GLOBAL $L^2$-BOUNDEDNESS THEOREMS FOR A CLASS OF FOURIER INTEGRAL OPERATORS AND THEIR APPLICATION (Recent Trends in Microlocal Analysis)

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GLOBAL $L^{2}$-BOUNDEDNESS THEOREMS FOR A CLASS OF FOURIER INTEGRAL OPERATORS AND THEIR APPLICATION

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This article is based on the joint work with Michael Ruzhansky (Imperial College) which will appear in [13], [14], [15] and so on.

Fourier integral operators

We consider the following Fourier integral operator:

\[ Tu(x) = \int_{\mathbb{R}^{n}} \int_{\mathbb{R}^{n}} e^{i\phi(x,y,\xi)} a(x,y,\xi) u(y) dyd\xi \]

\((x \in \mathbb{R}^{n})\), where \(a(x,y,\xi)\) is an amplitude function and \(\phi(x,y,\xi)\) is a real phase function of the form

\[ \phi(x,y,\xi) = x \cdot \xi + \varphi(y,\xi). \]

Note that, by the equivalence of phase function theorem, Fourier integral operators with the local graph condition can always be written in this form locally.

Local $L^{2}$ mapping property of (1) has been established by Hörmander [9] and Eskin [7]. The aim of this article is to present global $L^{2}$-boundedness properties of operators (1).

When is $T$ globally $L^{2}$-bounded?

- (Asada and Fujiwara [1]) Assume that all the derivatives of \(a(x,y,\xi)\) and all the derivatives of each entry of the matrix

\[ D(\phi) = \begin{pmatrix} \partial_{x}\partial_{y}\phi & \partial_{x}\partial_{\xi}\phi \\ \partial_{x}\partial_{y}\phi & \partial_{x}\partial_{\xi}\phi \end{pmatrix} \]

are bounded. Also assume that \(|\det D(\phi)| \geq C > 0\). Then $T$ is $L^{2}(\mathbb{R}^{n})$-bounded.

This result was used to construct the fundamental solution of Schrödinger equation in the way of Feynman's path integral.

(The result of Kumanogo [12] was used to construct the fundamental solution of hyperbolic equations, and it requires that

\[ J(y,\xi) = \phi(x,y,\xi) - (x - y) \cdot \xi \]

satisfies

\[ |\partial^{\alpha}_{\nu} \partial^{\beta}_{\xi} J(y,\xi)| \leq C_{\alpha\beta}(1 + |\xi|)^{1-|\beta|} \]

for all $\alpha$ and $\beta$.)

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However, there one had to make a quite restrictive and not always natural as- sumption on the boundedness of $\partial_\xi \partial_\xi \phi$, which fails in many important cases.

The case we have in mind is

\[ \phi(x, y, \xi) = x \cdot \xi - y \cdot \psi(\xi), \]

where $\psi(\xi)$ is a smooth function of growth order 1. If we take $\psi(\xi) = \xi$, then we have $\phi(x, y, \xi) = x \cdot \xi - y \cdot \xi$, and the operator $T$ defined by it is a pseudo-differential operator.

We cannot use Asada-Fujiwara's result with our example (2), because the boundedness of the entries of $\partial_\xi \partial_\xi \phi$ fails generally. (We cannot use Kumanogoo's either by the same reason.)

**Why is the phase function (2) important?**

Because it is used to represent a canonical transformations. In fact, if we take $\alpha(x, y, \xi) = 1$, we have

\[ Tu(x) = F^{-1}[(Fu)(\psi(\xi))](x) \]

hence

\[ T \cdot \sigma(D) = (\sigma \circ \psi)(D) \cdot T. \]

Especially, for a positive and homogeneous function $p(\xi) \in C^\infty(\mathbb{R}^n \setminus 0)$ of degree 1, we have the relation

\[ T \cdot (-\Delta) \cdot T^{-1} = p(D)^2 \]

if we take

\[ \psi(\xi) = p(\xi) \frac{\nabla p(\xi)}{|\nabla p(\xi)|} \]

and assume that the hypersurface

\[ \Sigma = \{ \xi; p(\xi) = 1 \} \]

has non-vanishing Gaussian curvature.

The curvature condition on $\Sigma$ means that the Gauss map

\[ \frac{\nabla p}{|\nabla p|} : \Sigma \to S^{n-1} \]

is a global diffeomorphism and its Jacobian never vanishes. (See Kobayashi and Nomizu [11].) Hence, we can construct the inverse $C^\infty$-map $\psi^{-1}(\xi)$ of $\psi(\xi)$ defined by (5). On account of (3), the inverse $T^{-1}$ can be given by replacing $\psi$ by $\psi^{-1}$.

The $L^2$-property of the Laplacian $-\Delta$ is well known in various situations. Our objective is to know the $L^2$-property of the operator $T$, so that we can extract the $L^2$-property of the operator $p(D)^2$ from that of the Laplacian.
Main result

The following is our main result, which is expected to have many applications. For \( m \in \mathbb{R} \), we set
\[
\langle x \rangle^m = (1 + |x|^2)^{m/2}.
\]
Let \( L_m^2(\mathbb{R}^n) \) be the set of functions \( f \) such that the norm
\[
\|f\|_{L_m^2(\mathbb{R}^n)} = \left( \int_{\mathbb{R}^n} |\langle x \rangle^m f(x)|^2 \, dx \right)^{1/2}
\]
is finite.

**Theorem 1.** Let \( \phi(x, y, \xi) = x \cdot \xi + \varphi(y, \xi) \). Assume that
\[
|\det \partial_y \partial_\xi \varphi(y, \xi)| \geq C > 0,
\]
and all the derivatives of entries of \( \partial_y \partial_\xi \varphi \) are bounded. Also assume that
\[
|\partial_\xi \varphi(y, \xi)| \leq C_\alpha \langle y \rangle \quad \text{for all } |\alpha| \geq 1,
\]
\[
|\partial_y^\alpha \partial_\xi^\beta \varphi(x, y, \xi)| \leq C_{\alpha \beta} \langle x \rangle^{-|\alpha|}
\]
for all \( \alpha, \beta, \) and \( \gamma \). Then \( T \) is bounded on \( L_m^2(\mathbb{R}^n) \) for any \( m \in \mathbb{R} \).

Theorem 1 says that, if amplitude functions \( a(x, y, \xi) \) have some decaying properties with respect to \( x \), we do not need the boundedness of \( \partial_\xi \partial_\xi \phi \) for the \( L^2 \)-boundedness, as required in Asada-Fujiwara [1], and we can have weighted estimates, as well.

The same is true when both phase and amplitude functions have some decaying properties with respect to \( y \).

**Theorem 2.** Let \( \phi(x, y, \xi) = x \cdot \xi + \varphi(y, \xi) \). Assume that
\[
|\det \partial_y \partial_\xi \varphi(y, \xi)| \geq C > 0.
\]
Also assume that
\[
|\partial_\xi \varphi(y, \xi)| \leq C_\alpha \langle y \rangle^{1-|\alpha|} \quad \text{for all } |\alpha| \geq 1,
\]
\[
|\partial_y^\alpha \partial_\xi^\beta a(x, y, \xi)| \leq C_{\alpha \beta} \langle x \rangle^{-|\alpha|}
\]
for all \( \alpha, \beta, \) and \( \gamma \). Then \( T \) is bounded on \( L_m^2(\mathbb{R}^n) \) for any \( m \in \mathbb{R} \).

If the amplitude \( a(x, y, \xi) \) is independent of the variable \( x \) or \( y \), the decaying property can be automatically satisfied. Furthermore, we can reduce the regularity assumptions for amplitude and phase functions in this case.

**Theorem 3.** Let \( \phi(x, y, \xi) = x \cdot \xi + \varphi(y, \xi) \) and \( a(x, y, \xi) = a(x, \xi) \). Assume that
\[
|\det \partial_y \partial_\xi \varphi(y, \xi)| \geq C > 0
\]
and each entry \( h(y, \xi) \) of \( \partial_y \partial_\xi \varphi(y, \xi) \) satisfies
\[
|\partial_\xi^\alpha h(y, \xi)| \leq C_\alpha, \quad |\partial_y^\beta h(y, \xi)| \leq C_\beta
\]
for \( |\alpha|, |\beta| \leq 2n + 1 \). Also assume
\[
\partial_\xi^\alpha \partial_y^\beta a(x, \xi) \in L^\infty(\mathbb{R}_x^n \times \mathbb{R}_\xi^n)
\]
for one of the followings:

(i) $\alpha, \beta \in \{0, 1\}^n$,
(ii) $|\alpha|, |\beta| \leq [n/2] + 1$,
(iii) $|\alpha| \leq [n/2] + 1, \beta \in \{0, 1\}^n$,
(iv) $\alpha \in \{0, 1\}^n, |\beta| \leq [n/2] + 1$.

Then $T$ is $L^2(\mathbb{R}^n)$-bounded.

Theorem 3 with $\varphi(y, \xi) = -y \cdot \xi$ is a refined version of known results on the $L^2$-boundedness of pseudo-differential operators with non-regular symbols: (i) with $\alpha, \beta \in \{0, 1, 2, 3\}^n$ is due to Calderón and Vaillancourt [3], (ii) is due to Cordes [6], and conditions (iii) with $|\alpha| \leq [n/2] + 1, \beta \in \{0, 1, 2\}^n$, is due to Coifman and Meyer [5].

**Theorem 4.** Let $\phi(x, y, \xi) = x \cdot \xi + \varphi(y, \xi)$ and $a(x, y, \xi) = a(y, \xi)$. Assume that

$$|\partial_y^\alpha \partial_\xi^\beta a(y, \xi)| \leq C_{\alpha \beta},$$

for $|\alpha|, |\beta| \leq 2n + 1$. Also assume that

$$|\det \partial_y \partial_\xi \varphi(y, \xi)| \geq C > 0$$

and each entry $h(y, \xi)$ of $\partial_y \partial_\xi \varphi(y, \xi)$ satisfies

$$|\partial_y^\alpha h(y, \xi)| \leq C_\alpha, \quad |\partial_\xi^\beta h(y, \xi)| \leq C_\beta$$

for $|\alpha|, |\beta| \leq 2n + 1$. Then the operator $T$ is $L^2(\mathbb{R}^n)$-bounded.

**An example of how to use our results**

Kato and Yajima [10] showed that the classical Schrödinger equation

$$\begin{cases}
(i \partial_t + \Delta_x)u(t, x) = 0, \\
u(0, x) = g(x)
\end{cases}$$

has the global smoothing estimate

$$(6) \quad \|\langle x \rangle^{-1}\langle D \rangle^{1/2}u\|_{L^2(\mathbb{R}_t \times \mathbb{R}^n)} \leq C\|g\|_{L^2(\mathbb{R}_t \times \mathbb{R}^n)},$$

where $n \geq 3$.

From this fact, we can extract a similar estimate for generalized Schrödinger equations

$$(7) \quad \begin{cases}
(i \partial_t - p(D)^2)u(t, x) = 0, \\
u(0, x) = g(x)
\end{cases}$$

- **Assumption.** $p(\xi) \in C^\infty(\mathbb{R}^n \setminus 0)$ is homogeneous of order 1, $p(\xi) > 0$, and the hypersurface $\Sigma = \{\xi; p(\xi) = 1\}$ has non-vanishing Gaussian curvature.

Remember that we have the relation

$$T^{-1} \cdot p(D)^2 = (-\triangle) \cdot T^{-1}$$
by (4). Operating $T^{-1}$ from the left hand side of equation (7), we have, by this relation,
\[
\begin{cases}
(i\partial_t - \Delta)T^{-1}u(t, x) = 0, \\
T^{-1}u(0, x) = T^{-1}g(x).
\end{cases}
\]
Hence, from (6) and Theorem 1, we obtain the following conclusion:

**Theorem 5.** Suppose $n \geq 3$. Under the assumption above, the solution $u(t, x)$ to generalized Schrödinger equation (7) has the same global smoothing estimate (6) as the classical one has.

**Remark 1.** Walther [16] consider the case of radially symmetric $p(\xi)^2$. Theorem 5 says that we can treat more general case.

**Smoothing effect with a structure**

By using the idea above, we can have more refined global smoothing estimates. In order to state them, we introduce some notations:

- Classical orbit determined by $p(D)^2$:
\[
\begin{cases}
\dot{x}(t) = \nabla_{\xi}p^2(\xi(t)), \quad \dot{\xi}(t) = 0 \\
x(0) = 0, \quad \xi(0) = k.
\end{cases}
\]

- The set of the path of all classical orbits:
\[
\Gamma_p = \{(x(t), \xi(t)); \text{ sol. of (8), } t \geq 0, k \in \mathbb{R}^n \setminus 0\} = \{(t\nabla p(\xi), \xi); \xi \in \mathbb{R}^n \setminus 0, t > 0\}.
\]

- Notation:
\[
\sigma(x, \xi) \sim \langle x \rangle^a|\xi|^b \quad \Leftrightarrow \quad \begin{cases}
\sigma(x, \xi) \in C^\infty(\mathbb{R}_x^n \times (\mathbb{R}_\xi^n \setminus 0)), \\
\sigma(\lambda x, \xi) = \lambda^a \sigma(x, \xi); (\lambda > 1, |x| \gg 1), \\
\sigma(x, \lambda \xi) = \lambda^b \sigma(x, \xi); (\lambda > 0).
\end{cases}
\]

**Theorem 6.** Suppose $n \geq 2$. Assume
\[
\sigma(x, \xi) = 0 \text{ on } \Gamma_p, \quad \sigma(x, \xi) \sim \langle x \rangle^{-1/2}|\xi|^{1/2}.
\]
Then the solution $u$ to equation (7) satisfies
\[
\|\sigma(X, D)u\|_{L^2(\mathbb{R}_t \times \mathbb{R}_x^n)} \leq C\|g\|_{L^2(\mathbb{R}_x^n)}.
\]
Remark 2. Without the structure condition $\sigma(x, \xi) = 0$ on $\Gamma_p$, we have the estimate in Theorem 6 for the followings:

- $\sigma(x, \xi) = \langle x \rangle^{-s} |\xi|^{1/2}$ (Ben-Artzi and Klainerman [2])
- $\sigma(x, \xi) = |x|^{s-1}|\xi|^\alpha$ (Kato and Yajima [10])

We have a similar result for inhomogeneous equations

(9)

\[
\left\{ \begin{array}{l}
(i\partial_t - p(D)^2) u(t, x) = f(t, x) \\
u(0, x) = 0.
\end{array} \right.
\]

Theorem 7. Suppose $n \geq 2$. Assume

$\sigma(x, \xi) \geq 0, \quad \sigma(x, \xi) = 0$ on $\Gamma_p$
\[
\sigma(x, \xi) \sim \langle x \rangle^{1/2} |\xi|.
\]

Then the solution $u$ to (9) satisfies the estimate

\[
\frac{\|\sigma(X, D_x)u\|_{L^2(\mathbb{R}_t \times \mathbb{R}_x^2)}}{\langle x \rangle^{3/2} f\|_{L^2(\mathbb{R}_t \times \mathbb{R}_x^2)}} \leq C.
\]

Combining Theorems 6 and 7, we have an estimate for the equation

(10)

\[
\left\{ \begin{array}{l}
(i\partial_t - p(D)^2) u(t, x) = f(t, x) \\
u(0, x) = g(x).
\end{array} \right.
\]

Corollary 8. Suppose $n \geq 2$ and $s, \tilde{s} \geq 0$. Assume

$\sigma(x, \xi) \geq 0, \quad \sigma(x, \xi) = 0$ on $\Gamma_p$
\[
\sigma(x, \xi) \sim |\xi|.
\]

Then the solution $u$ to (10) satisfies the estimate

\[
\frac{\|\langle x \rangle^{1/2} \sigma(X, D_x)u\|_{H^1_t(H^s_x)}}{\langle x \rangle^{3/2} f\|_{H^1_t(H^\tilde{s}_x)}} \leq C\|\langle x \rangle^{2s+\tilde{s}+1/2} g\|_{L^2(\mathbb{R}_x^2)} + C\|\langle x \rangle^{3/2} f\|_{H^1_t(H^\tilde{s}_x)}.\]
Derivative Nonlinear Schrödinger Equation

Finally, we refer to further applications. We consider the following nonlinear Schrödinger equation:

\begin{equation}
\begin{cases}
(i\partial_t + \triangle_x) u(t, x) = |\nabla u(t, x)|^N \\
u(0, x) = g(x), \quad t \in \mathbb{R}, \ x \in \mathbb{R}^n.
\end{cases}
\end{equation}

What is the condition of the initial data \(g(x)\) for equation (11) to have time global solution? There are some answers:

- \(N \geq 3\) (Chihara [4]). Smooth, rapidly decay, and sufficiently small.
- \(N \geq 2\) (Hayashi, Miao and Naumkin [8]). \(g \in H^{[n/2]+5}\), rapidly decay, and sufficiently small.

**Question:** Can we weaken the smoothness assumption for \(g(x)\)?

**Answer:** Yes if the non-linear term has a "structure"!

Instead of (11), we consider

\begin{equation}
\begin{cases}
(i\partial_t - p(D)^2) u(t, x) = |\sigma(X, D_x)u|^N \\
u(0, x) = g(x), \quad t \in \mathbb{R}, \ x \in \mathbb{R}^n,
\end{cases}
\end{equation}

where

\begin{equation}
\begin{cases}
\sigma(x, \xi) \geq 0, \quad \sigma(x, \xi) = 0 \quad \text{on} \quad \Gamma_p, \\
\sigma(x, \xi) \sim |\xi|.
\end{cases}
\end{equation}

- Examples of nonlinear terms which satisfy (13) in the case \(p(D)^2 = -\triangle_x\):

\[
\sigma(x, \xi) = \left| \frac{x}{|x|} \wedge \xi \right|^2 |\xi|^{-1} \quad \text{for large} \ |x|
\]

**Theorem 9.** Suppose \(n \geq 2,\ s > (n+3)/2,\) and \(N \geq 3.\) Assume that \(|x|^{\langle D_x \rangle^s}g \in L^2\) and its \(L^2\)-norm is sufficiently small. Then equation (12) has a time global solution.

(In the case \(N = 2,\) we need more structure.)

Key point to the proof of Theorem 9. Use Corollary 8 with \(f = |\sigma(X, D_x)u|^N.\) The space \(H^s_t(H^\tilde{s}_x)\) is an algebra if \(s > 1/2\) and \(\tilde{s} > n/2.\) Then we have

\[
\left\| \langle x \rangle^{3/2} |\sigma(X, D_x)u|^N \right\|_{H^s_t(H^\tilde{s}_x)} \leq \left\| \langle x \rangle^{1/(2N)+1/N} \sigma(X, D_x)u \right\|^N_{H^s_t(H^\tilde{s}_x)}
\]

\[
\leq \left\| \langle x \rangle^{1/2} \sigma(X, D_x)u \right\|^N_{H^s_t(H^\tilde{s}_x)}
\]

if \(N \geq 3.\)
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