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Catastrophes of Ecosystems

By

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1. Introduction

A lot of theoretical ecologists (Volterra, Lotka, MacArthur, May, e.t.c.) have tried to represent temporal developments of various ecosystems in various cases by differential equations. Such formulations are next ones.

$$\frac{dN_i}{dt} = F_i(N_1, N_2, \cdots N_m, a_i^1, a_i^2, \cdots a_i^k) \qquad i = 1, 2, \cdots m$$

where N_i is the number of *i*-th species, and a_i^s $(s=1, 2, \dots, k)$ are coefficients in the function F_i . Then we must get solutions $N_i(t)$ of these equations as functions of a_i^{k} 's and initial values $N_i(0)$'s. This is impossible except a few of very simple cases.

So, qualitative properties of these equations have been researched by using properties of the functions F_i 's, also by various men.

Especially, behaviours when the time t becomes infinity, are most interesting. These final states, of course, change dependent on a_i^k . Recently topologists (Thom,¹ Zieman²) researched how properties of the solutions of dynamical systems changes when the parameters of the system change continuously. This is so called 'catastor-ophe theory'. In this paper, we look again at basic equations of mathematical ecology from this view-point.

2. Malthus Equation

If one individual produces e other individuals per unit time, the time variation of whole individuals N, is represented by next equation (Malthus³).

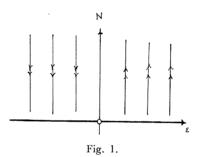
$$\frac{dN}{dt} = e N$$

The solution is

$$N = N(0) \exp(et) ,$$

where N(0) is the value of N at the time t=0.

The behaviour of the solution at sufficiently large t, depends on the value e. Drawing the orbits and stationary points in a space $e \times N$, we can see this behaviour at one glance. (Fig. 1) The set of the stationary points dN/dt=0 in this space, is called a stationary manifold. Here, this is straight line N=0. The right half (e>0)is a repellar, that is, any orbits starting from the neighborhood of this half line leave there. Conversely the left half (e<0) is an attractor, that is, orbits approach to this. Thus, the stationary manifold is separated to two parts carrying different properties at a point (0, 0). Such a point is called a catastorophe point.



3. Saturation Level and Constant Flow

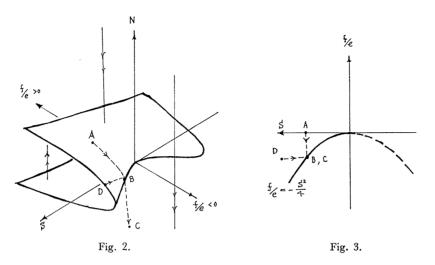
As we saw in the previous section, if e > 0, N becomes infinity. Actually, intraspecies competitions occur when N becomes large, and N saturates to a value s. (Verhulst⁴) What matter happens if we add a constant flow furthermore? (the positive flow means immigrations and the negative flow means emigrations or captures) Such a situation is represented by next equation.

$$\frac{dN}{dt} = e N (s - N) + f$$

The stationary manifold in the space $N \times s \times f/e$, is a paraboloid $f/e=N^2-sN$. (Fig. 2) The upper surface of the paraboloid is an attractor and lower surface is repellar. When f>0, all orbits starting from N(0)>0, approach to the attractor (stable states). But when f is negative (for example, fishery), there are two cases. One is stable one, and the other is the case having no equilibrium points. In the parameter space $s \times f/e$, the two regions are separated by a line $f/e=-s^2/4$ (Fig. 3). This is named 'fold catastorophe' by Thom.

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Starting from a point A (s>0, f=0) in Fig. 2 and Fig. 3, let us decrease f. At the moment the point reaches B on the catastorophe, the point falls down rapidly to C(N=0). The same thing occurs if we decrease s, starting from D. In other words, the population may extinct rapidly, even if we increase a fish catch slowly or the saturation level decreases continuously because of changes of environments such as a pollution.

4. Competition

Next, we consider interactions between two species. The growth rates e_1, e_2 , of each species are functions of N_1, N_2 . If two species compete one another for same food or habitat, e_i is decreasing function of N_j . We assume e_i is first order function of N_j , so that

$$e_1(N_1, N_2) = e_1^0 - a_{11}N_1 - a_{12}N_2$$
$$e_2(N_1, N_2) = e_2^0 - a_{21}N_1 - a_{22}N_2$$

where e_i^0 , a_{ij} are all positive. Because we want to seek only qualitative properties of the solution, it is sufficient that we assume $e_1^0 = e_2^0 = 1$, $a_{11} = a_{12} = 1$, $a_{21} = 1/a$, $a_{22} = 1/b$.

$$\begin{split} \frac{dN_1}{dt} &= (1 - N_1 - N_2)N_1 \\ \frac{dN_2}{dt} &= (1 - N_1/a - N_2/b)N_2 \end{split}$$

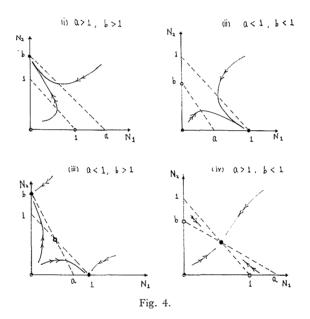
where 1/a represents how much species 1 disturbs species 2, and 1/b represents how

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much species 2 disturbs itself. The global situation is separated to next four cases (Fig. 4).

- (i) a > 1, b > 1; extinction of species 1.
- (ii) a < 1, b < 1; extinction of species 2.
- (iii) a < 1, b > 1; extinction of either species 1 or species 2.
- (iv) a > 1, b < 1; coexistence of both species.

The manifold $dN_1/dt=0$, $dN_2/dt=0$ in the four-dimentional space $N_1 \times N_2 \times a \times b$



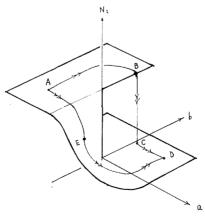


Fig. 5.

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is two-dimentional surface. It is impossible to illustrate it on the two-dimentional paper. So, we project only attractor of the manifold on three-dimentional space $N_1 \times a \times b$ (Fig. 5). Mapping on parameter space $a \times b$ brings a cusp-like catastrophe at a point (1,1) (Fig. 5). If we project the attractor on another space $N_1 \times a \times b$, we get similar figure.

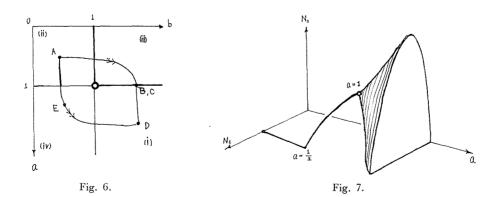
There are two types of processes for plant succession from one species to another species.⁵⁾ One is rapid substitution in a short interval. The other is slow change through coexistence states. These processes are reappeared on this model, by changing parameters a,b continuously through pathes ABCD and AED in Fig. 5 and 6.

5. Predation

We consider the case which species 2 captures and eats species 1. The reproduction rate of species 1 has a maximum at a suitable value of N_1 , and decreases after then, so that we may write

$$\frac{dN_1}{dt} = (-N_1^2 + 2N_1)N_2 - aN_1N_2$$
$$\frac{dN_2}{dt} = -N_2 + aN_1N_2$$

There are three cases depending on the predation rate a. When it is small (a < 1/2), the predator extincts. As it becomes larger to some extent (1/2 < a < 1), the two species coexist with constant populations. When a is more larger (a > 1), the stable state is a sustained oscillation or a limite cycle. The attractor in space $N_1 \times N_2 \times a$ is illustrated in Fig. 7. At a=1, we see a catastorophe which is a bifurcation point from the stable point to the periodic attractor.



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