

# The LR-dispersion problem

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## 1 Introduction

The facility location problem and many of its variants have been studied[6, 7]. A typical problem is to find a set of locations to place facilities with the designated cost minimized. By contrast, in this paper we consider the dispersion problem, which finds a set of locations with the designed cost maximized.

Given a set  $P$  of  $n$  points, and the distance  $d$  for each pair of points, and an integer  $k$  with  $k \leq n$ , we wish to find a subset  $S \subset P$  with  $|S| = k$  such that some designated cost is maximized[1, 4, 5, 9, 10, 11, 12, 13].

In one of typical cases the cost to be maximized is the minimum distance between two points in  $S$ . If  $P$  is a set of points on the plane then the problem is NP-hard[11, 13], and if  $P$  is a set of points on the line then the problem can be solved in  $O(\max\{n \log n, kn\})$  time[11, 13] by dynamic programming approach, and in  $O(n \log \log n)$  time[1] by sorted matrix search method[3, 8].

In this paper we consider two variants of the dispersion problem on the line. Let  $P$  be a set of points on the horizontal line. We wish to find a subset  $S \subset P$  with  $|S| = k$  maximizing  $cost(S)$  defined as follows.

Let the cost  $cost(s)$  of  $s \in S = \{s_1, s_2, \dots, s_k\}$  be the sum of the distance to its left neighbor in  $S$  and the distance to its right neighbor in  $S$ . We assume  $s_1, s_2, \dots, s_k$  are sorted from left to right. Especially the leftmost point  $s_1 \in S$  has no left neighbor, so we define the cost of  $s_1$  is  $d(s_1, s_2)$ . Similarly the cost of the rightmost point  $s_k$  is  $d(s_{k-1}, s_k)$ . And the  $cost(S)$  of  $S$  is the minimum cost among the costs  $cost(s_1), cost(s_2), \dots, cost(s_k)$ . We call the problem above the *LR-dispersion problem*. An  $O(kn^2 \log n)$  time algorithm based on dynamic programming is known[2].

In this paper we design an algorithm to solve the LR-dispersion problem. Our algorithm runs in  $O(n \log n)$  time, and based on matrix search method[3, 8].

The remainder of this paper is organized as follows. Section 2 contains an algorithm for the decision version of the LR-dispersion problem. Section 3 gives our algorithm for the LR-dispersion problem. Section 4 treats one more variant of the dispersion problem. Finally Section 5 is a conclusion.

## 2 $(\lambda, k)$ -LR-dispersion

In this section we give a linear time algorithm to solve a decision version of the LR-dispersion problem.

Given a set  $P = \{p_1, p_2, \dots, p_n\}$  of points on a horizontal line, and two numbers  $k$  and  $\lambda$  we wish to decide if there exists a subset  $S \subset P$  with  $|S| = k$  and  $cost(S) \geq \lambda$ . We call the problem as the  $(\lambda, k)$ -LR-dispersion problem.

We have the following lemma.

**Lemma 1.** If  $(\lambda, k)$ -LR-dispersion problem has a solution  $S = \{s_1, s_2, \dots, s_k\} \subset P$ , then  $S' = \{p_1, s_2, s_3, \dots, s_{k-1}, p_n\}$  is also a solution of the  $(\lambda, k)$ -LR-dispersion problem.

**Proof.** Since  $cost(S) \leq cost(S')$ , if  $S$  is a solution then  $S'$  is also a solution and  $cost(S) = cost(S')$  holds.  $\square$

The algorithm below is a greedy algorithm to solve the  $(\lambda, k)$ -LR-dispersion problem. Note that  $cost(s_i)$  for  $i = 3, 4, \dots, k-1$  is  $d(s_{i-2}, s_i)$ . By setting a dummy point  $s_0 = s_1$ ,  $cost(s_2)$  is also  $d(s_{2-2}, s_2) = d(s_1, s_2)$ . Also note that  $cost(k) = d(s_{k-1}, s_k)$ .

Now we prove the correctness of the algorithm. Assume for a contradiction that the algorithm output NO for a given problem but it has a solution.

Let  $G = \{g_1, g_2, \dots, g_{k'}\}$  with  $k' < k$  be the points chosen by the algorithm, and  $O = \{o_1, o_2, \dots, o_k\}$  the points of a solution. By Lemma 1 we can assume  $o_1 = p_1$  and  $o_k = p_n$ . Note that  $g_1 = o_1 = p_1$  and  $g_{k'} = o_k = p_n$  hold. We have the following two cases.

**Case 1 :** For all  $i$ ,  $1 \leq i < k'$ ,  $g_i \leq o_i$  holds.

Then our greedy algorithm can choose at least one more point  $o_{k'}$  or more left point. A contradiction.

**Case 2 :** For some  $i$ ,  $1 \leq i < k'$ ,  $g_i > o_i$  holds.

Since  $g_2$  is chosen in a greedy manner, we can assume  $g_2 \leq o_2$ . Let  $j$  be the minimum such  $i$ . Since  $g_{j-2} \leq o_{j-2}$  and  $g_{j-1} \leq o_{j-1}$  hold, our greedy algorithm choose  $o_i$  or more left point as  $g_i$ . A contradiction.

**Theorem 1.** One can solve the decision version of the LR-dispersion problem in  $O(n)$  time.

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**Algorithm 1** find  $(\lambda, k)$ -LR-dispersion  $(P, k, \lambda)$

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/*  $P = \{p_1, p_2, \dots, p_n\}$  and  $p_1, p_2, \dots, p_n$  are sorted from left to right */
/* Choose  $s_1$  and  $s_k$  */
 $s_1 = p_1, s_k = p_n$ 
 $s_0 = s_1$  /* Dummy */
/* Choose  $s_2, s_3, \dots, s_{k-1}$  */
 $c = 2$ 
for  $i = 2$  to  $k - 1$  do
  while  $d(s_{i-2}, p_c) < \lambda$  and  $d(p_c, p_n) \geq \lambda$  do
     $c++$ 
  end while
  if  $d(p_c, p_n) < \lambda$  then
    /* no solution since  $d(p_c, p_n) < \lambda$  */
    return NO
  else
    /*  $d(s_{i-2}, p_c) \geq \lambda$  holds */
     $s_i = p_c$  /*  $s_i$  is found */
     $c++$ 
  end if
end for
/* Output */
return  $S = \{s_1, s_2, \dots, s_k\}$ 

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### 3 LR-dispersion

One can design an  $O(n \log n)$  time algorithm to solve the LR-dispersion problem, based on the sorted matrix search method[3, 8].

First let  $M$  be the matrix in which each element  $m_{i,j}$  is  $d(p_i, p_j)$  if  $i < j$ , otherwise 0. Then  $m_{i,j} \leq m_{i,j+1}$  and  $m_{i,j} \geq m_{i+1,j}$  always holds, so the elements in the rows and columns are sorted, respectively. The cost  $cost(S)$  of a solution  $S$  of the LR-dispersion problem is some element in the matrix. We are going to find the largest  $\lambda$  in  $M$  for which the  $(\lambda, k)$ -LR-dispersion problem has a solution.

By appending a suitable number of large enough elements to  $M$  as the elements in the topmost rows and the rightmost columns we can assume  $n$  is a power of 2. Note that the elements in the rows and columns are still sorted, respectively. Let  $M$  be the resulting matrix. Our algorithm consists of rounds  $s = 1, 2, \dots, \log n$ , and maintains a set  $L_s$  of (non-overlapping) submatrices of  $M$  possibly containing the optimal value  $\lambda^*$ . Hypothetically first we set  $L_0 = \{M\}$ . Assume we are now starting round  $s$ .

For each subset  $M$  in  $L_{s-1}$  we divide  $M$  into the four submatrices with  $n/2^s$  rows and  $n/2^s$  columns and put them into  $L_s$ . We never copy these submatrices. We just update the index of the corner elements of each submatrix.

Let  $\lambda_{min}$  be the median of the lower left corner elements of the submatrices in  $L_s$ . Then for the  $\lambda = \lambda_{min}$  we solve the  $(\lambda, k)$ -LR-dispersion problem, using the algorithm in Section 2. We have the following two cases.

If the  $(\lambda, k)$ -LR-dispersion problem has no solution then we remove from  $L_s$  each submatrix with the lower left corner element (the smallest element) greater than  $\lambda_{min}$ . Since  $\lambda_{min} > \lambda^*$  holds, each removed submatrix has no chance to contain  $\lambda^*$ . Thus we can remove at least  $|L_s|/2$  submatrices from  $L_s$ .

Otherwise if the  $(\lambda, k)$ -LR-dispersion problem has a solution then we remove from  $L_s$  each submatrix with the upper right corner element (the largest element) smaller than  $\lambda_{min}$ . Since  $\lambda_{min} \leq \lambda^*$  holds, each removed submatrix has no chance to contain  $\lambda^*$ . Also if  $L_s$  has several submatrices with the upper right corner element equal to  $\lambda_{min}$  then we remove them except one from  $L_s$ . Now we can observe that, for each "chain" of submatrices, which is the sequence of submatrices in  $L_s$  with lower left to upper right diagonals on the same line, the number of submatrices (1) having the lower left corner element smaller than  $\lambda_{min}$  (2) but remaining in  $L_s$ , is at most one (since the elements on "the common diagonal line" are sorted). Thus, if  $|L_s|/2 > D_s$ , where  $D_s = 2^{s+1}$  is the number of chains plus one, then we can remove at least  $|L_s|/2 - D_s + 1$  submatrices from  $L_s$ .

Similarly let  $\lambda_{max}$  be the median of the upper right corner elements of submatrices in  $L_s$ , and for the  $\lambda = \lambda_{max}$  we solve the  $(\lambda, k)$ -LR-dispersion problem and similarly remove some submatrices from  $L_s$ . This ends round  $s$ .

Now after round  $\log n$  each matrix in  $L_{\log n}$  has just one element, then we can find the  $\lambda^*$  using a binary search with the linear time decision algorithm in Section 2.

We can prove that at the end of round  $s$  the number of submatrices in  $L_s$  is at most  $2D_s$ , as follows.

First  $L_0$  has 1 submatrix, which is less than  $2D_0 = 4$ . By induction assume that  $L_{s-1}$  has  $2D_{s-1} = 2 \cdot 2^s$  submatrices.

At round  $s$  we first partite each submatrix in  $L_{s-1}$  into four submatrices then put them into  $L_s$ . Now the number of submatrices in  $L_s$  is at most  $4 \cdot 2D_{s-1} = 4D_s$ . We have four cases.

If the  $(\lambda, k)$ -LR-dispersion problem has no solution for  $\lambda = \lambda_{min}$  then we can remove at least a half of the submatrices in  $L_s$  is at most  $2D_s$ , as desired. If the  $(\lambda, k)$ -LR-dispersion problem has a solution for  $\lambda = \lambda_{max}$  then we can remove at least a half of the submatrices in  $L_s$  is at most  $2D_s$ , as desired. Otherwise if  $|L_s|/2 \leq D_s$  then the number of the submatrices in  $L_s$  (even before the removal) is at most  $2D_s$ , as desired. Otherwise (1) after the check for  $\lambda = \lambda_{min}$  we can remove at least  $|L_s|/2 - D_s$  submatrices (consisting of too small elements) from  $L_s$ , and (2) after check for  $\lambda = \lambda_{max}$  we can remove at least  $|L_s|/2 - D_s$  submatrices (consisting of too large elements) from  $L_s$ , so the number of the remaining submatrices in  $L_s$  is at most  $|L_s| - 2(|L_s|/2 - D_s) = 2D_s$ , as desired.

Thus at the end of round  $s$  the number of submatrices in  $L_s$  is always at most  $2D_s$ , and at the end of round  $\log n$  the number of submatrices is at most  $2D_{\log n} = 4n$ .

Now we consider the running time. We implicitly treat each submatrix as the index of the upper right element in  $M$  and the number of lows (= the number of columns). Except for the calls of the linear time decision algorithm for the  $(\lambda, k)$ -LR-dispersion problem, we need  $O(|L_{s-1}|) = O(D_{s-1})$  time for each round  $s = 1, 2, \dots, \log n$ , and  $D_0 + D_1 + \dots + D_{\log n-1} = 2 + 4 + \dots + 2^{\log n} < 2 \cdot 2^{\log n} = 2n$  holds, so this part needs  $O(n)$  time in total. (Here we use the linear time algorithm to find the median.)

Since each round calls the linear time decision algorithm twice and the number of round is  $\log n$  this part needs  $O(n \log n)$  time in total.

After round  $s = \log n$  each matrix has just one element. Then we can find the  $\lambda^*$  among the  $|L_{\log n}| \leq 2D_{\log n} = 4n$  elements by (1) sorting them, then (2) performing binary search with the linear time decision algorithm at most  $\log 4n$  times. This part needs  $O(n \log n)$  time.

Thus the total running time is  $O(n \log n)$ . With a similar method we have solved the (original) dispersion problem in  $O(n \log n)$  time[1].

**Theorem 2.** One can solve the LR-dispersion problem in  $O(n \log n)$  time.

## 4 Generalization

In this section we consider one more variant of the dispersion problem and give an algorithm to solve the problem, which runs in  $O(n \log n)$  time. In the original dispersion problem the cost is the minimum distance between two points  $s_i$  and  $s_{i+1}$ . We generalize this to the minimum distance between  $s_i$  and  $s_{i+h}$ , for given  $h$ .

Given a set  $P = \{p_1, p_2, \dots, p_n\}$  of points on a horizontal line, and the distance  $d$  for each pair of points, and two integers  $k, h$  with  $k, h \leq n$ , we wish to find a subset  $S = \{s_1, s_2, \dots, s_k\} \subset P$  maximizing  $cost(S)$  defined as follows.

$Lcost(S) = \min\{d(s_1, s_2), d(s_1, s_3), \dots, d(s_1, s_h)\}$ ,  $Rcost(S) = \min\{d(s_{k-h+1}, s_k), d(s_{k-h+2}, s_k), \dots, d(s_{k-1}, s_k)\}$  and  $Mcost(S) = \min\{d(s_1, s_{1+h}), d(s_2, s_{2+h}), \dots, d(s_{k-h}, s_k)\}$  then  $cost(S) = \min\{Lcost(S), Rcost(S), Mcost(S)\}$ .

We call the problem above the  $h$ -dispersion problem. The original dispersion problem on the line is the  $h$ -dispersion problem with  $h = 1$  and the LR-dispersion problem is the  $h$ -dispersion problem with  $h = 2$ .

**Lemma 2.** If  $(\lambda, k)$ - $h$ -dispersion problem has a solution  $S = \{s_1, s_2, \dots, s_k\} \subset P$ , then  $S' = \{p_1, s_2, s_3, \dots, s_{k-1}, p_n\}$  is also a solution of the  $(\lambda, k)$ - $h$ -dispersion problem.

**Proof.** Since  $cost(S) \leq cost(S')$ , if  $S$  is a solution then  $S'$  is also a solution and  $cost(S) = cost(S')$  holds.  $\square$

The algorithm below is a greedy algorithm to solve the problem. Now we prove the correctness of the algorithm.

Assume for a contradiction that the algorithm output NO for a given problem but it has a solution.

Let  $G = \{g_1, g_2, \dots, g_{k'}\}$  with  $k' < k$  be the points chosen by the algorithm, and  $O = \{o_1, o_2, \dots, o_k\}$  the points of a solution. By Lemma 2 we can assume  $o_1 = p_1$  and  $o_k = p_n$ . Note that  $g_1 = o_1 = p_1$  and  $g_{k'} = o_k = p_n$  hold. We have the following two cases:

**Case 1 :** For all  $i, 1 \leq i < k', g_i \leq o_i$  holds.

Then our greedy algorithm can choose at least one more points  $o_{k'}$  or more left point. A contradiction.

**Case 2 :** For some  $i, 1 \leq i < k', g_i > o_i$  holds. Since  $g_2, g_3, \dots, g_h$  are chosen in a greedy manner, we can assume  $g_j \leq o_j$  for  $j = 2, 3, \dots, h$ . Let  $j$  be the minimum such  $i$ . Since  $g_{j-h} \leq o_{j-h}, g_{j-h+1} \leq o_{j-h+1}, \dots, g_{j-1} \leq o_{j-1}$  hold, our greedy algorithm choose  $o_i$  or more left point as  $g_i$ . A contradiction.

**Theorem 3.** One can solve the decision version of the  $h$ -dispersion problem in  $O(n)$  time.

Therefore, similar to the algorithm in Section 3, we can design  $O(n \log n)$  time algorithm to solve the  $h$ -dispersion problem.

**Theorem 4.** One can solve the  $h$ -dispersion problem in  $O(n \log n)$  time.

## 5 Conclusion

In this paper we have presented two algorithms to solve the LR-dispersion problem and the  $h$ -dispersion problem. The running time of the algorithms are  $O(n \log n)$ .

An  $O(n \log \log n)$  time algorithm to solve the original dispersion problem on the line is known[1]. Can we design an  $O(n \log \log n)$  time algorithm to solve the  $h$ -dispersion problem ?

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**Algorithm 2** find  $(\lambda, k)$ - $h$ -dispersion  $(P, h, k, \lambda)$

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/\* Choose  $s_1$  and  $s_k$  \*/

$s_1 = p_1, s_k = p_n$

/\* Dummy \*/

$s_0 = s_1, s_{-1} = s_1, s_{-2} = s_1, \dots, s_{-h+2} = s_1$

/\* Choose  $s_2, s_3, \dots, s_{k-1}$  \*/

$c = 2$

**for**  $i = 2$  **to**  $k - 1$  **do**

**while**  $d(s_{i-h}, p_c) < \lambda$  **and**  $d(p_c, p_n) \geq \lambda$  **do**

$c++$

**end while**

**if**  $d(p_c, p_n) < \lambda$  **then**

    /\* no solution since  $d(p_c, p_n) < \lambda$  \*/

**return** NO

**else**

    /\*  $d(s_{i-h}, p_c) \geq \lambda$  holds \*/

$s_i = p_c$

    /\*  $s_i$  is found \*/

$c++$

**end if**

**end for**

/\* Output \*/

**return**  $S = \{s_1, s_2, \dots, s_k\}$

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