

Homogenization and penalization of Hamilton-Jacobi equations with integral terms

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1. Introduction

We consider the functional partial differential equation

$$u^\varepsilon(x, \xi) + H\left(\frac{x}{\varepsilon}, Du^\varepsilon(x, \xi), \xi\right) = \frac{1}{\delta(\varepsilon)} \int_I k(\xi, \eta) [u^\varepsilon(x, \eta) - u^\varepsilon(x, \xi)] d\eta \quad (\text{E})_\varepsilon$$

for $(x, \xi) \in \mathbf{R}^n \times I$,

where ε and $\delta(\varepsilon)$ are a positive parameter and a positive parameter satisfying $\delta(\varepsilon) \rightarrow 0$ as $\varepsilon \searrow 0$ respectively, I is a finite interval of \mathbf{R} , H is a Borel measurable function on $\mathbf{R}^{2n} \times I$ such that for each $\xi \in I$ the function $H(\cdot, \xi)$ is continuous on \mathbf{R}^{2n} , and k is a bounded, positive, Borel measurable function on $I \times I$.

Equation $(\text{E})_\varepsilon$ appears as a fundamental equation in optimal control of the system whose states are described by ordinary differential equations, subject to random changes of states in I and to control which induce the integral term in $(\text{E})_\varepsilon$ and the nonlinearity of H , respectively.

An evolution equation similar to $(\text{E})_\varepsilon$ was considered in Ishii-Shimano[11]. They proved a convergence theorem in which the limit equation is identified with a nonlinear parabolic PDE. The second and third terms of $(\text{E})_\varepsilon$ indicate the effects of homogenization and penalization, respectively. Our motivation is to study the interaction in the asymptotics between the effects of the almost periodic homogenization and penalization in $(\text{E})_\varepsilon$.

In this paper we deal with the almost periodic homogenization. In [8], Ishii studied the almost periodic homogenization of Hamilton-Jacobi equations. There are many references concerning the homogenization of Hamilton-Jacobi equations. However most of these deal with the periodic homogenization. See e.g., [1,4,5,6,7,10]. Except for the periodic and almost periodic cases, Souganidis studied stochastic homogenization for the Cauchy problem for first-order PDE in [12], and Arisawa dealt with the quasi-periodic homogenization for second-order Hamilton-Jacobi-Bellman equations in [3].

Our plan is the following. In Section 2 we explain some properties for the integral operator of $(\text{E})_\varepsilon$ and give our definition of viscosity solutions. In Section 3 we consider three cell problems. These cell problems play important parts in proofs of our main theorems. In Section 4 we state convergence theorems which are our main theorems. Our main theorems, Theorems 4.2, 4.3 and 4.4, say that the equation, which the limit

function of the viscosity solution u^ε of $(E)_\varepsilon$, as $\varepsilon \rightarrow 0$, varies according to the ranges of $\gamma := \lim_{\varepsilon \rightarrow 0} \delta(\varepsilon)/\varepsilon$, $\gamma = 0$, $0 < \gamma < \infty$, or $\gamma = \infty$. In Section 5 we deal with functional first-order PDE including two positive parameters. Theorem 5.2 says that in the case where $\gamma = 0$ $(E)_\varepsilon$ is influenced by the penalization first, and then the penalized PDE is homogenized, and that in the case where $\gamma = \infty$ it is homogenized first, and then is penalized. In the case where $\gamma \in (0, \infty)$ we can interpret that $(E)_\varepsilon$ is homogenized and penalized at the same time.

2. Preliminaries

For any Borel subset $\Omega \subset \mathbf{R}^m$, $\mathcal{B}(\Omega)$ denotes the space of all Borel functions on Ω , and $\mathcal{B}^\infty(\Omega)$ denotes the Banach space of bounded Borel functions f on Ω with norm $\|f\|_\infty$, where we write $\|f\|_\infty = \sup_\Omega |f|$. I denotes a fixed finite interval, with length $|I| > 0$, and also the identity operator on a given space.

Throughout this paper we fix positive numbers κ_0, κ_1 , with $\kappa_0 < \kappa_1$, and assume that k is a Borel function on $I \times I$ such that $\kappa_0 \leq k(\xi, \eta) \leq \kappa_1$ for all $\xi, \eta \in I$.

Next we define the continuous linear operator $K : \mathcal{B}^\infty(I) \rightarrow \mathcal{B}^\infty(I)$ by

$$Kf(\xi) = \int_I k(\xi, \eta) f(\eta) d\eta \quad \text{for } \xi \in I.$$

We define \bar{k} by

$$\bar{k}(\xi) = \int_I k(\xi, \eta) d\eta \quad \text{for } \xi \in I$$

and define $C : \mathcal{B}^\infty(I) \rightarrow \mathcal{B}^\infty(I)$ and $L : \mathcal{B}^\infty(I) \rightarrow \mathcal{B}^\infty(I)$ by

$$Cf(\xi) = \bar{k}(\xi) f(\xi) \quad \text{for } \xi \in I$$

and

$$Lf(\xi) = \int_I \frac{k(\xi, \eta)}{\bar{k}(\xi)} f(\eta) d\eta \quad \text{for } \xi \in I.$$

We set

$$l(\xi, \eta) = \frac{k(\xi, \eta)}{\bar{k}(\xi)} \quad \text{for } \xi, \eta \in I.$$

By the Fredholm-Riesz-Schauder theory, there exists a unique function $r \in \mathcal{B}^\infty(I)$ such that

$$\int_I r(\xi) l(\xi, \eta) d\xi = r(\eta) \quad \text{for all } \eta \in I, \quad (2.1)$$

$$\int_I r(\xi) d\xi = 1. \quad (2.2)$$

Moreover, by the Perron-Frobenius theory, we see that $r(\xi) > 0$ for all $\xi \in I$. Then by (2.1) we see that

$$\frac{\kappa_0}{\kappa_1 |I|} \leq r(\xi) \leq \frac{\kappa_1}{\kappa_0 |I|} \quad \text{for } \xi \in I. \quad (2.3)$$

We define \bar{r} by

$$\bar{r}(\xi) = \frac{r(\xi)}{\bar{k}(\xi)} / \int_I \frac{r(\eta)}{\bar{k}(\eta)} d\eta \quad \text{for } \xi \in I.$$

Then from (2.3) we have

$$\frac{\kappa_0^3}{\kappa_1^3|I|} \leq \bar{r}(\xi) \leq \frac{\kappa_1^3}{\kappa_0^3|I|} \quad \text{for } \xi \in I. \quad (2.4)$$

For any integrable function $h : I \rightarrow \mathbf{R}$, we define

$$\{h\}^{\perp, \infty} = \{f \in \mathcal{B}^\infty(I) \mid \int_I h(\xi)f(\xi)d\xi = 0\}.$$

Since $\text{Im}(K - C) \subset \{\bar{r}\}^{\perp, \infty}$, we may regard $K - C$ as an operator from $\{\bar{r}\}^{\perp, \infty}$ into $\{\bar{r}\}^{\perp, \infty}$. Observe that the bounded linear operator $L - I : \{r\}^{\perp, \infty} \rightarrow \{1\}^{\perp, \infty}$ is invertible, where $1(\xi) = 1$ for all $\xi \in I$. Consequently, $K - C$ is invertible. We denote this inverse operator by $(K - C)^{-1}$.

Before we give the definition of viscosity solutions of

$$F(x, u(x, \xi), D_x u(x, \xi), \xi) = \int_I k(\xi, \eta)[u(x, \eta) - u(x, \xi)]d\eta \quad \text{for } (x, \xi) \in \mathbf{R} \times I, \quad (\text{E})$$

where F is Borel measurable on $\mathbf{R}^n \times \mathbf{R} \times \mathbf{R}^n \times I$ such that for each $\xi \in I$ the function $F(\cdot, \xi)$ is continuous on $\mathbf{R}^n \times \mathbf{R} \times \mathbf{R}^n$, we introduce the notation. We denote by $\mathcal{U}^+(\mathbf{R}^n \times I)$ the set of those functions u on $\mathbf{R}^n \times I$ such that for each $x \in \mathbf{R}^n$ the function $u(x, \cdot)$ is Borel measurable and integrable in I and for each $\xi \in I$ the function $u(\cdot, \xi)$ is upper semicontinuous in \mathbf{R}^n . We set $\mathcal{U}^-(\mathbf{R}^n \times I) = -\mathcal{U}^+(\mathbf{R}^n \times I)$. For any $\Omega \subset \mathbf{R}^n$, $C(\Omega) \otimes \mathcal{B}(I)$ denotes the set of functions f on $\Omega \times I$ such that for each $x \in \Omega$ the function $f(x, \cdot)$ is Borel measurable in I and for each $\xi \in I$ the function $f(\cdot, \xi)$ is continuous in Ω . We call a continuous function $\omega : [0, \infty) \rightarrow [0, \infty)$ a modulus if ω is non-decreasing in $[0, \infty)$ and $\omega(0) = 0$.

Definition. (i) We call $u \in \mathcal{U}^+(\mathbf{R}^n \times I)$ a viscosity subsolution of (E) if whenever $\varphi \in C^1(\mathbf{R}^n)$, $\xi \in I$, and $u(\cdot, \xi) - \varphi$ attains its local maximum at \hat{x} , then

$$F(\hat{x}, u(\hat{x}, \xi), D\varphi(\hat{x}), \xi) \leq \int_I k(\xi, \eta)[u(\hat{x}, \eta) - u(\hat{x}, \xi)]d\eta.$$

(ii) We call $u \in \mathcal{U}^-(\mathbf{R}^n \times I)$ a viscosity supersolution of (E) if whenever $\varphi \in C^1(\mathbf{R}^n)$, $\xi \in I$, and $u(\cdot, \xi) - \varphi$ attains its local minimum at \hat{x} , then

$$F(\hat{x}, u(\hat{x}, \xi), D\varphi(\hat{x}), \xi) \geq \int_I k(\xi, \eta)[u(\hat{x}, \eta) - u(\hat{x}, \xi)]d\eta.$$

(iii) We call $u \in C(\mathbf{R}^n) \otimes \mathcal{B}(I)$ a viscosity solution of (E) if it is both a viscosity sub- and supersolution of (E).

3. Three cell problems

We begin this section by giving our assumptions on H .

(A1) $H \in C(\mathbf{R}^{2n}) \otimes \mathcal{B}(I)$.

(A2) $\lim_{R \rightarrow \infty} \inf \{H(x, p, \xi) \mid x, p \in \mathbf{R}^n, \xi \in I, |p| \geq R\} = \infty$.

(A3) For each $R > 0$ the family $\{H(\cdot + z, \cdot, \cdot) \mid z \in \mathbf{R}^n\}$ of functions is relatively compact in $\mathcal{A}(\mathbf{R}^n \times B(0, R) \times I)$, where $\mathcal{A}(\mathbf{R}^n \times B(0, R) \times I)$ denotes the set of functions $f \in C(\mathbf{R}^n \times B(0, R)) \otimes \mathcal{B}(I)$, with norm $\|\cdot\|_{\mathcal{A}(\mathbf{R}^n \times B(0, R) \times I)} := \sup_{\mathbf{R}^n \times B(0, R) \times I} |\cdot|$, which satisfy for a modulus μ_R and a positive constant M_R ,

$$\begin{aligned} |f(x, p, \xi) - f(y, q, \xi)| &\leq \mu_R(|x - y| + |p - q|), \quad |f(x, p, \xi)| \leq M_R \\ &\text{for all } x, y \in \mathbf{R}^n, p, q \in B(0, R), \xi \in I, \end{aligned} \quad (\#)$$

where $B(0, R)$ denotes the closed ball of \mathbf{R}^n with radius R centered at the origin.

(A4) The family $\{H(\cdot + z, \cdot, \cdot) \mid z \in \mathbf{R}^n\}$ of functions is subset of $\mathcal{A}(\mathbf{R}^{2n} \times I)$, where $\mathcal{A}(\mathbf{R}^{2n} \times I)$ denotes the set of functions $f \in C(\mathbf{R}^{2n}) \otimes \mathcal{B}(I)$ such that for each $R > 0$ there exist a modulus μ_R and a positive constant M_R for which condition (#) is satisfied. Moreover, for every sequence $\{z_j\} \subset \mathbf{R}^n$ there are a subsequence $\{z_{j_k}\} \subset \{z_j\}$ and a function $\tilde{H} \in \mathcal{A}(\mathbf{R}^{2n} \times I)$ such that

$$\lim_{k \rightarrow \infty} \sup_{(x, p, \xi) \in \mathbf{R}^n \times \mathbf{R}^n \times I} |H(x + z_{j_k}, p, \xi) - \tilde{H}(x, p, \xi)| = 0.$$

Assumptions (A3) and (A4) relate to the almost periodic homogenization. Note that (A4) is a stronger condition than (A3).

Example. We consider the function $H(x, p, \xi) = b(\xi)|p|^m + f(x)$, where $m > 0$, $b \in \mathcal{B}^\infty(I)$ is positive, and $f \in C(\mathbf{R}^n)$ is almost periodic. Then the function H satisfies (A1), (A2) and (A4).

Theorem 3.1. *Assume that (A1)-(A3) hold. Let $\hat{p} \in \mathbf{R}^n$. There is a unique constant $\lambda \in \mathbf{R}$ such that for each $\theta > 0$ there is a bounded and Lipschitz continuous viscosity solution v of*

$$\begin{cases} \int_I \bar{r}(\eta) H(x, \hat{p} + Dv(x), \eta) d\eta \leq \lambda + \theta \text{ for } x \in \mathbf{R}^n, \\ \int_I \bar{r}(\eta) H(x, \hat{p} + Dv(x), \eta) d\eta \geq \lambda - \theta \text{ for } x \in \mathbf{R}^n. \end{cases}$$

The problem of finding a constant λ described in the above theorem is a type of the so-called ergodic problem. We adapted here the formulation of Arisawa[2].

We can define the effective function $\bar{H}_0 : \mathbf{R}^n \rightarrow \mathbf{R}$ by setting $\bar{H}_0(\hat{p}) = \lambda$, where λ is the constant given by Theorem 3.1.

Proposition 3.2. *\bar{H}_0 is continuous on \mathbf{R}^n .*

We refer to [8] for a proof of Theorem 3.1 and Proposition 3.2.

Theorem 3.3. *Assume that (A1), (A2) and (A4) hold. Let $\hat{p} \in \mathbf{R}^n$ and $\gamma > 0$. There is a unique constant $\lambda_\gamma \in \mathbf{R}$ such that for each $\theta > 0$ there is a bounded viscosity solution*

$v \in C(\mathbf{R}^n) \otimes \mathcal{B}(I)$ of

$$\begin{cases} H(x, \hat{p} + D_x v(x, \xi), \xi) \leq \lambda_\gamma + \theta + \frac{1}{\gamma} \int_I k(\xi, \eta) [v(x, \eta) - v(x, \xi)] d\eta \\ \quad \text{for } (x, \xi) \in \mathbf{R}^n \times I, \\ H(x, \hat{p} + D_x v(x, \xi), \xi) \geq \lambda_\gamma - \theta + \frac{1}{\gamma} \int_I k(\xi, \eta) [v(x, \eta) - v(x, \xi)] d\eta \\ \quad \text{for } (x, \xi) \in \mathbf{R}^n \times I. \end{cases}$$

Here we define $\bar{H}_\gamma : \mathbf{R}^n \rightarrow \mathbf{R}$ by setting $\bar{H}_\gamma(\hat{p}) = \lambda_\gamma$, where λ_γ is the constant given by Theorem 3.3.

Proposition 3.4. \bar{H}_γ is continuous on \mathbf{R}^n .

Theorem 3.5. Assume that (A1)-(A3) hold. Let $p \in \mathbf{R}^n$. There is a unique function $\lambda \in \mathcal{B}^\infty(I)$ such that for each $\theta > 0$ there is a bounded viscosity solution $v \in C(\mathbf{R}^n) \otimes \mathcal{B}(I)$ of

$$\begin{cases} H(x, \hat{p} + D_x v(x, \xi), \xi) \leq \lambda(\xi) + h(\xi) & \text{for } (x, \xi) \in \mathbf{R}^n \times I, \\ H(x, \hat{p} + D_x v(x, \xi), \xi) \geq \lambda(\xi) - h(\xi) & \text{for } (x, \xi) \in \mathbf{R}^n \times I, \end{cases}$$

for all $(x, \xi) \in \mathbf{R}^n \times I$, where $h \in \mathcal{B}^\infty(I)$ and h satisfies $\int_I |h(\eta)| d\eta \leq \theta$.

Here we define $\bar{H}_\infty : \mathbf{R}^n \times I \rightarrow \mathbf{R}$ by setting $\bar{H}_\infty(\hat{p}, \xi) = \lambda(\xi)$, where λ is the function given by Theorem 3.5.

Proposition 3.6. $\bar{H}_\infty \in C(\mathbf{R}^n) \otimes \mathcal{B}(I)$. Moreover, for each $R > 0$ there is a modulus ω_R such that

$$|\bar{H}_\infty(p, \xi) - \bar{H}_\infty(q, \xi)| \leq \omega_R(|p - q|) \quad \text{for all } p, q \in B(0, R), \xi \in I.$$

4. Convergence theorems

We state uniqueness and existence results for $(E)_\varepsilon$.

Theorem 4.1. Assume that (A1)-(A3) hold. Let $\varepsilon > 0$. There is a unique bounded viscosity solution $u^\varepsilon \in C(\mathbf{R}^n) \otimes \mathcal{B}(I)$ of $(E)_\varepsilon$.

Consult sections 3 and 4 of [9] for the proof of Theorem 4.1. However, note that the equations considered in [9] are slightly different from $(E)_\varepsilon$.

Theorem 4.2. Assume that (A1)-(A3) hold and that $\lim_{\varepsilon \rightarrow 0} \delta(\varepsilon)/\varepsilon = 0$. Let u^ε be the bounded viscosity solution of $(E)_\varepsilon$ and u be the (unique) bounded viscosity solution of

$$u(x) + \bar{H}_0(Du(x)) = 0 \quad \text{for } x \in \mathbf{R}^n. \quad (\text{LE})_0$$

Then

$$\limsup_{\varepsilon \searrow 0} \{ |u^\varepsilon(x, \xi) - u(x)| \mid x \in \mathbf{R}^n, \xi \in I \} = 0.$$

Theorem 4.3. Assume that (A1), (A2) and (A4) hold and that

$$\lim_{\varepsilon \rightarrow 0} \frac{\delta(\varepsilon)}{\varepsilon} = \gamma \in (0, \infty).$$

Let u^ε be the bounded viscosity solution of $(E)_\varepsilon$ and u be the bounded viscosity solution of

$$u(x) + \bar{H}_\gamma(Du(x)) = 0 \quad \text{for } x \in \mathbf{R}^n. \quad (\text{LE})_\gamma$$

Then

$$\limsup_{\varepsilon \searrow 0} \{|u^\varepsilon(x, \xi) - u(x)| \mid x \in \mathbf{R}^n, \xi \in I\} = 0.$$

Theorem 4.4. Assume that (A1)-(A3) hold and that $\lim_{\varepsilon \rightarrow 0} \delta(\varepsilon)/\varepsilon = \infty$. Let u^ε be the bounded viscosity solution of $(E)_\varepsilon$ and u be the bounded viscosity solution of

$$u(x) + \int_I \bar{r}(\eta) \bar{H}_\infty(Du(x), \eta) d\eta = 0 \quad \text{for } x \in \mathbf{R}^n. \quad (\text{LE})_\infty$$

Then

$$\limsup_{\varepsilon \searrow 0} \{|u^\varepsilon(x, \xi) - u(x)| \mid x \in \mathbf{R}^n, \xi \in I\} = 0.$$

5. Functional first-order PDE with two parameters

In this section we consider the functional PDE with two parameters:

$$u^{\varepsilon, \delta}(x, \xi) + H\left(\frac{x}{\varepsilon}, Du^{\varepsilon, \delta}(x, \xi), \xi\right) = \frac{1}{\delta} \int_I k(\xi, \eta) [u^{\varepsilon, \delta}(x, \eta) - u^{\varepsilon, \delta}(x, \xi)] d\eta \quad (\text{E})_{\varepsilon, \delta}$$

for $(x, \xi) \in \mathbf{R}^n \times I$,

where ε and δ are positive parameters.

We give a result for the existence and uniqueness of viscosity solution of $(E)_{\varepsilon, \delta}$ without proving it. (See Theorem 4.1.)

Theorem 5.1. Assume that (A1)-(A3) hold. Let $\varepsilon, \delta > 0$. There is a unique bounded viscosity solution $u^{\varepsilon, \delta} \in C(\mathbf{R}^n) \otimes \mathcal{B}(I)$ of $(E)_{\varepsilon, \delta}$.

We consider the asymptotic behavior of the viscosity solution of $(E)_{\varepsilon, \delta}$, as $\delta \searrow 0$, and then $\varepsilon \searrow 0$ or $\varepsilon \searrow 0$, and then $\delta \searrow 0$. We state a main theorem of this section.

Theorem 5.2. Assume that (A1)-(A3) hold.

(i) If u is a bounded viscosity solution of $(\text{LE})_0$, then

$$u(x) = \lim_{\varepsilon \searrow 0} \lim_{\delta \searrow 0} u^{\varepsilon, \delta}(x, \xi) \quad \text{for } (x, \xi) \in \mathbf{R}^n \times I.$$

(ii) If u is a bounded viscosity solution of $(LE)_\infty$, then

$$u(x) = \lim_{\varepsilon \searrow 0} \lim_{\delta \searrow 0} u^{\varepsilon, \delta}(x, \xi) \quad \text{for } (x, \xi) \in \mathbf{R}^n \times I.$$

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