1	Title: Japanese macaques depend not only on neighbours but also on more distant members for
2	group cohesion
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#### 25 Abstract

A well-known behavioural model for group aggregation is that an individual depends on a few 26 neighbouring individuals to adjust its movement, such as departure (repulsion) from and 27 approach (attraction) to neighbours. However, an individual may rely not only on a few closest 28 29 neighbours, but also on more distant individuals, in a group of stable membership. We measured temporal changes in the local density of individuals around a focal individual and 30 changes in distance to other focal individuals in a group of wild Japanese macaques to 31 determine whether the macaques depended only on a few neighbours or also on more distant 32 individuals for adjustments in cohesiveness. We used simultaneous focal animal sampling, with 33 two observers recording the individuals' locations using a global positioning system (GPS), 34 over three seasons. Numbers of individuals within 20 m from an animal tended to increase after 35 36 10 min when there were a small number of individuals around the animal. However, the number tended to decrease when there was a larger number of individuals. It remained similar when 37 there were an intermediate number of individuals. The two focal animals tended to separate 38 39 after 10 min when the interindividual distance was short. However, they tended to move closer when far apart. They remained a similar distance apart when they were at an intermediate 40 distance. Contact calls, which are suggested to function as locating group members and keeping 41 cohesiveness, were emitted more frequently when the distance between the two focal animals 42 was very large in two seasons. However, the rate of contact calls was not influenced by the 43 number of individuals within 20 m from an animal. These results suggest that individual 44 45 Japanese macaques do not only rely on a few closest neighbours, but also on more distant group members. Japanese macaques may know the general whereabouts of the whole group, and when 46 they stay at the periphery of the group, they may emit contact calls frequently and move towards 47 the central zone so as not to become separated from the group. 48

### 50 Introduction

51 Many social animals exhibit cohesive aggregation, such as insect swarming, fish 52 schooling, bird flocking, and mammalian herding (Cavagna et al. 2010; Schellinck & White 53 2011). While maintaining a close distance to others is favourable for predation avoidance 54 (Hamilton 1971), it is unfavourable for foraging because of competition among group members 55 (e.g., Wrangham, 1980). The cost of grouping may be mediated by adjusting an individual's 56 proximity to other group members (Aureli et al. 2008), raising the question of how animals 57 adjust proximity and cohere as a group.

Theoretical studies have proposed models of individual movement strategies explaining collective group motion in which an animal monitors the locations and movements of a few closest neighbours and adjusts its movements to those of those neighbours. For example, when an individual is too close to its neighbour, it travels in the opposite direction (repulsion) and when an individual is far from its neighbour, it moves towards the neighbour (attraction) (Schellinck & White 2011).

64 Such models provide simple mechanisms of collective movement, which require an animal to know the locations of other animals within a close distance, but not those of all 65 members of the group. However, some other behavioural processes may be at work during 66 collective movement in social animals that form small groups with stable memberships and 67 have high cognitive ability, such as primates (Aureli et al. 2008; Shimooka 2003) and dolphins 68 (Karczmarski et al. 2005). One possible behavioural process is that an individual relies not only 69 70 on a few close neighbours, but also on individuals more distant in location and/or movement of the whole group. To examine this, we observed adjustments of proximity among Japanese 71 macaques (Macaca fuscata) in the wild. 72

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Japanese macaques form female philopatric groups. Females reside in the natal group,

whereas males emigrate out of the group at adolescence (Yamagiwa & Hill 1998). There is a
linear dominance hierarchy, based on kin relationships, between resident females (Hill &
Okayasu 1995), and the groups are relatively cohesive with stable membership. The group's
habitat and activities vary seasonally (Tsuji et al. 2006). It has been suggested that the
frequently emitted contact call, or "coo call" (Green 1975), is an important means of
maintaining group cohesiveness (Koda & Sugiura 2010; Suzuki & Sugiura 2011).

Japanese macaques are known to change their behaviour, such as monitoring other individuals, depending on the proximity to nearby members (Suzuki & Sugiura 2011). Thus, it is likely that they rely on the neighbours for the adjustment of proximity, however, it is possible that Japanese macaques also may rely on more distant animals. Although the data on proximity to distant animals is quite limited, they may locate approximate position of the whole group (Wada & Matsuzawa 1986).

As the first aim of this study, we examined a basic assumption that Japanese macaques adjust proximity to group members. If they do, proximity to group members is expected to increase when they are far apart and *vice versa*. In particular, we predicted that 1) the number of individuals within 20 m of an animal would increase and/or 2) distance to the other focal female would decrease (both indicating increased proximity to group members), if an animal is far apart from group members and *vice versa*.

Our second aim is to examine whether Japanese macaques rely on the neighbour individuals and/or more distant individuals for their adjustment of proximity. If they adjust proximity relying only on neighbours, change (i.e., increase and decrease) in proximity to group members is expected to be accounted for by initial state of proximity to the neighbours. In this case, we predicted that 1) variance in change in number of individuals within 20 m and 2) variance in change in distance to the other focal individual would largely be accounted for by the initial number of individuals within 20 m. Alternatively, they may rely not only on
neighbours but also on more distant individuals. In this case, we predicted that variances in
these two response variables would be accounted for both by the initial number of individuals
within 20 m and also by the initial distance to the other focal animal.

We also examined the rate of contact calls with the same analytical design to explore the possibility that macaques change behaviour related to group aggregation depending not only on close neighbours but also on more distant animals.

We propose that macaques rely on both close neighbours and more distant animals and that they know the location of the whole group and adjust their movements based on such information. In addition, we discuss possible mechanisms and functions of adjustment of proximity.

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#### 110 Methods

111 Subjects

112 We studied the A group of wild Japanese macaques on Kinkazan Island, northern Japan (38.30°N, 141.56°E; elevation 0–445 m ASL). Members of the A group have been identified 113 individually since 1983 and are used to human observers (Sato 1988). No natural predator of 114 these monkeys exists on the island and hunting is forbidden by law and religion. During the 115 study period, the subject group included 31–39 individuals: 17 adult females ( $\geq$  5 years old), 116 5–13 adult males ( $\geq$  5 years old), 2–5 juvenile females (1–4 years old), 2–4 juvenile males (1–4 117 years old), and 5–8 infants (< 1 year old). The macaques' range covered approximately  $3 \text{ km}^2$ 118 during the study period. Details of the subjects and their habitat have been described elsewhere 119 (Tsuji et al. 2006; Tsuji & Takatsuki 2004; Tsuji & Takatsuki 2012). 120 We collected data during three seasons: autumn (16 October to 8 November, 2003), 121

winter (10-22 February, 2004), and summer (6-23 July, 2004). Observation was conducted in 122 6:30–16:40 in autumn, 7:15–16:55 in winter, and 6:15–18:30 in summer. Data were collected 123 124 almost equally during these hours. We chose 10, 9, and 7 females of varying dominance ranks as the subjects in the autumn, winter, and summer, respectively. Seven of the animals were 125 126 observed during all three study periods. The mean observation times per individual were 33.1±5.0, 31.9±3.5, and 29.1±1.3 h in the autumn, winter, and summer, respectively. We 127 observed 30 of 45 possible pairs in autumn, 29 of 36 possible pairs in winter, and all 21 possible 128 pairs in summer. The mean observation times per pair were  $7.3\pm0.1$  (mean  $\pm$  SE),  $9.3\pm0.1$ , and 129  $4.4\pm0.1$  h in the autumn, winter, and summer, respectively. 130

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### 132 Data Collection

Two observers followed each anoestrous focal adult female using the focal animal 133 sampling method. We excluded oestrous females from the study because they tended to stay on 134 135 the periphery of the group to mate with low-ranking or non-troop males (Hayakawa 2007). Each observation session lasted 4 h, during which we recorded the number of coo calls 136 (Green 1975; Sugiura 2007b) emitted by each focal animal per minute. We recorded the number 137 of individuals within 20 m of each focal animal in 5-min intervals by instantaneous sampling. 138 We excluded infants < 1 year of age because they were usually dependent on other individuals. 139 We excluded data when visibility was < 20 m. 140 We measured location, time, and the positional dilution of precision (PDOP, a 141 measurement of position accuracy) using a GPS receiver (IPS-5100; Sony, Tokyo, Japan or 142 GPS Pathfinder Pocket; Trimble, Sunnyvale, CA, USA). We recorded GPS data every 1 s on a 143 handheld computer (200LX or iPAQ h2210; Hewlett-Packard, Tokyo, Japan). We typically 144

remained within a horizontal distance of 10 m from the focal animal and considered the position

of the observer to be that of the focal animal. We excluded GPS data recorded when the focal animal was out of view or was > 15 m away for > 1 min.

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149 Analysis

We used two measures of proximity, covering different ranges of distance. One is proximity to group members at close range (0–20 m). We measured the number of individuals within 20 m from the focal adult female (i.e., the density of individuals around an animal) and its change after 10 min. Another is proximity to a group member over a longer distance ( $\geq$  40 m). We measured the distance to the other focal individual observed simultaneously with GPS (i.e., the distance between two random adult females in a group) and its change after 10 min.

We converted location data into rectangular coordinates using universal traverse mercator (UTM) projection. To remove large location errors, we used only measurements with a PDOP smaller (better) than 6.5 with a three-dimensional fix (D'Eon & Delparte 2005). We chose the location data with the smallest PDOP within a window of -15 to +15 s from the sampling time. On occasion, three observers simultaneously followed a focal animal. In these cases, we used the distance between each pair combination (e.g., A-B, A-C, B-C) as independent data.

We examined three response variables as behavioural correlates of adjustment of proximity: 1) change in number of individuals, 2) change in distance between two focal animals, and 3) contact call (coo call) rate. We tested whether the variance in each of these three response variables was influenced by two explanatory variables: 1) initial number of individuals within 20 m from a focal animal and 2) initial distance to the other focal animal.

167 Changes in numbers of individuals and in distance to the other focal animal were sampled
 168 in 15-min intervals (at a minimum). Call rate was sampled in 5-min intervals (at a minimum).

The sampling interval was extended by 5 min (i.e., 20, 25, 30 min) if loss of the focal animal, 169 loss of the number of individuals around the focal animal, or unreliable GPS positions occurred. 170 171 We performed all analyses separately in each of the three seasons, because the cohesiveness of the group varied largely with season (Sugiura et al. 2011). Our main interest 172 was to examine whether the adjustment of proximity occurs in each season, as opposed to being 173 due to merely seasonal variation in proximities among group members. Thus, we conducted 174 analysis in each season to simplify the design of statistical analyses. Interindividual distances 175 were extremely large (0–1225 m) and subgrouping occurred during the summer (Sugiura et al. 176 2011). We divided the distances into three categories of non-subgrouping, subgrouping, and 177 unknown, following a previous study (Sugiura et al. 2011). We used data categorised as 178 non-subgrouping and subgrouping separately in the present analysis. Our main objective was to 179 examine the adjustment of proximity in normal grouping (i.e., non-subgrouping). However, 180 behavioural differences between grouping and subgrouping were also of interest, because the 181 182 differences may reveal characteristics of grouping. Thus, we also analysed the behaviour during subgrouping. 183

We used data when the initial distance to the other focal individual was  $\geq 40$  m. Two 184 explanatory variables, initial number of individuals within 20 m of the focal animal and initial 185 distance, correlated weakly with each other, when we included all the data. However, this 186 correlation disappeared, excluding the data where the distance to the other focal animal was 187 < 40 m. Our main objective was to examine which of the explanatory variables accounted for 188 response variables; thus, we excluded data where the effects of the two factors were difficult to 189 separate. This procedure tends to exclude instances where the group spread was small. 190 191 The change in number of individuals was calculated as (number of individuals after 10 min) – (initial number of individual). Thus, a positive value indicates that the local density of 192

individuals around the focal animal increased (increase in proximity), whereas a negative value indicates a decrease in the local density of individuals (decrease in proximity). The change in distance was calculated as (initial distance) – (distance after 10 min). Thus, a positive value indicates approach (increase in proximity), whereas a negative value indicates greater separation (decrease in proximity). Call rate was the number of coo calls made by the focal animal from 0 to +1 min, where we measured the number of individuals around the focal animal at 0 min.

To analyse changes in numbers of individuals and in distance, two explanatory variables (initial numbers near the focal animal and distance to the other focal animal) were treated as continuous variables. To analyse contact call rate, we treated one explanatory variable (distance to the other focal animal) as a discrete variable to describe the general trend in coo call rate at different interindividual distances, because our exploratory analyses revealed that the rate of coo calls did not change linearly with the initial distance, but increased especially at long distances.

207 Statistical analyses were conducted using generalised linear mixed models and the SAS software (ver. 9.2; SAS Institute, Cary, NC). We used a normal distribution to analyse changes 208 in numbers of individuals and changes in distances, and a generalised Poisson distribution to 209 analyse coo call rates. Analyses of changes in numbers of individuals and rates of coo calls were 210 performed on an individual basis. For the analysis, we treated the focal individuals as a random 211 factor. Analysis of changes in distance was performed on a pair basis, because this response 212 213 variable was derived from the positions of the two focal animals. For this, we used two explanatory variables; 1) initial number of individuals around the focal animals as an average of 214 the numbers of individuals around the two focal animals, and 2) initial distance between the two 215 focal animals. We treated the focal pair was a random factor. Post hoc pairwise comparisons 216

217 were conducted for the analyses of coo call rate, using the Bonferroni correction.

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## 219 **Results**

## 220 Changes in numbers of individuals at a close distance

221 We examined the changes in the number of individuals within 20 m from the focal animal after 10 min (Fig. 1). A positive value indicated that the number of individuals increased 222 (increase in proximity), a negative value indicated that it decreased (decrease in proximity), and 223 a value of zero indicated that it remained the same. Changes in number of individuals were 224 influenced negatively by the initial number of individuals in each of the three seasons during 225 non-subgrouping; that is, when the number of individuals around the focal animal was small, 226 the number of individuals tended to increase after 10 min (Fig. 1, autumn,  $F_{1,9} = 21.9$ , p = 0.001; 227 winter,  $F_{1,8} = 23.0$ , p = 0.001; summer  $F_{1,6} = 43.1$ , p = 0.0006). The same tendency was 228 observed during subgrouping in the summer, where each of the two focal individuals was in a 229 230 separate subgroup ( $F_{1,6} = 56.7, p = 0.0003$ ). 231 By contrast, the changes in the numbers of individuals were not affected by the initial distance to the other focal animal in any season, including in subgrouping in the summer 232 (autumn,  $F_{1,9} = 0.08$ , p = 0.79; winter,  $F_{1,8} = 0.76$ , p = 0.41; summer, non-subgrouping,  $F_{1,6} = 0.76$ 233 4.97, p = 0.06; summer, subgrouping,  $F_{1,6} = 1.48$ , p = 0.27). 234

235

236 *Changes in Distance* 

We examined changes in distance after 10 min between two individuals (Fig. 2). A positive value indicated that the distance decreased (increase in proximity to the other focal individual), a negative value indicated that it increased (decrease in proximity), and a value of zero indicated that it remained the same. Changes in distance were influenced positively by the initial distance during non-subgrouping. When the distance to the other focal animal was larger, they tended to come closer after 10 min (Fig. 2A–C, autumn,  $F_{1,24} = 28.2$ , p < 0.0001; winter,  $F_{1,28} = 52.6$ , p < 0.0001; summer, non-subgrouping,  $F_{1,18} = 10.8$ , p = 0.004). This tendency was not observed during subgrouping in the summer (Fig. 2D,  $F_{1,13} = 2.0$ , p = 0.18).

In contrast, variance in changes in distance were not accounted for by the initial number of individuals around the focal animal in any season, including in subgrouping in the summer (autumn,  $F_{1,21} = 1.99$ , p = 0.17; winter,  $F_{1,28} = 1.18$ , p = 0.29; summer, non-subgrouping,  $F_{1,18} =$ 1.09, p = 0.31; summer, subgrouping,  $F_{1,11} = 3.32$ , p = 0.10).

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## 250 Rate of Contact Calls

We examined whether the contact call rates of focal animals varied based on the distance 251 from another focal animal and on the number of individuals around the focal animal. In the 252 autumn, the effect of distance apart was significant but that of the number of individuals was not 253 (Fig. 3A, distance,  $F_{4,41} = 2.66$ , p = 0.046; number of individual,  $F_{1,9} = 0.18$ , p = 0.68). Pairwise 254 255 comparisons revealed no significant difference between any pair. However, call rates tended to be higher with an interindividual distance of 90–230 m, versus those of 40–50 m (p = 0.06). 256 Also in the winter, the effect of distance apart was significant but that of the number of 257 individuals was not (Fig. 3B, distance,  $F_{7,63} = 3.60$ , p = 0.003; number of individual,  $F_{1,8} =$ 258

259 0.0001, p = 0.99). Pairwise comparisons revealed that call rates were significantly higher for 260 interindividual distances of 120–270 m, compared to distances of 40–50 m and 60–70 m (p <261 0.05).

In the summer, none of the effects was significant during non-subgrouping (distance,  $F_{11,72} = 0.74, p = 0.70$ ; number of individual,  $F_{1, 6} = 1.53, p = 0.26$ ) or subgrouping (distance,  $F_{8,45} = 0.24, p = 0.98$ ; number of individual,  $F_{1, 6} = 0.61, p = 0.43$ ). 265

## 266 Discussion

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# 268 Adjustment of Proximity to Close Neighbours

269 In our observations, the number of individuals within 20 m of the focal individual tended to increase after a short period of time when there was a small number of individuals around her 270 and tended to decrease when there was a larger number of individuals in each of three seasons, 271 including when the two focal animals were in different subgroups. In contrast, the change in 272 number of individuals was not accounted for by the distance to the other focal individual. 273 These results suggest that Japanese macaques adjust their proximity to group members 274 relying on the local density of group members within a close distance. Japanese macaques 275 increased the number of neighbours, i.e., increased proximity, when they were far apart and vice 276 versa. This adjustment appears to be a negative feedback of local density that may stabilize it. In 277 this sense, this adjustment may be similar to attraction-repulsion movement toward the 278 neighbours, and may be a common mechanism of aggregation with those of other animals, such 279

as fish school (Aoki 1982) and bird flocks (Lukeman et al. 2010).

The mean number of individuals within 20 m of a focal animal (when the distance to the other focal animal was  $\geq 40$  m) was 3.1 in autumn, 2.0 in winter, 1.4 in non-subgrouping in summer, and 1.3 in subgrouping in summer. Thus, the local density of individuals around focal animals was high in autumn, middle in winter and low in summer. Although the density of animals differed among seasons, adjustment of proximity to neighbours was constantly observed in each of the three seasons.

The mean visibility in the subject group's habitat is ca. 30–50 m (Koda et al. 2008); thus, Japanse macaques are likely to keep sight of group members within a close distance, ca. 20 m. It has been suggested that they monitor group members visually and adjust their movements to
keep cohesiveness with other group members (Koda & Sugiura 2010; Suzuki & Sugiura 2011).
Such adjustment continued even when the group was split into subgroups in the summer. This is
consistent with the view that the group is split into two (or a few) subunits that move
collectively with group members.

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# 295 Adjustment of Proximity to Distant Individuals

The distance to the other focal animal also tended to decrease after a short period of time when the distance was longer and tended to increase when the distance was shorter in each of three seasons, except in subgrouping in the summer. This change of distance, however, was not accounted for by the numbers of individuals within 20 m from the focal animals.

These results suggest that Japanese macaques adjust their proximity to group members at relatively far distances. Focal pairs of macaques tended to separate after a short period of time when they were close together and tended to move closer when they were farther apart. This indicates that individual Japanese macaques move to cohere with group members at relatively far distances. This adjustment may also be a negative feedback of distance to far individuals, which may stabilize the proximity to distant group members.

The mean distance between the two focal individuals (when the distance was  $\ge 40$  m) was 58.2 m in autumn, 72.0 m in winter, 85.1 m in non-subgrouping in summer, and 365.8 m in subgrouping in summer. Thus, the distance between two individuals was short in autumn, middle in winter and long in summer. Although the distance differed among seasons, adjustment of proximity to distant individuals was constantly observed in each of the three seasons, except in subgrouping in summer.

312 Such movement was not accounted by the local density of group members within a close

distance. Because the distance to the other focal animal and the number of individuals within 20 313 m was not correlated, they might not be able to know the distance to the other focal animal from 314 315 the local density of animals around them. These changes were observed even when the distance to the other focal animal was more than 40 m. Considering visibility in the habitat, it seems 316 unlikely that a focal individual directly monitored the position and movement of the other focal 317 individual. This tendency, however, disappeared when the two animals were in separate 318 subgroups. On such occasions, Japanese macaques lost the location of the other subgroup and 319 their movements became independent of each other. 320

However, it is possible that Japanese macaques depend only on nearby individuals but 321 not distant members. An alternative explanation is that Japanese macaques monitor more subtle 322 information from the nearby individuals, which enable them to adjust proximity to distant 323 individuals. A possible cue is temporal change of proximity of nearby group members, which 324 may reflect group cohesiveness. However, change in local density of individuals in 10 min 325 326 (average change in number of individuals within 20 m from the two focal animals from 0 to +10min) did not explain the variance in change in distance between two focal individuals (Sugiura 327 et. al., unpublished data). There are several possible cues from nearby individuals, e.g., timing 328 and amount of change in proximity, activity of nearby individuals and social relationships to 329 nearby individuals. In the present study, we could not record these detailed information of 330 neighbour individuals in a natural setting. Continuous observation of nearby individuals, such 331 as video recording would be applicable to further examinations. 332

In addition, we analyzed the change in distance on a pair basis, and used the numbers of nearby group members of the two focal individuals (average number) as an explanatory variable. However, an individual can know its own nearby members but not that of the other distant focal animal. Thus, the average number of nearby group members is a relatively rough approximation and it might have reduced the effect of nearby group members on the change of
distance. This limitation can be improved if we can analyze this effect on an individual basis,
e.g., discriminating one of the two animals that is more responsible for the change of distance.

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## 341 Contact Calls at Different Proximity

Our results show that the coo call rate increased, especially for the longest distance class, in the autumn and winter. The coo call rate, however, was not influenced by the number of individuals within 20 m in any season. When the distance between two animals fell in the largest distance class, one or both focal animal(s) was likely to stay at the periphery of the spread group. Thus, the macaques seemed to emit contact calls frequently in the peripheral zone to contact group members. Therefore, Japanese macaques are apparently aware of which group zone they are in.

Such use of the contact call seems quite reasonable, considering the function of coo calls. 349 350 The coo calls of Japanese macaques have been suggested to maintain group cohesiveness (Itani 1963; Mitani 1986) and are often emitted by individuals that may be likely to become separated 351 from the group (Koda & Sugiura 2010; Suzuki & Sugiura 2011). Similar usage of contact calls 352 are found in other species of primates. Chacma baboons (Papio cynocephalus) emit contact 353 calls more frequently when they were separated from the group (Rendall et al. 2000). 354 White-faced capuchin monkeys (Cebus capucinus) emit contact calls more often at the 355 peripheral zone of the group and the calls are likely to relate to group movement (Boinski & 356 Campbell 1995). 357

Coo calls are, however, often elicited by the other's coo calls as vocal response (Sugiura 2007a). Thus, increase of coo call rate might have caused by the increase of coo calls of the other individuals. Because we did not record the vocalization from the other individuals, in this study, we can not examine the effect of other's call. Further observation should be needed,
recording the rate of calls from other individuals and discriminating between spontaneous call
(i.e., without preceding calls of the other individual) and response call (i.e., with preceding calls
of the other individual).

We failed to detect difference in call rate in summer. The mean coo call rate per minute (when the distance to the other focal animal was  $\geq 40$  m) was 0.36 in autumn, 0.22 in winter, 0.54 in non-subgrouping in summer, and 0.44 in subgrouping in summer. In summer, subject females produced coo calls frequently, probably because the group dispersed and they needed vocal contact most in this season. In this season, they may emit coo calls so frequently at any distance that they do not emit additional coo calls when they stayed far from the other focal animals.

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### 373 Possible Mechanisms of Adjustment of Proximity to Distant Individuals

Japanese macaques may somehow locate the general whereabouts of the entire group. Assuming that macaques are aware of their proximity to their group's central zone, individual movement from the peripheral zone towards the central zone may explain the more rapid approach from greater interindividual distances apart.

One possible mechanism for knowing the general location of the entire group is monitoring the movements of nearby group members. It appears difficult for an individual to see all of the group members directly, because it spreads over a wider area than one can see in the forest. In such conditions, movements of nearby group members may help to know the general location of the entire group. For example, if an individual remembers that most group members passed ahead of it, it ascertains that it is in a peripheral position in the group. Such a mechanism is plausible, considering their cognitive abilities (Roberts 2002) and that Japanese

macaques usually travel straight to food sources (Maruhashi et al. 1998). Another possible 385 mechanism is vocal communication. Audible range of contact calls is usually wider than visible 386 387 range in forest, and contact calls from group members appears to help an individuals to locate the whole group. If they locate the general whereabouts of the entire group, they may change 388 behaviour in relation to their own spatial position, e.g., central – peripheral zone of the group 389 (Janson 1990; Robinson 1981). Further examination of behavioural changes in relation to 390 relative position of the group is necessary, such as monitoring behaviour of group members 391 (Kazahari & Agetsuma 2010; Suzuki 2011) and contact calls (Boinski & Campbell 1995; 392 Rendall et al. 2000; this study). 393

Another possible mechanism for knowing the location of the group is that group 394 members share knowledge of food resources and aggregate at a food patch (Ramos-Fernandez 395 et al. 2006). If we assume that each individual accurately knows information of food resources 396 and knows where group members go next, they can aggregate at such places without locating 397 the whole group. However, it is unlikely that group members share the prior knowledge of food 398 resources to such degree that they can forecast the other members' destinations. Aggregating at 399 400 a food patch may help them to cohere, but monitoring the position of the group should be needed. 401

In addition, Japanese macaques do not always aggregate at a large food patch, especially in lean seasons. In the subject group, they feed on clumped food such as fruiting trees for about 80 % of feeding time in autumn (Sugiura et al. 2011), where aggregating at such food patches may be possible. However, they feed on scattered food such as herb for about 85% and 63% of feeding time in winter and in summer, respectively (Sugiura et al. 2011), where they feed alone or with a few members. In such ecological condition, aggregating at a food patch would be difficult. In spite of these drastic changes of food availability, we observed a significant effect of initial distance of the focal pair on the change in distance between them, in different seasons.
Thus, aggregating at a food patch alone can not account for group cohesion, although this
should also help them to cohere.

In this study, the subjects did not engage in a particular activity, but did in various ones 412 413 when we sampled their movements. The proportion of activities also varied in different seasons. In spite of this variation, the adjustment of distance between two distant animals was constantly 414 observed in each of the three seasons. Thus, it is unlikely that adjustment of proximity is derived 415 from a particular situation, such as aggregating at food patches. In autumn, the proportions of 416 activities of subject animals were 17.0 % in grooming, 12.4 % in resting, 54.2 % in foraging, 417 15.7 % in moving and 0.7 % in agonistic interaction. In winter, the proportions were 11.1 % in 418 grooming, 6.4 % in resting, 72.7 % in foraging, 9.4 % in moving and 0.3 % in agonistic 419 interaction. In summer, the proportions were 11.1 % in grooming, 21.5 % in resting, 32.9 % in 420 foraging, 34.4 % in moving and 0.3 % in agonistic interaction. 421

422

### 423 Possible Function of Adjustment of Proximity to Distant Individuals

A major cost of grouping is feeding competition with group members (van Schaik & van 424 Noordwijk 1986), but adjusting proximity to group members can mediate the feeding 425 competition. Adjusting proximity not only to members in close proximity but also to more 426 distant members should bring more flexible group cohesion and foraging tactics. If we assume 427 that Japanese macaques keep a particular distance to a few neighbours, they should need to 428 429 synchronize their arrival and leave of a food patch with their neighbours. Such adjustment of proximity to neighbours should be a firm means for cohesion but are likely to affect feeding 430 competition. 431

432

Actually, however, Japanese macaques seem to flexibly change their proximity and group

cohesiveness. They change their proximity to group members depending on the quality of food 433 (Sugiura et al. 2011). In addition, they do not always synchronize their foraging (Agetsuma 434 1995) or timing of leave from food patches (Kazahari & Agetsuma 2010). Japanese macaques 435 appear to adjust proximity to distant members, probably by locating approximate position of the 436 whole group. This may bring them more freedom of positioning themselves and thus, freedom 437 of food choice with lesser competition and/or better feeding efficiency. Predation free condition 438 in this study should contribute to such flexible adjustment of proximity. Lack of predation may 439 reduce the necessity of their keeping cohesiveness with nearby individuals, and made the 440 adjustment proximity to distant individuals more detectable. 441

The present study suggests that Japanese macaques adjust their proximity to group 442 members, relying not only on neighbouring group members, but also on more distant animals. 443 Although adjustment of proximity to neighbours have been reported in a variety of species, 444 adjustment of proximity to distant group members may be unique to group living animals that 445 446 form a relatively small group with stable memberships, like Japanese macaques. However, it is 447 still possible that Japanese macaques rely only on the information from nearby group members, and it accounts for the change in distance between two distant individuals. Further examination 448 of the influence of nearby group members on the change of distance should be necessary, such 449 as their activities, movements and coo calls. Examination from another view point would also 450 possible. If they relay also on the distant group members, they should know the location of the 451 whole group and adjust their movements based on such information. Examination of this 452 453 possibility would also help to elucidate our hypothesis and to understand the mechanism of group cohesion in Japanese macaques and other group living animals. 454

455

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Figure 1. Initial numbers of individuals within 20 m from the focal individual (x axis) and 466 changes in the number of individuals after 10 min (y axis), in the autumn (A), the winter (B), 467 non-subgrouping in the summer (C), and subgrouping in the summer (D). A positive value 468 indicates that the number of individuals increased, a negative value indicates that it decreased, 469 and a value of zero indicates that it remained the same. A line represents the linear estimate by a 470 generalised linear model, where the initial distance is the mean. Size of marks vary with the 471 sample size (see legends in the figure), because multiple samples are plotted at the same point. 472 473 Figure 2. Initial distance between two individuals (x axis) and changes in distance apart after 474

475 10 min (y axis) in the autumn (A), the winter (B), non-subgrouping in the summer (C), and 476 subgrouping in the summer (D). A positive value indicates that the distance apart became 477 shorter, a negative value indicates that it became greater, and a value of zero indicates that it 478 remained the same. A line represents the linear estimate by a generalised linear model, where 479 the initial number is the mean.

480

Figure 3. Initial distance between two individuals (*x* axis) and mean coo-call rates during the following 1 min (*y* axis) in the autumn (A), the winter (B), non-subgrouping in the summer (C), and subgrouping in the summer (D). Error bars show 95% confidence intervals of means. Classes connected with bold lines showed a significant difference in *post hoc* pairwise comparisons (P < 0.05, panel B), and those connected with dashed lines showed a near-significant difference (P = 0.06, panel A).

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Initial distance (m)