

P-wave picking for earthquake early warning: refinement of a T^{pd} method

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SUMMARY

Detecting *P*-wave onsets for online processing is an important component for real-time seismology. As earthquake early warning systems around the world come into operation, the importance of reliable *P*-wave detection has increased, since the accuracy of the earthquake information depends primarily on the quality of the detection. In addition to the accuracy of arrival time determination, the robustness in the presence of noise and the speed of detection are important factors in the methods used for the earthquake early warning. In this paper, we tried to improve the *P*-wave detection method designed for real-time processing of continuous waveforms. We used the new T^{pd} method, and proposed a refinement algorithm to determine the *P*-wave arrival time. Applying the refinement process substantially decreases the errors of the *P*-wave arrival time. Using 606 strong motion records of the 2011 Tohoku earthquake sequence to test the refinement methods, the median of the error was decreased from 0.15 to 0.04 s. Only three *P*-wave arrivals were missed by the best threshold. Our results show that the T^{pd} method provides better accuracy for estimating the *P*-wave arrival time compared to the STA/LTA method. The T^{pd} method also shows better performance in detecting the *P*-wave arrivals of the target earthquakes in the presence of noise and coda of previous earthquakes. The T^{pd} method can be computed quickly, so it would be suitable for the implementation in earthquake early warning systems.

Key words: Earthquake early warning; Earthquake ground motions; Earthquake hazards.

1 INTRODUCTION

Detecting *P*-wave onsets in continuous seismic data streams is a fundamental component of real-time seismology. Conventionally, the STA/LTA method (ratio between short-term and long-term averages) has been widely used for the *P*-wave detection (e.g. Allen 1978). Since this method is reasonably robust and computationally simple, it has long been used as the standard technique.

Since earthquake early warning systems have been established at a number of locations around the world (Allen *et al.* 2009), the importance of reliable *P*-wave detection has increased. Not only the accuracy of the arrival time, but also the robustness for noisy signals and the speed of detection are essential for earthquake early warning.

There have been several more sophisticated algorithms proposed recently. Hildyard *et al.* (2008) and Nippress *et al.* (2010) proposed the damped predominant period (T^{pd}) method, which uses the change of frequency between the *P*-wave arrival and background noise. Methods using higher order statistics have also been explored by researchers (Saragiotis *et al.* 2002; Galiana-Merino *et al.* 2008; Nippress *et al.* 2010). These methods are more sensitive to the change of statistical distribution of amplitudes. This means that the

methods are also more affected by noise, so it is common to combine the techniques with other approaches to refine the triggers (e.g. Nippress *et al.* 2010; Ross & Ben-Zion 2014). Adding multiband filters before the STA/LTA can also improve the accuracy (Satriano *et al.* 2008). Furthermore, autoregressive techniques (e.g. Takahashi & Kitagawa 1988, 1991; Leonard & Kennett 1999), wavelet methods (e.g. Anant & Dowla 1997; Hafez *et al.* 2010) and a singular value decomposition method (e.g. Kurzon *et al.* 2014) have been proposed to improve the *P*-wave discrimination. Applications of deep learning in the phase detection have also been proceeding rapidly (e.g. Ross *et al.* 2018; Zhu & Beroza 2019; Mousavi *et al.* 2020). Although these methods show better performance, the speed of the detection after the phase arrival can be a limiting factor, which is also important for earthquake early warning systems.

In order to improve the *P*-wave detection method in real-time processing, we focus on the T^{pd} method, which is simple and easily implemented for fast computations. An earthquake early warning system may be processing thousands of components at the same time; therefore, fast computation is important. The method uses recursive computation and does not require large memory. It uses only a few samples after the *P*-wave arrivals to detect the signal arrival, which enables the quick detection of the *P* waves. We

propose refined algorithms for the P -wave arrival time and test them by using the aftershock data set of the 2011 Tohoku-oki earthquake. We evaluate the results in terms of accuracy of arrival time, speed of detection and robustness to noise.

2 DATA

We used seismic data recorded by Hi-net and the JMA strong motion seismic network from 2011 March 1 to April 30. We selected 18 earthquakes shown in Table 1: 17 earthquakes with maximum JMA seismic intensity ≥ 5 upper during the period, including the $M9.0$ main shock, and the largest foreshock ($M7.3$) with intensity 5 lower. The table also indicates ‘immediate’ events that occur closely in time and have higher noise levels because of the first event. For comparison purposes, the stations where P -wave arrival times were manually determined by JMA were used. We selected at most 50 of the closest stations to the epicentre for each event. We used a total of 606 seismic waveforms for the evaluations of the methods. All waveforms are up-down (UD) components with 3 min duration. The JMA seismic network uses accelerometers, whereas the Hi-net uses short-period velocity seismometers. For the analyses of P -wave detections, acceleration records were used, so velocity records are differentiated once in the time domain. All data are sampled at 100 Hz.

3 T^{pd} METHOD

3.1 Basic algorithm

T^{pd} is a method proposed by Hildyard *et al.* (2008) that uses the change of frequency due to the P -wave arrival. Suppose that x_i is the input signal, then T^{pd} is calculated by

$$T_i^{pd} = 2\pi \sqrt{\frac{X_i}{D_i + D_s}}, \quad (1)$$

where

$$X_i = \alpha X_{i-1} + x_i^2, \quad (2)$$

$$D_i = \alpha D_{i-1} + (\partial x_i / \partial t)^2 \quad (3)$$

and α is a damping parameter. This parameter is defined as $\alpha = \exp^{\ln(0.1) * dt / \tau_w}$, that is the amplitude decreases to 0.1 after τ_w seconds with a sampling period dt . D_s is a constant to stabilize T^{pd} . An appropriate choice of D_s will reduce the value of T^{pd} when D_i is very small, and prevent large T^{pd} being recorded for low-amplitude signals even when they contain long periods. According to Hildyard *et al.* (2008),

$$D_s = \frac{4\pi^2 \langle x_i^2 \rangle \tau_w}{\tau_{mx}^2 dt}, \quad (4)$$

where $\langle x_i^2 \rangle$ denotes the average noise level squared. T^{pd} will be close to τ_{mx} if the data are close to the noise level. In our case, we used the following long-time average for the recursive computation:

$$\langle x_i^2 \rangle = \langle x_{i-1}^2 \rangle + (1 - \exp^{\ln(0.1) * dt / 100}) * (x_i^2 - \langle x_{i-1}^2 \rangle). \quad (5)$$

By following Hildyard *et al.* (2008), we use $\tau_w = 4.5$ and $\tau_{mx} = 0.019$.

Figures 1(a) and (b) show the traces of acceleration and T^{pd} in quiet and noisy environments. T^{pd} increases rapidly at the wave onset, and it decays slower after that. The original method uses the value of T^{pd} as a trigger condition.

If we have two earthquakes consecutively, the shape of T^{pd} is likely to be two step functions. Therefore, detecting the second event by a single threshold would be difficult if the two earthquakes occur closely in time. In order to detect both events, we use the maximum change of T^{pd} in 3 s as a trigger condition:

$$\Delta T_{\max}^{pd} > c_1 \quad (6)$$

where $\Delta T_{\max}^{pd} = \max\{T_i^{pd} - T_j^{pd} \mid (i - 3/dt) \leq j < i\}$ and $c_1 = 0.015$. A P wave is detected if ΔT_{\max}^{pd} exceeds the threshold of c_1 . The most probable threshold will be discussed later.

3.2 Refinement of the arrival time estimate

The trigger threshold (c_1) should be set so that it is not triggered by noise but triggered on a signal arrival as quickly as possible. In general, T^{pd} increases as a function of time at around the P -wave arrival (see Fig. 1b). It would be more precise if we can pick the time step when T^{pd} starts increasing from the noise level. In order to refine the P -wave arrival time, we try to find the largest change of the wave characteristics slightly prior to the detection. We propose a three-step refinement process.

Step 1 T^{pd} refinement in a short time window: The first step is to find a sudden change of T^{pd} in a short time window. We search the time when the change of T^{pd} exceeds $0.5\Delta T_{\max}^{pd}$ within 0.15 s prior to the trigger. The refined time step j is defined as

$$\max\{j \mid T_j^{pd} < T_i^{pd} - 0.5\Delta T_{\max}^{pd} \cap T_{j+1}^{pd} \geq T_i^{pd} - 0.5\Delta T_{\max}^{pd}, \quad (i - 0.15/dt) \leq j < i\} \quad (7)$$

where i is the triggered time step. Note that more than 82 per cent of data (497/606) can find the time step j within 0.15 s prior to the trigger.

Step 2 T^{pd} refinement in a long time window: If the change of T^{pd} is not large enough in this short time window, we apply the second refinement scheme with a longer time window. We search the time when the change of T^{pd} exceeds $0.8\Delta T_{\max}^{pd}$ within 3 s prior to the trigger. The refined time step is defined as

$$\max\{j \mid T_j^{pd} < T_i^{pd} - 0.8\Delta T_{\max}^{pd} \cap T_{j+1}^{pd} \geq T_i^{pd} - 0.8\Delta T_{\max}^{pd}, \quad (i - 3/dt) \leq j < i\}. \quad (8)$$

Step 3 dT^{pd} refinement: In the third step, the refined time step is further refined by the smoothed derivative of T^{pd} (dT^{pd}). The refined time step k is defined as the time when dT^{pd} exceeds a threshold within 1 s prior to the time step from the second refinement scheme (j):

$$\max\{k \mid dT_k^{pd} < c_2 \cap dT_{k+1}^{pd} \geq c_2, (j - 1/dt) \leq k < j\}, \quad (9)$$

where $dT_i^{pd} = (T_{i+1}^{pd} - T_{i-2}^{pd}) / (3dt)$ and $c_2 = 0.01$.

Fig. 1 shows the refinement process for an emergent P -wave arrival in quiet (left) and noisy (right) environments, respectively. A signal was detected since the change of T^{pd} is larger than 0.015 within 3 s (Fig. 1b).

In a quiet environment, the change of T^{pd} was very sharp, and the first refinement scheme of eq. (7) was satisfied due to the sharp change (Fig. 1c, left). The next refinement process using dT^{pd} found the waveform arrival only 0.05 s after the manual detection (Fig. 1d, left).

In a noisy environment, T^{pd} has an emergent onset, and eq. (7) was not satisfied in the first refinement. The second refinement process was applied, and the onset of the increase of T^{pd} was found by eq. (8) (Fig. 1c, right). The third refinement process using dT^{pd} was not so effective due to the unstable slope of T^{pd} (Fig. 1d, right).

Table 1. List of earthquakes used in this study.

No.	Date	Time	Lat.	Lon.	Dep.	<i>M</i>	SI	Ndata	Err	Name
1	03/09/11	11:45:13	38.3285	143.2798	8.3	7.3	5−	30	−	Tohoku foreshock
2	03/11/11	14:46:18	38.1035	142.8610	23.7	9	7	50	−	Tohoku
3	03/11/11	15:15:34	36.1208	141.2525	42.7	7.6	6+	26	−	Tohoku (immediate)
4	03/11/11	16:29:00	39.0225	142.3112	17.0	6.6	5+	10	−	Tohoku (immediate)
5	03/11/11	17:40:54	37.4240	141.2732	29.9	6	5+	10	−	Tohoku (immediate)
6	03/12/11	03:59:15	36.9860	138.5978	8.4	6.7	6+	50	0.1	Nagano
7	03/12/11	04:31:55	36.9488	138.5725	0.8	5.9	6−	24	0.6	Nagano (immediate)
8	03/12/11	05:42:19	36.9732	138.5905	3.8	5.3	6−	19	0.5	Nagano (immediate)
9	03/15/11	22:31:46	35.3095	138.7145	14.3	6.4	6+	27	0.3	Shizuoka
10	03/19/11	18:56:48	36.7837	140.5715	5.4	6.1	5+	36	0.3	Ibaraki
11	03/23/11	07:12:28	37.0848	140.7878	7.6	6	5+	29	0.2	Fukushima-Hamadori
12	03/23/11	07:34:56	37.0982	140.7958	6.7	5.5	5+	29	3.6	Fukushima (immediate)
13	03/23/11	18:55:20	37.1110	140.7607	9.0	4.7	5+	34	0.4	Fukushima
14	04/01/11	19:49:44	40.2568	140.3640	12.4	5	5+	50	0.1	Akita
15	04/07/11	23:32:43	38.2042	141.9202	65.9	7.2	6+	49	−	Miyagi-oki
16	04/11/11	17:16:12	36.9457	140.6727	6.4	7	6−	50	0.1	Fukushima-Hamadori
17	04/12/11	14:07:42	37.0525	140.6435	15.1	6.4	6−	33	0.3	Fukushima-Nakadori
18	04/16/11	11:19:31	36.3408	139.9455	78.8	5.9	5+	50	0.2	Ibaraki

Notes: The indices are event number, earthquake occurrence date, time, latitude, longitude, depth, JMA magnitude (moment magnitude for Tohoku earthquake), maximum JMA seismic intensity, number of waveforms used, location error of inland earthquakes between JMA catalogue and location calculated with automatic triggers of this study, and name of the earthquake from the left. ‘Immediate’ stands for the immediate aftershocks (within a few hours after a large earthquake). The catalogue is obtained from the Japan unified high-resolution relocated catalogue for earthquakes.

3.3 Detriggering and retriggering

It is necessary to establish a detriggered condition to avoid triggering due to secondary phases (such as the *S* wave) but not to miss the *P* wave for the next event. We detrigger (i.e. allow triggering another *P* phase) if T^{pd} is less than 0.01 and 20 s passed after the trigger.

We can trigger again (retrigger the same *P* phase) if the following conditions are satisfied:

- (1) 5 s passed after the previous trigger, and
- (2) $\Delta T_{\max}^{pd} > c_1$ and $\Delta T_{\max}^{pd} > \Delta T_{\max}^{pd}(\text{previous})$.

The second condition indicates that the ΔT_{\max}^{pd} should be larger than that of the previous trigger. In this way, we avoid a trigger by the *S* wave, but do not miss a *P* wave of a closely following event, if the second event is much larger than the first one. However, any signals within 5 s after a trigger will be ignored. Subsequent events within 5 s of an initial trigger will not be detected. The pseudo-code of the refined T^{pd} algorithm is shown in Fig. 2.

4 RESULTS

We tested 606 waveforms that contain the *P*-wave arrival of a large earthquake. Each 3 min record includes the *P*-wave arrival of the target earthquake plus possible small earthquakes. Our goal is to minimize the missed *P*-wave arrivals for the target earthquakes and to suppress false triggers by noise or smaller earthquakes. We evaluate our method by the accuracy of correct triggers, missed *P* waves and false triggers by noise, by comparison with *P*-wave arrivals manually picked by JMA.

4.1 Accuracy of detection of *P*-wave arrival times

Figs 3(a) and (b) show histograms of the *P*-wave detection error of the test data set before and after the refinement. The number of the correct triggers, and the intervals of the 95 and 50 per cent of the data are shown in the figure. We defined a *P*-wave detection within

2 s from the JMA manually determined *P*-wave arrival as a correct trigger.

Applying the refinement process decreases the error and increases the detectability. The median of the error was decreased from 0.15 to 0.04 s. The number of missed *P*-wave arrivals for the target earthquakes was also decreased from 11 to 3. In total, 603 out of 606 waveforms were picked correctly by the T^{pd} method. Fig. 3(c) shows the difference of the *P*-wave triggers before and after the refinement. The difference is about 0.1 s on average, but some triggers changed the arrival times by 1–2 s after the refinement. In general, the refinement process improves the arrival times slightly for waveforms in the quiet environment, but it is more effective for the waveforms in the noisy environment, whose *P*-wave onsets are emergent.

Fig. 4 shows the *P*-wave detection error for each earthquake. Events that occur immediately after other earthquakes (within a few minutes to few hours) have larger errors than isolated events. These events have higher noise levels because of the coda and aftershocks from the first event. Some earthquakes have a clear trend in the errors. For example, our results for the Tohoku main shock (no. 2) tend to have later arrival times than the manually determined *P*-wave arrivals. This earthquake has very emergent onsets of the *P* waves due to ‘noise’ caused by the source characteristics and farther epicentre distance compared to other events. An immediate aftershock of the Fukushima-Hamadori earthquake (no. 12) has earlier arrival times than the JMA arrival times. We checked the original waveforms and found there were two *P*-wave arrivals in a very short time (< 1 s). This may be due to a small earthquake not in the JMA catalogue. It is difficult to distinguish a small event before a target earthquake, since we do not allow retriggering for 5 s after a trigger.

4.2 Missed and false triggers

Other than the correct detections, there are missed *P* waves and false triggers. Among three missed *P* waves, two records were completely missed and one record missed the *P* but was triggered by the *S*. Fig. 5

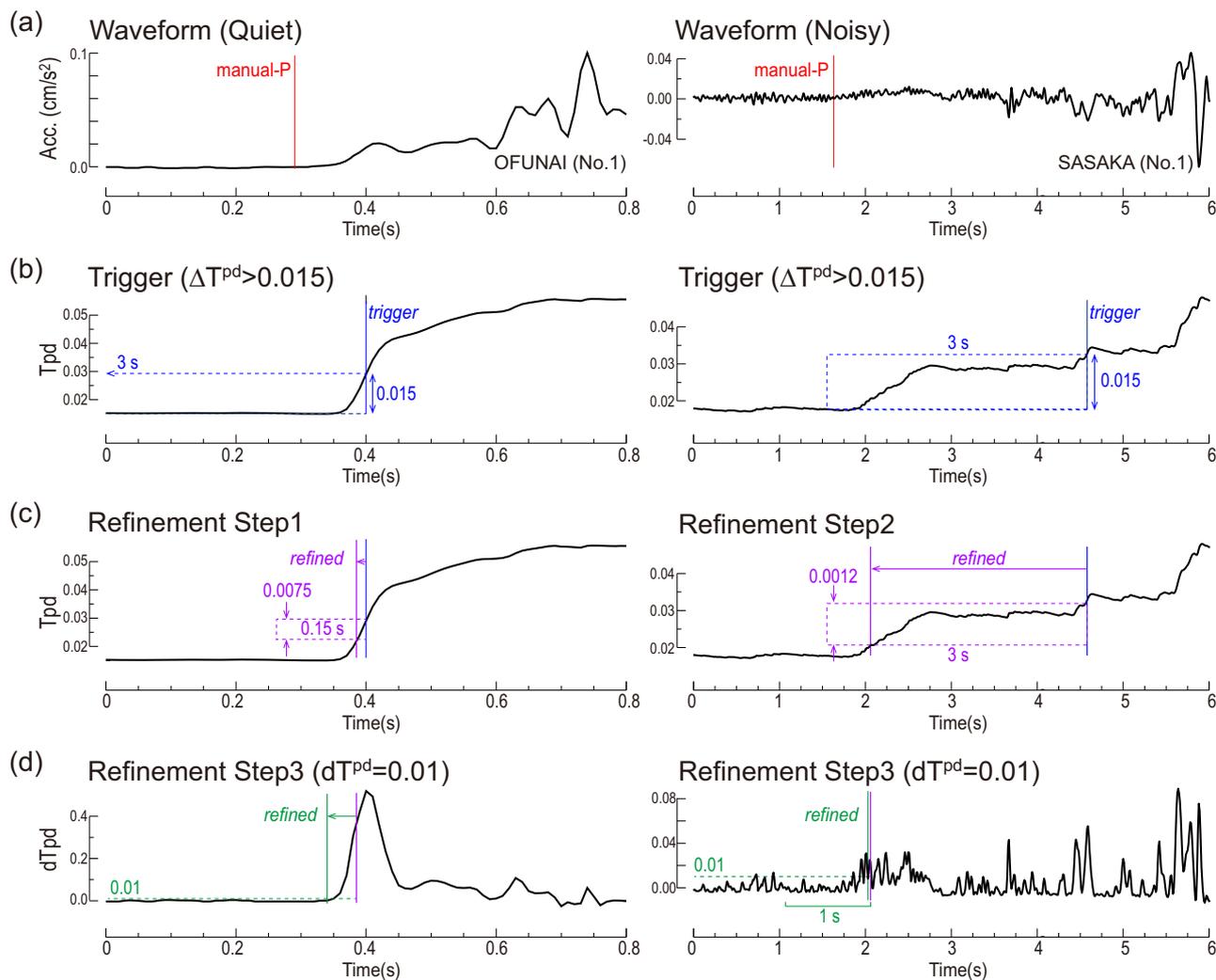


Figure 1. Examples of the trigger time refinement on the seismic records in quiet (left) and noisy (right) environments, respectively. (a) Acceleration waveforms, (b) T^{pd} triggers, (c) T^{pd} refinements and (d) dT^{pd} refinements. The left waveform is Tohoku foreshock (earthquake no.1 in Table 1) at station OFUNAI and the right waveform is the same event at station SASAKA.

shows the acceleration and T^{pd} traces of these three records. Due to high background noise, the increase of the T^{pd} was very slow, and the change of T^{pd} was not large enough to exceed the threshold in 3 s. The P -wave arrival at the OURI station (Fig. 5c) was contaminated by a previous small earthquake, so it was extremely difficult to correctly determine the arrival time.

We had 228 extra triggers in the 606 waveforms that were not associated with the target earthquake. Using theoretical arrival times of the earthquakes in the JMA catalogue, 55 and 18 picks were identified as P and S waves, respectively, of small earthquakes in the catalogue. The remaining 155 picks were caused by noise or earthquakes not in the catalogue. Since an earthquake catalogue is not complete after a large earthquake, it is hard to tell whether or not these were real seismic phases. Although they may be earthquake triggers, we define the picks not associated with earthquakes in the JMA catalogue as false triggers.

4.3 Grid search for the threshold of detection

We tried to find a threshold of the trigger (c_1 in eq. 6), which shows the best performance for detecting the large target earthquakes and

does not trigger on other phases or noise. There is a clear trade-off between these criteria. We performed a grid search for the following range of parameters: $c_1 = (0.010, 0.011, \dots, 0.020)$.

Fig. 6 shows the relationship between the number of missed P waves and false triggers for different thresholds. As expected, the number of the missed P waves increases as the threshold increases and the number of false triggers increases as the threshold decreases. However, there seems to be a lowerbound for the number of missed P waves. The number of the missed P waves does not change significantly for $c_1 \leq 0.016$. To minimize both the number of false triggers and missed P waves for the target earthquakes, we selected $c_1 = 0.015$.

4.4 Estimating location from the automatic triggers

To evaluate the effect of the P -wave detection on the location estimation, we compared locations of earthquakes using JMA manual picks and our automatic picks. We used 12 inland earthquakes in our data set which have good azimuthal station coverage. The JMA2001 1-D velocity structure model (Ueno *et al.* 2002) was used with the program Fasthypo (Herrmann 1979) for calculating the locations.

Algorithm 1 Outline of the refined T^{pd} method.

```

while end of data do
    * Compute  $T_{pd}$ , smoothed derivative  $dT^{pd}$ , and the largest change in 3s  $\Delta T_{max}^{pd}$ 
     $T_i^{pd} = 2\pi\sqrt{\frac{X_i}{D_i+D_s}}$ 
     $dT_i^{pd} = (T_{i+1}^{pd} - T_{i-2}^{pd})/(3 * dt)$ 
     $\Delta T_{max}^{pd} = \max(T_i^{pd} - T_j^{pd}), j \in (\text{previous } 3 \text{ s})$ 

    if  $\Delta T_{max}^{pd} > c_1 \wedge 5 \text{ s}$  passed from the previous trig then
        if 20 s passed from the prev. trig  $\vee$  (within 20 s  $\wedge \Delta T_{max}^{pd} > \Delta T_{max}^{pd}(\text{prev.})$ ) then
            * Signal detected. Refine the arrival time in the previous 0.15 s.
            for  $j = (i - 0.15/dt) \rightarrow i$  do
                if  $T_j^{pd} < (T_i^{pd} - 0.5\Delta T_{max}^{pd}) \leq T_{j+1}^{pd}$  then
                    refined time step =  $j$ 
                end if
            end for

            if not refined then
                for  $j = (i - 3/dt) \rightarrow i$  do
                    if  $T_j^{pd} < (T_i^{pd} - 0.8\Delta T_{max}^{pd}) \leq T_{j+1}^{pd}$  then
                        refined time step =  $j$ 
                    end if
                end for
            end if

            * Additional refinement in the previous 1 s from the first refinement.
            for  $k = (j - 1/dt) \rightarrow j$  do
                if  $dT_k^{pd} < 0.01 \leq dT_{k+1}^{pd}$  then
                    refined time step =  $k$ 
                end if
            end for
        end if
    end while

```

Figure 2. Pseudo-code of the refined T^{pd} method.

The differences between the two epicentres are shown in Table 1. The differences were less than 1 km for most of the earthquakes except the immediate aftershocks of the Fukushima-Hamadori earthquake. As we have shown in the Fig. 4, for these events, the *P*-wave arrival times were contaminated by a small earthquake right

before the target earthquake. In general, the difference of the *P*-wave arrival times determined by the JMA manual processing and the automatic triggers in our method is very small. As a result, we consider that the location errors of the earthquakes using our method are small. The earthquake early warning system determines the

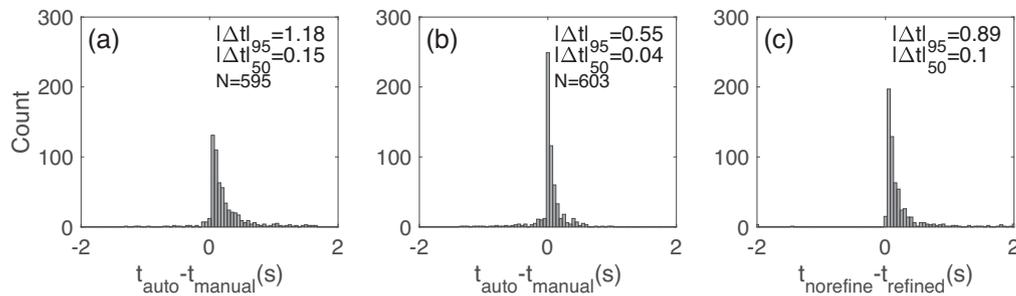


Figure 3. Effect of the refinement for the accuracy of P -wave arrival times. (a) No refinement, (b) with refinement and (c) the difference between (a) and (b). The number of the correct triggers, and the interval of the 95 and 50 per cent of the data are also shown.

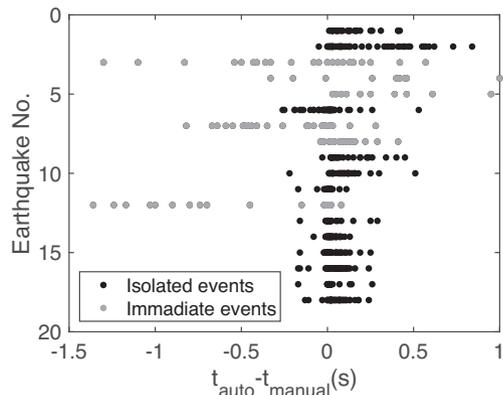


Figure 4. For each earthquake, difference between P -wave arrival time determined manually by JMA and automatic detection in this study. The vertical axis corresponds to the earthquake number in Table 1. The black and grey symbols indicate isolated events and immediate aftershocks, respectively.

location using a few early triggers; therefore, the accuracy of these triggers is important for obtaining a good location. In noisy environments, the refinement process proposed in this paper should provide better estimates of P -wave arrival times and improve the determined location when using data with high noise levels.

5 DISCUSSION

5.1 Choice of parameters

The performance of the P -wave detection by the T^{pd} method depends on the parameter tuning. The optimal parameters may be different depending on the data set, but we propose this formulation of the method so that parameter tuning is not needed for every new data set. We tried to select parameters that were less dependent on the data set. We use two parameters for the P -wave detection and six parameters for the refinement. Seven of the parameters were pre-determined by the trial and error, as explained in the following.

The T^{pd} method uses two parameters to detect the P -wave arrivals (a threshold of ΔT_{\max}^{pd} and its time window). These two parameters have a trade-off: a smaller threshold of ΔT_{\max}^{pd} will be suitable for a narrow time window, and the threshold of ΔT_{\max}^{pd} becomes large if the time window increases. Therefore, we fixed the time window as 3 s and searched for the threshold of ΔT_{\max}^{pd} . This time window was determined so that we can capture the increase of ΔT_{\max}^{pd} properly. In a noisy environment, the increase of ΔT_{\max}^{pd} is very slow, and we may miss the P -wave arrival if the window is too short. On the other hand, the width of the time window restricts the detection of

multiple signals in a short time, so the time window cannot be too long. After trial and error, we found that the 3 s window was suitable to detect 99 per cent (603/606) of the P -wave arrivals in our data set. The best threshold with this time window was determined by the grid search (Fig. 6).

In the refinement process, we use two parameters (time window and threshold) for each refinement scheme (six parameters in total). The growth of T^{pd} is different depending on the background noise level. In a quiet environment, T^{pd} increases very rapidly (Fig. 1a). We see a sharp increase of T^{pd} in a short time (less than 0.1 s) and a monotonic function. For this type of waveform, a short time window and smaller threshold (0.15 s and 50 per cent of ΔT_{\max}^{pd}) of the refinement are effective (eq. 7). The onset of the increase of T^{pd} is clearer on the derivative of T^{pd} , since it changes from negative to positive at the onset. Therefore, another refinement is performed by using dT^{pd} . This additional refinement was performed at most 1 s and the threshold was set to 0.01, to capture the time of the zero-crossing (eq. 9).

In a noisy environment, T^{pd} increases gradually and the onset is more difficult to determine than the quiet environment (Fig. 1b). The first refinement cannot find the onset of the waveforms and the second refinement with a longer time window and larger threshold (3 s and 80 per cent of ΔT_{\max}^{pd}) is applied (eq. 8). The additional refinement using dT^{pd} is not very effective due to the quick variation of dT^{pd} .

With these three refinement schemes, the method can be applied to a data set with both high and low noise levels. We avoid using the direct amplitude of T^{pd} as a threshold, since it may depend on the data set. Instead, we use the change of T^{pd} and the derivative of T^{pd} as a threshold.

5.2 Comparison with the STA/LTA method

The STA/LTA method is one of the most widely used methods for P -wave detection (e.g. Allen 1978). We compared the performance of T^{pd} method to the STA/LTA method. We used $C_3 = 0.021934$ and $C_4 = 0.000227$ for the parameters of the STA and LTA, respectively (Allen 1978; Yamada *et al.* 2014), and performed a grid search for the following range of the STA/LTA threshold: $C_5 = (6, 7, \dots, 30)$ (Allen 1978).

The robustness under noisy conditions depends on the threshold level of the detection. As we decrease the threshold, more signals are detected, but there are more false triggers. One way to evaluate the robustness is to examine the trade-off between missed P waves of target earthquakes and false triggers. Fig. 6 shows this relationship for the STA/LTA and T^{pd} methods. The results with various thresholds used in the grid search are shown in this plot. The T^{pd} method

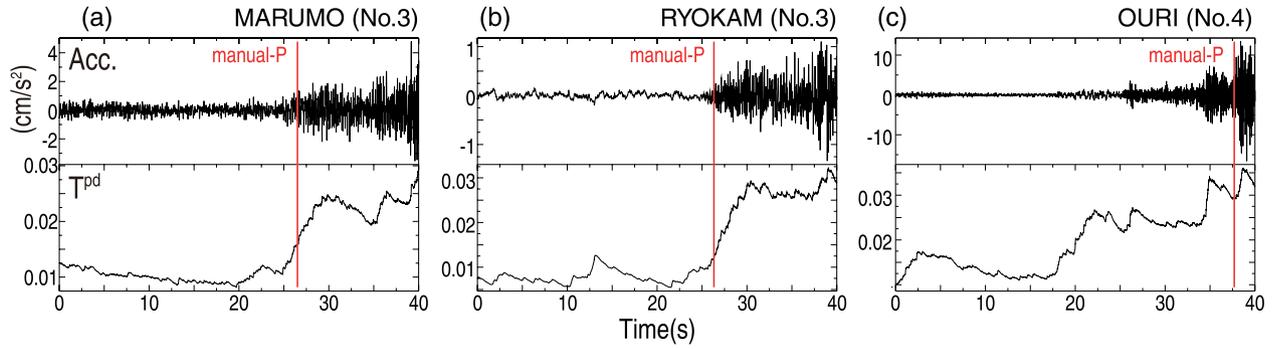


Figure 5. Acceleration and T^{pd} waveforms for missed *P*-wave arrivals. (a) Earthquake no. 3 in Table 1 at station MARUMO, (b) earthquake no. 3 at station RYOKAM and (c) earthquake no. 4 at station OURI.

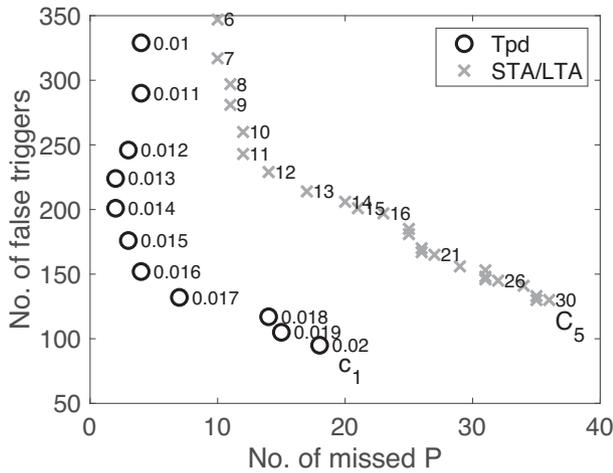


Figure 6. Relationship between the number of missed *P* waves of target earthquakes and false triggers in our test data set for T^{pd} and STA/LTA. The numbers indicate the threshold of the trigger (c_1 for T^{pd} and C_5 for STA/LTA).

shows better performance in detecting *P*-wave arrivals of the target earthquakes with a smaller number of false triggers, suggesting more robustness in the noisy environment.

Fig. 7 shows an example of T^{pd} and STA/LTA traces of a noisy records in our test data set. Both trigger methods show a sharp change at the *P*-wave arrival, but T^{pd} does not change significantly afterwards, which makes it easier to distinguish between the ambient noise and *P*-wave signal. If we use the best threshold of STA/LTA in Fig. 6 ($C_5 = 12$), the STA/LTA method missed the *P* wave and detected the *S* wave in Fig. 7(a). As for the waveform in Fig. 7(b), the STA/LTA method detected both the *P*-wave arrival and small noise right before it, whereas the T^{pd} method triggers only on the *P*-wave arrival.

5.3 Test with continuous data of the 2016 Kumamoto sequence

Since the method and parameter tuning were developed using the 2011 Tohoku sequence, we also tested the method on the 2016 Kumamoto sequence, without redetermining the parameters. The Kumamoto earthquakes are shallow onshore events, compared to the offshore subduction events of the Tohoku sequence. We applied the T^{pd} method to the continuous seismic recordings of the Kumamoto sequence. We used seismic data recorded by Hi-net and the JMA

strong motion seismic network on 2016 April 14–16. We ran the T^{pd} method on the entire continuous data set to detect *P* phases, and then extracted the phases associated with 18 large earthquakes with maximum JMA seismic intensity ≥ 5 lower. We defined the phases as correct detections, if they were within 2 s of the theoretical *P*-wave arrival times, calculated using the JMA locations.

The numbers of the correct *P*-wave detections for the closest 30 stations from the epicenter are shown in Supporting Information Table S1. The detection performance is satisfactory (only one or no *P*-wave arrivals are missed) for most of the events. The exceptions are four earthquakes (nos. 6, 12, 17 and 18) where nos. 6, 12 and 17 are immediate aftershocks within 7 min after the previous large earthquakes and the *P*-wave detection rate is less than 70 per cent of the 30 stations. The T^{pd} method with parameters determined from the Tohoku earthquake provides good results on the Kumamoto sequence.

We evaluate possible incorrect *P*-wave detections using the continuous data 1 hr before the Kumamoto earthquake (20:00–21:00 on 2016 April 14). There are no earthquakes in the JMA seismic catalogue around the Kumamoto region, so this is a very quiet period. We run the T^{pd} method on the 1-hr continuous data with 233 stations and detected 209 single-station triggers. Although the number seems to be large, some stations are very noisy and triggered frequently. For the Japanese earthquake early warning to the public, triggers at multiple stations are required to avoid a false alarm. Therefore, we classify a trigger as noise if it is only one trigger among the 10 closest stations. With this filter, all 209 triggers described above are classified as noise, not earthquakes. Therefore, we have no false positive detections that are classified as earthquakes. Although this filter causes the delay of the warning, it is the simplest way to avoid false alarms for a place with a dense seismic network.

5.4 Applicability to real-time processing

We measured the speed of computation in applying the T^{pd} method on continuous waveforms. The computation time required for reading the 1-hr 997-channel data from the hard disk and applying the T^{pd} method is about 36 min (operation environment: CPU, Xeon 3.46 GHz; OS, Linux CentOS 6; memory, 48 GB; compiler, gcc ver.4.4.7). Currently, we are testing this triggering method for about 1000-channel real-time data on the same server. The program has been working continuously for several months. This program was designed to process every 1 s and used recursive computation. Therefore, it does not require a large memory and CPU, even when we process 1000 continuous channels.

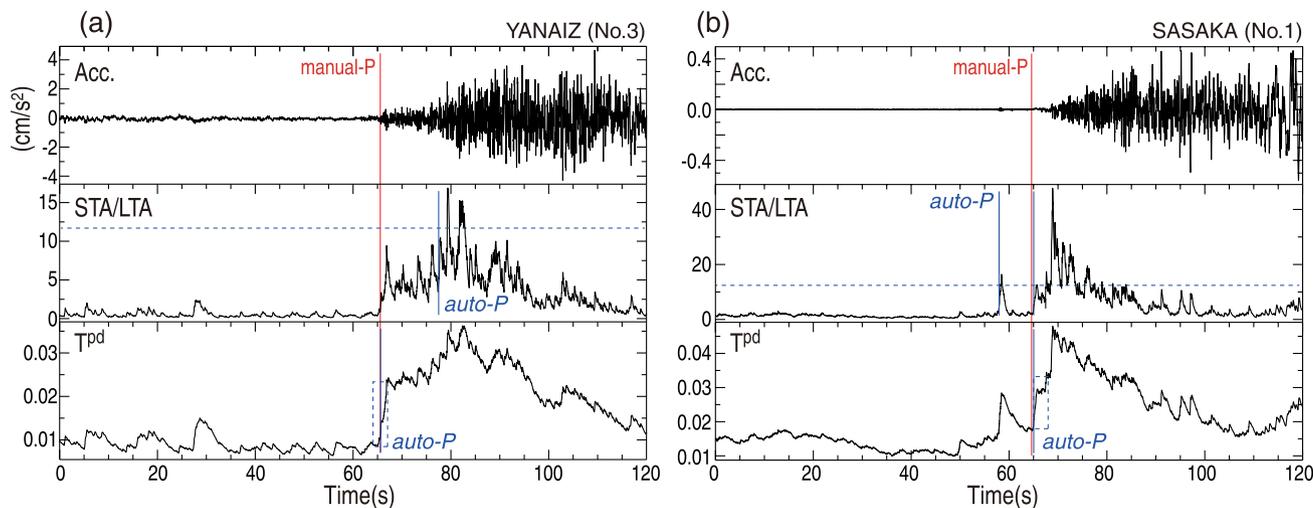


Figure 7. Example of noisy waveforms. Acceleration, STA/LTA and T^{pd} waveforms from the top. JMA manual determined P -wave arrival (marked as manual- P) and automatic triggers using STA/LTA and refined T^{pd} methods (marked as auto- P). (a) Earthquake no. 3 in Table 1 at station YANAIZ and (b) earthquake no. 1 at station SASAKA.

Note that we use the acceleration waveforms to apply the T^{pd} method, but the velocity waveforms have a similar trend of T^{pd} , since the T^{pd} is the ratio between the waveform and its derivative. We tested the velocity waveforms and found that this method was also applicable to the velocity waveforms.

6 CONCLUSIONS

In this paper, we tried to improve the P -wave detection method for real-time processing of continuous data. We used a new T^{pd} methods, and proposed a refinement algorithm to determine the P -wave arrival time.

Applying a refinement process substantially decreases the error of the P -wave arrival time. For the 606 waveforms of the test data set, the median of the error was decreased from 0.15 to 0.04 s. The number of the missed P waves decreased from 11 to 3. Our results show that the T^{pd} method with the refinement has good accuracy for detecting P -wave arrival times for large earthquakes.

We also proposed simple dettrigger and retrigger schemes, which are required for the real-time continuous system. The computation time required for processing the 1-hr 1000-channel data is about 36 min.

Our results show that the T^{pd} method has better performance for detecting P -wave arrivals than the STA/LTA method. It is more robust in detecting the P -wave arrivals of the target large earthquakes and less sensitive to false triggers. The T^{pd} method is computationally fast, so it would be suitable for implementation in earthquake early warning systems.

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DATA AVAILABILITY

We use the seismic waveform data provided by the JMA and NIED. The Hi-net data provided by the NIED are available at <https://doi.org/10.17598/NIED.0003> (last accessed August 2021). The JMA data were provided under research collaboration with the JMA. Data can be purchased from the Japan Meteorological Business Support Center.

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SUPPORTING INFORMATION

Supplementary data are available at [GJI](https://doi.org/10.1093/gji/ggk000) online.

Table S1. List of the large earthquakes from the 2016 Kumamoto sequence.

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