M, \omega)$ such that ρ is locally Lipschitz, we define the *m*-relative Fisher information by

$$I_m(\mu|\nu) := \frac{1}{m^2} \int_M \left| \nabla [e'_m(\rho) - e'_m(\sigma)] \right|^2 \rho \, d\omega = \frac{1}{(m-1)^2} \int_M \left| \nabla (\rho^{m-1} - \sigma^{m-1}) \right|^2 d\mu.$$
(5.2)

It will be demonstrated in Proposition 7.10 that $\sqrt{I_m(\mu|\nu)}$ is the absolute gradient of $H_m(\cdot|\nu)$ at μ . Thus it is natural to expect that the convexity of $H_m(\cdot|\nu)$ yields the following inequality.

Theorem 5.2 (HWI and Logarithmic Sobolev inequalities) We assume that $m \in [(n-1)/n, \infty) \setminus \{1/2, 1\}, \nu(M) = 1$, $\operatorname{Ric}_N \geq 0$, $\operatorname{Hess} \Psi \geq K > 0$ and that Ψ is locally Lipschitz. Then we have, for any $\mu = \rho \omega \in \mathcal{P}^2_{\operatorname{ac}}(\overline{M_0}, \omega)$ such that $H_m(\mu|\nu) < \infty$ and ρ is Lipschitz,

$$H_m(\mu|\nu) \le \sqrt{I_m(\mu|\nu)} \cdot W_2(\mu,\nu) - \frac{K}{2} W_2(\mu,\nu)^2,$$
(5.3)

$$H_m(\mu|\nu) \le \frac{1}{2K} I_m(\mu|\nu).$$
 (5.4)

Proof. Let $\mu_t = \rho_t \omega \in \mathcal{P}^2_{ac}(\overline{M_0}, \omega)$, $t \in [0, 1]$, be the optimal transport from $\mu_0 = \mu$ to $\mu_1 = \nu$ given by $\mu_t = (\mathcal{T}_t)_{\sharp} \mu$ with $\mathcal{T}_t(x) = \exp_x(t\nabla\varphi(x))$, and put $H(t) := H_m(\mu_t|\nu)$. Then it follows from (5.1) that

$$H(0) \le \frac{H(0) - H(t)}{t} - \frac{K}{2}(1 - t)W_2(\mu, \nu)^2.$$
(5.5)

We shall estimate the term

$$H(0) - H(t) = \frac{1}{m(m-1)} \int_M \{(\rho^m - \rho_t^m) - m(\rho - \rho_t)\sigma^{m-1}\} d\omega.$$

Since the function $f(s) := s^m/(m-1)$ is convex, we have

$$\frac{\rho^m - \rho_t^m}{m - 1} \le f'(\rho)(\rho - \rho_t) = \frac{m}{m - 1}\rho^{m - 1}(\rho - \rho_t),$$

and hence

$$H(0) - H(t) \le \frac{1}{m-1} \int_M (\rho^{m-1} - \sigma^{m-1})(\rho - \rho_t) \, d\omega.$$

As $(\mathcal{T}_t)_{\sharp}\mu = \mu_t$, we observe

$$\int_{M} (\rho^{m-1} - \sigma^{m-1}) \rho_t \, d\omega = \int_{M} \{ \rho(\mathcal{T}_t)^{m-1} - \sigma(\mathcal{T}_t)^{m-1} \} \, d\mu.$$

This yields

$$H(0) - H(t) \le \frac{1}{m-1} \int_M \left\{ (\rho^{m-1} - \sigma^{m-1}) - \left(\rho(\mathcal{T}_t)^{m-1} - \sigma(\mathcal{T}_t)^{m-1} \right) \right\} d\mu.$$

Thus we obtain

$$\limsup_{t \to 0} \frac{H(0) - H(t)}{t} \leq \frac{1}{|m-1|} \int_{M} |\nabla(\rho^{m-1} - \sigma^{m-1})| \cdot d(\mathcal{T}_{0}, \mathcal{T}_{1}) \, d\mu$$
$$\leq \frac{1}{|m-1|} \left(\int_{M} |\nabla(\rho^{m-1} - \sigma^{m-1})|^{2} \, d\mu \right)^{1/2} \left(\int_{M} d(\mathcal{T}_{0}, \mathcal{T}_{1})^{2} \, d\mu \right)^{1/2}$$
$$= \sqrt{I_{m}(\mu|\nu)} \cdot W_{2}(\mu, \nu).$$

Combining this with (5.5), we conclude that

$$H_m(\mu|\nu) \le \sqrt{I_m(\mu|\nu)} \cdot W_2(\mu,\nu) - \frac{K}{2} W_2(\mu,\nu)^2 \le \frac{1}{2K} I_m(\mu|\nu).$$

Remark 5.3 It is established in [Ta2] that, in the Euclidean space $(M, \omega) = (\mathbb{R}^n, dx)$, equality of (5.3) and (5.4) is characterized by using *m*-Gaussian measures.

We finally show a kind of Poincaré inequality. Observe that letting m = 1 recovers the usual global Poincaré inequality $\int_M f^2 d\nu \leq K^{-1} \int_M |\nabla f|^2 d\nu$.

Proposition 5.4 (Global Poincaré inequality) Assume that (M, g) is compact, $m \in [(n-1)/n, \infty) \setminus \{1/2, 1\}, \nu(M) = 1, \operatorname{Ric}_N \geq 0$, $\operatorname{Hess} \Psi \geq K > 0$ and that Ψ is Lipschitz. Then, for any Lipschitz function $f : \overline{M_0} \longrightarrow \mathbb{R}$ such that $\int_{\overline{M_0}} f \, d\nu = 0$, we have

$$\int_M f^2 \sigma^{m-1} \, d\nu \le \frac{1}{K} \int_M |\nabla(f \sigma^{m-1})|^2 \, d\nu.$$

Proof. Apply (5.4) to $\mu = \rho \omega := (1 + \varepsilon f) \sigma \omega$ for small $\varepsilon > 0$ and obtain

$$\frac{1}{m(m-1)} \int_M \{\rho^m - m\rho\sigma^{m-1} + (m-1)\sigma^m\} \, d\omega \le \frac{1}{2K} \frac{1}{(m-1)^2} \int_M |\nabla(\rho^{m-1} - \sigma^{m-1})|^2 \, d\mu.$$

We remark that $H_m(\mu|\nu) < \infty$ as M is compact. On the one hand,

$$\rho^{m} - m\rho\sigma^{m-1} + (m-1)\sigma^{m} = (1 + \varepsilon f)^{m}\sigma^{m} - m(1 + \varepsilon f)\sigma^{m} + (m-1)\sigma^{m}$$
$$= \sigma^{m}\{(1 + \varepsilon f)^{m} - 1 - m(\varepsilon f)\}$$
$$= m(m-1)\sigma^{m}\frac{f^{2}}{2}\varepsilon^{2} + O(\varepsilon^{3}),$$

where $O(\varepsilon^3)$ is uniform on M thanks to the compactness of M. On the other hand,

$$\begin{aligned} |\nabla(\rho^{m-1} - \sigma^{m-1})|^2 &= \left|\nabla\left[\left((1 + \varepsilon f)^{m-1} - 1\right)\sigma^{m-1}\right]\right|^2 \\ &= |\nabla[(m-1)f\varepsilon\sigma^{m-1}] + O(\varepsilon^2)|^2 \\ &= (m-1)^2\varepsilon^2|\nabla(f\sigma^{m-1})|^2 + O(\varepsilon^3). \end{aligned}$$

Thus we have, letting ε go to zero,

$$\int_M f^2 \sigma^m \, d\omega \le \frac{1}{K} \int_M |\nabla(f \sigma^{m-1})|^2 \, d\nu.$$

6 Concentration of measures

This section is devoted to an application of Proposition 5.1 to the concentration of measures. Let us assume $\nu(M) = 1$ and define the *concentration function* by

$$\alpha_{(M,\nu)}(r) := \sup \left\{ 1 - \nu \left(B(A,r) \right) \, | \, A \subset M, \, \, \nu(A) \ge 1/2 \right\}$$

for r > 0, where A is any measurable set and

$$B(A,r) := \{ y \in M \mid \inf_{x \in A} d(x,y) < r \}.$$

The function $\alpha_{(M,\nu)}$ describes how the probability measure ν concentrates on the neighborhood of an arbitrary set of half the total measure in a quantitative way (in other words, a kind of large deviation principle). An especially interesting situation is that a sequence $\{(M_i, \nu_i)\}_{i \in \mathbb{N}}$ satisfies $\lim_{i \to \infty} \alpha_{(M_i, \nu_i)}(r) = 0$ for all r > 0, that means that

 (M_i, ν_i) is getting more and more concentrated. We refer to [Le] for the basic theory and applications of the concentration of measure phenomenon.

In the classical case of m = 1, it is well-known that the concentration of measures has rich connections with functional inequalities appearing in Section 5. For instance, the L^1 -transport inequality $W_1(\mu, \nu) \leq \sqrt{(2/K) \operatorname{Ent}_{\nu}(\mu)}$ implies the normal concentration $\alpha(r) \leq Ce^{-cr^2}$ with constants c, C > 0 depending only on K ([Le, Section 6.1]). In the same spirit, we show that an application of Proposition 5.1 gives new examples of concentrating spaces.

We set $G_c = G_c(\nu) := \int_M \sigma^c d\omega$ for c > 1/2. Recall from Lemma 2.5(i) that, if m < 1, Ric_N ≥ 0 and if Hess $\Psi \ge K > 0$, then

$$G_c(\nu) \le C_1(\omega)^{1-c}\nu(M)^c + C_2(m,c,\omega)K^{c/(m-1)} < \infty$$
 (6.1)

holds for each $c \in (1/2, 1]$.

Theorem 6.1 (m < 1 case) Let (M, ω) satisfy $\operatorname{Ric}_N \ge 0$ and $m \in [(n-1)/n, 1) \cap (1/2, 1)$.

(i) Assume that $\nu(M) = 1$ and Hess $\Psi \ge K > 0$. Then we have

$$\alpha_{(M,\nu)}(r)^{\theta-m} \ln_m \left(2\alpha_{(M,\nu)}(r) \right) \le -G_{(m-\theta)/(1-\theta)}^{\theta-1} \left\{ \left(\sqrt{\frac{mK}{2}}r - \sqrt{G_m} \right)^2 - G_m \right\}$$
(6.2)

for all r > 0 and $\theta \in [0, 2m - 1)$.

(ii) Take a sequence $\nu_i = \exp_m(-\Psi_i)\omega \in \mathcal{P}_{\mathrm{ac}}(M,\omega)$, $i \in \mathbb{N}$, such that $\operatorname{Hess} \Psi_i \ge K_i$ and $\lim_{i\to\infty} K_i = \infty$. Then we have $\lim_{i\to\infty} \alpha_{(M,\nu_i)}(r) = 0$ for all r > 0.

Proof. (i) Note that $\nu \in \mathcal{P}^2_{ac}(M,\omega)$ by Lemma 2.5(ii) and m > 1/2. We also remark that (6.2) clearly holds for $r \leq 2\sqrt{2G_m/mK}$. Indeed, then the right-hand side is nonnegative and the trivial bound $\alpha_{(M,\nu)}(r) \leq 1/2$ implies $\ln_m(2\alpha_{(M,\nu)}(r)) \leq 0$.

Suppose $r > 2\sqrt{2G_m/mK}$, take a measurable set $A \subset M$ with $\nu(A) \ge 1/2$ and put $B := M \setminus B(A, r), a := \nu(A), b := \nu(B),$

$$\mu_A := \frac{\chi_A}{a}\nu, \qquad \mu_B := \frac{\chi_B}{b}\nu.$$

We assumed b > 0 since there is nothing to prove if b = 0 for all such A. Observe that $W_1(\mu_A, \mu_B) \ge r$ as $d(x, y) \ge r$ for all $x \in A$ and $y \in B$. The triangle inequality of W_1 and Proposition 5.1 together imply (as $W_1 \le W_2$ by the Schwarz inequality)

$$r \le W_1(\mu_A, \mu_B) \le W_1(\mu_A, \nu) + W_1(\nu, \mu_B) \le \sqrt{\frac{2}{K}H_m(\mu_A|\nu)} + \sqrt{\frac{2}{K}H_m(\mu_B|\nu)}.$$

Note that

$$H_m(\mu_A|\nu) = \frac{1}{m(1-m)} \int_A \frac{ma^{m-1} - 1}{a^m} \sigma^m \, d\omega + \frac{1}{m} G_m$$

and $ma^{m-1} - 1 < 0$ since $a \ge 1/2 > m^{1/(1-m)}$. Thus we obtain

$$\sqrt{\frac{mK}{2}}r \le \sqrt{G_m} + \sqrt{G_m + b^{-m}\frac{mb^{m-1} - 1}{1 - m}} \int_B \sigma^m d\omega.$$

We observe from $r > 2\sqrt{2G_m/mK}$ that $\sqrt{mK/2r} > 2\sqrt{G_m}$ which yields $0 < mb^{m-1}-1 < (2b)^{m-1}-1$. Hence we have

$$\left(\sqrt{\frac{mK}{2}}r - \sqrt{G_m}\right)^2 - G_m \le -b^{-m}\ln_m(2b)\int_B \sigma^m \,d\omega. \tag{6.3}$$

It follows from the Hölder inequality that

$$\int_{B} \sigma^{m} d\omega = \int_{B} \sigma^{\theta + (m-\theta)} d\omega \le \left(\int_{B} \sigma \, d\omega\right)^{\theta} \left(\int_{B} \sigma^{(m-\theta)/(1-\theta)} \, d\omega\right)^{1-\theta} \le b^{\theta} G^{1-\theta}_{(m-\theta)/(1-\theta)},$$

where the assumption $\theta < 2m-1$ ensures $(m-\theta)/(1-\theta) > 1/2$. Therefore we obtain the desired inequality (6.2) by choosing $A_i \subset M$ such that $\lim_{i\to\infty} \nu(M \setminus B(A_i, r)) = \alpha_{(M,\nu)}(r)$.

(ii) Thanks to (6.1), we know that

$$\limsup_{i \to \infty} G_c(\nu_i) \le C_1(\omega)^{1-c} < \infty$$

for all $c \in (1/2, 1]$. Therefore we deduce from (i) with $\theta = 0$ that, setting $\alpha_i := \alpha_{(M,\nu_i)}(r)$,

$$-\infty = \lim_{i \to \infty} \alpha_i^{-m} \ln_m(2\alpha_i) = -\lim_{i \to \infty} \frac{\alpha_i^{-1}}{2^{1-m}} \frac{1 - (2\alpha_i)^{1-m}}{1 - m}$$

$$\alpha_i = 0$$

which shows $\lim_{i\to\infty} \alpha_i = 0$.

Remark 6.2 (1) Taking the proof of Lemma 2.5(i) into account, we can generalize Theorem 6.1(ii) as follows. Suppose that a sequence $\{(M_i, \omega_i, \nu_i)\}_{i \in \mathbb{N}}$ satisfies, for $m \in [(n-1)/n, 1) \cap (1/2, 1)$,

- (a) $\operatorname{Ric}_N \geq 0$ for all (M_i, ω_i) ,
- (b) $\nu_i = \exp_m(-\Psi_i)\omega_i \in \mathcal{P}_{\mathrm{ac}}(M_i, \omega_i)$ so that $\operatorname{Hess} \Psi_i \ge K_i$ and $\lim_{i \to \infty} K_i = \infty$,
- (c) $\sup_{i\in\mathbb{N}}\omega_i(B(x_i,R)) < \infty$ and $\sup_{i\in\mathbb{N}} \operatorname{area}_{\omega_i}(S(x_i,R)) < \infty$ for some R > 0, where $x_i \in M_i$ is the minimizer of Ψ_i .

Then we have $\lim_{i\to\infty} \alpha_{(M_i,\nu_i)}(r) = 0$ for all r > 0.

(2) Taking the limit of (6.2) as $m \to 1$ and then $\theta \to 1$, we obtain

$$\ln\left(2\alpha(r)\right) \le -\left(\sqrt{\frac{K}{2}}r - 1\right)^2 + 1.$$

Here $\lim_{c\to 1} G_c = G_1 = 1$ follows from the dominated convergence theorem since $\sigma^c \leq \max\{\sigma, \sigma^{c_0}\} \in L^1(M, \omega)$ for $1/2 < c_0 \leq c < 1$. Therefore we recover the normal concentration

$$\alpha(r) \le \frac{1}{2} \exp\left[-\left(\sqrt{\frac{K}{2}}r - 1\right)^2 + 1\right] \le \frac{1}{2}e^{-Kr^2/4 + 2}$$

which is well-known to hold for (M, ω) with $\operatorname{Ric}_{\infty} \geq K > 0$.

Theorem 6.1(ii) is applicable to the fundamental example of *m*-Gaussian measures (see Example 2.6).

Example 6.3 Let $\{N_m(v_i, V_i)\}_{i \in \mathbb{N}} \subset \mathcal{P}^2_{\mathrm{ac}}(\mathbb{R}^n, dx)$ be a sequence of *m*-Gaussian measures with $m \in [(n-1)/n, 1) \cap (1/2, 1)$ satisfying

$$\lim_{i \to \infty} (\det V_i)^{(1-m)/2} \Lambda_i^{-1} = \infty,$$

where Λ_i is the largest eigenvalue of V_i . Then we have $\lim_{i\to\infty} \alpha_{(\mathbb{R}^n, N_m(v_i, V_i))}(r) = 0$ for all r > 0. Note that $(\det V_i)^{(1-m)/2} \Lambda_i^{-1} \leq \Lambda_i^{(1-m)n/2-1} \leq \Lambda_i^{-1/2}$.

Under the additional assumption that $\omega(M) < \infty$, we further obtain the *m*-normal concentration. We first prove a computational lemma for later use.

Lemma 6.4 (i) For any $m \in (1/2, 1)$ and a, r > 0, we have

$$\exp_m\left(-(ar-1)^2+1\right) \le (2m-1)^{1/(m-1)}\exp_m\left(-\frac{a^2}{2}r^2\right).$$

(ii) For any $m \in (1,2)$ and a, r > 0, we have

$$\exp_m\left((ar-1)^2-1\right) \ge \left(\frac{2}{m}-1\right)^{1/(m-1)}\exp_m\left(\frac{a^2}{2}r^2\right).$$

Proof. (i) We just calculate

$$\begin{aligned} \exp_m \left(-(ar-1)^2 + 1 \right) &\leq \exp_m \left(-\frac{a^2}{2}r^2 + 2 \right) \\ &= \left\{ 1 + (m-1)\left(-\frac{a^2}{2}r^2 + 2 \right) \right\}^{1/(m-1)} \\ &= (2m-1)^{1/(m-1)} \left\{ 1 + (m-1)\left(-\frac{a^2}{2(2m-1)}r^2 \right) \right\}^{1/(m-1)} \\ &\leq (2m-1)^{1/(m-1)} \exp_m \left(-\frac{a^2}{2}r^2 \right). \end{aligned}$$

(ii) We similarly find

$$\begin{split} \exp_m\left((ar-1)^2 - 1\right) &\geq \exp_m\left[\left(1 - \frac{m}{2}\right)a^2r^2 - \frac{2}{m}\right] \\ &= \left\{\left(\frac{2-m}{m}\right) + (m-1)\left(1 - \frac{m}{2}\right)a^2r^2\right\}^{1/(m-1)} \\ &= \left(\frac{2}{m} - 1\right)^{1/(m-1)} \left\{1 + \frac{m}{2}(m-1)a^2r^2\right\}^{1/(m-1)} \\ &\geq \left(\frac{2}{m} - 1\right)^{1/(m-1)} \exp_m\left(\frac{a^2}{2}r^2\right). \end{split}$$

Note that the hypothesis $m \in (1, 2)$ ensures that

$$\left(1 - \frac{m}{2}\right)a^2r^2 - \frac{2}{m} > -\frac{2}{m} > -\frac{1}{m-1}.$$

Corollary 6.5 (*m*-normal concentration) Assume that $m \in [(n-1)/n, 1) \cap (1/2, 1)$, $\nu(M) = 1, \ \omega(M) < \infty, \ \text{Ric}_N \ge 0 \ and \ \text{Hess} \ \Psi \ge K > 0$. Then we have

$$\alpha_{(M,\nu)}(r) \le \frac{(2m-1)^{1/(m-1)}}{2} \exp_m\left(-\frac{mK}{4\omega(M)^{1-m}}r^2\right)$$

for all r > 0.

Proof. Let us use the same notation as the proof of Theorem 6.1. We deduce from the Hölder inequality that

$$\int_B \sigma^m \, d\omega \le \left(\int_B \sigma \, d\omega\right)^m \omega(B)^{1-m} = b^m \omega(B)^{1-m} \le b^m \omega(M)^{1-m}$$

and, similarly, $G_m \leq \omega(M)^{1-m}$. In particular, $r^2 > 8\omega(M)^{1-m}/mK$ (otherwise the assertion is clear since $(2m-1)^{1/(m-1)} \exp_m(-2) > 1$) implies $r^2 > 8G_m/mK$. Therefore we deduce from (6.3) that

$$\left(\sqrt{\frac{mK}{2}}r - \omega(M)^{(1-m)/2}\right)^2 - \omega(M)^{1-m} \le \left(\sqrt{\frac{mK}{2}}r - \sqrt{G_m}\right)^2 - G_m$$
$$\le -b^{-m}\ln_m(2b) \int_B \sigma^m \, d\omega \le -\omega(M)^{1-m}\ln_m(2b),$$

and hence

$$\alpha_{(M,\nu)}(r) \le \frac{1}{2} \exp_m \left[-\left(\omega(M)^{(m-1)/2} \sqrt{\frac{mK}{2}}r - 1\right)^2 + 1 \right].$$

Then Lemma 6.4(i) completes the proof.

Remark 6.6 Note that, for m < 1, $\exp_m(-cr^2)$ is greater than e^{-cr^2} and is a polynomial of r, so that the *m*-normal concentration is weaker than the exponential concentration $\alpha(r) \leq Ce^{-cr}$. This is natural and the most we can expect, because the *m*-Gaussian measures have only the polynomial decay.

For m > 1, Lemma 2.5(iii) ensures that $\operatorname{supp} \nu$ is bounded. Thus $\|\sigma\|_{\infty} < \infty$ and $G_c(\nu) < \infty$ for all c > 0. Then the proof of Theorem 6.1(i) is applicable to $m \in (1, 2]$ and gives the same estimate (6.2) for all r > 0 and $\theta \in [0, 1)$. Furthermore, for m < 2, we again obtain the *m*-normal concentration (depending on $\|\sigma\|_{\infty}$).

Proposition 6.7 (m > 1 case) Let (M, ω) satisfy $\operatorname{Ric}_N \geq 0$ and $m \in (1, 2]$.

(i) Assume that $\nu(M) = 1$ and Hess $\Psi \ge K > 0$. Then we have (6.2) for all r > 0 and $\theta \in [0, 1)$.

(ii) If in addition m < 2, then we have

$$\alpha_{(M,\nu)}(r)^{-1} \ge \left(\frac{2}{m} - 1\right)^{1/(m-1)} \exp_m\left(\frac{mK\|\sigma\|_{\infty}^{1-m}}{4}r^2\right)$$

for all r > 0.

Proof. (i) This is completely the same as Theorem 6.1(i), since $1/2 \ge m^{1/(1-m)}$ holds also for $m \in (1, 2]$.

(ii) In (6.3) (with m > 1), we observe $\int_B \sigma^m d\omega \leq b \|\sigma\|_{\infty}^{m-1}$ and $G_m \leq \|\sigma\|_{\infty}^{m-1}$. Note also that $r^2 > 8 \|\sigma\|_{\infty}^{m-1}/mK$ (otherwise $((2-m)/m)^{1/(m-1)} \exp_m(2) < 1$ immediately gives the assertion) ensures $r^2 > 8G_m/mK$. These yield

$$\left(\sqrt{\frac{mK}{2}}r - \|\sigma\|_{\infty}^{(m-1)/2}\right)^2 - \|\sigma\|_{\infty}^{m-1} \le -b^{1-m}\|\sigma\|_{\infty}^{m-1}\ln_m(2b) \le \|\sigma\|_{\infty}^{m-1}\ln_m(b^{-1}).$$

Hence we have

$$\alpha_{(M,\nu)}(r)^{-1} \ge \exp_m\left[\left(\|\sigma\|_{\infty}^{(1-m)/2}\sqrt{\frac{mK}{2}}r - 1\right)^2 - 1\right],$$

and Lemma 6.4(ii) completes the proof.

Note that we obtained the estimate of the form $\alpha(r) \leq C \exp_m(-cr^2)$ for m < 1, while $\alpha(r) \leq C \{\exp_m(cr^2)\}^{-1}$ for m > 1. This is in a sense natural because the domain of \exp_m is $(-\infty, 1/(1-m))$ for m < 1 and $[-1/(m-1), \infty)$ for m > 1.

Remark 6.8 We deduce from Proposition 6.7(ii) that, if $\lim_{i\to\infty} K_i \|\sigma_i\|_{\infty}^{1-m} = \infty$ for some sequence $\{(M_i, \nu_i)\}_{i\in\mathbb{N}}$ satisfying $\operatorname{Hess} \Psi_i \geq K_i$, then we have $\lim_{i\to\infty} \alpha_{(M_i,\nu_i)}(r) =$ 0 for all r > 0 (e.g., a sequence of *m*-Gaussian measures $\{N_m(v_i, V_i)\}_{i\in\mathbb{N}}$ such that $\lim_{i\to\infty} \Lambda_i = 0$, compare this with Example 6.3). This is, however, an immediate consequence of a stronger conclusion $\lim_{i\to\infty} \operatorname{diam}(\operatorname{supp} \nu_i) = 0$ of Lemma 2.5(iii) (valid for all m > 1). Indeed,

diam
$$(\operatorname{supp} \nu_i)^2 \le \frac{8}{K_i} \left(\frac{1}{m-1} - \inf_{M_i} \Psi_i \right) = \frac{8}{K_i} \frac{\|\sigma_i\|_{\infty}^{m-1}}{m-1}.$$

7 Gradient flow of H_m

In this section, we show that the gradient flow of the *m*-relative entropy produces a weak solution to the porous medium equation (m > 1) or the fast diffusion equation (m < 1). This kind of interpretation of evolution equations has turned out extremely useful after the pioneering work due to Jordan et al. [JKO]. There are several ways of explaining this coincidence (see, e.g., [JKO], [AGS] and [Vi2, Chapter 23]), among them, here we follow the rather 'metric geometric' approach in [Oh1]. To do this, we start with a review of the geometric structure of the Wasserstein space and the general theory of gradient flows in it in accordance with the strategy in [Oh1] (see also [GO]). Throughout the section, (M,g) is assumed to be compact, so that $\mathcal{P}^2(M) = \mathcal{P}(M)$ and $\sigma \in L^m(M, \omega)$.

7.1 Geometric structure of $(\mathcal{P}(M), W_2)$

We briefly review the geometric structure of $(\mathcal{P}(M), W_2)$. It is known that $(\mathcal{P}(M), W_2)$ is an Alexandrov space of nonnegative curvature if and only if (M, g) has the nonnegative sectional curvature ([St2, Proposition 2.10], [LV2, Theorem A.8]). In the case where (M, g)is not nonnegatively curved, although $(\mathcal{P}(M), W_2)$ does not admit any lower curvature bound ([St2, Proposition 2.10]), we can show the following (see also [Oh1, Theorem 3.6]).

Theorem 7.1 ([Gi, Theorem 3.4, Remark 3.5]) Given $\mu \in \mathcal{P}(M)$ and unit speed geodesics $\alpha, \beta : [0, \delta) \longrightarrow \mathcal{P}(M)$ with $\alpha(0) = \beta(0) = \mu$, the joint limit

$$\lim_{s,t\to 0} \frac{s^2 + t^2 - W_2(\alpha(s),\beta(t))^2}{2st} \in [-1,1]$$

exists.

Theorem 7.1 means that an angle between α and β makes sense, so that $(\mathcal{P}(M), W_2)$ looks like a Riemannian space (rather than a Finsler space), and we can investigate its infinitesimal structure in the manner of the theory of Alexandrov spaces. For $\mu \in \mathcal{P}(M)$, denote by $\Sigma'_{\mu}[\mathcal{P}(M)]$ the set of all (nontrivial) unit speed minimal geodesics emanating from μ . Given $\alpha, \beta \in \Sigma'_{\mu}[\mathcal{P}(M)]$, Theorem 7.1 verifies that the *angle*

$$\angle_{\mu}(\alpha,\beta) := \arccos\left(\lim_{s,t\to 0} \frac{s^2 + t^2 - W_2(\alpha(s),\beta(t))^2}{2st}\right) \in [0,\pi]$$

is well-defined. We define the space of directions $(\Sigma_{\mu}[\mathcal{P}(M)], \angle_{\mu})$ as the completion of $(\Sigma'_{\mu}[\mathcal{P}(M)]/\sim, \angle_{\mu})$, where $\alpha \sim \beta$ holds if $\angle_{\mu}(\alpha, \beta) = 0$. The tangent cone $(C_{\mu}[\mathcal{P}(M)], \sigma_{\mu})$ is defined as the Euclidean cone over $(\Sigma_{\mu}[\mathcal{P}(M)], \angle_{\mu})$, i.e.,

$$C_{\mu}[\mathcal{P}(M)] := \left(\Sigma_{\mu}[\mathcal{P}(M)] \times [0, \infty) \right) / \left(\Sigma_{\mu}[\mathcal{P}(M)] \times \{0\} \right),$$

$$\sigma_{\mu} \big((\alpha, s), (\beta, t) \big) := \sqrt{s^2 + t^2 - 2st \cos \angle_{\mu}(\alpha, \beta)}.$$

Using this infinitesimal structure, we introduce a class of 'differentiable curves'.

Definition 7.2 (Right differentiability) We say that a curve $\xi : [0, l) \longrightarrow \mathcal{P}(M)$ is right differentiable at $t \in [0, l)$ if there is $\mathbf{v} \in C_{\xi(t)}[\mathcal{P}(M)]$ such that, for any sequences $\{\varepsilon_i\}_{i\in\mathbb{N}}$ of positive numbers tending to zero and $\{\alpha_i\}_{i\in\mathbb{N}}$ of unit speed minimal geodesics from $\xi(t)$ to $\xi(t+\varepsilon_i)$, the sequence $\{(\alpha_i, W_2(\xi(t), \xi(t+\varepsilon_i))/\varepsilon_i)\}_{i\in\mathbb{N}} \subset C_{\xi(t)}[\mathcal{P}(M)]$ converges to \mathbf{v} . Such \mathbf{v} is clearly unique if it exists, and then we write $\dot{\xi}(t) = \mathbf{v}$.

7.2 Gradient flows in $(\mathcal{P}(M), W_2)$

Consider a lower semi-continuous function $f : \mathcal{P}(M) \longrightarrow (-\infty, +\infty]$ which is K-convex in the weak sense for some $K \in \mathbb{R}$. We in addition suppose that f is not identically $+\infty$, and define $\mathcal{P}^*(M) := \{\mu \in \mathcal{P}(M) \mid f(\mu) < \infty\}.$

Given $\mu \in \mathcal{P}^*(M)$ and $\alpha \in \Sigma_{\mu}[\mathcal{P}(M)]$, we set

$$D_{\mu}f(\alpha) := \liminf_{\Sigma'_{\mu}[\mathcal{P}(M)] \ni \beta \to \alpha} \lim_{t \to 0} \frac{f(\beta(t)) - f(\mu)}{t}.$$

Define the absolute gradient (called the local slope in [AGS]) of f at $\mu \in \mathcal{P}^*(M)$ by

$$|\nabla_{\!\!-} f|(\mu) := \max\left\{0, \limsup_{\tilde{\mu} \to \mu} \frac{f(\mu) - f(\tilde{\mu})}{W_2(\mu, \tilde{\mu})}\right\}$$

Note that $-D_{\mu}f(\alpha) \leq |\nabla_f|(\mu)$ for any $\alpha \in \Sigma_{\mu}[\mathcal{P}(M)]$.

Lemma 7.3 ([Oh1, Lemma 4.2]) For each $\mu \in \mathcal{P}^*(M)$ with $0 < |\nabla_f|(\mu) < \infty$, there exists unique $\alpha \in \Sigma_{\mu}[\mathcal{P}^*(M)]$ satisfying $D_{\mu}f(\alpha) = -|\nabla_f|(\mu)$.

Using α in the above lemma, we define the *negative gradient vector* of f at μ as

$$\nabla_{\!\!-} f(\mu) := \left(\alpha, |\nabla_{\!\!-} f|(\mu) \right) \in C_{\mu}[\mathcal{P}(M)].$$

In the case of $|\nabla_f|(\mu) = 0$, we simply define $\nabla_f(\mu)$ as the origin of $C_{\mu}[\mathcal{P}(M)]$.

Definition 7.4 (Gradient curves) A continuous curve $\xi : [0, l) \longrightarrow \mathcal{P}^*(M)$ which is locally Lipschitz on (0, l) is called a *gradient curve* of f if $|\nabla_{-}f|(\xi(t)) < \infty$ for all $t \in (0, \infty)$ and if it is right differentiable with $\dot{\xi}(t) = \nabla_{-}f(\xi(t))$ at all $t \in (0, l)$. We say that a gradient curve ξ is *complete* if it is defined on entire $[0, \infty)$.

Theorem 7.5 ([Oh1, Theorem 5.11, Corollary 6.3], [GO, Theorem 4.2])

- (i) From any $\mu \in \mathcal{P}^*(M)$, there starts a unique complete gradient curve $\xi : [0, \infty) \longrightarrow \mathcal{P}^*(M)$ of f with $\xi(0) = \mu$.
- (ii) Given any two gradient curves $\xi, \zeta : [0, \infty) \longrightarrow \mathcal{P}^*(M)$ of f, we have

$$W_2(\xi(t),\zeta(t)) \le e^{-Kt} W_2(\xi(0),\zeta(0))$$
 (7.1)

for all $t \in [0, \infty)$.

To be precise, the uniqueness in (i) is a consequence of the K-contraction property (7.1). Therefore the gradient flow $G : [0, \infty) \times \mathcal{P}^*(M) \longrightarrow \mathcal{P}^*(M)$ of f, given as $G(t, \mu) = \underline{\xi}(t)$ in Theorem 7.5(i), is uniquely determined and extended to the closure $G : [0, \infty) \times \overline{\mathcal{P}^*(M)} \longrightarrow \overline{\mathcal{P}^*(M)}$ continuously.

7.3 *m*-relative entropy and the porous medium/fast diffusion equation

We recall basic notions of calculus on weighted Riemannian manifolds (M, ω) with $\omega = e^{-\psi} \operatorname{vol}_q$. For a C^1 -vector field V on M, we define the weighted divergence as

$$\operatorname{div}_{\omega} V := \operatorname{div} V - \langle V, \nabla \psi \rangle,$$

where div V denotes the usual divergence of V for $(M, \operatorname{vol}_g)$. Note that, for any $f \in C^1(M)$,

$$\int_{M} \langle \nabla f, V \rangle \, d\omega = \int_{M} \langle \nabla f, e^{-\psi} V \rangle \, d\mathrm{vol}_{g} = -\int_{M} f \operatorname{div}(e^{-\psi} V) \, d\mathrm{vol}_{g}$$
$$= -\int_{M} f \operatorname{div}_{\omega} V \, d\omega.$$

For $f \in C^2(M)$, the weighted Laplacian is defined by

$$\Delta^{\omega} f := \operatorname{div}_{\omega}(\nabla f) = \Delta f - \langle \nabla f, \nabla \psi \rangle.$$

Then it is an established fact that the gradient flow of the corresponding relative entropy (or the *free energy*)

$$\operatorname{Ent}_{\omega}(\rho\omega) = \int_{M} \rho \ln \rho \, d\omega = \int_{M} (\rho e^{-\psi}) \ln(\rho e^{-\psi}) \, d\operatorname{vol}_{g} + \int_{M} \psi \, d\mu$$

produces a solution to the associated heat equation (or the Fokker-Planck equation)

$$\frac{\partial \rho}{\partial t} = \Delta^{\omega} \rho = e^{\psi} \big\{ \Delta(\rho e^{-\psi}) + \operatorname{div} \left((\rho e^{-\psi}) \nabla \psi \right) \big\}.$$

See [JKO, Theorem 5.1], [Vi1, Subsection 8.4.2] for the Euclidean case, [Oh1, Theorem 6.6], [GO, Theorem 4.6], [Vi2, Corollary 23.23] for the Riemannian case, and [OS1, Section 7] for the Finsler case.

We shall see that a similar argumentation gives a weak solution to the *porous medium* equation for m > 1 or the fast diffusion equation for m < 1 (with drift) of the form

$$\frac{\partial \rho}{\partial t} = \frac{1}{m} \Delta^{\omega}(\rho^m) + \operatorname{div}_{\omega}(\rho \nabla \Psi)$$
(7.2)

as gradient flow of the *m*-relative entropy $H_m(\cdot|\nu)$. This is demonstrated by Otto [Ot] for the Tsallis entropy as well as $H_m(\cdot|N_m(0,cI_n))$ with respect to the *m*-Gaussian measures $N_m(0,cI_n)$ on (\mathbb{R}^n, dx) , and by Villani [Vi2, Theorem 23.19] on weighted Riemannian manifolds in a different way of interpretation from ours. Here we present a precise proof along the strategy of [Oh1], [GO]. Recall that $\nu = \exp_m(-\Psi)\omega$.

Theorem 7.6 (Gradient flow of H_m) Let (M, g) be compact, $m \in ((n-1)/n, 1) \cup (1, 2]$ and Ψ be Lipschitz. If a curve $(\mu_t)_{t \in [0,\infty)} \subset \mathcal{P}_{ac}(M,\omega)$ is a gradient curve of $H_m(\cdot|\nu)$, then its density function ρ_t is a weak solution to the porous medium or the fast diffusion equation (7.2). To be precise,

$$\int_{M} \phi_{t_1} d\mu_{t_1} - \int_{M} \phi_{t_0} d\mu_{t_0} = \int_{t_0}^{t_1} \int_{M} \left\{ \frac{\partial \phi_t}{\partial t} + \frac{1}{m} \rho_t^{m-1} \Delta^{\omega} \phi_t + \frac{1}{m-1} \langle \nabla \phi_t, \nabla (\sigma^{m-1}) \rangle \right\} d\mu_t dt$$
(7.3)

holds for all $0 \le t_0 < t_1 < \infty$ and $\phi \in C^{\infty}(\mathbb{R} \times M)$, where $\mu_t = \rho_t \omega$, $\phi_t = \phi(t, \cdot)$.

Proof. Fix $t \in (0, \infty)$ and, given small $\delta > 0$, choose $\mu^{\delta} \in \mathcal{P}(M)$ as a minimizer of the function

$$\mu \longmapsto H_m(\mu|\nu) + \frac{W_2(\mu,\mu_t)^2}{2\delta}$$

We postpone the proof of the following technical claim until the end of the section. We remark that the hypotheses m > (n - 1)/n and $m \le 2$ come into play in the proof of Claim 7.7(i) and (iii), respectively.

Claim 7.7 (i) Such μ^{δ} indeed exists and is absolutely continuous with respect to ω .

(ii) We have

$$\lim_{\delta \to 0} \frac{W_2(\mu^{\delta}, \mu_t)^2}{2\delta} = 0, \qquad \lim_{\delta \to 0} H_m(\mu^{\delta}|\nu) = H_m(\mu_t|\nu).$$

In particular, μ^{δ} converges to μ_t weakly.

(iii) Moreover, by putting $\mu^{\delta} = \rho^{\delta} \omega$, $(\rho^{\delta})^m$ converges to ρ_t^m in $L^1(M, \omega)$.

Take a Lipschitz function $\varphi : M \longrightarrow \mathbb{R}$ such that $\mathcal{T}(x) := \exp_x(\nabla \varphi(x))$ gives the optimal transport from μ^{δ} to μ_t . We consider the transport $\mu^{\delta}_{\varepsilon} := (\mathcal{F}_{\varepsilon})_{\sharp} \mu^{\delta}$ in another direction for small $\varepsilon > 0$, where $\mathcal{F}_{\varepsilon}(x) := \exp_x(\varepsilon \nabla \phi_t(x))$. It immediately follows from the choice of μ^{δ} that

$$H_m(\mu_{\varepsilon}^{\delta}|\nu) + \frac{W_2(\mu_{\varepsilon}^{\delta},\mu_t)^2}{2\delta} \ge H_m(\mu^{\delta}|\nu) + \frac{W_2(\mu^{\delta},\mu_t)^2}{2\delta}.$$
(7.4)

We first estimate the difference of distances. Observe that, as $(\mathcal{F}_{\varepsilon} \times \mathcal{T})_{\sharp} \mu^{\delta}$ is a (not necessarily optimal) coupling of $\mu_{\varepsilon}^{\delta}$ and μ_t ,

$$\begin{split} \limsup_{\varepsilon \to 0} \frac{W_2(\mu_{\varepsilon}^{\delta}, \mu_t)^2 - W_2(\mu^{\delta}, \mu_t)^2}{\varepsilon} \\ &\leq \limsup_{\varepsilon \to 0} \frac{1}{\varepsilon} \int_M \left\{ d \big(\mathcal{F}_{\varepsilon}(x), \mathcal{T}(x) \big)^2 - d \big(x, \mathcal{T}(x) \big)^2 \right\} d\mu^{\delta}(x) \\ &= - \int_M 2 \langle \nabla \phi_t, \nabla \varphi \rangle \, d\mu^{\delta}. \end{split}$$

We used the first variation formula for the distance d in the last line (cf. [Ch, Theorem II.4.1]). Thanks to the compactness of M, there is a constant C > 0 such that

$$\phi_t(\mathcal{T}(x)) \le \phi_t(x) + \langle \nabla \phi_t(x), \nabla \varphi(x) \rangle + Cd(x, \mathcal{T}(x))^2.$$

Thus we obtain, by virtue of Claim 7.7(ii),

$$\begin{split} \liminf_{\delta \to 0} \frac{1}{2\delta} \limsup_{\varepsilon \to 0} \frac{W_2(\mu_{\varepsilon}^{\delta}, \mu_t)^2 - W_2(\mu^{\delta}, \mu_t)^2}{\varepsilon} &\leq -\limsup_{\delta \to 0} \frac{1}{\delta} \int_M \langle \nabla \phi_t, \nabla \varphi \rangle \, d\mu^{\delta} \\ &\leq \liminf_{\delta \to 0} \frac{1}{\delta} \bigg[\int_M \{\phi_t - \phi_t(\mathcal{T})\} \, d\mu^{\delta} + CW_2(\mu^{\delta}, \mu_t)^2 \bigg] \\ &= \liminf_{\delta \to 0} \frac{1}{\delta} \bigg\{ \int_M \phi_t \, d\mu^{\delta} - \int_M \phi_t \, d\mu_t \bigg\}. \end{split}$$

Next we calculate the difference of entropies in (7.4). We put $\mu^{\delta} = \rho^{\delta} \omega$, $\mu^{\delta}_{\varepsilon} = \rho^{\delta}_{\varepsilon} \omega$ and $\mathbf{J}^{\omega}_{\varepsilon} := e^{\psi - \psi(\mathcal{F}_{\varepsilon})} \det(D\mathcal{F}_{\varepsilon})$. Then we obtain from the Jacobian equation $\rho^{\delta}_{\varepsilon}(\mathcal{F}_{\varepsilon}) \mathbf{J}^{\omega}_{\varepsilon} = \rho^{\delta}$ (Theorem 2.10) that

$$H_m(\mu_{\varepsilon}^{\delta}|\nu) - \frac{1}{m} \int_M \sigma^m d\omega = \frac{1}{m(m-1)} \int_M \{(\rho_{\varepsilon}^{\delta})^{m-1} - m\sigma^{m-1}\} d\mu_{\varepsilon}^{\delta}$$
$$= \frac{1}{m(m-1)} \int_M \{\rho_{\varepsilon}^{\delta}(\mathcal{F}_{\varepsilon})^{m-1} - m\sigma(\mathcal{F}_{\varepsilon})^{m-1}\} d\mu^{\delta}$$
$$= \frac{1}{m(m-1)} \int_M \left\{ \left(\frac{\rho^{\delta}}{\mathbf{J}_{\varepsilon}^{\omega}}\right)^{m-1} - m\sigma(\mathcal{F}_{\varepsilon})^{m-1} \right\} d\mu^{\delta}.$$

Thus we have

$$H_m(\mu^{\delta}|\nu) - H_m(\mu_{\varepsilon}^{\delta}|\nu)$$

= $\frac{1}{m(m-1)} \int_M \left[(\rho^{\delta})^{m-1} \{ 1 - (\mathbf{J}_{\varepsilon}^{\omega})^{1-m} \} - m \{ \sigma^{m-1} - \sigma(\mathcal{F}_{\varepsilon})^{m-1} \} \right] d\mu^{\delta}.$

Note that, as $\det(D\mathcal{F}_0) = 1$,

$$\lim_{\varepsilon \to 0} \frac{\mathbf{J}_{\varepsilon}^{\omega} - 1}{\varepsilon} = \lim_{\varepsilon \to 0} \frac{e^{\psi - \psi(\mathcal{F}_{\varepsilon})} \det(D\mathcal{F}_{\varepsilon}) - 1}{\varepsilon} = \operatorname{trace}(\operatorname{Hess} \phi_t) - \langle \nabla \phi_t, \nabla \psi \rangle$$
$$= \Delta \phi_t - \langle \nabla \phi_t, \nabla \psi \rangle = \Delta^{\omega} \phi_t.$$

Hence we obtain, together with Claim 7.7(iii),

$$\lim_{\varepsilon \to 0} \frac{H_m(\mu^{\delta}|\nu) - H_m(\mu_{\varepsilon}^{\delta}|\nu)}{\varepsilon}$$
$$= \int_M \left\{ \frac{1}{m} (\rho^{\delta})^{m-1} \Delta^{\omega} \phi_t + \frac{1}{m-1} \langle \nabla \phi_t, \nabla(\sigma^{m-1}) \rangle \right\} d\mu^{\delta}$$
$$\to \int_M \left\{ \frac{1}{m} \rho_t^{m-1} \Delta^{\omega} \phi_t + \frac{1}{m-1} \langle \nabla \phi_t, \nabla(\sigma^{m-1}) \rangle \right\} d\mu_t$$
(7.5)

as δ tends to zero.

These together imply

$$\liminf_{\delta \to 0} \frac{1}{\delta} \left\{ \int_M \phi_t \, d\mu^\delta - \int_M \phi_t \, d\mu_t \right\} \ge \int_M \left\{ \frac{1}{m} \rho_t^{m-1} \Delta^\omega \phi_t + \frac{1}{m-1} \langle \nabla \phi_t, \nabla (\sigma^{m-1}) \rangle \right\} d\mu_t.$$

Moreover, equality holds since we can change ϕ into $-\phi$. Recall from [GO, (4)] (see also [Oh1, Lemma 6.4]) that

$$\lim_{\delta \to 0} \frac{1}{\delta} \left\{ \int_M h \, d\mu_{t+\delta} - \int_M h \, d\mu^{\delta} \right\} = 0$$

holds for all $h \in C^{\infty}(M)$. Therefore we conclude

$$\begin{split} &\lim_{\delta \to 0} \frac{1}{\delta} \bigg\{ \int_{M} \phi_{t+\delta} \, d\mu_{t+\delta} - \int_{M} \phi_{t} \, d\mu_{t} \bigg\} \\ &= \lim_{\delta \to 0} \frac{1}{\delta} \bigg\{ \int_{M} (\phi_{t+\delta} - \phi_{t}) \, d\mu_{t+\delta} + \int_{M} \phi_{t} \, d\mu_{t+\delta} - \int_{M} \phi_{t} \, d\mu_{t} \bigg\} \\ &= \int_{M} \bigg\{ \frac{\partial \phi_{t}}{\partial t} + \frac{1}{m} \rho_{t}^{m-1} \Delta^{\omega} \phi_{t} + \frac{1}{m-1} \langle \nabla \phi_{t}, \nabla (\sigma^{m-1}) \rangle \bigg\} \, d\mu_{t} \end{split}$$

as desired.

Remark 7.8 In Theorem 7.6, assuming μ_t is absolutely continuous is redundant. For m > 1, $H_m(\mu_t|\nu) < \infty$ immediately implies $\mu_t \in \mathcal{P}_{ac}(M, \omega)$. For m < 1, if μ_t with t > 0

has a nontrivial singular part μ^s , then the modification of μ_t as in the proof of Claim 7.7(i) with $\mu^{\delta} = \mu_t$ gives a measure $\hat{\mu}_r \in \mathcal{P}_{ac}(M, \omega)$ for small r > 0 such that

$$W_2(\mu_t, \hat{\mu}_r)^2 \le \mu^s(M)r^2, \qquad H_m(\hat{\mu}_r|\nu) \le H_m(\mu_t|\nu) - C(\omega, m)\mu^s(M)r^{n(1-m)}$$

with C > 0. As n(1-m) < 1, these yield $|\nabla H_m(\cdot|\nu)|(\mu_t) = \infty$ as r goes to zero, which contradicts the definition of gradient curves (compare this with [AGS, Theorem 10.4.8]).

Recall from Theorem 4.1 that the entropy $H_m(\cdot|\nu)$ is K-convex if (and only if) $\operatorname{Ric}_N \geq 0$ and $\operatorname{Hess} \Psi \geq K$. Combining this with Theorems 7.5, 7.6, we obtain the following.

Corollary 7.9 Suppose that (M, g) is compact and $\overline{M_0}$ is convex. Then the weak solution $(\mu_t)_{t \in [0,\infty)} \subset \mathcal{P}_{ac}(\overline{M_0}, \omega)$ to the porous medium (or the fast diffusion) equation (7.2) constructed in Theorem 7.6 enjoys the K-contraction property (7.1) under the assumptions $\operatorname{Ric}_N \geq 0$ and $\operatorname{Hess} \Psi \geq K$ on $\overline{M_0}$.

The argument in the proof of Theorem 7.6 also shows that the absolute gradient of $H_m(\cdot|\nu)$ at μ coincides with the square root of the *m*-relative Fisher information introduced in (5.2), for general *m*. Compare this with Theorem 5.2.

Proposition 7.10 Take $m \in [(n-1)/n, 1) \cup (1, \infty)$ and $\mu = \rho \omega \in \mathcal{P}_{ac}(M, \omega)$ such that ρ is Lipschitz. For any $(d^2/2)$ -convex function $\varphi : M \longrightarrow \mathbb{R}$ and the corresponding transport $\mu_t := (\mathcal{T}_t)_{\sharp} \mu$ with $\mathcal{T}_t(x) := \exp_x(t\nabla\varphi(x)), t \ge 0$, it holds that

$$\lim_{t \to 0} \frac{H_m(\mu_t|\nu) - H_m(\mu|\nu)}{t} = \frac{1}{m-1} \int_M \langle \nabla(\rho^{m-1} - \sigma^{m-1}), \nabla\varphi \rangle \, d\mu.$$

In particular, we have $|\nabla_{-}[H_m(\cdot|\nu)]|(\mu) = \sqrt{I_m(\mu|\nu)}$ and, if $|\nabla_{-}[H_m(\cdot|\nu)]|(\mu) < \infty$, then the negative gradient vector $\nabla_{-}[H_m(\cdot|\nu)](\mu)$ is achieved by

$$\nabla \varphi = -\nabla \left(\frac{\rho^{m-1} - \sigma^{m-1}}{m-1} \right).$$

Proof. Recall that φ is twice differentiable a.e., and that μ_t is absolutely continuous for t < 1 ([Vi2, Theorem 8.7]). Using the calculation deriving (7.5), we obtain

$$\begin{split} \lim_{t \to 0} & \frac{H_m(\mu|\nu) - H_m(\mu_t|\nu)}{t} \\ &= \int_M \left\{ \frac{1}{m} \rho^{m-1} \Delta^\omega \varphi + \frac{1}{m-1} \langle \nabla \varphi, \nabla(\sigma^{m-1}) \rangle \right\} d\mu \\ &= -\int_M \left\{ \frac{1}{m} \langle \nabla(\rho^m), \nabla \varphi \rangle - \frac{\rho}{m-1} \langle \nabla \varphi, \nabla(\sigma^{m-1}) \rangle \right\} d\omega \\ &= -\frac{1}{m-1} \int_M \langle \nabla(\rho^{m-1} - \sigma^{m-1}), \nabla \varphi \rangle d\mu. \end{split}$$

As any geodesic with respect to W_2 is realized in this way (Theorem 2.8), we have $|\nabla [H_m(\cdot|\nu)]|(\mu) = \sqrt{I_m(\mu|\nu)}$ and, if $|\nabla [H_m(\cdot|\nu)]|(\mu) < \infty$,

$$\nabla [H_m(\cdot|\nu)](\mu) = -\nabla \left(\frac{\rho^{m-1} - \sigma^{m-1}}{m-1}\right).$$

Remark 7.11 The family of *m*-Gaussian measures (Example 2.6) is closely related to the Barenblatt solution to (7.2) (without drift), and again has a role to play here. On the unweighted Euclidean space (\mathbb{R}^n, dx), it is known by [OW, Proposition 5] that a solution to (7.2) starting from an *m*-Gaussian measure will keep being *m*-Gaussian. An explicit expression of such solutions is given in [Ta2].

7.4 Proof of Claim 7.7

(i) The existence follows from, as usual, the compactness of $\mathcal{P}(M)$ and the lower semicontinuity of $H_m(\cdot|\nu)$ (Lemma 3.4). The absolute continuity is obvious for m > 1.

For m < 1, decompose μ^{δ} into absolutely continuous and singular parts $\mu^{\delta} = \rho \omega + \mu^s$ and suppose $\mu^s(M) > 0$. We modify μ^{δ} into $\hat{\mu}_r \in \mathcal{P}_{ac}(M, \omega)$ as

$$d\hat{\mu}_r(x) = \hat{\rho}_r(x) \, d\omega(x) := \left\{ \rho(x) + \int_M \frac{\chi_{B(y,r)}(x)}{\omega(B(y,r))} \, d\mu^s(y) \right\} d\omega(x)$$

for small r > 0. Then we find

$$\begin{split} \int_{M} \sigma^{m-1} d\hat{\mu}_{r} &\leq \int_{M} \sigma^{m-1} d\mu^{\delta} + \int_{M} \left| \sigma(y)^{m-1} - \frac{1}{\omega(B(y,r))} \int_{B(y,r)} \sigma^{m-1} d\omega \right| d\mu^{s}(y) \\ &\leq \int_{M} \sigma^{m-1} d\mu^{\delta} + \Big\{ \sup_{M} |\nabla(\sigma^{m-1})| \cdot r \Big\} \mu^{s}(M). \end{split}$$

Given an optimal coupling $\pi = \pi_1 + \pi_2$ of μ^{δ} and μ_t such that $(p_1)_{\sharp}\pi_1 = \rho\omega$ and $(p_1)_{\sharp}\pi_2 = \mu^s$,

$$d\hat{\pi}_{r}(x,z) := d\pi_{1}(x,z) + \int_{y \in M} \frac{\chi_{B(y,r)}(x)}{\omega(B(y,r))} d\omega(x) d\pi_{2}(y,z)$$

is a coupling of $\hat{\mu}_r$ and μ_t . Hence we observe

$$W_{2}(\hat{\mu}_{r},\mu_{t})^{2} \leq \int_{M\times M} d(x,z)^{2} d\pi_{1}(x,z) + \int_{M\times M} \{d(y,z)+r\}^{2} d\pi_{2}(y,z)$$

$$\leq \int_{M\times M} d(x,z)^{2} d\pi(x,z) + \{2\operatorname{diam} M+r\}r\pi_{2}(M\times M)$$

$$\leq W_{2}(\mu^{\delta},\mu_{t})^{2} + \{3\operatorname{diam} M\cdot r\}\mu^{s}(M).$$

Finally, it follows from the Hölder inequality that

$$\begin{split} &\int_{M} \hat{\rho}_{r}^{m} d\omega = \int_{M} \left[\int_{M} \left\{ \frac{\rho(x)}{\mu^{s}(M)} + \frac{\chi_{B(y,r)}(x)}{\omega(B(y,r))} \right\} d\mu^{s}(y) \right]^{m} d\omega(x) \\ &\geq \mu^{s}(M)^{m-1} \int_{M} \left[\int_{M} \left\{ \frac{\rho(x)}{\mu^{s}(M)} + \frac{\chi_{B(y,r)}(x)}{\omega(B(y,r))} \right\}^{m} d\mu^{s}(y) \right] d\omega(x) \\ &\geq \mu^{s}(M)^{m-1} \int_{M} \left\{ \int_{M \setminus B(y,r)} \frac{\rho^{m}}{\mu^{s}(M)^{m}} d\omega + \int_{B(y,r)} \frac{1}{\omega(B(y,r))^{m}} d\omega \right\} d\mu^{s}(y) \\ &= \int_{M} \rho^{m} d\omega - \mu^{s}(M)^{-1} \int_{M} \left(\int_{B(y,r)} \rho^{m} d\omega \right) d\mu^{s}(y) \\ &+ \mu^{s}(M)^{m-1} \int_{M} \omega \left(B(y,r) \right)^{1-m} d\mu^{s}(y). \end{split}$$

As M is compact, we find

$$\mu^{s}(M)^{m-1} \int_{M} \omega (B(y,r))^{1-m} d\mu^{s}(y) \ge \mu^{s}(M)^{m} C_{1}(\omega,m) r^{n(1-m)},$$

and, for all $y \in \operatorname{supp} \mu^s$,

$$\int_{B(y,r)} \rho^m d\omega = \int_{B(y,r)} (\rho \sigma^{m-1})^m \sigma^{m(1-m)} d\omega$$
$$\leq \left(\int_{B(y,r)} \rho \sigma^{m-1} d\omega \right)^m \left(\int_{B(y,r)} \sigma^m d\omega \right)^{1-m}$$
$$\leq \left(\int_{B(y,r)} \rho \sigma^{m-1} d\omega \right)^m C_2(\omega,\sigma,m) r^{n(1-m)}.$$

Since $\lim_{r\to 0} \sup_{y\in M} \int_{B(y,r)} \rho \sigma^{m-1} d\omega = 0$, these imply for small r > 0

$$\int_M \hat{\rho}_r^m \, d\omega \ge \int_M \rho^m \, d\omega + \frac{1}{2} C_1(\omega, m) \mu^s(M)^m r^{n(1-m)}.$$

Combining these, we conclude that

$$H_m(\hat{\mu}_r|\nu) + \frac{W_2(\hat{\mu}_r, \mu_t)^2}{2\delta} - H_m(\mu^{\delta}|\nu) - \frac{W_2(\mu^{\delta}, \mu_t)^2}{2\delta} \\ \leq -C_3(\omega, m)\mu^s(M)^m r^{n(1-m)} + C_4(M, \sigma, m, \delta)\mu^s(M)r,$$

where $C_3, C_4 > 0$. Then n(1-m) < 1 and $\mu^s(M) > 0$ yield that

$$H_m(\hat{\mu}_r|\nu) + \frac{W_2(\hat{\mu}_r, \mu_t)^2}{2\delta} < H_m(\mu^{\delta}|\nu) + \frac{W_2(\mu^{\delta}, \mu_t)^2}{2\delta}$$

holds for small r > 0. This contradicts the choice of μ^{δ} , therefore we obtain $\mu^s(M) = 0$. (ii) By the choice of μ^{δ} , we have

$$H_m(\mu^{\delta}|\nu) + \frac{W_2(\mu^{\delta},\mu_t)^2}{2\delta} \le H_m(\mu_t|\nu)$$

which immediately implies $\lim_{\delta\to 0} W_2(\mu^{\delta}, \mu_t)^2 \leq \lim_{\delta\to 0} 2\delta H_m(\mu_t|\nu) = 0$. Thus μ^{δ} converges to μ_t weakly, and hence

$$\limsup_{\delta \to 0} \frac{W_2(\mu^{\delta}, \mu_t)^2}{2\delta} \le H_m(\mu_t | \nu) - \liminf_{\delta \to 0} H_m(\mu^{\delta} | \nu) \le 0$$

by the lower semi-continuity (Lemma 3.4). This further yields

$$H_m(\mu_t|\nu) \le \liminf_{\delta \to 0} H_m(\mu^{\delta}|\nu) \le \limsup_{\delta \to 0} H_m(\mu^{\delta}|\nu) \le H_m(\mu_t|\nu),$$

where the last inequality follows again from the choice of μ^{δ} .

(iii) This is a consequence of the following general lemma.

 \diamond

Lemma 7.12 Assume $m \in [(n-1)/n, 1) \cup (1, 2]$ and that a sequence $\{\mu_i\}_{i \in \mathbb{N}} \subset \mathcal{P}_{ac}(M, \omega)$ converges to $\mu \in \mathcal{P}_{ac}(M, \omega)$ weakly as well as $\lim_{i\to\infty} H_m(\mu_i|\nu) = H_m(\mu|\nu) < \infty$. Then, by setting $\mu_i = \rho_i \omega$ and $\mu = \rho \omega$, ρ_i^m converges to ρ^m in $L^1(M, \omega)$.

Proof. Note that the convergence of $H_m(\mu_i|\nu)$ ensures $\lim_{i\to\infty} \int_M \rho_i^m d\omega = \int_M \rho^m d\omega$. We shall show the following:

(*) For any constant C > 0, it holds $\lim_{i\to\infty} \|\min\{\rho_i, C\} - \min\{\rho, C\}\|_{L^2(M,\omega)} = 0$. Then we have, for m < 1,

$$\int_{M} |\rho_{i}^{m} - \rho^{m}| \, d\omega \leq \int_{M} |\rho_{i} - \rho|^{m} \, d\omega \leq \omega(M)^{1-m} \left(\int_{M} |\rho_{i} - \rho| \, d\omega \right)^{m},$$

and

$$\int_{M} |\rho_{i} - \rho| d\omega$$

$$\leq \int_{M} \left[|\min\{\rho_{i}, C\} - \min\{\rho, C\} | + \max\{\rho_{i} - C, 0\} + \max\{\rho - C, 0\} \right] d\omega$$

$$\rightarrow 0$$

as $i \to \infty$ and then $C \to \infty$. Precisely,

$$\int_{M} \max\{\rho_{i} - C, 0\} d\omega = \int_{M} (\rho_{i} - \min\{\rho_{i}, C\}) d\omega \to 1 - \int_{M} \min\{\rho, C\} d\omega \quad (i \to \infty)$$
$$\to 0 \quad (C \to \infty),$$

where (*) is used when taking the limit as $i \to \infty$. For $m \in (1, 2]$, we similarly find

$$\int_{M} |\rho_{i}^{m} - \rho^{m}| d\omega \leq m \int_{M} |\rho_{i} - \rho| \max\{\rho_{i}, \rho\}^{m-1} d\omega$$
$$\leq m \left(\int_{M} |\rho_{i} - \rho|^{m} d\omega \right)^{1/m} \left(\int_{M} (\rho_{i} + \rho)^{m} d\omega \right)^{(m-1)/m}, \tag{7.6}$$

and

$$\int_{M} |\rho_{i} - \rho|^{m} d\omega$$

$$\leq 2^{m-1} \int_{M} \left[|\min\{\rho_{i}, C\} - \min\{\rho, C\} |^{m} + \max\{\rho_{i} - C, 0\}^{m} + \max\{\rho - C, 0\}^{m} \right] d\omega$$

$$\to 0$$

as $i \to \infty$ and then $C \to \infty$. Indeed,

$$\int_{M} \max\{\rho_{i} - C, 0\}^{m} d\omega = \int_{M} (\rho_{i} - \min\{\rho_{i}, C\})^{m} d\omega \leq \int_{M} (\rho_{i}^{m} - \min\{\rho_{i}, C\}^{m}) d\omega$$
$$\rightarrow \int_{M} (\rho^{m} - \min\{\rho, C\}^{m}) d\omega \quad (i \to \infty)$$
$$\rightarrow 0 \quad (C \to \infty),$$

where we used the calculation as in (7.6) and (*) to see

$$\lim_{i \to \infty} \int_M |\min\{\rho_i, C\}^m - \min\{\rho, C\}^m | d\omega = 0.$$

To show (*), we suppose that it is false. Then there are some constants $C, \varepsilon > 0$ and a sequence $\{l_j\}_{j \in \mathbb{N}} \subset \mathbb{N}$ going to infinity such that

$$\|\min\{\rho, C\} - \min\{\rho_{l_j}, C\}\|_{L^2(M,\omega)} \ge \varepsilon$$
 (7.7)

for all $j \in \mathbb{N}$. Note that, as $d^2[t^m/m(m-1)]/dt^2 = t^{m-2}$,

$$\frac{1}{m(m-1)} \left(\frac{\rho + \rho_{l_j}}{2}\right)^m \le \frac{\rho^m + \rho_{l_j}^m}{2m(m-1)} - \frac{\max\{\rho, \rho_{l_j}\}^{m-2}}{8} |\rho - \rho_{l_j}|^2.$$

For the second term, we observe

$$\max\{\rho, \rho_{l_j}\}^{m-2} |\rho - \rho_{l_j}|^2 \ge C^{m-2} |\min\{\rho, C\} - \min\{\rho_{l_j}, C\}|^2.$$

This is clear if $\max\{\rho, \rho_{l_j}\} \leq C$ or $\min\{\rho, \rho_{l_j}\} \geq C$, and follows from $\tau^{m-2}(\tau-\varepsilon)^2 \geq (1-\varepsilon)^2$ for $\tau \geq 1 \geq \varepsilon$ otherwise. Thus we obtain, by (7.7),

$$\frac{1}{m(m-1)} \int_{M} \left(\frac{\rho + \rho_{l_j}}{2}\right)^{m} d\omega$$

$$\leq \int_{M} \frac{\rho^{m} + \rho_{l_j}^{m}}{2m(m-1)} d\omega - \frac{C^{m-2}}{8} \int_{M} |\min\{\rho, C\} - \min\{\rho_{l_j}, C\}|^2 d\omega$$

$$\leq \int_{M} \frac{\rho^{m} + \rho_{l_j}^{m}}{2m(m-1)} d\omega - \frac{C^{m-2}}{8} \varepsilon^{2}.$$

This means that $\bar{\mu}_j := \{(\rho + \rho_{l_j})/2\}\omega$ satisfies

$$\limsup_{j \to \infty} H_m(\bar{\mu}_j | \nu) \le \lim_{i \to \infty} H_m(\mu_i | \nu) - \frac{C^{m-2}}{8} \varepsilon^2 = H_m(\mu | \nu) - \frac{C^{m-2}}{8} \varepsilon^2,$$

this contradicts the lower semi-continuity of $H_m(\cdot|\nu)$ (Lemma 3.4).

8 Finsler case

We finally stress that most results in this article are extended to Finsler manifolds, according to the theory developed in [Oh2], [OS1] (see also a survey [Oh3]). Briefly speaking, a Finsler manifold is a differentiable manifold equipped with a (Minkowski) norm on each tangent space. Restricting these norms to those coming from inner products, we have the family of Riemannian manifolds as a subclass. We refer to [BCS], [Sh] for the basics of Finsler geometry, and to [Oh2], [OS1], [Oh3] for the details omitted in the following discussion.

A Finsler manifold (M, F) will be a pair of an *n*-dimensional C^{∞} -manifold M and a C^{∞} -Finsler structure $F : TM \longrightarrow [0, \infty)$ satisfying the following regularity, positive homogeneity, and strong convexity conditions:

- (1) F is C^{∞} on $TM \setminus 0$, where 0 stands for the zero section;
- (2) $F(\lambda v) = \lambda F(v)$ holds for all $v \in TM$ and $\lambda \ge 0$;
- (3) In any local coordinate system $(x^i)_{i=1}^n$ of an open set $U \subset M$ and the corresponding coordinate $v = \sum_i v^i (\partial/\partial x^i)|_x$ of $T_x M$ with $x \in U$, the $n \times n$ -matrix

$$\left(\frac{\partial^2(F^2)}{\partial v^i \partial v^j}(v)\right)_{i,j=1}^n$$

is positive-definite for all $v \in T_x M \setminus 0$ and $x \in U$.

Then the distance d, geodesics and the exponential map are defined in the same manner as Riemannian geometry, whereas d is typically nonsymmetric (and not a distance in the precise sense) since F is merely positively homogeneous. Nonetheless, d satisfies the positivity and the triangle inequality.

On a Finsler manifold (M, F), there is no constructive measure as good as the Riemannian volume measure in the Riemannian case (cf. [Oh4]), but we can consider an arbitrary positive C^{∞} -measure ω on M and associate it with the weighted Ricci curvature Ric_N ([Oh2]). This curvature turns out extremely useful, and the argument in [Oh2] is applicable to generalizing the whole results in Sections 4–6 to the Finsler setting. (We need a little trick only in Proposition 5.4, put $\mu = (1 - \varepsilon f)\sigma\omega$ when m < 1 to have $\nabla[((1 - \varepsilon f)^{m-1} - 1)\sigma^{m-1}] = \nabla[(1 - m)f\varepsilon\sigma^{m-1}] = (1 - m)\varepsilon\nabla(f\sigma^{m-1}).)$

Theorem 8.1 Let (M, F) be a forward complete, connected Finsler manifold and ω be a positive C^{∞} -measure on M. Then the following results in this article hold true also for (M, F, ω) (with appropriate interpretations for the nonsymmetric distance, cf. [Oh2]):

- Equivalence between the convexity of $H_m(\cdot|\nu)$ and a curvature bound (Theorem 4.1);
- Functional inequalities (Propositions 5.1, 5.4, Theorem 5.2);
- Concentration of measures (Theorem 6.1, Corollary 6.5, Proposition 6.7).

As for Section 7, due to the lack of the analogue of Theorem 7.1, we can not directly follow the Riemannian argument. Nonetheless, we can apply the discussion in [OS1] using a (formal) Finsler structure of the Wasserstein space, and obtain results corresponding to Theorem 7.6 and Proposition 7.10. The point is the usage of the structure of the underlying space M, while we did not explicitly use it in Subsections 7.1, 7.2. See [OS1, Sections 6, 7] for further details. We remark that, however, the K-contraction property (7.1) essentially depends on the Riemannian structure and can not be expected in the Finsler setting (cf. [OS2]).

Let (M, F) be compact from now on. Due to Otto's idea [Ot, Section 4], we introduce a Finsler structure of $(\mathcal{P}(M), W_2)$ as follows. Given $\mu \in \mathcal{P}(M)$, we define the *tangent* space $(T_{\mu}\mathcal{P}, F_W(\mu, \cdot))$ at μ by

$$F_W(\mu, \nabla \varphi) := \left(\int_M F(\nabla \varphi)^2 \, d\mu \right)^{1/2} \quad \text{for } \varphi \in C^\infty(M),$$
$$T_\mu \mathcal{P} := \left(\overline{\{\nabla \varphi \, | \, \varphi \in C^\infty(M)\}}, F_W(\mu, \cdot) \right),$$

where the gradient vector $\nabla \varphi(x) \in T_x M$ is the Legendre transform of the derivative $D\varphi(x) \in T_x^*M$, and the closure was taken with respect to $F_W(\mu, \cdot)$. We remark that the gradient ∇ is a nonlinear operator (i.e., $\nabla(\varphi_1 + \varphi_2)(x) \neq \nabla \varphi_1(x) + \nabla \varphi_2(x)$ and $\nabla(-\varphi)(x) \neq -\nabla \varphi(x)$ in general), since the Legendre transform is nonlinear unless $F|_{T_xM}$ is Riemannian.

Now, we take a locally Lipschitz curve $(\mu_t)_{t\in I} \subset (\mathcal{P}(M), W_2)$ on an open interval $I \subset \mathbb{R}$. We can associate it with the *tangent vector field* $\dot{\mu}_t = \Phi(t, \cdot) \in T_{\mu_t}\mathcal{P}$, that is, Φ is a Borel vector field on $I \times M$ with $\Phi(t, x) \in T_x M$ and $F(\Phi) \in L^{\infty}_{loc}(I \times M, d\mu_t dt)$ satisfying the *continuity equation* $\partial \mu_t / \partial t + \operatorname{div}(\Phi_t \mu_t) = 0$ in the weak sense that

$$\int_{I} \int_{M} \left\{ \frac{\partial \phi_t}{\partial t} + D\phi_t(\Phi_t) \right\} d\mu_t dt = 0$$
(8.1)

holds for all $\phi \in C_c^{\infty}(I \times M)$ ([AGS, Theorem 8.3.1], [OS1, Theorem 7.3]). Using these 'differentiable' structures, we can consider gradient curves in a way different from the 'metric' approach in Section 7.

Definition 8.2 Given a function $f : \mathcal{P}(M) \longrightarrow (-\infty, \infty]$ and $\mu \in \mathcal{P}(M)$ with $f(\mu) < \infty$, we say that f is *differentiable* at μ if there is $\Phi \in T_{\mu}\mathcal{P}$ such that

$$\lim_{t\downarrow 0} \frac{f((\mathcal{T}_t)_{\sharp}\mu) - f(\mu)}{t} = \int_M \mathcal{L}(\Phi)(\nabla\varphi) \, d\mu$$

holds for all $\varphi \in C^{\infty}(M)$, where $\mathcal{T}_t(x) := \exp_x(t\nabla\varphi)$ and $\mathcal{L} : T_xM \longrightarrow T_x^*M$ stands for the Legendre transform. Then we write $\nabla_W f(\mu) = \Phi$.

Then a gradient curve should be a solution to $\dot{\mu}_t = \nabla_W [-H_m(\cdot|\nu)](\mu_t)$. We first show that $\nabla_W [-H_m(\cdot|\nu)](\mu_t)$ is described by the Fisher information like Proposition 7.10.

Proposition 8.3 Take $\mu = \rho\omega \in \mathcal{P}_{ac}(M,\omega)$ with $\rho^m \in H^1(M,\omega)$. If $\rho^{m-1} - \sigma^{m-1} \notin H^1(M,\mu)$, then $-H_m(\cdot|\nu)$ is not differentiable at μ . If $\rho^{m-1} - \sigma^{m-1} \in H^1(M,\mu)$, then $-H_m(\cdot|\nu)$ is differentiable at μ and we have

$$\nabla_W[-H_m(\cdot|\nu)](\mu) = \nabla\left(\frac{\rho^{m-1} - \sigma^{m-1}}{1 - m}\right) \in T_\mu \mathcal{P}.$$

Proof. Fix arbitrary $\varphi \in C^{\infty}(M)$ and put $\mathcal{T}_t(x) := \exp_x(t\nabla\varphi(x)), \ \mu_t = \rho_t \omega := (\mathcal{T}_t)_{\sharp} \mu$ for sufficiently small t > 0. Then the Jacobian equation $\rho = \rho_t(\mathcal{T}_t)\mathbf{J}_t^{\omega}$ holds μ -a.e. ([Oh2, Theorem 5.2]), where $\mathbf{J}_t^{\omega}(x)$ stands for the Jacobian of $D\mathcal{T}_t(x) : T_x M \longrightarrow T_{\mathcal{T}_t(x)} M$ with respect to ω . Thus we obtain, as in the proof of Theorem 7.6,

$$H_m(\mu_t|\nu) = H_m(\mu|\nu) + \frac{1}{m(m-1)} \int_M \left[\rho^{m-1}\{(\mathbf{J}_t^{\omega})^{1-m} - 1\} + m\{\sigma^{m-1} - \sigma(\mathcal{T}_t)^{m-1}\}\right] d\mu.$$

We observe, as $\rho^m \in H^1(M, \omega)$,

$$\begin{split} \lim_{t \to 0} \int_{M} \frac{(\mathbf{J}_{t}^{\omega})^{1-m} - 1}{t} \rho^{m} d\omega &= (1-m) \lim_{t \to 0} \int_{M} \frac{\mathbf{J}_{t}^{\omega} - 1}{t} \rho^{m} d\omega \\ &= (1-m) \lim_{t \to 0} \int_{M} \frac{\rho^{m} - \rho(\mathcal{T}_{t})^{m}}{t} \mathbf{J}_{t}^{\omega} d\omega = (m-1) \int_{M} D(\rho^{m}) (\nabla \varphi) d\omega \\ &= m \int_{M} D(\rho^{m-1}) (\nabla \varphi) d\mu, \end{split}$$

and hence

$$\lim_{t \to 0} \frac{H_m(\mu|\nu) - H_m(\mu_t|\nu)}{t} = \int_M D\left(\frac{\rho^{m-1} - \sigma^{m-1}}{1 - m}\right) (\nabla\varphi) \, d\mu.$$

This yields

$$\nabla_W[-H_m(\cdot|\nu)](\mu) = \nabla\left(\frac{\rho^{m-1} - \sigma^{m-1}}{1 - m}\right)$$

provided that $\rho^{m-1} - \sigma^{m-1} \in H^1(M,\mu)$. Suppose $\rho^{m-1} - \sigma^{m-1} \notin H^1(M,\mu)$. Note that $\rho^{m-1} - \sigma^{m-1} \in L^2(M,\mu)$ since $\rho^m \in L^2(M,\omega)$ and M is compact, thus we find $F(\nabla(\rho^{m-1} - \sigma^{m-1})) \notin L^2(M,\mu)$. Therefore we obtain

$$\limsup_{\tilde{\mu}\to\mu}\frac{H_m(\mu|\nu)-H_m(\tilde{\mu}|\nu)}{W_2(\mu,\tilde{\mu})}=\infty$$

by approximating $\rho^{m-1} - \sigma^{m-1}$ with $\phi \in C^{\infty}(M)$ and choosing $\varphi = \phi/(1-m)$. Hence $H_m(\cdot|\nu)$ is not differentiable at μ .

Theorem 8.4 Let $(\mu_t)_{t\in[0,\infty)} \subset \mathcal{P}_{ac}(M,\omega)$ be a continuous curve that is locally Lipschitz on $(0,\infty)$, and assume that $\mu_t = \rho_t \omega$ satisfies $\rho_t^m \in H^1(M,\omega)$ as well as $\rho_t^{m-1} - \sigma^{m-1} \in H^1(M,\mu_t)$ for a.e. $t \in (0,\infty)$. Then we have

$$\dot{\mu}_t = \nabla_W [-H_m(\cdot|\nu)](\mu_t)$$

at a.e. $t \in (0, \infty)$ if and only if $(\rho_t)_{t \in [0,\infty)}$ is a weak solution to the reverse porous medium (or fast diffusion) equation of the form

$$\frac{\partial \rho}{\partial t} = -\operatorname{div}_{\omega} \left[\rho \nabla \left(\frac{\rho^{m-1} - \sigma^{m-1}}{1 - m} \right) \right].$$
(8.2)

Proof. If $\dot{\mu}_t = \nabla_W [-H_m(\cdot|\nu)](\mu_t)$ holds for a.e. t, then Proposition 8.3 yields

$$\dot{\mu}_t = \nabla \left(\frac{\rho_t^{m-1} - \sigma^{m-1}}{1 - m} \right) \qquad \text{a.e. } t.$$

Thus it follows from the continuity equation (8.1) that

$$\int_{0}^{\infty} \int_{M} \frac{\partial \phi_{t}}{\partial t} d\mu_{t} dt = -\int_{0}^{\infty} \int_{M} D\phi_{t} \left[\nabla \left(\frac{\rho_{t}^{m-1} - \sigma^{m-1}}{1 - m} \right) \right] d\mu_{t} dt$$

for all $\phi \in C_c^{\infty}((0,\infty) \times M)$. Therefore ρ_t weakly solves (8.2).

Conversely, if ρ_t is a weak solution to (8.2), then the same calculation implies that

$$\Phi_t = \nabla \left(\frac{\rho_t^{m-1} - \sigma^{m-1}}{1 - m} \right)$$

satisfies the continuity equation (8.1). Therefore Proposition 8.3 shows $\dot{\mu}_t = \Phi_t = \nabla_W [-H_m(\cdot|\nu)](\mu_t).$

We meant by the 'reverse' porous medium (or fast diffusion) equation the equation with respect to the *reverse* Finsler structure $\overleftarrow{F}(v) := F(-v)$. As the gradient vector for \overleftarrow{F} is written by $\overleftarrow{\nabla} u = -\nabla(-u)$, (8.2) is indeed rewritten as

$$\frac{\partial \rho}{\partial t} = \operatorname{div}_{\omega} \left[\rho \overleftarrow{\nabla} \left(\frac{\rho^{m-1} - \sigma^{m-1}}{m-1} \right) \right].$$

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