

Identification and Prediction for the Long Range Runoff Systems

By

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In this paper, the runoff simulation method has been discussed in order to obtain effective information for water resource planning. The framework consists of the identification of the long range runoff systems and the simulation for the areal daily precipitation while the runoff data are simulated by their combination.

First, for identifying the long range runoff systems, the improved statistical unit hydrograph method is proposed based on the techniques of information theory. Next, the daily precipitation data are simulated over a long period and in a wide area through the successive combination of regional correlation analysis between the base or sub-base and surrounding stations, spatial simulation between the base and sub-base stations, and sequential simulation at the base station. Finally, by the combination of the improved statistical unit hydrograph method and the simulation method for areal daily precipitation, the observed data are shown with sufficient accuracy.

1. Introduction

In the development of water resource planning and design, it is a basic problem to establish techniques for the long range runoff simulation. Most studies on runoff simulation are based on time series analysis of runoff data. Because of the short length of observed runoff data, however, the stability of frequency distribution is in itself a problem and moreover, it seems to be an essential defect that those methods pay no attention to the runoff mechanism. In addition to those circumstances, considering that long range runoff phenomena are essentially stochastic processes and the observed daily precipitation data are better in length and accuracy than runoff data, the runoff simulation should be constructed by the following procedures:

First, construct the basin system model from both the observed runoff data and corresponding precipitation data. In this case, we should introduce into the model

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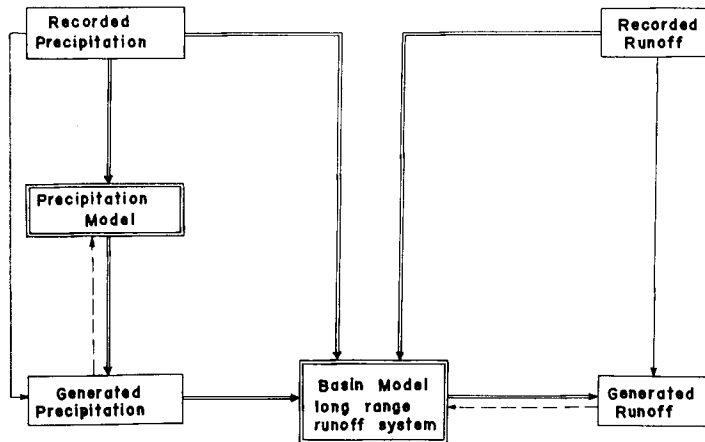


Fig. 1. Flow chart for runoff simulation.

not only the deterministic or physical characteristics but also the statistical laws involved in the transformation system from precipitation to river discharge.

Next, complement the lack of runoff data from the combination of the basin model and observed daily precipitation data. Furthermore, for predicting the future the daily river discharge, establish the simulation methods of daily precipitation in space and time and combine them with the basin system model.

Finally, it may be concluded that the runoff simulation consists of making the basin system model and establishing the simulation method of daily precipitation in space and time. The flow chart for the above description is shown in Figure 1.

2. Improved statistical unit-hydrograph method

The authors are interested in information theory, especially in Wiener's filtering theory and have investigated how to apply this theory to long range runoff systems¹⁾.

At first, the statistical properties of daily precipitation and river discharge series are discussed by using correlation analysis. Then, after the time-invariant-linearization of runoff system is made according to the physical mechanism of runoff phenomena, the unit-impulse response function is derived from the Wiener-Hopf equation. We have designated this response as "the statistical unit-hydrograph", and subsequently written it as SUH. The results applied to the Yura River basin have verified that the SUH method may be effective for identifying the long range runoff system. At the same time, however, there still have remained some problems, such as the peak values of SUH differ from year to year and the accuracy of prediction is unsatisfactory, especially in the lower stages of river discharge. These problems result from the fact

that separation method of surface runoff from observed hydrographs is still unsatisfactory and the subsurface and groundwater runoffs are considered as the same runoff system in spite of their different linearities.

From these circumstances, the authors hope to improve and modify the SUH method by the following approach: The major improvements and modifications are to divide the observed hydrographs into the subsurface and groundwater runoff components and to introduce the effect of evapotranspiration on water content in the subsurface stratum into the model.

2-1. Supplies to subsurface and groundwater runoff systems

The runoff process depends on time-distribution of water content in the subsurface stratum. In the rainy season, especially, we must remove the initial loss and the surface runoff components from observed daily precipitation data, for estimating the effective input data for linear system. Figure 2 shows a schematic representation of water content distribution in the subsurface stratum. In Fig. 2, W_s , W_c and W_a are the saturated water content, the capillary saturated water content and the adsorbed water content respectively. Each value is determined from the product of depth and effective porosity of subsurface stratum²⁾.

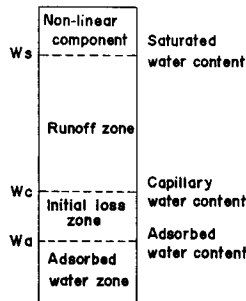


Fig. 2. Schematic representation of water content distribution in the subsurface stratum.

For the purpose of practical runoff analysis, we define the runoff zone as domain W_c-W_s and the initial loss zone as domain W_a-W_c . Furthermore, considering that surface runoff is proportional to water content in the subsurface stratum, we may find that water contents in the runoff zone and in the initial loss zone decrease according to Eqs. (1) and (2) respectively.

$$S(i+1) = \{S(i) + (f_c + e_v(i))/\alpha\} e^{-\alpha} - (f_c + e_v(i))/\alpha \quad (1)$$

$$S(i+1) = S(i) - e_v(i) \quad (2)$$

in which $S(i)$ and $S(i+1)$ are water contents in the day i and $i+1$, a , the recession coefficient of subsurface runoff, f_c , the final infiltration rate and $e_v(i)$, the daily evapotranspiration rate. Consequently, the daily decrease rate of water content in the runoff zone $DS(i) (=S(i)-S(i+1))$, is divided into components $Rs(i)$ and $Rc(i)$, supplied to the subsurface and groundwater runoffs respectively. In this case, because the maximum value of input component to the groundwater runoff system equals f_c , it follows that:

$$\left. \begin{array}{l} \left. \begin{array}{l} Rs(i) = DS(i) - (f_c + e_v(i)) \\ Rc(i) = f_c \\ Rs(i) = 0 \\ Rc(i) = DS(i) - e_v(i) \end{array} \right\} \text{if } DS(i) \geq f_c + e_v(i) \\ \left. \begin{array}{l} \\ \\ \\ \end{array} \right\} \text{if } DS(i) < f_c + e_v(i) \end{array} \right\} \quad (3)$$

When it rains, $S(i)$ being in the runoff zone, $(S(i)+R(i))$ corresponds to $S(i)$, in which $R(i)$ is daily precipitation intensity. Of course, this is true only if $W_c < S(i)+R(i) \leq W_s$. On the other hand, the initial loss component $L(i)$ and the surface runoff component $NL(i)$ are estimated as follows:

$$\left. \begin{array}{l} L(i) = W_c - S(i) \quad \text{if } S(i) + R(i) \geq W_c \\ L(i) = R(i) \quad \text{if } S(i) + R(i) < W_c \\ NL(i) = S(i) + R(i) - W_c \quad \text{if } S(i) + R(i) \geq W_s \end{array} \right\} \quad (4)$$

Next, it is an important problem to estimate the daily evapotranspiration rate. Considering that the evapotranspiration rate $e_v(i)$, is highly correlated with the pan evaporation rate $E(i)$ and water content in the subsurface stratum $S(i)$, the relationship between $e_v(i)$, $E(i)$ and $S(i)$ may be expressed by Figure 3³⁾. Therefore, in the runoff zone, $e_v(i)$ may be replaced by $E(i)$ and in the initial loss zone $e_v(i)$ may be replaced by Eq. (5).

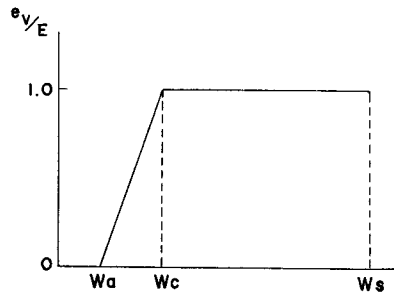


Fig. 3. Relationship between soil moisture content and evapotranspiration.

$$e_v(i) = \{S(i) - Wa\} \cdot E(i) / (Wc - Wa) \tag{5}$$

Unfortunately, if pan evaporation has not been observed in the runoff zone, we must neglect $e_v(i)$ and estimate $e_v(i)$ with Eq. (6) in the initial loss zone.

$$S(i+1) = S(i) \cdot e^{-\beta} \tag{6}$$

in which β is the recession coefficient of water content in the initial loss zone.

2-2. Prediction for the amount of groundwater runoff

Assuming that the groundwater runoff system is linear, we can predict the amount of groundwater runoff $Q_G^*(i)$ by the following equation, in which $h_G(\tau)$ is the unitgraph of groundwater runoff system and is given by Figure 4.

$$Q_G^*(i) = \sum_{\tau=0}^{T_G} h_G(\tau) \cdot R_G(i-\tau) \tag{7}$$

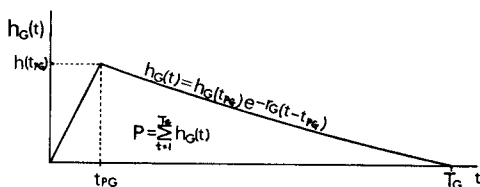


Fig. 4. Unitgraph of groundwater runoff system.

In Fig. 4, r_G is the recession coefficient of groundwater runoff (It is estimated from the observed hydrographs); t_{PG} , the peak lag time (in most cases, t_{PG} =one day); T_G , the duration time for the groundwater runoff over a long period of time (T_G =40-50 days is suitable for practical purposes); and p , the loss rate discharged into the deeper groundwater layer and other basins (In general, though, the value nearly equals 1.0 in the upper basin area, and is less than 1.0 in the downward. For practical analysis, when the hydrographs $Q_G^*(i)$ do not agree with observed groundwater hydrograph, the value p may be changed. This process is repeated until $Q_G^*(i)$ is judged to be an adequate representation of groundwater hydrograph).

2-3. Statistical unit hydrograph of subsurface runoff system

Separating the groundwater runoff estimated by Eq. (7) from the observed hydrographs and moreover, removing the surface runoff component from the residual hydrographs, we get the subsurface runoff hydrographs $Q_s(i)$. Then, we can find the statistical unit hydrograph of subsurface runoff system $h_s(\tau)$ from solving the following

Wiener-Hopf equation with $R_s(i)$ as input and $Q_s(i)$ as output⁴⁾:

$$\Phi_{RQ}(\tau) = \sum_{k=0}^{T_s} h_s(k) \cdot \Phi_{RR}(\tau-k) \tag{8}$$

in which $\Phi_{RR}(\tau)$ and $\Phi_{RQ}(\tau)$ are given by Eqs. (9) and (10):

$$\Phi_{RR}(\tau) = \frac{1}{N-\tau} \sum_{i=1}^{N-\tau} R_s(i) \cdot R_s(i+\tau) \tag{9}$$

$$\Phi_{RQ}(\tau) = \frac{1}{N-\tau} \sum_{i=1}^{N-\tau} R_s(i) \cdot Q_s(i+\tau) \tag{10}$$

where N is the number of days for the period considered, and T_s is a duration time of subsurface runoff.

In this case, provided the maximum value of subsurface runoff be approximated by the maximum daily decrease rate of water content in the runoff zone, the value $DSmax$ may be given as follows:

$$DSmax \doteq (W_s - W_c + f_c/a)(1 - e^{-a}) - f_c \tag{11}$$

Therefore, as first step, when the difference between $Q_c^*(i)$ and observed hydrograph $Q(i)$ is larger than $DSmax$, the excess part is separated as the surface runoff component, and the subsurface runoff $Q_s^*(i)$ may be predicted by the following equation:

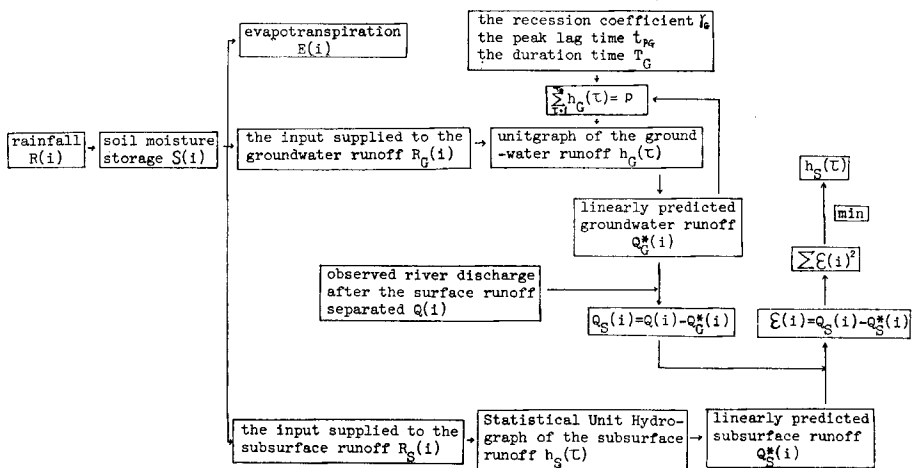


Fig. 5. Flow chart for the improved statistical unit hydrograph method.

$$Q_s^*(i) = \sum_{\tau=0}^{T_s} h_s(\tau) \cdot R_s(i-\tau) \quad (12)$$

However, considering that the maximum value DSmax does not discharge into the subsurface runoff in a moment, the separation of surface runoff component should be practically modified by the following approach. That is to say, only when $Q_s^*(i)$ predicted by Eq. (12) is smaller than $Q_s(i)$ under the condition of $R_s(i-1)=\text{DSmax}$ or $\approx \text{DSmax}$, the difference between $Q_s^*(i)$ and $Q_s(i)$ should be separated as surface runoff component, namely $Q_s(i)=Q_s^*(i)$, and in other days, $Q_s(i)=Q(i)-Q_s^*(i)$. Ultimately, the SUH of subsurface runoff system may be estimated between such modified $Q_s(i)$ and $R_s(i)$. The flow chart of the above procedures is shown in Figure 5.

3. Stochastic structures in space and time of daily precipitation and their simulation

3-1. Classification of precipitation stations

Though there are many stations for acquiring precipitation data, we have experienced situations when usable records are sparse, unavailable, or quite short in the time length of observation. In other situations, precipitation records may be adequate in length and accuracy, but quite sparsely distributed areally. Thus, it becomes increasingly important to estimate the precipitation variables at a number of observing stations for relatively short periods of time from observations taken at one station over a long interval of time.

In this paper, we classify observing stations into the base station, the sub-base stations and the surrounding stations, and estimate the stochastic structures in space and time from their interrelations and lastly, simulate the daily precipitation sequences. Where the base station is a representative station in the basin and adequate both in length and accuracy; the sub-base station is a representative station in the tributary and shorter in length than the base station; and the last stations are surrounding the base and sub-base stations and are inadequate in length and accuracy.

3-2. Regional correlation analysis between the base or the sub-base station and the surrounding stations

The statistical concepts of correlation analysis play an important role to interpolate the precipitation variable. The inter-station correlation coefficient r equals:

$$r = \frac{\sum_{i=1}^n x_i y_i - n \cdot \bar{x} \cdot \bar{y}}{\sqrt{\left(\sum_{i=1}^n x_i^2 - n \cdot \bar{x}^2\right) \left(\sum_{i=1}^n y_i^2 - n \cdot \bar{y}^2\right)}} \quad (13)$$

and is a measure of association between the variables, x_i and y_i , taken simultaneously in time at the base and the surrounding stations, provided linear association between x_i and y_i , y_i will be predicted as follows:

$$y_i = \hat{\alpha} \cdot x_i + \hat{\beta} + \varepsilon_i \quad (14)$$

in which $\hat{\alpha}$ and $\hat{\beta}$ are given by Eq. (15) and ε is the residual random variable.

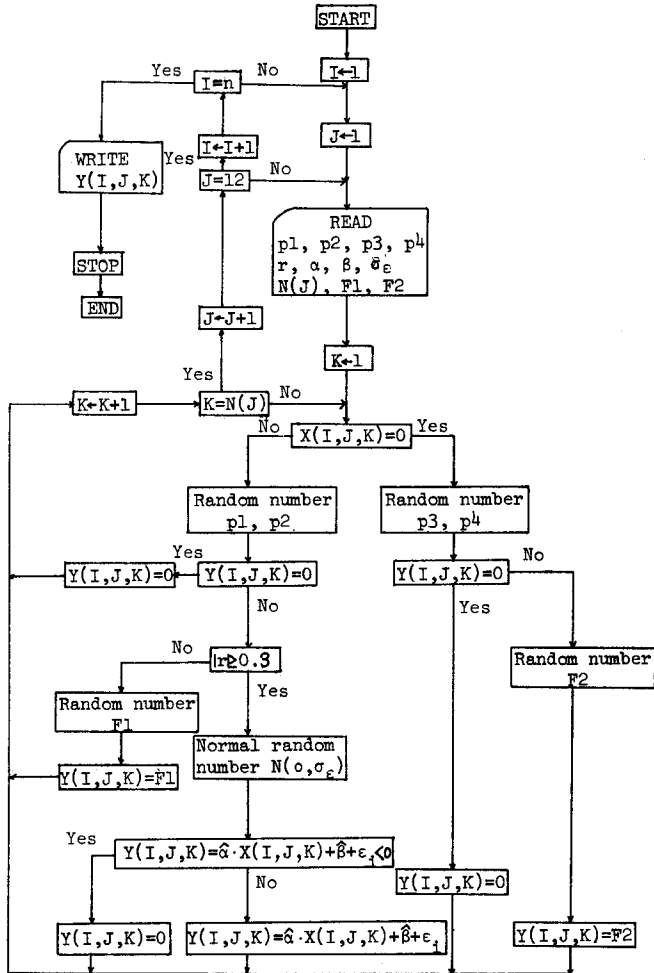
$$\left. \begin{aligned} \hat{\alpha} &= r \cdot \sqrt{\frac{\left(\sum_{i=1}^n y_i^2 - n \cdot \bar{y}^2\right)}{\left(\sum_{i=1}^n x_i^2 - n \cdot \bar{x}^2\right)}} \\ \hat{\beta} &= \bar{y} - \hat{\alpha} \cdot \bar{x} \end{aligned} \right\} \quad (15)$$

However, considering that the pairs of daily precipitation (x_i, y_i) have generally bivariate exponential distribution, we must modify the above procedures as follows: Between higher correlated stations, we have experienced that the residual random variable ε distributes normally within the subdivided classes of x . Thus, we estimate the standard deviation σ_ε in each subdivision of the residual series $\{y_i - (\hat{\alpha} \cdot x_i + \hat{\beta})\}$ and generate ε_i according to the class of x , based on standard normal distribution $\mathcal{N}(0, \sigma_\varepsilon)$. In the end, we can relate y_i to x_i and estimate missing data as accurately as feasible by Eq. (14).

Furthermore, combining the surrounding stations so that the regional correlations on the base station are the same, we can describe isolines of inter-station correlation coefficient about a base station⁵⁾. Because the correlation between variables at different points tend to decrease with an increase of distance and difference in height between points, isolines do not show concentricity.

3-3. Spatial simulation between the base and sub-base stations

Because the great increase of distance between the base and sub-base stations makes the regional correlation coefficient lower, it is difficult to apply directly the above procedure to the correlation analysis between both points. Thus, we define four systems from the precipitation and no precipitation states of the base and sub-base stations: First; precipitation-precipitation system ($R.R$), second; precipitation-no precipitation system ($R.D$), third; no precipitation-precipitation system ($D.R$), fourth;



I : Year
 J : Month
 K : Day
 N(J) : Days of J-th month
 p1 : Probability of R.R
 p2 : Probability of R.D
 p3 : Probability of D.R
 p4 : Probability of D.D
 n : Simulated year
 r : Correlation Coefficient of R.R system
 $\hat{\alpha}$: Regression Coefficient
 $\hat{\beta}$: Constant
 σ_ϵ : Residual standard deviation
 F1 : Distribution function of R.R system in the
 F2 : Distribution function of D.R System
 X(I, J, K) : Precipitation in the base station
 Y(I, J, K) : Simulated precipitation in the sub-1

Fig. 6. Flow chart for the spatial simulation between the base and sub-base stations.

no precipitation-no precipitation system (D.D). Table 1 shows their occurrence probabilities.

Also, we have observed that the sub-base stations have themselves inherent occurrence probabilities. In general, the values P_2 and P_3 are higher with an increase

Table 1. Occurrence probabilities of (R.R), (R.D), (D.R) and (D.D) systems.

Sub-base station	R	D	
Base station			
R	P1	P2	P1+P2 = 1
D	P3	P4	P3+P4 = 1

of distance and difference of height between the base and sub-base stations, and the value P_1 in rainy and typhoon seasons is higher compared with any other season.

Next, in (R.R) and (D.R) systems, we must estimate the daily precipitation at the sub-base station. For (R.R) system, the daily precipitation $R(i)$ at sub-base station will be estimated by the same equation as Eq. (14). In this case, if $|r| < 0.3$, the daily precipitation will be generated independently from the distribution of daily precipitation at sub-base station, F_1 . For (D.R) system, the daily precipitation will be generated independently from the distribution of daily precipitation at sub-base station, F_2 . Where F_1 and F_2 are estimated from samples contained in (R.R) and (D.R) systems respectively.

Figure 6 shows the flow chart for the above procedures on spatial simulation.

3-4. Sequential simulation at the base station

It still remains to simulate the daily precipitation at the base station for predicting future precipitation over a long period.

We consider two processes ($R^*(i')$, $D(i')$) ($i' = 1, 2, \dots$) instead of one single process of the daily precipitation $R(i)$ ($i = 1, 2, \dots$). Figure 7 shows two processes of daily precipitation. In Fig. 7, $R^*(i')$ corresponds to the precipitation intensity $R(i) > 0$, and $D(i')$ corresponds to the continuous dry days.

Next, assumed that 1) these vectors are mutually independent and have a common

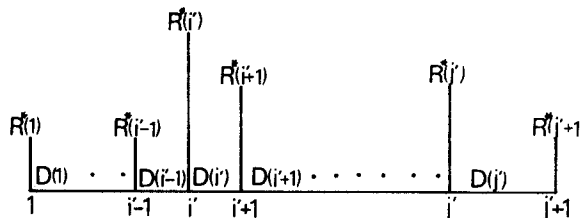
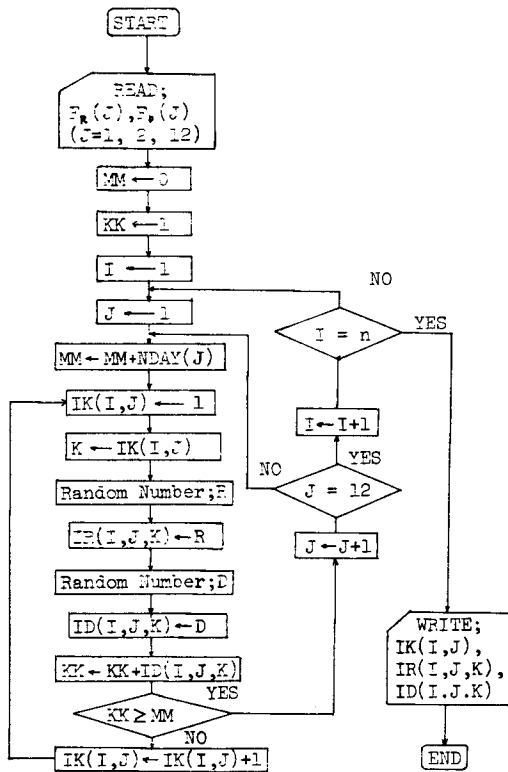


Fig. 7. Illustration of the daily precipitation intensity $R^*(i)$ and the continuous dry days $D(i)$.

distribution function, and 2) $R^*(i')$ is independent of $D(i')$, we may transform the daily precipitation $R(i')$ into two mutually independent processes, $(R^*(i'), D(i'))$.

Therefore, we may simulate the daily precipitation at the base station by the following procedures:

- 1) For each month, count the frequency distributions of R^* and D respectively.
- 2) For each R^* and D , divide up the year into the months with similar distribution by the χ^2 -test of independence.
- 3) Reorganize the months with similar distribution for both R^* and D , and call those months "populations".



I; Year $F_r(j)$; Distribution function of
 J; Month the daily precipitation intensity
 KK; Day $F_d(j)$; Distribution function of
 MM, Total days the continuous dry days
 n; Simulated year $IR(I, J, K)$; Simulated precipitation intensity
 NDAY(J); Days of J-th month $ID(I, J, K)$; Simulated dry days
 $IK(I, J)$; Number of precipitation days

Fig. 8. Flow chart for the sequential simulation at the base station.

- 4) For each population, after the probabilities of exceedance over the subdivided classes are calculated for R^* and D , the distribution functions F_R and F_D are estimated from the least square method.

Once the populations are defined and the functions F_R and F_D are determined, the daily precipitation may be simulated according to Figure 8.

4. Application to the Yodo River basin and their results

4-1. The research data

Figure 9 shows the general map of the basin. The basin may be divided broadly

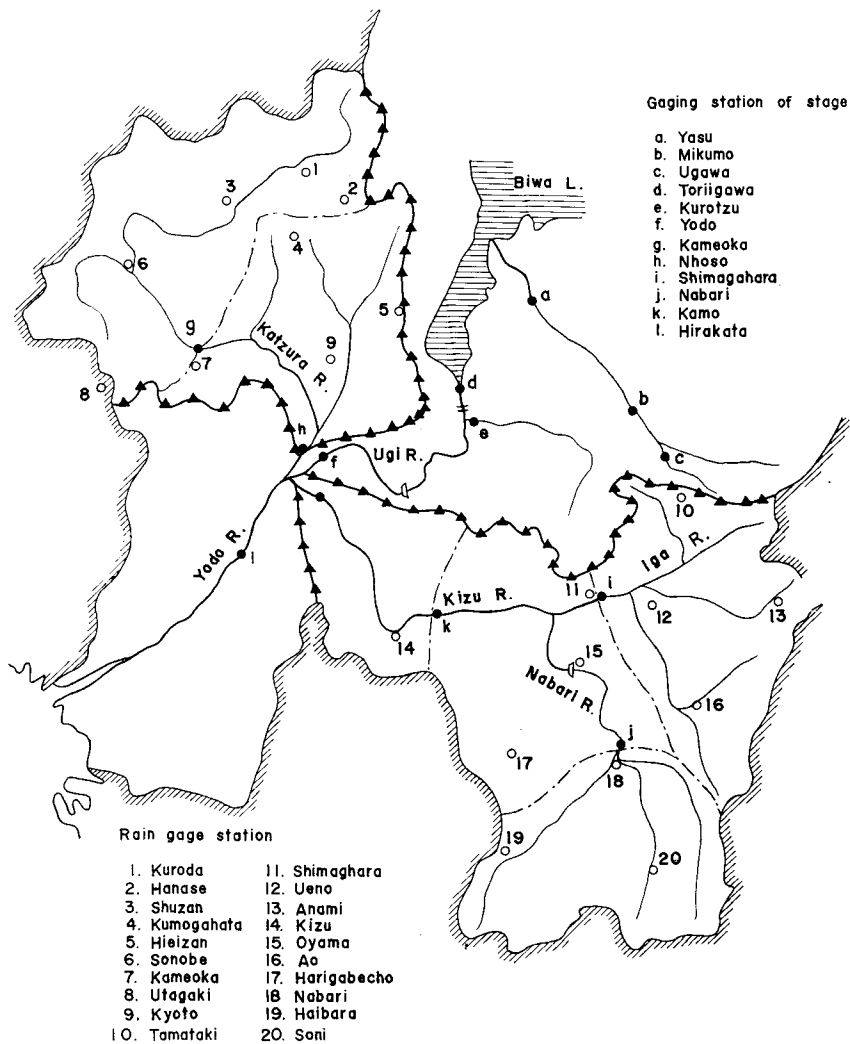


Fig. 9. General map of Yodo River basin.

into Kizu, Uji and Katsura River basins and in the upper region of Uji River basin there is Lake Biwa. The research data for identifying the long range runoff systems are Kameoka and Nohso in the Katsura River basin, and Nabari, Shimagahara and Kamo in the Kizu River basin. Because of the storage effect by Lake Biwa and an artificial control by Amagase dam, the Uji River basin was not analyzed.

Furthermore, the areal precipitation as input data to those analytical basins was calculated by the Thiessen method of precipitation stations shown in Fig. 9.

4-2. Unitgraph of groundwater runoff system and SUH of subsurface runoff systems

Once the daily decrease rate of water content in the subsurface stratum was calculated according to Eqs. (1) and (2), the unitgraph of groundwater runoff system and the SUH of subsurface runoff system are estimated based on Fig. 5. The analytical constants and parameters are summarized in Table 2. The runoff rate p in the downstream becomes smaller than that in the upstream.

Also, Fig. 10 shows the improved statistical unit hydrograph of subsurface runoff

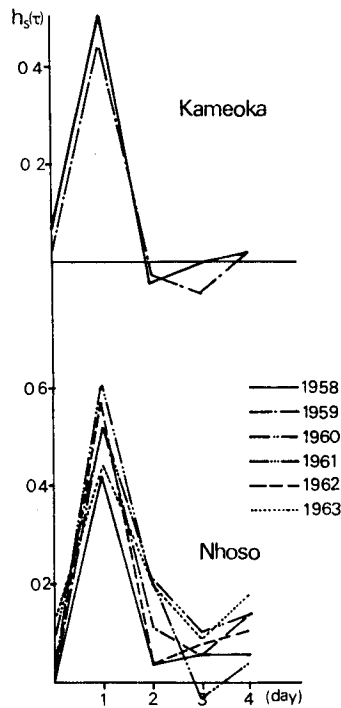


Fig. 10. Statistical unit hydrograph of subsurface runoff system at Kameoka and Nohso stations.

Table 2. Analytical constants and parameters.

Watershed	α (hr ⁻¹)	t_2-t_1 (hr)	γD (mm)	β (day ⁻¹)	r_G (day ⁻¹)	T_G (day)	t_{pG} (day)	p^*
Kameoka	0.0245	100	110	0.026	0.0700	50	1	1.0
Nhoso	0.0339	80	110	0.026	0.0550	50	1	0.9

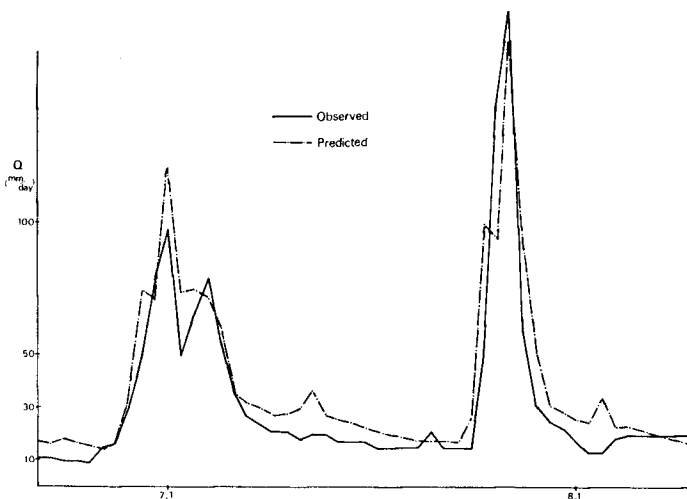


Fig. 11. Comparison between the observed and predicted river discharges at Kameoka.

system at Kameoka and Nohso. They coincide very well every year, not only in the whole shape but also in their peak values. Furthermore, the sum of predicted subsurface runoff and groundwater runoff components is shown in Fig. 11 compared with the observed runoff sequences. They coincide very well and it may be concluded that the prediction of groundwater and subsurface runoff is very satisfactory.

4-3. Spatial and sequential simulation results on the daily precipitation

For simulating the daily precipitation, Kyoto station was selected as the base station and Sonobe and Ueno stations as the sub-base stations. Their data length are 80 years (1886–1965) at Kyoto, 40 years (1926–1965) at Sonobe, 28 years (1938–1965) at Ueno and 6 years (1958–1963) at other stations. Fig. 12 shows the isolines of inter-station correlations about Kyoto, Sonobe and Ueno stations.

Table 3 shows the occurrence numbers of (*R.R*), (*R.D*), (*D.R*) and (*D.D*) systems between Ueno, Sonobe and Kyoto stations. The occurrence number of (*R.R*) system is smaller than that of (*D.D*) system. On the other hand, though the number of (*R.D*) nearly equals that of (*D.R*) throughout the year between Kyoto and Ueno, for Sonobe

station, (*D.R*) system has a great occurrence number in winter season. Also, Table 4 shows the comparison between observed data and simulated data with different standard deviations for $R^*(z) \geq 10$ and $R^*(z) < 10$ (mm/day). The simulated data has

Table 3. Occurrence numbers of (R.R), (R.D), (D.R) and (D.D).

MONTH	1		2		3		4		5		6	
STATION												
OSAKA (1926-1945)	92	53	108	54	164	74	168	43	168	35	183	42
	26	447	23	373	37	343	29	358	28	387	39	334
UENO (1938-1945)	31	19	54	9	82	13	69	10	76	4	87	10
	13	183	20	139	14	137	12	147	13	153	13	128
HIKONE (1926-1945)	116	29	128	34	174	64	153	58	138	65	151	74
	220	253	158	238	104	276	73	314	59	356	65	308
SONOBE (1926-1945)	95	50	114	48	153	85	152	59	133	70	157	68
	108	365	100	296	88	292	76	311	64	351	76	297
MONTH	7		8		9		10		11		12	
STATION												
OSAKA (1926-1945)	160	89	131	76	185	38	159	33	133	39	102	52
	33	336	53	358	62	313	27	399	30	296	38	426
UENO (1938-1945)	70	23	64	19	73	21	73	8	53	11	36	15
	14	139	37	126	20	124	11	154	13	161	12	183
HIKONE (1926-1945)	164	85	125	82	179	68	143	49	123	49	102	52
	72	297	73	338	72	279	89	337	106	320	169	295
SONOBE (1926-1945)	175	74	131	76	184	63	133	59	123	49	103	51
	61	308	64	347	79	272	83	343	95	331	101	363

Table 4. Comparison between observed data and simulated data at Ueno.

Month	1	2	3	4	5	6	7	8	9	10	11	12
R. R	0.791	0.739	0.789	0.837	0.851	0.858	0.798	0.717	0.767	0.866	0.788	0.742
	0.656	0.757	0.731	0.738	0.864	0.679	0.611	0.641	0.655	0.727	0.756	0.651
D. R	0.081	0.093	0.114	0.082	0.109	0.142	0.171	0.186	0.142	0.102	0.076	0.104
	0.077	0.135	0.093	0.080	0.072	0.084	0.108	0.233	0.145	0.063	0.072	0.065

upper: observed under: simulated

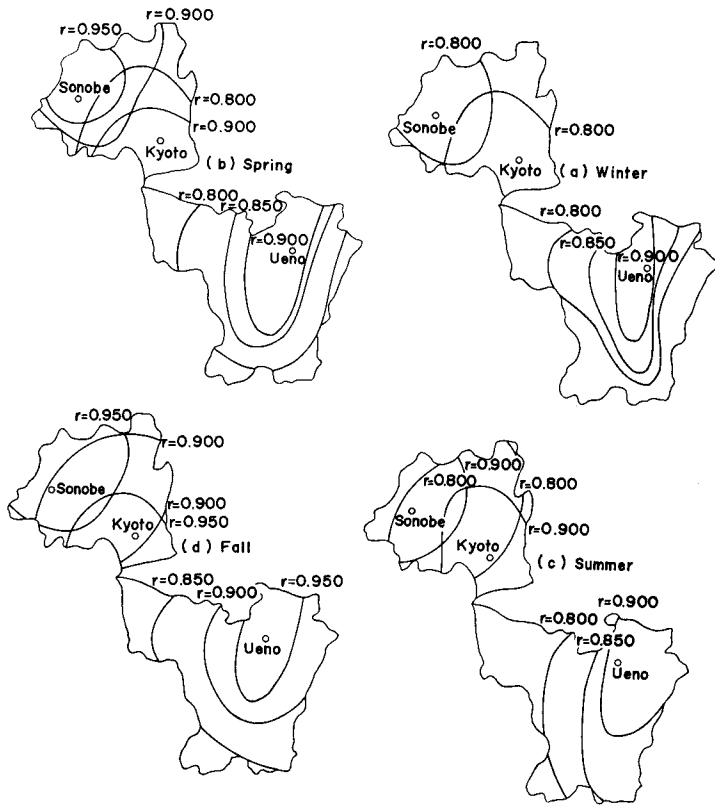


Fig. 12. Isolines of inter-station correlations about Kyoto, Sonobe and Ueno stations.

good agreement with the observed, except for June and July. We believe that if the variable $R^*(i)$ are subdivided much more, their agreement will become better.

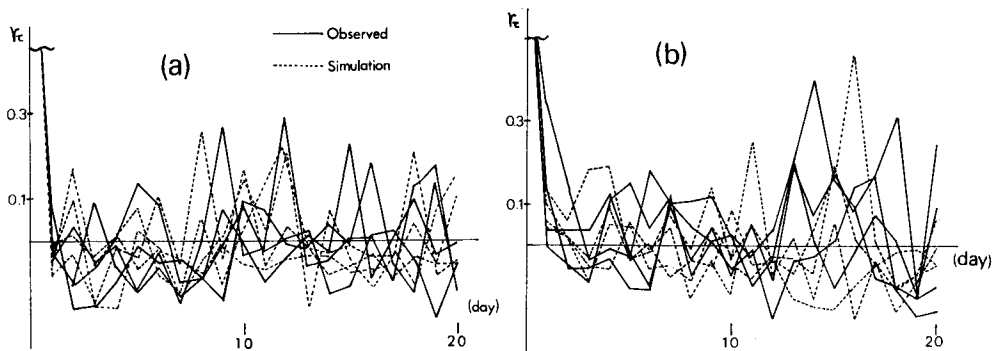


Fig. 13. Comparison between observed and simulated data (daily precipitation) (a) Winter (b) Summer.

Table 5. Distributions of the daily precipitation intensity and the continuous dry days.

Month		1	2	3	4	5	6
Number of Precipitation days	Mean Value	8.675	9.225	12.075	11.950	11.100	13.600
	Variance	11.815	7.461	8.994	7.741	5.733	12.810
Number of Continuous dry days	Mean Value	3.055	2.809	2.372	2.352	2.681	2.052
	Standard Deviation	3.025	2.527	1.937	1.806	2.369	1.820
Month days divided by Mean value of Continuous dry days		9.820	9.968	12.647	12.755	11.189	14.619
Month		7	8	9	10	11	12
Number of Precipitation days	Mean Value	12.525	9.825	12.650	9.700	8.350	8.050
	Variance	16.102	11.635	12.079	8.677	3.772	8.818
Number of Continuous dry days	Mean Value	2.275	2.776	2.178	2.813	3.361	3.326
	Standard Deviation	2.386	2.868	2.004	2.598	2.915	3.189
Month days divided by Mean value of Continuous dry days		13.186	10.806	13.774	10.664	8.925	9.019

Finally, let us discuss the simulated results at Kyoto base station. Table 5 shows that the continuous dry days have approximately an exponential distribution and the number of precipitation days the poisson distribution respectively. Also, considering that the values at the lowest low nearly equals the mean value of the number of precipitation days, our treatment for two processes R^* and D may be effective for sequential simulation. Thus, we divided the year into the following seven populations by the χ^2 -test of independence. I, Dec., Jan., Feb.; II, Mar.; III, Apr., May; IV, Jun.,

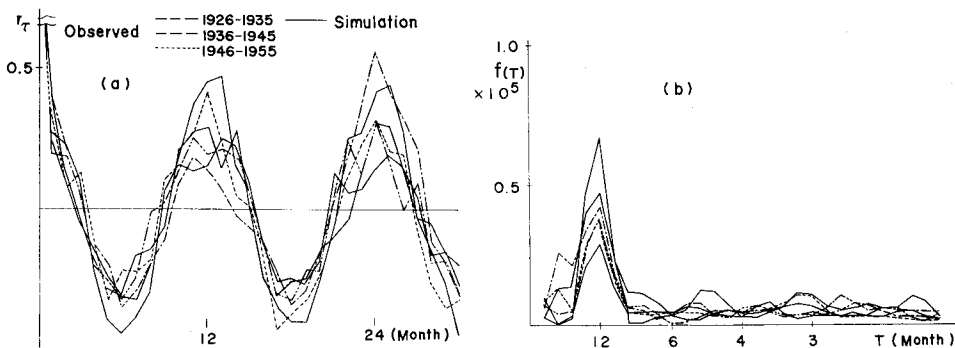


Fig. 14. Comparison between observed and simulated data (monthly precipitation) (a) Correlogram (b) Power spectrum.

Jul.; V, Aug.; VI, Sep.; VII, Oct., Nov.. The comparisons between observed and simulated data are shown in Fig. 13 and Fig. 14. Fig. 13 corresponds to the daily precipitation and Fig. 14 to the monthly precipitation with the sum of simulated daily data. The simulated data reflects sufficiently the characteristics of observed data.

From the above results, we may conclude that methods proposed in this paper are effective for simulating the daily precipitation over a long period and in a wide area.

5. Application to the runoff simulation at Nohso

5-1. Areal precipitation as input to SUH method

Combining the simulated daily precipitation with the improved statistical unit hydrograph, we obtain the simulated runoff data. In this case, because the input to SUH are lumped data, we must estimate the areal precipitation from the simulated data given in section 4. The procedures are as follows:

a) for estimating the daily precipitation at all other stations up to the length of observed data at the sub-base station - First, determine the influential domain of the base or sub-base station from the regional correlation analysis between the base or sub-base station and the surrounding stations. Second, interpolate the daily precipitation at stations in the domain by Eq. (14). Lastly, these estimated data and the observed daily precipitation at the base or sub-base station are transformed into the areal daily precipitation by Thiessen method.

b) for estimating the daily precipitation at all other stations up to the length of observed data at the base station - In this case, interpolate the daily precipitation at the sub-base station with spatial simulation method between the base and sub-base stations. Next, using the regional correlation analysis, estimate the daily precipitation at all stations up to the length of observed data at the base station. The last procedure is the same as method a).

c) for estimating the daily precipitation at all other stations up to more than the length of observed data at the base station - Simulate the daily precipitation at the base station for long period with sequential simulation and using successively methods b) and a). The daily precipitation at all other stations are estimated up to more than the length of observed data at the base station. Lastly, combining these simulated data with the Thiessen method, we obtain the areal daily precipitation for a long period.

5-2. Comparison between the observed and simulated runoff data

At Nohso in the Katsura River basin, the daily areal precipitation was simulated according to method b) in the previous section, 5-1. That is to say, once the influential domains of Kyoto base station and Sonobe sub-base station were determined from the

regional correlation results such as Fig. 12, and the daily precipitation at Sonobe was estimated from spatial simulation between Kyoto and Sonobe stations, we transformed the simulated data at the sub-base station and the observed data at the base station into the data at all other stations in their domains. Finally, all of this data was transformed into the areal precipitation with the Thiessen method.

On the other hand, as for the basin system models, we used the average of the improved statistical unit hydrographs shown in Fig. 10 and the unitgraph with the same parameters as Table 2. Therefore, combining the simulated daily areal precipitation with the long range runoff system models, the runoff data were simulated.

Fig. 15 shows the comparison between the observed and simulated data. The simulated runoff data reflect sufficiently the observed data. If we are allowed to hope for better agreement, we must improve the simulation method only in those days which show the greatest precipitation intensity. However, considering that these methods are applied to June with intensive variation of river discharge, the good agreement between the observed and simulated data may verify that the combination of the improved statistical unit hydrograph method and the simulation method of the areal daily precipitation are effective for the runoff simulation.

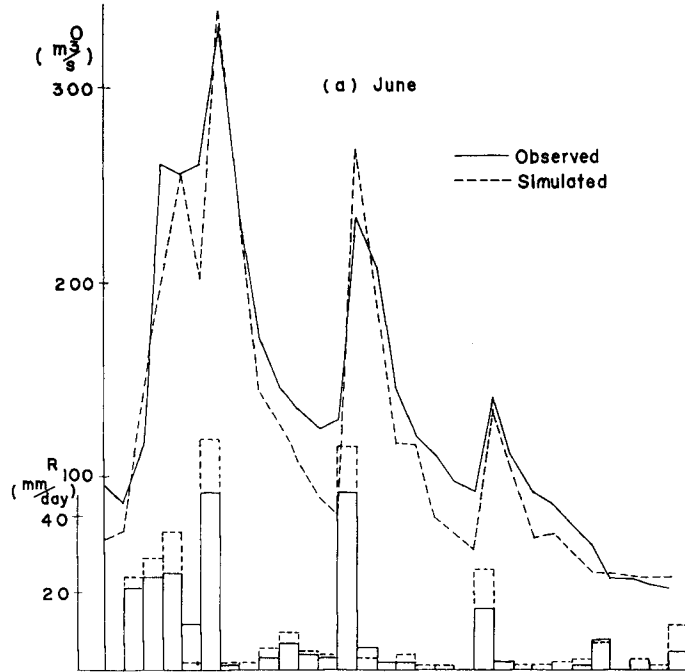


Fig. 15. Comparison between observed and simulated data (areal daily precipitation and daily river discharge).

6. Conclusions

In this paper, the runoff simulation method has been discussed in order to obtain effective information for water resources planning. The framework consists of the identification of the long range runoff system and the simulation for the areal daily precipitations while the runoff data are simulated by their combination. The results obtained are summarized as follows:

- 1) The improved statistical unit hydrograph method is an effective method for the analysis and synthesis of long range runoff system responses, especially, the satisfactory agreement between the observed data and the predicted ones makes it possible to predict the daily runoff data and to complement the lack of runoff data.
- 2) Once the precipitation stations are classified into the base, sub-base and surrounding stations, the daily precipitation data are simulated over a long period and in a wide area through the successive combination of regional correlation analysis between the base or sub-base and surrounding stations, spatial simulation between the base and sub-base stations, and sequential simulation at the base station.
- 3) The simulated runoff data by the combination of SUH method and the simulation method for daily precipitation, reflect the observed data with sufficient accuracy. So, it is concluded that a series of these simulation techniques may offer useful information for water resources planning.

In the future, those methods will be applied to many other basins and techniques for water resources planning will be developed using these approaches.

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