

# Projective Differential Geometry of Non-Developable Surfaces. II.

By

**Jôyô Kanitani.**

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## CHAPTER. III.

### RECIPROCAL LINES.

1. Consider points

$$\left. \begin{aligned}
 \rho &= \frac{\partial x}{\partial u} + ax, \\
 \sigma &= \frac{\partial x}{\partial v} + \beta x, \\
 y &= D\sigma - D'\rho, \\
 z &= D'\sigma - D''\rho, \\
 \tau &= \frac{1}{2} \left\{ \frac{\partial y}{\partial v} - \frac{\partial z}{\partial v} + \beta y - az \right\} + \gamma x,
 \end{aligned} \right\} (1)$$

where  $a, \beta, \gamma$  are analytic functions of  $u, v$  in the domain  $R$ .

The points  $\rho, \sigma, y$  and  $z$  are on the tangent plane of the given surface at the point  $x$ .

From (1) we have

$$| x \rho \sigma \tau | = -1.$$

Therefore, the points  $x, \rho, \sigma, \tau$  are not coplanar. In other words, the point  $\tau$  does not lie on the tangent plane at  $x$ .

By the same method as in **chap. II.** we can see that  $(x_i, y_i, z_i, \tau_i)$  ( $i=1, 2, 3, 4$ ) are four independent systems of the solutions of the completely integrable system of the linear partial differential equations

$$\begin{aligned}
\frac{\partial x}{\partial u} &= -D'y + Dz - ax, \\
\frac{\partial x}{\partial v} &= -D''y + D'z - \beta x, \\
\frac{\partial y}{\partial u} &= \left\{ D'(B - \frac{\partial D}{\partial v} + D'a) - D(C'' - \frac{\partial D''}{\partial u} + D'\beta) \right\} y \\
&\quad - \left\{ D'(C - \frac{\partial D}{\partial u} + Da) - D(B - \frac{\partial D'}{\partial u} + D\beta) \right\} z - \mathfrak{A}_{\alpha, \beta} x, \\
\frac{\partial y}{\partial v} &= \tau + \left\{ D''(B - \frac{\partial D}{\partial v} + D'a) - D'(C'' - \frac{\partial D''}{\partial u} + D'\beta) \right\} y \\
&\quad - \left\{ D''(C - \frac{\partial D}{\partial u} + Da) - D'(B - \frac{\partial D'}{\partial u} + D\beta) \right\} z \\
&\quad - (\mathfrak{A}'_{\alpha, \beta} + \gamma)x, \\
\frac{\partial z}{\partial u} &= -\tau + \left\{ D'(C'' - \frac{\partial D'}{\partial v} + D''a) - D(B'' - \frac{\partial D''}{\partial v} + D''\beta) \right\} y \\
&\quad - \left\{ D'(B - \frac{\partial D}{\partial v} + D'a) - D(B - \frac{\partial D}{\partial u} + D'\beta) \right\} z \\
&\quad - (\mathfrak{A}''_{\alpha, \beta} - \gamma)x, \\
\frac{\partial z}{\partial v} &= \left\{ D''(C'' - \frac{\partial D'}{\partial v} + D''a) - D'(B'' - \frac{\partial D''}{\partial v} + D''\beta) \right\} y \\
&\quad - \left\{ D''(B - \frac{\partial D}{\partial v} + D'a) - D'(C'' - \frac{\partial D''}{\partial u} + D'\beta) \right\} z - \mathfrak{A}''_{\alpha, \beta} x, \\
\frac{\partial \tau}{\partial u} &= a\tau + (\mathfrak{A}_{\alpha, \beta} - \mathfrak{Q}_{\alpha, \beta})(D''y - D'z) \\
&\quad - (\mathfrak{A}'_{\alpha, \beta} - \mathfrak{Q}'_{\alpha, \beta} + \theta_{\alpha, \beta} + \gamma - \theta)(D'y - Dz) \\
&\quad - \left\{ \frac{\partial}{\partial v} \mathfrak{A}_{\alpha, \beta} - \frac{\partial}{\partial u} (\mathfrak{A}'_{\alpha, \beta} + \gamma) + \frac{1}{2} \left| \mathfrak{A}_{\alpha, \beta} D_u D \right| \right. \\
&\quad \left. - \left| \mathfrak{A}_{\alpha, \beta} \mathfrak{C} D \right| - \left( \frac{\partial a}{\partial v} - \frac{\partial \beta}{\partial u} \right) \left( \frac{1}{2} \frac{\partial D}{\partial v} - \frac{1}{2} \frac{\partial D'}{\partial u} \right. \right. \\
&\quad \left. \left. + D\beta - D'a \right) + 2\gamma a \right\} x, \\
\frac{\partial \tau}{\partial v} &= \beta\tau + (\mathfrak{A}'_{\alpha, \beta} - \mathfrak{Q}'_{\alpha, \beta} + \theta - \theta_{\alpha, \beta} - \gamma)(D''y - D'z) \\
&\quad - (\mathfrak{A}''_{\alpha, \beta} - \mathfrak{Q}''_{\alpha, \beta})(D'y - Dz) \\
&\quad - \left\{ \frac{\partial}{\partial v} (\mathfrak{A}'_{\alpha, \beta} - \gamma) - \frac{\partial}{\partial u} \mathfrak{A}''_{\alpha, \beta} + \frac{1}{2} \left| \mathfrak{A}_{\alpha, \beta} D_v D \right| \right. \\
&\quad \left. - \left| \mathfrak{A}_{\alpha, \beta} \mathfrak{B} D \right| - \left( \frac{\partial a}{\partial v} - \frac{\partial \beta}{\partial u} \right) \left( \frac{1}{2} \frac{\partial D'}{\partial v} - \frac{1}{2} \frac{\partial D''}{\partial u} \right. \right. \\
&\quad \left. \left. + D'\beta - D''a \right) + 2\gamma\beta \right\} x,
\end{aligned} \tag{2}$$

where

$$\begin{aligned} \mathfrak{X}_{\alpha,\beta} &= A + Ba - C\beta - D\left(\frac{\partial\beta}{\partial u} - a\beta\right) + D'\left(\frac{\partial a}{\partial u} - a^2\right), \\ \mathfrak{X}'_{\alpha,\beta} &= A' + B'a - C - \frac{1}{2}D\left(\frac{\partial\beta}{\partial v} - \beta^2\right) + \frac{1}{2}D''\left(\frac{\partial a}{\partial u} - a^2\right) \\ &\quad + \frac{1}{2}D'\left(\frac{\partial a}{\partial v} - \frac{\partial\beta}{\partial u}\right), \\ \mathfrak{X}''_{\alpha,\beta} &= A'' + B''a - C''\beta - D'\left(\frac{\partial\beta}{\partial v} - \beta^2\right) + D''\left(\frac{\partial a}{\partial v} - a\beta\right), \\ \mathfrak{X}_{\alpha,\beta} &= L + 2\mathfrak{B}a - 2\mathfrak{C}\beta, \\ \mathfrak{X}'_{\alpha,\beta} &= L' + 2\mathfrak{B}'a - 2\mathfrak{C}'\beta, \\ \mathfrak{X}''_{\alpha,\beta} &= L'' + 2\mathfrak{B}''a - 2\mathfrak{C}''\beta, \\ \theta_{\alpha,\beta} &= \frac{1}{2}\frac{\partial^2 D}{\partial v^2} - \frac{\partial^2 D'}{\partial u\partial v} + \frac{1}{2}\frac{\partial^2 D''}{\partial u^2} - \frac{1}{4}\left|D_u \ D_v \ D\right| + \frac{\partial}{\partial v}(D\beta - D'a) \\ &\quad - \frac{\partial}{\partial u}(D'\beta - D''a). \end{aligned}$$

In virtue of (1), higher derivatives of  $x$  may be expressed by linear functions of  $x, y, z, \tau$ .

Let

$$\frac{\partial^{i+j}x}{\partial u^i\partial v^j} = p_{ij}\tau + q_{ij}y + r_{ij}z + s_{ij}x.$$

Then we have from (1)

$$\begin{aligned} p_{20} &= -D, \quad p_{11} = -D', \quad p_{20} = -D'', \\ q_{20} &= -(2C' - B - D\beta), \\ r_{20} &= C - Da, \\ q_{11} &= -(C'' - D'\beta), \\ r_{11} &= (B - D'a), \\ q_{02} &= -(B'' - D''\beta), \\ r_{02} &= (2B' - C'' - D''a), \\ s_{20} &= D'\mathfrak{X}_{\alpha,\beta} - D\left(\mathfrak{X}'_{\alpha,\beta} - \gamma\right) - \frac{\partial a}{\partial u} + a^2, \\ s_{11} &= \frac{1}{2}\left(D''\mathfrak{X}_{\alpha,\beta} - D\mathfrak{X}''_{\alpha,\beta} - \frac{\partial a}{\partial v} - \frac{\partial\beta}{\partial u} + 2a\beta + 2D'\gamma\right), \end{aligned}$$

$$\begin{aligned}
s_{02} &= D'' \left( \mathfrak{A}'_{\alpha, \beta} + \gamma \right) - D' \mathfrak{A}''_{\alpha, \beta} - \frac{\partial \beta}{\partial v} + \beta^2, \\
p_{30} &= - \left( C + \frac{\partial D}{\partial u} \right), \\
p_{21} &= - \left( B + \frac{\partial D'}{\partial v} \right), \\
F_{12} &= - \left( C'' + \frac{\partial D'}{\partial v} \right), \\
F_{03} &= - \left( B'' + \frac{\partial D''}{\partial v} \right), \\
q_{30} &= \frac{\partial}{\partial u} \left( p_{21} + \frac{\partial D}{\partial v} \right) - \beta p_{30} + 2q_{20} (\mathfrak{B} D' - L \mathfrak{C}'') + 2r_{20} (\mathfrak{B} D'' - \mathfrak{C}'' D') \\
&\quad - D D' (\theta - \theta_{\alpha, \beta} - 2\gamma) + D (D'' \mathfrak{Q}_{\alpha, \beta} - D' \mathfrak{Q}'_{\alpha, \beta}) - (D s_{11} + D' s_{20}) \\
&\quad - (D q_{20} q_{11} + D' q_{20} r_{11} + D' q_{11} r_{20} + D'' r_{20} r_{11}), \\
r_{30} &= - \frac{\partial}{\partial u} \left( p_{30} + \frac{\partial D}{\partial u} \right) + \alpha p_{30} + 2q_{20} (D \mathfrak{B} - D' \mathfrak{C}) \\
&\quad + 2r_{20} (D' \mathfrak{B} - \mathfrak{C} D'') + D^2 (\theta - \theta_{\alpha, \beta} - 2\gamma) - D (D' \mathfrak{Q}_{\alpha, \beta} - D \mathfrak{Q}'_{\alpha, \beta}) \\
&\quad + 2D s_{20} + D q_{20}^2 + 2D' q_{20} r_{20} + D'' r_{20}^2, \\
q_{21} &= \frac{\partial}{\partial v} \left( p_{21} + \frac{\partial D}{\partial v} \right) - \beta p_{21} + 2q_{20} (\mathfrak{C}'' D' - D \mathfrak{B}'') + 2r_{20} (\mathfrak{C}'' D'' \\
&\quad - D' \mathfrak{B}''') - D D'' (\theta - \theta_{\alpha, \beta} - 2\gamma) + D (D'' \mathfrak{Q}'_{\alpha, \beta} - D \mathfrak{Q}''_{\alpha, \beta}) \\
&\quad - (D'' s_{20} + D' s_{02}) - (D q_{20} q_{02} + D' q_{20} r_{02} + D' r_{20} q_{02} + D'' r_{20} r_{02}) \\
&= \frac{\partial}{\partial u} \left( p_{12} + \frac{\partial D'}{\partial v} \right) - \beta p_{21} + 2q_{11} (\mathfrak{B} D' - D \mathfrak{C}'') \\
&\quad + 2r_{11} (\mathfrak{B} D'' - D' \mathfrak{C}'') - D'^2 (\theta - \theta_{\alpha, \beta} - 2\gamma) + D' (D'' \mathfrak{Q}_{\alpha, \beta} - D' \mathfrak{Q}'_{\alpha, \beta}) \\
&\quad - 2D' s_{11} - (D q_{11}^2 + 2D' q_{11} r_{11} + D'' r_{11}^2), \\
r_{21} &= - \frac{\partial}{\partial v} \left( p_{30} + \frac{\partial D}{\partial u} \right) + \alpha p_{12} + 2q_{20} (L \mathfrak{C}'' - D' \mathfrak{B}) + 2r_{20} (D' \mathfrak{C}'' \\
&\quad - D'' \mathfrak{B}) + D D' (\theta - \theta_{\alpha, \beta} - 2\gamma) - D (D' \mathfrak{Q}'_{\alpha, \beta} - D \mathfrak{Q}''_{\alpha, \beta}) \\
&\quad + D' s_{20} + D s_{11} + D q_{20} q_{11} + D' q_{20} r_{11} + D' q_{11} r_{20} + D'' r_{11} r_{20}, \\
q_{12} &= \frac{\partial}{\partial u} \left( F_{03} + \frac{\partial D''}{\partial v} \right) - \beta p_{12} + 2q_{02} (D' \mathfrak{B} - D \mathfrak{C}'') + r_{02} (D'' \mathfrak{B} - D' \mathfrak{C}'') \\
&\quad - D' D'' (\theta - \theta_{\alpha, \beta} - 2\gamma) + L'' (D'' \mathfrak{Q}_{\alpha, \beta} - D' \mathfrak{Q}'_{\alpha, \beta}) \\
&\quad - (D' s_{02} + D'' s_{11}) - (D q_{11} q_{02} + D' r_{11} q_{02} + D' q_{11} r_{02} + D'' r_{11} r_{02}),
\end{aligned} \tag{3}$$

$$\begin{aligned}
 r_{12} &= -\frac{\partial}{\partial u} \left( p_{12} + \frac{\partial D''}{\partial u} \right) + \alpha p_{12} + 2q_{02} (D\mathfrak{B} - D'\mathfrak{C}) + 2r_{02} (D'\mathfrak{B} \\
 &\quad - D''\mathfrak{C}'') + D D'' (\theta - \theta_{\alpha,\beta} - 2\gamma) - D'' (D\mathfrak{L}'_{\alpha,\beta} - D\mathfrak{L}''_{\alpha,\beta}) \\
 &\quad + (D s_{02} + D'' s_{20}) + D q_{20} q_{02} + D' q_{02} r_{20} + D' q_{20} r_{02} + D'' q_{20} r_{20} \\
 &= -\frac{\partial}{\partial v} \left( p_{21} + \frac{\partial D'}{\partial v} \right) + \alpha p_{12} + 2q_{11} (D\mathfrak{C}'' - D'\mathfrak{B}) + 2r_{11} (D'\mathfrak{C}'' \\
 &\quad - D''\mathfrak{B}) + D'^2 (\theta - \theta_{\alpha,\beta} - 2\gamma) - D' (D' \mathfrak{L}'_{\alpha,\beta} - D\mathfrak{L}''_{\alpha,\beta}) \\
 &\quad + 2D' s_{11} + D q_{11}^2 + 2D' q_{11} r_{11} + D'' r_{11}^2, \\
 q_{03} &= \frac{\partial}{\partial v} \left( p_{03} + \frac{\partial D''}{\partial v} \right) - \beta p_{03} + q_{02} (D'\mathfrak{C}'' - D\mathfrak{B}'') + 2r_{02} (D'' \mathfrak{C}'' \\
 &\quad - D'\mathfrak{B}'') - D''^2 (\theta - \theta_{\alpha,\beta} - 2\gamma) + D'' (D'' \mathfrak{L}'_{\alpha,\beta} - D' \mathfrak{L}''_{\alpha,\beta}) \\
 &\quad - 2D'' s_{02} - (D q_{02}^2 + 2D' q_{02} r_{02} + D'' r_{02}^2), \\
 r_{03} &= -\frac{\partial}{\partial v} \left( p_{12} + \frac{\partial D''}{\partial v} \right) + \alpha p_{03} + 2q_{02} (D\mathfrak{C}'' - D'\mathfrak{B}) + 2r_{02} (D'\mathfrak{C}'' \\
 &\quad - D''\mathfrak{B}) + D' D'' (\theta - \theta_{\alpha,\beta} - 2\gamma) - D'' (D' \mathfrak{L}'_{\alpha,\beta} - D\mathfrak{L}''_{\alpha,\beta}) \\
 &\quad + D' s_{02} + D'' s_{11} + D q_{11} q_{02} + D' r_{11} q_{02} + D' r_{02} r_{11} + D'' r_{11} r_{02}, \\
 p_{40} &= \frac{\partial}{\partial u} p_{30} + \alpha p_{30} - r_{30}, \\
 p_{31} &= \frac{\partial}{\partial v} p_{30} + \beta p_{30} + q_{30}, \\
 p_{22} &= \frac{\partial}{\partial v} p_{21} + \beta p_{21} + q_{21}, \\
 p_{13} &= \frac{\partial}{\partial u} p_{03} + \alpha p_{03} - r_{03}, \\
 p_{04} &= \frac{\partial}{\partial v} p_{03} + \beta p_{03} + q_{03}.
 \end{aligned}$$

In the vicinity of a point  $(u, v)$  in the domain  $R$ , we have

$$\begin{aligned}
 x(u+du, v+dv) &= x(u, v) + \left( du \frac{\partial}{\partial u} + dv \frac{\partial}{\partial v} \right) x(u, v) \\
 &\quad + \frac{1}{2} \left( du \frac{\partial}{\partial u} + dv \frac{\partial}{\partial v} \right)^2 x(u, v) \\
 &\quad + \frac{1}{6} \left( du \frac{\partial}{\partial u} + dv \frac{\partial}{\partial v} \right)^3 x(u, v) \\
 &\quad + \frac{1}{24} \left( du \frac{\partial}{\partial u} + dv \frac{\partial}{\partial v} \right)^4 x(u, v) \\
 &\quad + \dots
 \end{aligned}$$

$$\begin{aligned}
&= x \left[ 1 - \kappa + \frac{1}{2} \left\{ \begin{matrix} s \\ 2 \end{matrix} \right\} + \dots \right] \\
&+ y \left[ -D' du - D'' dv + \frac{1}{2} \left\{ \begin{matrix} q \\ 2 \end{matrix} \right\} + \frac{1}{6} \left\{ \begin{matrix} q \\ 3 \end{matrix} \right\} + \dots \right] \\
&+ z \left[ D du + D' dv + \frac{1}{2} \left\{ \begin{matrix} r \\ 2 \end{matrix} \right\} + \frac{1}{2} \left\{ \begin{matrix} r \\ 3 \end{matrix} \right\} + \dots \right] \\
&+ \tau \left[ -\frac{1}{2} (D du^2 + 2D' du dv + D'' dv^2) + \frac{1}{6} \left\{ \begin{matrix} p \\ 3 \end{matrix} \right\} \right. \\
&\quad \left. + \frac{1}{24} \left\{ \begin{matrix} p \\ 4 \end{matrix} \right\} + \dots \right] \quad \left. \vphantom{\begin{matrix} p \\ 3 \end{matrix}} \right\} (3) \\
&= x \left[ 1 - \kappa + \frac{1}{2} \left\{ \begin{matrix} s \\ 2 \end{matrix} \right\} + \dots \right] \\
&+ \rho \left[ du - \frac{1}{2} (D' \left\{ \begin{matrix} q \\ 2 \end{matrix} \right\} + D'' \left\{ \begin{matrix} r \\ 2 \end{matrix} \right\}) - \frac{1}{6} (D' \left\{ \begin{matrix} q \\ 3 \end{matrix} \right\} + D'' \left\{ \begin{matrix} r \\ 3 \end{matrix} \right\}) \right. \\
&\quad \left. + \dots \right] \\
&+ \sigma \left[ dv + \frac{1}{2} (D \left\{ \begin{matrix} q \\ 2 \end{matrix} \right\} + D' \left\{ \begin{matrix} r \\ 2 \end{matrix} \right\}) + \frac{1}{6} (D \left\{ \begin{matrix} q \\ 2 \end{matrix} \right\} + D' \left\{ \begin{matrix} r \\ 3 \end{matrix} \right\}) \right. \\
&\quad \left. + \dots \right] \\
&+ \tau \left[ -\frac{1}{2} (D du^2 + 2D' du dv + D'' dv^2) + \frac{1}{6} \left\{ \begin{matrix} p \\ 3 \end{matrix} \right\} + \frac{1}{24} \left\{ \begin{matrix} p \\ 4 \end{matrix} \right\} \right. \\
&\quad \left. + \dots \right],
\end{aligned}$$

where

$$\kappa = \alpha du + \beta dv,$$

$$\left\{ \begin{matrix} p \\ n \end{matrix} \right\} = \sum_{i=0}^n {}_n C_i \rho_{n-i, i} du^{n-i} dv^i,$$

etc.

Let  $w_i$  ( $i=0, 1, 2, 3, 8$ ) be projective coordinates referred to the tetrahedron of reference with vertices at the points  $v, \rho, \sigma, \tau$ . In virtue of (4), projective coordinates of any point of the given surface in the vicinity of the point  $x$  ( $u, v$ ) referred to this tetrahedron of reference, are given by the equations

$$\left. \begin{aligned} w_0 &= 1 - \kappa + \frac{1}{2} \left\{ \frac{s}{2} \right\} + \dots\dots\dots, \\ w_1 &= du - \frac{1}{2} \left( D' \left\{ \frac{q}{2} \right\} + L'' \left\{ \frac{r}{2} \right\} \right) - \frac{1}{6} \left( L' \left\{ \frac{q}{3} \right\} + L'' \left\{ \frac{r}{3} \right\} \right) \\ &\quad + \dots\dots\dots, \\ w_2 &= dv + \frac{1}{2} \left( D \left\{ \frac{q}{2} \right\} + L' \left\{ \frac{r}{2} \right\} \right) + \frac{1}{6} \left( D \left\{ \frac{q}{3} \right\} + L' \left\{ \frac{r}{3} \right\} \right) \\ &\quad + \dots\dots\dots, \\ w_3 &= -\frac{1}{2} (Ddu^2 + 2L'du\,dv + D''dv^2) + \frac{1}{6} \left\{ \frac{p}{3} \right\} + \frac{1}{24} \left\{ \frac{p}{4} \right\} \\ &\quad + \dots\dots\dots, \end{aligned} \right\} (5)$$

if the unit point be properly chosen.

Let us now introduce non-homogeneous coordinates by putting

$$\xi = \frac{w_1}{w_0}, \quad \eta = \frac{w_2}{w_0}, \quad \zeta = \frac{w_3}{w_0}.$$

Then we have from (5)

$$\left. \begin{aligned} \xi &= du - \frac{1}{2} \left( L' \left\{ \frac{q}{2} \right\} + L'' \left\{ \frac{r}{2} \right\} \right) + \kappa du - \frac{1}{6} \left( D' \left\{ \frac{q}{3} \right\} + D'' \left\{ \frac{r}{3} \right\} \right) \\ &\quad - \frac{\kappa}{2} \left( L' \left\{ \frac{q}{2} \right\} + L'' \left\{ \frac{r}{2} \right\} \right) - du \left( \frac{1}{2} \left\{ \frac{s}{2} \right\} - \kappa^2 \right) + \dots\dots\dots, \\ \eta &= dv + \frac{1}{2} \left( D \left\{ \frac{q}{2} \right\} + L' \left\{ \frac{r}{2} \right\} \right) + \kappa dv + \frac{1}{6} \left( D \left\{ \frac{q}{3} \right\} + L' \left\{ \frac{r}{3} \right\} \right) \\ &\quad + \frac{\kappa}{2} \left( D \left\{ \frac{q}{2} \right\} + L' \left\{ \frac{r}{2} \right\} \right) - dv \left( \frac{1}{2} \left\{ \frac{s}{2} \right\} - \kappa^2 \right) + \dots\dots\dots, \\ \zeta &= -\frac{1}{2} (Ddu^2 + 2D'du\,dv + D''dv^2) + \frac{1}{6} \left\{ \frac{p}{3} \right\} - \frac{\kappa}{2} (Ddu^2 \\ &\quad + 2D'dudv + D''dv^2) + \frac{1}{24} \left\{ \frac{p}{4} \right\} + \frac{\kappa}{6} \left\{ \frac{p}{3} \right\} + \frac{1}{2} \left( \frac{1}{2} \left\{ \frac{s}{2} \right\} \right. \\ &\quad \left. - \kappa^2 \right) (Ddu^2 + 2D'dudv + D''dv^2) + \dots\dots\dots, \end{aligned} \right\} (6)$$

Therefore, we can develop  $\zeta$  in a power series of  $\xi, \eta$  of the form

$$\left. \begin{aligned} \zeta &= a_{20}\xi^2 + a_{11}\xi\eta + a_{02}\eta^2 \\ &+ a_{30}\xi^3 + a_{21}\xi^2\eta + a_{12}\xi\eta^2 + a_{03}\eta^3 \\ &+ a_{40}\xi^4 + a_{31}\xi^3\eta + a_{22}\xi^2\eta^2 + a_{13}\xi\eta^3 + a_{04}\eta^4 + \dots \end{aligned} \right\} (7)$$

Substituting the values of  $\xi, \eta, \zeta$  given by (6) in (7), and equating the coefficients of the terms of the same degree with respect to  $u$  and  $v$  in both sides of the resulting equation, we can determine the coefficients in (7).

First, comparing the terms of the second degree with respect to  $u$  and  $v$  in both sides of (7), we have

$$a_{20} = -\frac{D}{2}, \quad a_{11} = -D', \quad a_{02} = -\frac{D''}{2}.$$

Next, comparing the terms of the third degree with respect to  $u$  and  $v$  in both sides of (7), we have

$$\begin{aligned} a_{30}du^3 + a_{21}du^2dv + a_{12}dudv^2 + a_{03}dv^3 &= \frac{1}{6} \left( 3 \left\{ \begin{matrix} r \\ 2 \end{matrix} \right\} du - 3 \left\{ \begin{matrix} q \\ 2 \end{matrix} \right\} dv \right. \\ &\left. + \left\{ \begin{matrix} p \\ 3 \end{matrix} \right\} \right) + \frac{\kappa}{2} (Ddu^2 + 2D'dudv + D''dv^2). \end{aligned}$$

Therefore, in virtue of (3), we get

$$a_{30} = \frac{1}{3}\mathfrak{C}, \quad a_{21} = \mathfrak{B}, \quad a_{12} = \mathfrak{C}'', \quad a_{03} = \frac{1}{3}\mathfrak{B}''.$$

Finally, comparing the terms of the third degree with respect to  $u$  and  $v$  in both sides of (7), we have

$$\begin{aligned} &a_{40}du^4 + a_{31}du^3dv + a_{22}du^2dv^2 + a_{13}dudv^3 + a_{04}dv^4 \\ &= \frac{1}{24} \left( 4 \left\{ \begin{matrix} r \\ 3 \end{matrix} \right\} du - 4 \left\{ \begin{matrix} q \\ 3 \end{matrix} \right\} dv + \left\{ \begin{matrix} p \\ 4 \end{matrix} \right\} \right) \\ &- \frac{1}{4} \left\{ \begin{matrix} s \\ 2 \end{matrix} \right\} (Ddu^2 + 2D'dudv + D''dv^2) \\ &- \frac{1}{8} \left( D \left\{ \begin{matrix} q \\ 2 \end{matrix} \right\}^2 + 2D' \left\{ \begin{matrix} q \\ 2 \end{matrix} \right\} \left\{ \begin{matrix} r \\ 2 \end{matrix} \right\} + D'' \left\{ \begin{matrix} r \\ 2 \end{matrix} \right\}^2 \right) \\ &- \frac{\kappa}{6} \left[ \left\{ \begin{matrix} p \\ 3 \end{matrix} \right\} + 2(\mathfrak{C}du^3 + 3\mathfrak{B}du^2dv + 3\mathfrak{C}''dudv^2 + \mathfrak{B}''dv^3) \right] \end{aligned}$$



$$-\frac{1}{2}\left\{\frac{q}{2}\right\}\begin{vmatrix} D & \mathfrak{C} & dv^2 \\ D' & \mathfrak{C}' & -dudv \\ D'' & \mathfrak{C}'' & du \end{vmatrix} -\frac{1}{2}\left\{\frac{r}{2}\right\}\begin{vmatrix} D & \mathfrak{B} & dv^2 \\ D' & \mathfrak{B}' & -dudv \\ D'' & \mathfrak{B}'' & du^2 \end{vmatrix}.$$

In virtue of (3), the right hand side of this equation is equal to

$$\frac{1}{12}\left(dv\frac{\partial}{\partial u}+dv\frac{\partial}{\partial v}-4\kappa\right)\left(\mathfrak{C}du^3+3\mathfrak{B}du^2dv+3\mathfrak{C}''du^2dv+\mathfrak{B}''dv^3\right)$$

$$+\frac{1}{8}\left\{Ddu^2+2D'dudv+D''dv^2\right\}$$

$$\times\left\{\frac{\partial}{\partial v}\begin{vmatrix} D & \mathfrak{C} \\ D' & \mathfrak{C}' \end{vmatrix}du^2+\frac{\partial}{\partial v}\begin{vmatrix} D & \mathfrak{C} \\ D'' & \mathfrak{C}'' \end{vmatrix}dudv+\frac{\partial}{\partial v}\begin{vmatrix} D' & \mathfrak{C}' \\ D'' & \mathfrak{C}'' \end{vmatrix}dv^2\right.$$

$$\left.-\frac{\partial}{\partial u}\begin{vmatrix} D & \mathfrak{B} \\ D' & \mathfrak{B}' \end{vmatrix}du^2-\frac{\partial}{\partial u}\begin{vmatrix} D & \mathfrak{B} \\ D'' & \mathfrak{B}'' \end{vmatrix}dudv-\frac{\partial}{\partial u}\begin{vmatrix} D' & \mathfrak{B}' \\ D'' & \mathfrak{B}'' \end{vmatrix}dv^2\right\}$$

$$-\frac{1}{8}(\theta_{\alpha,\beta}+2\gamma)(Ddu^2+2D'dudv+D''dv^2)^2$$

$$-\frac{1}{8}\left\{\frac{\partial D}{\partial v}du^2+2\frac{\partial D'}{\partial v}dudv+\frac{\partial D''}{\partial v}dv^2\right\}\begin{vmatrix} D & \mathfrak{C} & dv^2 \\ D' & \mathfrak{C}' & -dudv \\ D'' & \mathfrak{C}'' & du^2 \end{vmatrix}$$

$$+\frac{1}{8}\left\{\frac{\partial D}{\partial u}du^2+2\frac{\partial D'}{\partial u}dudv+\frac{\partial D''}{\partial u}dv^2\right\}\begin{vmatrix} D & \mathfrak{B} & dv^2 \\ D' & \mathfrak{B}' & -dudv \\ D'' & \mathfrak{B}'' & du^2 \end{vmatrix}$$

$$+\frac{1}{4}\left\{Ddu^2+2D'dudv+D''dv^2\right\}\begin{vmatrix} D & \mathfrak{L}_{\alpha,\beta} & dv^2 \\ D' & \mathfrak{L}_{\alpha,\beta} & -dudv \\ D'' & \mathfrak{L}_{\alpha,\beta} & du^2 \end{vmatrix}.$$

Therefore, denoting  $\varphi_n$  the terms of n-th the degree with respect to  $\xi$  and  $\eta$  in the development of  $\zeta$ , we have

$$\begin{aligned}
 \varphi_2 &= -\frac{1}{2}(D\xi^2 + 2D'\xi\eta + D''\eta^2), \\
 \varphi_3 &= \frac{1}{3}(\mathfrak{C}\xi^3 + 3\mathfrak{B}\xi^2\eta + 3\mathfrak{C}''\xi\eta^2 + \mathfrak{B}''\eta^3), \\
 \varphi_4 &= \frac{1}{12}\left\{ \xi\left(\frac{\partial\mathfrak{C}}{\partial u}\xi^2 + 3\frac{\partial\mathfrak{B}}{\partial u}\xi^2\eta + 3\frac{\partial\mathfrak{C}''}{\partial u}\xi\eta^2 + \frac{\partial\mathfrak{B}''}{\partial u}\eta^3\right) \right. \\
 &\quad \left. \eta\left(\frac{\partial\mathfrak{C}}{\partial v}\xi^2 + 3\frac{\partial\mathfrak{B}}{\partial v}\xi^2\eta + 3\frac{\partial\mathfrak{C}''}{\partial v}\xi\eta^2 + \frac{\partial\mathfrak{B}''}{\partial v}\eta^3\right) \right\} \\
 &\quad - \frac{1}{3}(a\xi + \beta\eta)\varphi_3 - \frac{1}{2}(\theta_{\alpha,\beta} + 2\gamma)\varphi_2^2 \\
 &\quad - \frac{1}{4}\varphi_2 \left\{ \frac{\partial}{\partial v} \begin{vmatrix} D & \mathfrak{C} \\ D' & \mathfrak{C}' \end{vmatrix} \xi^2 + \frac{\partial}{\partial v} \begin{vmatrix} D & \mathfrak{C} \\ D'' & \mathfrak{C}'' \end{vmatrix} \xi\eta + \frac{\partial}{\partial v} \begin{vmatrix} D' & \mathfrak{C}' \\ D'' & \mathfrak{C}'' \end{vmatrix} \eta^2 \right. \\
 &\quad \left. - \frac{\partial}{\partial u} \begin{vmatrix} D & \mathfrak{B} \\ D' & \mathfrak{B}' \end{vmatrix} \xi^2 - \frac{\partial}{\partial u} \begin{vmatrix} D & \mathfrak{B} \\ D'' & \mathfrak{B}'' \end{vmatrix} \xi\eta - \frac{\partial}{\partial u} \begin{vmatrix} D' & \mathfrak{B}' \\ D'' & \mathfrak{B}'' \end{vmatrix} \eta^2 \right\} \quad (9) \\
 &\quad - \frac{1}{8} \left( \frac{\partial D}{\partial v} \xi^2 + 2 \frac{\partial D'}{\partial v} \xi\eta + \frac{\partial D''}{\partial v} \eta^2 \right) \begin{vmatrix} D & \mathfrak{C} & \eta^2 \\ D' & \mathfrak{C}' & -\xi\eta \\ D'' & \mathfrak{C}'' & \xi^2 \end{vmatrix} \\
 &\quad + \frac{1}{8} \left( \frac{\partial D}{\partial u} \xi^2 + 2 \frac{\partial D'}{\partial u} \xi\eta + \frac{\partial D''}{\partial u} \eta^2 \right) \begin{vmatrix} D & \mathfrak{B} & \eta^2 \\ D' & \mathfrak{B}' & -\xi\eta \\ D'' & \mathfrak{B}'' & \xi^2 \end{vmatrix} \\
 &\quad - \frac{1}{2} \varphi_2^2 \begin{vmatrix} D & \mathfrak{Q}_{\alpha,\beta} & \eta^2 \\ D' & \mathfrak{Q}'_{\alpha,\beta} & -\xi\eta \\ D'' & \mathfrak{Q}''_{\alpha,\beta} & \xi^2 \end{vmatrix}
 \end{aligned}$$

2. From (9) we can see that any quadric which has contact of the second order with the give surface at the point  $x$  is of the form

$$\zeta = \varphi_2 + \zeta(\lambda\xi + \mu\eta + \nu\zeta),$$

referring to the non-homogeneous coordinates introduced in n° 1, which give, for the development of  $\zeta$  to the terms of the fourth degree inclusive,

$$\zeta = \varphi_2 + \varphi_2(\lambda\xi + \mu\eta) + \varphi_2(\lambda\xi + \mu\eta)^2 + \nu\varphi_2^2.$$

The projection from the point  $\tau$  of the curve of the intersection of the  $\xi$ - $\eta$  plane, *i. e.*, the tangent plane at  $x$ , has for its equation

$$o = \varphi_3 - \varphi_2(\lambda\xi + \mu\eta) + \varphi_4 - \varphi_2(\lambda\xi + \mu\eta)^2 - \nu\varphi_2^2 + \dots$$

Hence this curve has a triple point at the origin and the tangents at this point are given by the equation

$$\varphi_3 - \varphi_2(\lambda\xi + \mu\eta) = 0.$$

For these three tangents to coincide,  $\lambda$  and  $\mu$  must satisfy the equation

$$\left. \begin{aligned} \frac{1}{3}(\mathfrak{C}k^3 + 3\mathfrak{B}k^2 + 3\mathfrak{C}''k + \mathfrak{B}'') + \frac{1}{2}(Dk^2 + 2D'k + D'')(\lambda k + \mu) &= 0, \\ \mathfrak{C}k^2 + 2\mathfrak{B}k + \mathfrak{C}'' + (Dk + D')(\lambda k + \mu) + \frac{1}{2}\lambda(Dk^2 + 2D'k + D'') &= 0, \\ \mathfrak{C}k + \mathfrak{B} + \frac{1}{2}D(\lambda k + \mu) + \lambda(Dk + D') &= 0, \end{aligned} \right\} (10)$$

where  $k = \frac{\xi}{y}$ .

The system of the equations (10) is equivalent to the system

$$\left. \begin{aligned} \mathfrak{C}k + \mathfrak{B} + \frac{1}{2}D(\lambda k + \mu) + \lambda(Dk + D') &= 0, \\ \mathfrak{B}k + \mathfrak{C}'' + \frac{1}{2}D'(\lambda k + \mu) + \frac{1}{2}\mu(Dk + D') + \frac{1}{2}\lambda(D'k + D'') &= 0, \\ \mathfrak{C}''k + \mathfrak{B}'' + \frac{1}{2}D''(\lambda k + \mu) + \mu(D'k + D'') &= 0. \end{aligned} \right\} (11)$$

Multiply the first equation (11) by  $D''$ , the second of it by  $-2D'$ , the third of it by  $D$ , and add them, then we have, in virtue of the equations (11) and (22) chap. 1,

$$(\lambda k + \mu) = 0.$$

Therefore the system (11) is equivalent to the system

$$\left. \begin{aligned} \mathfrak{C}k^3 + \mathfrak{B}k^2 - \mu k(Dk + D') &= 0, \\ 2\mathfrak{B}k^2 + 2\mathfrak{C}''k + \mu k(Dk + D') - \mu(D'k + D'') &= 0, \\ \mathfrak{C}'k + \mathfrak{B}'' + \mu(D'k + D'') &= 0. \end{aligned} \right\} (12)$$

From (12) we have

$$\mathfrak{C}k^3 + 3\mathfrak{B}k^2 + 3\mathfrak{C}'' + \mathfrak{B}'' = 0.$$

Therefore, we know that if the tangents at the triple point coincide, they must coincide with one of the tangents defined by the equation

$$\mathfrak{C}\xi^3 + 3\mathfrak{B}\xi^2\eta + 3\mathfrak{C}''\xi\eta^2 + \mathfrak{B}''\eta^3 = 0,$$

which are called *the tangents of the quadric osculation* by Darboux<sup>1</sup>. Hence the equation

$$\mathfrak{C}dx^3 + 3\mathfrak{B}lx^2dv + 3\mathfrak{C}''dudx^3 + \mathfrak{B}''d^3 = 0$$

gives the Darboux's *curve of the quadric osculation*.

3. If the tangents at the said triple point themselves are those of the quadric osculation,  $\lambda$  and  $\mu$  must be equal to zero. Therefore, the quadric  $Q$  given by the equation

$$\zeta = \varphi_2 + \nu\zeta^2 \dots \dots \dots (13)$$

has the following properties :—

1° It has contact of the second order with the given surface  $S$  at the point  $x$ , and accordingly, intersects with  $S$  at a curve of which the point  $x$  is a triple point.

2° The tangents of the curve of intersection of  $S$  and  $Q$  at the point  $x$  are those of the quadric osculation.

We shall call this quadric the *semi-canonical quadric*. From (13) we know that there are  $\infty^1$  semi-canonical quadrics at a point of  $S$ .

Referring to the homogeneous co-ordinates introduced in n°1, the equation of the semi-cononical quadric  $Q$  is

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<sup>1</sup> Bull. sci. math. Fr. ser. 2 vol. 4 p. 385 (1880).

$$w_3 w_0 = -\frac{1}{2}(Dw_1^2 + 2D'w_1w_2 + D''w_2^2) + \nu w_3^2.$$

The polar line of the point  $(o, a_1, a_2, o)$  with respect to Q is

$$(a_1D + a_2D')w' + (a_1D' + a_2D'')w_2 = 0$$

and that of the point  $(b_0, 0, 0, b_3)$  is

$$b_3w_0 + b_0w_3 - 2\nu b_3w_3 = 0.$$

Therefore either of the lines  $\rho \sigma$  and  $x \tau$  in the reciprocal polar of the other with respect to Q. We shall speak of the lines  $\rho \sigma$  and  $x \tau$  as the reciprocal line of the other.

4. When the point  $x$  moves on the given surface the lines  $\rho \sigma$  and  $x \tau$  form congruences which are called respectively the congruence  $\Gamma$  and the congruence  $\Gamma'$  by Green<sup>1</sup>.

The points  $y$  and  $z$  lie on the line  $\rho \sigma$ . Hence if the point  $x$  moves so that line  $\rho \sigma$  describes a developable surface, the points  $y, z, dy$  and  $dz$  necessarily lie in a plane ; accordingly, in virtue of (2),

$$\begin{vmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ dv & 0 & 0 & -\mathfrak{A}_{\alpha,\beta}du - (\mathfrak{A}'_{\alpha,\beta} + \gamma)dv \\ -du & 0 & 0 & -(\mathfrak{A}'_{\alpha,\beta} - \gamma)du - \mathfrak{A}''_{\alpha,\beta}dv \end{vmatrix} \\ = -(\mathfrak{A}_{\alpha,\beta}du^2 + 2\mathfrak{A}'_{\alpha,\beta}dudv + \mathfrak{A}''_{\alpha,\beta}dv^2) = 0 \dots \dots (14)$$

Therefore the net of curves given by (14) corresponds to the developable surfaces of the congruence  $\Gamma$ .

The necessary and sufficient condition that this net may form a conjugate net is

$$D\mathfrak{A}''_{\alpha,\beta} - 2D'\mathfrak{A}'_{\alpha,\beta} + D''\mathfrak{A}_{\alpha,\beta} = -\left(\frac{\partial a}{\partial v} - \frac{\partial \beta}{\partial u}\right) = 0,$$

or

$$\frac{\partial a}{\partial u} = \frac{\partial \beta}{\partial v}.$$

<sup>1</sup> Trans. Amer Math. Soc 20, p. 79.

5. Let the point

$$\phi = y + \lambda z$$

be one of the focal points on the line  $\rho \sigma$ .

Then all the surfaces of the congruence  $I$  which contain the line  $\rho \sigma$  have the tangent plane at  $\phi$  common. In other words the points  $\left(y, z, \frac{\partial \phi}{\partial u}, \frac{\partial \phi}{\partial v}\right)$ , and accordingly, in virtue of (2), the points

$$\begin{aligned} & y, \quad z, \\ & \lambda \tau - \left\{ \mathfrak{A}_{\alpha, \beta} + \lambda (\mathfrak{A}'_{\alpha, \beta} + \gamma) \right\} x, \\ & -\tau - \left\{ (\mathfrak{A}_{\alpha, \beta} - \gamma) + \lambda \mathfrak{A}''_{\alpha, \beta} \right\} x \end{aligned}$$

must be coplanar. Therefore,  $\lambda$  must satisfy the equation

$$\begin{vmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \lambda & 0 & 0 & \mathfrak{A}_{\alpha, \beta} - \lambda (\mathfrak{A}'_{\alpha, \beta} + \gamma) \\ -1 & 0 & 0 & -(\mathfrak{A}'_{\alpha, \beta} - \lambda \gamma) - \lambda \mathfrak{A}''_{\alpha, \beta} \end{vmatrix} = 0,$$

or

$$\lambda^2 \mathfrak{A}''_{\alpha, \beta} + 2\lambda \mathfrak{A}_{\alpha, \beta} + \mathfrak{A}_{\alpha, \beta} = 0,$$

6. If the point  $x$  moves so that line  $x \tau$  describes a developable surface of the congruence  $I'$ , the points  $x, \tau, dx$  and  $d\tau$  and accordingly, in virtue of (2) the points

$$\left. \begin{aligned} & x, \quad \tau, \quad \rho du + \sigma dv, \\ & \left\{ (\mathfrak{A}'_{\alpha, \beta} - \mathfrak{Q}'_{\alpha, \beta}) du + (\mathfrak{A}''_{\alpha, \beta} - \mathfrak{Q}''_{\alpha, \beta}) dv \right\} \rho \\ & - \left\{ (\mathfrak{A}_{\alpha, \beta} - \mathfrak{Q}_{\alpha, \beta}) du - (\mathfrak{A}'_{\alpha, \beta} - \mathfrak{Q}'_{\alpha, \beta}) dv \right\} \sigma \end{aligned} \right\} (15)$$

must be coplanar. But the points  $x, \rho, \sigma, \tau$  are not coplanar. Therefore, the last two points of (15) must coincide with the point of the intersection of the line  $\rho \sigma$  and the plane on which points (15) lie. Accordingly, we must have

$$(\mathfrak{A}_{\alpha, \beta} - \mathfrak{Q}_{\alpha, \beta}) du^2 + 2(\mathfrak{A}'_{\alpha, \beta} - \mathfrak{Q}'_{\alpha, \beta}) du dv + (\mathfrak{A}''_{\alpha, \beta} - \mathfrak{Q}''_{\alpha, \beta}) dv^2 = 0 \dots (16)$$

Therefore, the net of the curves defined by (16) corresponds to the developable surfaces of the congruence  $I'$ .

The necessary and sufficient condition that this net form a conjugate net is

$$D(\mathfrak{X}''_{\alpha,\beta} - \mathfrak{X}''_{\alpha,\beta}) - 2D'(\mathfrak{X}'_{\alpha,\beta} - \mathfrak{X}'_{\alpha,\beta}) + D''(\mathfrak{X}''_{\alpha,\beta} - \mathfrak{X}''_{\alpha,\beta}) \\ = - \left( \frac{\partial a}{\partial v} - \frac{\partial \beta}{\partial u} \right) = 0,$$

or

$$\frac{\partial a}{\partial v} = \frac{\partial \beta}{\partial u}.$$

In the same manner as in n°5, we can see that in order that the point  $\tau + \mu x$  may be one of the focal points on the line  $x\tau$ , the points

$$x, \quad \tau, \\ (\mathfrak{X}'_{\alpha,\beta} - \mathfrak{X}'_{\alpha,\beta} + \mu - \theta + \theta_{\alpha,\beta} + \gamma)\rho - (\mathfrak{X}_{\alpha,\beta} - \mathfrak{X}_{\alpha,\beta})\sigma, \\ (\mathfrak{X}''_{\alpha,\beta} - \mathfrak{X}''_{\alpha,\beta})\rho + \left\{ \mu - \theta + \theta_{\alpha,\beta} + \gamma - (\mathfrak{X}'_{\alpha,\beta} - \mathfrak{X}'_{\alpha,\beta}) \right\}$$

must be coplaner. Accordingly,

$$\mu = \theta - \theta_{\alpha,\beta} - \gamma \pm \sqrt{(\mathfrak{X}'_{\alpha,\beta} - \mathfrak{X}'_{\alpha,\beta})^2 - (\mathfrak{X}_{\alpha,\beta} - \mathfrak{X}_{\alpha,\beta})(\mathfrak{X}''_{\alpha,\beta} - \mathfrak{X}''_{\alpha,\beta})}.$$

The harmonic conjugate of the point  $x$  with respect to the focal points is the point

$$\tau + (\theta - \theta_{\alpha,\beta} - \gamma)x.$$

If the two focal points coincide, this point itself is the focal point.

7. Now let us suppose the parameter curves to be asymptotic curves. In this case, have

$$D = D'' = 0 \dots \dots \dots (17)$$

Accordingly, in virtue of (21), (26) **chap. 1**,

$$\left. \begin{aligned} \mathfrak{C}' = \mathfrak{B} = \mathfrak{B}' = \mathfrak{C}'' = \mathfrak{X}' = 0, \\ D'^2 = 1. \end{aligned} \right\} \dots \dots \dots (18)$$

From the last equation of (18) we have

$$D' = \pm 1.$$

If  $D' = -1$ , then carry out the transformation

$$\bar{x}_i = e^{-\frac{i\tau}{4}} x_i.$$

By this transformation, we have

$$\bar{D}' = -D'.$$

Therefore, we may suppose, without loss of generality,  $D'$  to be equal to 1.

If we make this supposition, we have

$$\left. \begin{aligned} B = \mathfrak{B} = 0, & & B' = \mathfrak{B}' = 0, \\ C' = \mathfrak{C}' = 0, & & C'' = \mathfrak{C}'' = 0, \\ B'' = \mathfrak{B}'' & & C = \mathfrak{C}, \\ & & \theta = B''C, \\ L = -\frac{\partial C}{\partial v}, & & L' = 0, & & L'' = \frac{\partial B''}{\partial u}, \\ \mathfrak{L} = -\frac{\partial C}{\partial v} - \frac{\theta_v}{\theta}C, & & \mathfrak{L}' = 0, & & \mathfrak{L}'' = \frac{\partial B''}{\partial u} + \frac{\theta_u}{\theta}B'', \end{aligned} \right\} (19)$$

from (17), (18) and their definitions.

Let us denote by  $R_u$  the ruled surface formed by tangents to the curve  $C_u$  ( $v = \text{const.}$ ), and by  $R_v$  the similar parametric ruled surface.

The tangent plane at the point  $\sigma$  to  $R_v$  is determined by the points  $x, \sigma, \frac{\partial \sigma}{\partial u}$ . But we have from (2), (17), (18),

$$\frac{\partial \sigma}{\partial u} = \frac{\partial z}{\partial u} = -\tau - (\mathfrak{N}'_{\alpha, \beta} - \gamma)x.$$

Therefore, this plane contains the point  $\tau$ . Similarly the tangent plane at the point  $\rho$  to  $R_u$  contains the point  $\tau$ . Therefore, *the two tangents to  $R_u$  and  $R_v$  at the points  $\rho$  and  $\sigma$  respectively intersect at the line  $x \tau$ .* Green has defined reciprocal lines by this property.

In virtue of (17) and the definitions of the fundamental deter-



minants, the normal co-ordinates  $x_i$  ( $i=1, 2, 3, 4$ ) are solutions of the system of equations

$$\left. \begin{aligned} \frac{\partial^2 x}{\partial u^2} &= C \frac{\partial x}{\partial v} + Ax, \\ \frac{\partial^2 x}{\partial v^2} &= B'' \frac{\partial x}{\partial u} - A'' x. \end{aligned} \right\} \dots \dots \dots (20)$$

Accordingly, if the given surface is a ruled surface,

$$B'' \text{ or } C=0,$$

in other words,

$$\theta=0.$$

But  $\theta$  is a relative invariant. Therefore, we know that *the necessary and sufficient condition for the ruled surface is  $\theta=0$ .*

From (17) and (20) we know that when

$$a = -\frac{1}{2} \frac{B''_u}{B}, \quad \beta = -\frac{1}{2} \frac{C_v}{C},$$

the lines  $\rho \sigma$  and  $x \tau$  are the directrices<sup>1</sup> of the first and second kind respectively, and that when

$$a = \frac{1}{4} \frac{C''_u}{C}, \quad \beta = \frac{1}{4} \frac{B''_v}{B},$$

the lines  $\rho \sigma$  and  $x \tau$  are the canonical edges<sup>2</sup> of the first and second kind respectively.

From the equations (9), (16), (17), (23), (33), and (36) in the **chap. 1**, and (1) in this chapter, we can easily see that when

$$a = \lambda \frac{|\mathfrak{L} \mathfrak{C} D|}{\theta} + \frac{1}{2} \frac{\theta_u}{\theta},$$

$$\beta = \lambda \frac{|\mathfrak{L} \mathfrak{B} D|}{\theta} + \frac{1}{2} \frac{\theta_v}{\theta},$$

$$\gamma = \mu \theta + \nu \theta,$$

where  $\lambda, \mu, \nu$  are constants, the line  $\rho \sigma$  is an invariant line and the

<sup>1</sup> Wilczynski, Trans. Amer. Math. Soc. (16) 311 (1916).

<sup>2</sup> Green, loc. cit.

point  $\tau$  is an invariant point. But in virtue of (17) and (19) when the parameter-curves are asymptotic lines,

$$-\frac{1}{2} \frac{|\mathfrak{L} \mathfrak{C} D|}{\theta} + \frac{1}{2} \frac{\theta_u}{\theta} = -\frac{1}{2} \frac{B''_u}{B},$$

$$-\frac{1}{2} \frac{|\mathfrak{L} \mathfrak{B} D|}{\theta} + \frac{1}{2} \frac{\theta_v}{\theta} = -\frac{1}{2} \frac{C''_v}{C},$$

$$-\frac{1}{4} \frac{|\mathfrak{L} \mathfrak{C} D|}{\theta} + \frac{1}{2} \frac{\theta_u}{\theta} = \frac{1}{4} \frac{C''_u}{C},$$

$$-\frac{1}{4} \frac{|\mathfrak{L} \mathfrak{C} D|}{\theta} + \frac{1}{2} \frac{\theta_v}{\theta} = \frac{1}{4} \frac{B''_v}{B}.$$

Therefore we know that, referring to any parameter-curves, the lines  $\rho \sigma$  and  $x \tau$  are directrices of the first and second respectively, if

$$a = -\frac{1}{2} \frac{|\mathfrak{L} \mathfrak{C} D|}{\theta} + \frac{1}{2} \frac{\theta_u}{\theta},$$

$$\beta = -\frac{1}{2} \frac{|\mathfrak{L} \mathfrak{B} D|}{\theta} + \frac{1}{2} \frac{\theta_v}{\theta}$$

and they are canonical edges of the first and second kind respectively, if

$$a = -\frac{1}{4} \frac{|\mathfrak{L} \mathfrak{C} D|}{\theta} + \frac{1}{2} \frac{\theta_u}{\theta},$$

$$\beta = -\frac{1}{4} \frac{|\mathfrak{L} \mathfrak{B} D|}{\theta} + \frac{1}{2} \frac{\theta_v}{\theta}.$$

8. Next, let us suppose that the parameter-curves form a conjugate net.

In this case, we have

$$D' = 0, \dots \dots \dots (23)$$

accordingly,

$$\left. \begin{aligned} D D'' &= -1, \\ \frac{B}{D} &= -\frac{B''}{D''}, \quad \frac{C}{D} = -\frac{C''}{D''}, \quad \frac{A}{D} = -\frac{A''}{D''} \end{aligned} \right\} (24)$$

Let us put

$$\left. \begin{aligned} l &= \frac{B}{D} = -\frac{B''}{D''}, & m &= -\frac{C}{D} = \frac{C''}{D''}, \\ n &= -\frac{A}{D} = \frac{A''}{D''}. \end{aligned} \right\} (25)$$

Then

$$\left. \begin{aligned} \mathfrak{B} &= -\frac{\mathfrak{B}''}{D''} = \left( l - \frac{1}{2} \frac{\partial \log D}{\partial v} \right), \\ \mathfrak{C} &= -\frac{\mathfrak{C}''}{D''} = -\left( m + \frac{1}{2} \frac{\partial \log D}{\partial u} \right). \end{aligned} \right\} (26)$$

In virtue of the definition of the normal fundamental determinants, the normal co-ordinates  $x_i$  ( $i=1, 2, 3, 4$ ) are the solutions of the equation

$$\frac{\partial^2 x}{\partial u \partial v} = l \frac{\partial x}{\partial u} + m \frac{\partial x}{\partial v} + nx.,$$

Therefore, if

$$\alpha = -m, \quad \beta = -l,$$

the line  $\rho \sigma$  is the ray<sup>1</sup> of the point  $x$ .

Now let us put

$$H = -\frac{\mathfrak{A}_{-m,-l}}{D}, \quad H' = \mathfrak{A}'_{-m,-l}, \quad H'' = \frac{\mathfrak{A}''_{-m,-l}}{D''}.$$

Then

$$\left. \begin{aligned} H &= n + l - \frac{\partial l}{\partial u}, \\ H' &= A' - \mathfrak{C}''m + \mathfrak{B}l + \frac{1}{2} D \left( \frac{\partial l}{\partial v} + l^2 \right) - \frac{1}{2} D'' \left( \frac{\partial m}{\partial u} + m^2 \right), \\ H'' &= n + lm - \frac{\partial m}{\partial v}. \end{aligned} \right\} (27)$$

Therefore,  $H$  and  $H''$  are Laplace-Darboux invariants.

From (14) and (27) we know that the ray-curve<sup>2</sup> is given by

<sup>1, 2</sup> Wilczynski, loci. cit.

the equation

$$DHdu^2 - 2H'dudv - D''H'' = 0.$$

The condition for the conjugacy of the ray curves is

$$\frac{\partial m}{\partial v} = \frac{\partial l}{\partial u},$$

which is equivalent to

$$H - H'' = 0. \text{ (1)}$$

If

$$\alpha = m + \frac{\partial \log D}{\partial u}, \quad \beta = l - \frac{\partial \log D}{\partial v},$$

then we have from (13), (23), (24), (25) and (26)

$$q_{20} = 0, \quad r_{20} = 2\mathfrak{C}, \quad q_{02} = -2\mathfrak{B}'', \quad r_{02} = 0, \dots \dots \dots (28)$$

$$\left. \begin{aligned} -\frac{\mathfrak{A}_{\alpha,\beta}}{D} &= H + 2\frac{\partial}{\partial u}(D\mathfrak{B}'') + 4\mathfrak{B}''\mathfrak{C}, \\ \mathfrak{A}'_{\alpha,\beta} &= H' - \frac{\partial \mathfrak{B}}{\partial v} + \frac{\partial \mathfrak{C}''}{\partial u} + 2D''\mathfrak{B}^2 - 2D\mathfrak{C}''^2, \\ \frac{\mathfrak{A}''_{\alpha,\beta}}{D''} &= H'' + 2\frac{\partial}{\partial v}(D''\mathfrak{C}) + 4\mathfrak{B}''\mathfrak{C}, \\ -\frac{\mathfrak{L}_{\alpha,\beta}}{D} = \frac{\mathfrak{L}''_{\alpha,\beta}}{D''} &= -\frac{\partial}{\partial u}(D\mathfrak{B}'') - \frac{\partial}{\partial v}(D''\mathfrak{C}) + 4\mathfrak{B}''\mathfrak{C}, \\ \mathfrak{L}'_{\alpha,\beta} &= \frac{\partial \mathfrak{C}''}{\partial u} - \frac{\partial \mathfrak{B}}{\partial v} + 2D''\mathfrak{B}^2 - 2D\mathfrak{C}''^2. \end{aligned} \right\} (29)$$

From (28) we know that the points  $\tau, \frac{\partial^2 x}{\partial u^2}, z, x$ , as well as the points  $\tau, \frac{\partial^2 x}{\partial v^2}, y, x$ , are coplanar. But, since  $D'$  is equal to zero, the plane determined by the points  $\frac{\partial^2 x}{\partial u^2}, y, x$ , and that determined by the points  $\frac{\partial^2 x}{\partial v^2}, y, x$  are osculating planes at  $x$  of the curves  $C_u, C_v$  respectively which meet at  $x$ . Therefore, the line  $x\tau$  is the axis<sup>2</sup> of  $x$ .

<sup>1, 2</sup> Wilczynski, loc. cit.

From (16) and (29) we know that the axis-curves are given by the equation

$$D\left\{H + 3\frac{\partial}{\partial u}(D\mathfrak{B}'') + \frac{\partial}{\partial v}(D''\mathfrak{C})\right\}du^2 - 2H'dudv - D''\left\{H'' + \frac{\partial}{\partial u}(D\mathfrak{B}''') + 3\frac{\partial}{\partial v}(D\mathfrak{C}''')\right\}dv^2 = 0.$$

The condition for the conjugacy of the axis-curve is

$$\frac{\partial}{\partial v}\left(m + \frac{\partial \log D}{\partial u}\right) = \frac{\partial}{\partial u}\left(l - \frac{\partial \log D}{\partial v}\right),$$

which is equivalent to

$$H - H'' + 2\frac{\partial^2 \log D}{\partial u \partial v} = 0.$$

We shall now find another property of the conjugate net with conjugate axis-curve.

Consider a cone of the second order passing through the tangents drawn to the curves  $C_u, C_v$  at a point  $x$  at which they meet.

The equation of this cone is of the form

$$a_1\xi^2 + a_2\xi\eta + a_3\xi\zeta + a_4\eta\zeta = 0,$$

referring to the non-homogeneous co-ordinates introduced in n°1.

Let

$$a = m + \frac{\partial \log D}{\partial u}, \quad \beta = l - \frac{\partial \log D}{\partial v}.$$

Then, in virtue of (6), (23), (24) and (28) non-homogeneous coordinates of points on the curves  $C_u$  and  $C_v$  passing through  $x$ , in the vicinity of  $x$ , are

$$\left. \begin{aligned} \xi &= du + \dots\dots\dots, \\ \eta &= \frac{1}{6}Dq_{30}du^3 + \dots\dots\dots, \\ \zeta &= -\frac{1}{2}Ddu^2 + \dots\dots\dots, \end{aligned} \right\} \dots\dots\dots (30)$$

and

$$\left. \begin{aligned} \xi &= -\frac{1}{6}D''r_{03}dv^3, \dots\dots\dots, \\ \eta &= dv + \dots\dots\dots, \\ \zeta &= -\frac{1}{2}D''dv^2 + \dots\dots\dots, \end{aligned} \right\} \dots\dots\dots (31)$$

respectively.

From (30) and (31) we can see that when the said cone has the contact of the third order with both of the curves  $C_u, C_v$  at the point  $x$ , we must have

$$Dr_{03} + D''q_{30} = 0.$$

In virtue of (3), (23), (24) and (28), this equation is equivalent to the equation

$$H - H'' + 2 \frac{\partial^2 \log D}{\partial u \partial v} = 0.$$

Therefore we have the following theorem:—

*With any point P on a surface S as vertex, we can draw a cone of the second degree so that it has the contact of the second order at P with both of the curves of a conjugate net N on S which meet at P, if, and only if, the axis curves of N also form a conjugate net.*

To be continued.