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The behavior of the interfaces in the fast reaction limits of some reaction-diffusion systems with unbalanced interactions

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1 Introduction

Let  $\Omega$  be a bounded domain in  $\mathbf{R}^N$  with smooth boundary  $\partial\Omega$ . Hilhorst-Hout-Peletier [2, 3] investigated a simple reaction-diffusion system with a huge positive parameter  $k$

$$\begin{cases} u_t = \Delta u - k u w & \text{in } \Omega, \\ w_t = -k u w & \text{in } \Omega \end{cases} \quad (1)$$

which describes a “fast reaction” between a diffusive reactant  $u$  and a non-diffusive one  $w$ . Assuming that the initial values of  $u$  and  $w$  are non-negative and fixing a positive number  $T$ , they derived the singular limit as  $k \rightarrow \infty$  of an initial-boundary value problem in  $\Omega \times (0, T)$  for a class of reaction-diffusion systems with a parameter  $k$  such as (1). Their results are summarized as follows: the solution  $(u_k, w_k)$  of their initial-boundary value problem possesses its singular limit  $(u_*, w_*)$  as  $k \rightarrow \infty$  such that  $u_* w_* \equiv 0$ ; therefore, when we use the notation

$$\begin{aligned} \Omega^u(t) &= \{x \in \Omega \mid u_*(x, t) > 0\}, & \Omega^w(t) &= \overline{\text{Int}\{x \in \Omega \mid w_*(x, t) > 0\}}, \\ \Gamma(t) &= \Omega \setminus (\Omega^u(t) \cup \Omega^w(t)), \end{aligned} \quad (2)$$

the region  $\Omega^u(t)$  and the region  $\Omega^w(t)$  are divided by an “interface”  $\Gamma(t)$ ; moreover  $u_*$  satisfies the one-phase Stefan problem

$$\begin{cases} u_{*,t} = \Delta u_* & \text{in } \Omega^u(t), \\ w_*|_{\Gamma(t)+0\mathbf{n}} V_{\mathbf{n}} = -\frac{\partial u_*}{\partial \mathbf{n}}|_{\Gamma(t)-0\mathbf{n}}, & u_*|_{\Gamma(t)} = 0 \end{cases} \quad (3)$$

in a weak sense. Here  $\mathbf{n}$  is the unit normal vector to  $\Gamma(t)$  oriented from  $\Omega^u(t)$  to  $\Omega^w(t)$ , and  $V_{\mathbf{n}}$  is the velocity of  $\Gamma(t)$  in the direction of  $\mathbf{n}$ .

In this article we consider generalized “fast reactions” between  $u$  and  $w$ :

$$\begin{cases} u_t = \Delta u - k u^{m_1} w^{m_3} & \text{in } \Omega, \\ w_t = -k u^{m_2} w^{m_4} & \text{in } \Omega, \end{cases} \quad (4)$$

where  $m_j \geq 1$  ( $j = 1, 2, 3, 4$ ). We are particularly interested in the situations where  $(m_1, m_3) \neq (m_2, m_4)$ , while Hilhorst-Hout-Peletier [2, 3] investigated situations where  $(m_1, m_3) = (m_2, m_4)$ . Even in the situations where  $(m_1, m_3) \neq (m_2, m_4)$  the corresponding

singular limit  $(u_*, w_*)$  of  $(u_k, w_k)$  as  $k \rightarrow \infty$ , if it exists, must formally satisfies  $u_* w_* \equiv 0$ . However, the rapid dynamics of (4) in such situations are very different from that in the situations where  $(m_1, m_3) = (m_2, m_4)$ . The rapid dynamics of (4) is essentially determined by the two-dimensional dynamical system

$$\begin{cases} u_t = -u^{m_1} w^{m_3}, \\ w_t = -u^{m_2} w^{m_4}. \end{cases} \quad (5)$$

Note that all the trajectories of (5) are straight and that the trajectories toward the axis  $u = 0$  intersect it slantwise if  $(m_1, m_3) = (m_2, m_4)$ . If  $(m_1, m_3) \neq (m_2, m_4)$ , then the trajectories toward the axis  $u = 0$  intersect it vertically in some situations; those trajectories touch the axis  $u = 0$  tangentially in other situations; in some situations among the other ones no trajectories possess intersections with the axis  $u = 0$ . When  $(m_1, m_3) \neq (m_2, m_4)$ , these various structures of the trajectories in (5) may cause any different behavior of the interface  $\Gamma(t)$  in the singular limit of (4). Related problems were investigated in [6] from the aspect of numerical simulation (see also [4]).

As the first attempt to solve the behavior of the interface  $\Gamma(t)$  in the situations where  $(m_1, m_3) \neq (m_2, m_4)$ , we will investigate typical four cases of such “unbalanced interactions” between  $u$  and  $w$ :  $(m_1, m_2, m_3, m_4) = (1, 1, 1, m)$ ,  $(1, 1, m, 1)$ ,  $(1, m, 1, 1)$  and  $(m, 1, 1, 1)$ , where  $m$  is a constant larger than 1. In each case we would like to reveal the interfacial dynamics in the fast reaction limit of (4) as  $k \rightarrow \infty$ . Hereafter we denote  $\Omega \times (0, T)$  by  $Q_T$  and consider (4) under the initial condition

$$u|_{t=0} = u_0, \quad w|_{t=0} = w_0 \quad \text{in } \Omega \quad (6)$$

and a boundary condition

$$\frac{\partial u}{\partial \nu} = 0 \quad \text{on } \partial\Omega, \quad (7)$$

where  $\nu$  denotes the unit outer normal vector of  $\partial\Omega$ .

## 2 Singular limits in Case $(m_1, m_2, m_3, m_4) = (1, 1, 1, m)$ or $(1, 1, m, 1)$ : moving interfaces

In these cases we can respectively reduce (4) into a reaction-diffusion system with a “balanced interaction”; namely into a system with  $(m_1, m_3) = (m_2, m_4)$  by some transformations of variables. When  $(m_1, m_2, m_3, m_4) = (1, 1, 1, m)$  with  $1 \leq m < 2$ , we put  $W_k = w_k^{2-m}$  for any solution  $(u_k, w_k)$  to (4). Then  $(u_k, W_k)$  becomes a solution to

$$\begin{cases} u_t = \Delta u - kuW^{1/(2-m)} & \text{in } \Omega, \\ W_t = -(2-m)kuW^{1/(2-m)} & \text{in } \Omega. \end{cases} \quad (8)$$

The singular limits of (8) with appropriate initial-boundary conditions were studied by Hilhorst, Hout and Peletier [2, 3]. They showed that  $u_*$  of the singular limit  $(u_*, W_*) =$

$\lim_{k \rightarrow \infty} (u_k, W_k)$  satisfies a one-phase Stefan problem with a finite normal velocity of the interface. In the same manner as the proofs in [2, 3], we can derive the singular limit of (8) with an initial condition

$$u|_{t=0} = u_0, \quad W|_{t=0} = w_0^{2-m} \quad \text{in } \Omega \quad (9)$$

and a boundary condition (7).

Throughout this section, we impose the following assumption on the initial datum  $(u_0, w_0)$ :

(H1)  $(u_0, w_0) \in C(\bar{\Omega}) \times L^\infty(\Omega)$ ,  $w_0$  is continuous in  $\text{supp } w_0$  and there exist positive constants  $M$  and  $m_w$  such that

$$\begin{aligned} u_0 w_0 &= 0, \quad 0 \leq u_0, w_0 \leq M \quad \text{in } \Omega, \\ m_w &\leq w_0 \quad \text{in } \text{supp } w_0. \end{aligned}$$

Under the assumption (H1), there exists a unique solution  $(u_k, W_k)$  of the initial-boundary value problem (8),(9) and (7) satisfying

$$\begin{aligned} u_k &\in C([0, T]; C(\bar{\Omega})) \cap C^1((0, T]; C(\bar{\Omega})) \cap C((0, T]; W^{2,p}(\Omega)) \quad (\forall p > 1), \\ w_k &\in C^1([0, T]; L^\infty(\Omega)) \end{aligned} \quad (10)$$

(see [1]). We obtain the following theorem in the same manner as the proofs in [2, 3].

**Theorem 2.1 (Hilhorst, Hout and Peletier [2, 3])** *Let  $(u_k, W_k)$  be the solution of (8) under the initial and boundary conditions (9) and (7), where  $1 \leq m < 2$ . Then there exist subsequences  $\{u_{k_n}\}$ ,  $\{W_{k_n}\}$  and functions  $(u_*, W_*) \in L^2(0, T; H^1(\Omega)) \times L^2(Q_T)$  such that*

$$\begin{aligned} u_{k_n} &\rightarrow u_* \quad \text{strongly in } L^2(Q_T) \text{ and weakly in } L^2(0, T; H^1(\Omega)), \\ W_{k_n} &\rightarrow W_* \quad \text{strongly in } L^2(Q_T), \end{aligned}$$

as  $k_n$  tends to infinity, where

$$u_* W_* = 0, \quad u_* \geq 0, \quad W_* \geq 0 \quad \text{a.e. in } Q_T.$$

Moreover,  $u_*$  and  $W_*$  satisfy

$$\iint_{Q_T} \{-(u_* - \lambda W_*) \zeta_t + \nabla u_* \cdot \nabla \zeta\} dx dt = \int_{\Omega} (u_0 - \lambda w_0^{2-m}) \zeta(\cdot, 0) dx \quad (11)$$

for all functions  $\zeta \in C^\infty(\bar{Q}_T)$  such that  $\zeta(x, T) = 0$ , where  $\lambda = 1/(2-m)$ .

Since  $u_* W_* \equiv 0$ , we can rewrite (11) as a classical one-phase Stefan problem with a finite propagation speed. Here we use  $\Omega^u(t)$ ,  $\Omega^w(t)$  and  $\Gamma(t)$  defined by (2) where  $w_* = W_*^{1/(2-m)}$  with  $1 \leq m < 2$ . Also we use the following notation:

$$Q_T^u = \bigcup_{0 < t < T} \Omega^u(t) \times \{t\}, \quad Q_T^w = \bigcup_{0 < t < T} \Omega^w(t) \times \{t\}, \quad \Gamma = \bigcup_{0 < t < T} \Gamma(t) \times \{t\}. \quad (12)$$

**Theorem 2.2** Set  $(m_1, m_2, m_3, m_4) = (1, 1, 1, m)$  where  $1 \leq m < 2$ . Let  $(u_k, w_k)$  be the solution of (4) under the initial-boundary conditions (6)-(7) and set  $W_k = w_k^{2-m}$ . Namely  $(u_k, W_k)$  is the solution of (8) satisfying (9) and (7). Let  $(u_*, W_*)$  be the limit given in Theorem 2.1 and set  $w_* = W_*^{1/(2-m)}$ . Suppose that  $\Gamma(t)$  is a smooth, closed and orientable hypersurface satisfying  $\Gamma(t) \cap \partial\Omega = \emptyset$  for all  $t \in [0, T]$ . Also assume that  $\Gamma(t)$  smoothly moves with a normal velocity  $V_n$  from  $\Omega^u(t)$  to  $\Omega^w(t)$ , and  $u_*$  is continuous in  $Q_T$  and smooth on  $\overline{Q_T^u}$ , and  $w_*$  is smooth on  $\overline{Q_T^w}$ . Then the following relations hold.

$$w_*(t) = w_0, \quad \text{in } Q_T^w;$$

$$\begin{cases} u_{*,t} = \Delta u_* & \text{in } Q_T^u, \\ u_* = 0, \quad \frac{w_0^{2-m}}{2-m} V_n = -\frac{\partial u_*}{\partial n} & \text{on } \Gamma, \\ \frac{\partial u_*}{\partial \nu} = 0 & \text{on } \partial\Omega \times (0, T), \\ u_* = u_0 & \text{on } \Omega^u(0) \times \{0\}. \end{cases}$$

When  $(m_1, m_2, m_3, m_4) = (1, 1, m, 1)$  with  $m \geq 1$ , we put  $W_k = w_k^m$  for any solution  $(u_k, w_k)$  to (4). Then  $(u_k, W_k)$  becomes a solution to

$$\begin{cases} u_t = \Delta u - kuW & \text{in } \Omega, \\ W_t = -mkuW & \text{in } \Omega. \end{cases} \quad (13)$$

Taking the fast reaction limit of (13) under the boundary condition (7) and an initial condition

$$u|_{t=0} = u_0, \quad W|_{t=0} = w_0^m \quad \text{in } \Omega, \quad (14)$$

we can similarly derive the same conclusions as those of Theorem 2.1 where  $\lambda = 1/m$ . Thus we obtain the following theorem. Here we use the notation  $\Omega^u(t)$ ,  $\Omega^w(t)$ ,  $\Gamma(t)$ ,  $Q_T^u$ ,  $Q_T^w$  and  $\Gamma$  defined by (2) and (12) where  $w_* = W_*^{1/m}$  with  $m \geq 1$ .

**Theorem 2.3** Set  $(m_1, m_2, m_3, m_4) = (1, 1, m, 1)$  where  $m \geq 1$ . Let  $(u_k, w_k)$  be the solution of (4) under the initial-boundary conditions (6)-(7) and set  $W_k = w_k^m$ . Namely  $(u_k, W_k)$  is the solution of (13) satisfying (14) and (7). Set  $w_* = W_*^{1/m}$  for the limit  $(u_*, W_*)$  given in Theorem 2.1 where (8), (9) and (11) are replaced by (13), (14) and

$$\iint_{Q_T} \{-(u_* - \lambda W_*) \zeta_t + \nabla u_* \cdot \nabla \zeta\} dx dt = \int_{\Omega} (u_0 - \lambda w_0^m) \zeta(\cdot, 0) dx \quad (15)$$

with  $\lambda = 1/m$ , respectively. Suppose that  $\Gamma(t)$  is a smooth, closed and orientable hypersurface satisfying  $\Gamma(t) \cap \partial\Omega = \emptyset$  for all  $t \in [0, T]$ . Also assume that  $\Gamma(t)$  smoothly moves with a normal velocity  $V_n$  from  $\Omega^u(t)$  to  $\Omega^w(t)$ , and  $u_*$  is continuous in  $Q_T$  and smooth

on  $\overline{Q_T^u}$ , and  $w_*$  is smooth on  $\overline{Q_T^w}$ . Then the following relations hold.

$$w_*(t) = w_0, \quad \text{in } Q_T^w;$$

$$\begin{cases} u_{*,t} = \Delta u_* & \text{in } Q_T^u, \\ u_* = 0, \quad \frac{w_0^m}{m} V_n = -\frac{\partial u_*}{\partial n} & \text{on } \Gamma, \\ \frac{\partial u_*}{\partial \nu} = 0 & \text{on } \partial\Omega \times (0, T), \\ u_* = u_0 & \text{on } \Omega^u(0) \times \{0\}. \end{cases}$$

### 3 Singular limits in Case $(m_1, m_2, m_3, m_4) = (1, m, 1, 1)$ : immovable interfaces

A free boundary appears in the fast reaction limit also in this case; however, this free boundary does not move.

Throughout this section, we impose (H1) on the initial datum  $(u_0, w_0)$  again, and assume  $m > 1$ . Under the assumption (H1), there exists a unique solution  $(u_k, w_k)$  of the initial-boundary value problem (4), (6) and (7) satisfying (10).

We give a result on the convergence of  $(u_k, w_k)$ .

**Theorem 3.1** *Set  $(m_1, m_2, m_3, m_4) = (1, m, 1, 1)$  where  $m > 1$ . Let  $(u_k, w_k)$  be the solution of (4) under the initial and boundary conditions (6) and (7). Then there exist subsequences  $\{u_{k_n}\}$  and  $\{w_{k_n}\}$  of  $\{u_k\}$  and  $\{w_k\}$ , respectively, and functions  $u_*$ ,  $w_*$  and a distribution  $U_*$  such that*

$$u_*, u_*^{\frac{m}{2}} \in L^\infty(Q_T) \cap L^2(0, T; H^1(\Omega)), \quad w_* \in L^\infty(Q_T), \quad U_* \in H^{-1}(Q_T), \quad (16)$$

$$0 \leq u_*, w_* \leq M, \quad u_* w_* = 0 \quad \text{a.e. in } Q_T, \quad U_* \geq 0 \quad \text{in } H^{-1}(Q_T), \quad (17)$$

$$u_{k_n} \rightarrow u_* \quad \text{strongly in } L^p(Q_T) (\forall p \geq 1), \quad \text{a.e. in } Q, \quad (18)$$

$$\text{weakly in } L^2(0, T; H^1(\Omega)) \text{ and weakly } * \text{ in } L^\infty(Q_T),$$

$$w_{k_n} \rightarrow w_* \quad \text{weakly in } L^p(Q_T) (\forall p \geq 1) \text{ and weakly } * \text{ in } L^\infty(Q_T), \quad (19)$$

$$\left| \nabla u_{k_n}^{\frac{m}{2}} \right|^2 \rightarrow U_* \quad \text{weakly in } H^{-1}(Q_T) \quad (20)$$

as  $k_n$  tends to infinity. Moreover  $u_*$ ,  $w_*$  and  $U_*$  satisfy

$$\begin{aligned} \iint_{Q_T} \left\{ -\left( \frac{1}{m} u_*^m - w_* \right) \zeta_t + \frac{2}{m} u_*^{\frac{m}{2}} \nabla u_*^{\frac{m}{2}} \cdot \nabla \zeta \right\} dx dt \\ + \frac{4(m-1)}{m^2} {}_{H^{-1}(Q_T)} \langle U_*, \zeta \rangle_{H_0^1(Q_T)} = 0 \end{aligned} \quad (21)$$

for all  $\zeta \in H_0^1(Q_T)$ .

We can prove  $U_* = \left| \nabla u_*^{\frac{m}{2}} \right|^2 \in L^1(Q_T)$  under additional conditions. Here we use the notation  $\Omega^u(t)$ ,  $\Omega^w(t)$ ,  $\Gamma(t)$ ,  $Q_T^u$ ,  $Q_T^w$  and  $\Gamma$  defined by (2) and (12). Then we can give an explicit equation of motion for the free boundary.

**Theorem 3.2** *Let  $u_*, w_*, U_*$  be the functions satisfying (16)-(20). Suppose that  $\Gamma(t)$  is a smooth, closed and orientable hypersurface satisfying  $\Gamma(t) \cap \partial\Omega = \emptyset$  for all  $t \in [0, T]$ . Also assume that  $\Gamma(t)$  smoothly moves with a normal velocity  $V_n$  from  $\Omega^u(t)$  to  $\Omega^w(t)$ , and  $u_*$  is continuous in  $Q_T$  and smooth on  $\overline{Q_T^u}$ , and  $w_*$  is smooth on  $\overline{Q_T^w}$ . Then the following relations hold.*

$$V_n = 0 \text{ on } \Gamma, \quad \text{that is, } \Omega^u(t) \equiv \Omega^u(0), \quad \Omega^w(t) \equiv \Omega^w(0), \quad \Gamma(t) \equiv \Gamma(0);$$

$$w_*(t) = w_0, \quad U_* = |\nabla u^{\frac{m}{2}}|^2 \quad \text{in } Q_T;$$

$$\begin{cases} u_{*,t} = \Delta u_* & \text{in } Q_T^u = \Omega^u(0) \times (0, T), \\ u_* = 0 & \text{on } \Gamma = \Gamma(0) \times (0, T), \\ \frac{\partial u_*}{\partial \nu} = 0 & \text{on } \partial\Omega \times (0, T), \\ u_* = u_0 & \text{on } \Omega^u(0) \times \{0\}. \end{cases}$$

See [5] for the proofs of Theorems 3.1 and 3.2.

## 4 Singular limits in Case $(m_1, m_2, m_3, m_4) = (m, 1, 1, 1)$ : vanishing interfaces

In this case the non-diffusive reactant  $w$  consumes much faster than diffusive one  $u$  in the limit as  $k \rightarrow \infty$ . This fact makes the propagation speed of  $\Gamma(t)$  too rapid. At least if  $m > 2$ , then  $\Omega^u(t)$  spread too rapidly for us to follow its boundary  $\Gamma(t)$ : actually we cannot observe any free boundary.

Throughout this section, we impose the following assumptions on the initial data:

(H2)  $(u_0, w_0) \in C^2(\overline{\Omega}) \times C^\alpha(\overline{\Omega})$  satisfy

$$u_0(x)w_0(x) = 0, \quad 0 \leq u_0(x) \leq M_u, \quad 0 \leq w_0(x) \leq M_w$$

for any  $x \in \Omega$ , where  $\alpha \in (0, 1)$  represents a Hölder exponent and

$$M_u := \max_{x \in \overline{\Omega}} |u_0|, \quad M_w := \max_{x \in \overline{\Omega}} |w_0|.$$

(H3)  $u_0$  holds the homogeneous Neumann boundary condition:

$$\frac{\partial u_0}{\partial \nu} = 0 \quad \text{on } \partial\Omega.$$

We can derive the following result on the singular limit of (4) (see [5]).

**Theorem 4.1** *Set  $(m_1, m_2, m_3, m_4) = (m, 1, 1, 1)$  where  $m > 1$ . Let  $(u_k, w_k)$  be the solution of (4) under the initial and boundary conditions (6) and (7). Then*

$$\begin{aligned} u_k &\rightarrow u_* && \text{in } C^0(\overline{Q_T}) && \text{as } k \rightarrow \infty, \\ w_k &\rightarrow 0 && \text{in } C^0(\overline{\Omega} \times [\varepsilon, T]) && \text{as } k \rightarrow \infty \text{ for any } \varepsilon \in (0, T), \end{aligned}$$

where  $u_*(x, t)$  belongs to  $C^{2,1}(\overline{Q_T})$  and satisfies the heat equation in the whole domain as follows :

$$\begin{cases} u_{*,t} = \Delta u_* & \text{in } Q_T, \\ \frac{\partial u_*}{\partial \nu} = 0 & \text{on } \partial\Omega \times (0, T), \\ u_* = u_0 & \text{on } \Omega \times \{0\}. \end{cases}$$

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