

A Note on the Asymptotic Behavior in Time of the Kinetic Energy in a Liquid-Solid Interaction Problem

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1 Introduction

Consider a sufficiently smooth, rigid body \mathcal{B} (the closure of a simply connected bounded domain of \mathbb{R}^3) completely immersed in a viscous liquid \mathcal{L} that fills the entire space outside \mathcal{B} . We assume that the center of mass G of \mathcal{B} is held fixed in a given position, while \mathcal{B} is allowed to rotate around G . The motion of the coupled system $\mathcal{S} := \mathcal{B} \cup \mathcal{L}$ is driven by a time dependent torque with respect to G , $M=M(t)$, acting on \mathcal{B} .

Recently, the question of the large time behavior of \mathcal{S} has attracted the attention of several authors, also in the more general case when G is free to move. More specifically, in [2] for \mathcal{B} a sphere, and in [5, 7] in the general case, under diverse assumptions on the initial data and driving mechanism, the same conclusion is drawn, namely, that as time grows indefinitely large, the velocity u of \mathcal{L} as well as translational (ξ) and angular (ω) velocities of \mathcal{B} will tend to 0 in certain norms. Actually, in [2, 7] it is also shown that G (in absence of external forces and torques) will cover a finite distance.

However, in the more general and interesting case of a body of *arbitrary* shape, the asymptotic decay in time of the velocity field of \mathcal{L} is established in norms that do not ensure that the total kinetic energy of the coupled system, defined as

$$E(t) := \frac{1}{2} \left\{ \rho \int_{\mathcal{D}} |u(t)|^2 + m |\xi(t)|^2 + \omega(t) \cdot \mathbf{I} \cdot \omega(t) \right\}$$

with m and \mathbf{I} mass and inertia tensor of \mathcal{B} , ultimately vanishes. Precisely, in [5, 7] it is proved that, as $t \rightarrow \infty$, while $\xi(t)$ and $\omega(t)$ tend pointwise to 0, the velocity field u tends to 0 in the L^q -norm if $q > 2$, thus excluding the case $q = 2$, representative of the kinetic energy of \mathcal{L} .⁽¹⁾

Objective of this note is to show that the kinetic energy, E , of any solution belonging to a suitable function class, \mathcal{C} , will eventually tend to 0. As shown in [5], the class \mathcal{C} is certainly not empty, provided the initial data are prescribed in appropriate function spaces with their magnitude is opportunely restricted, and $M(t)$ vanishes as $t \rightarrow \infty$ in the L^2 -sense. The method we use relies heavily upon establishing a space-weighted estimate on the solutions in combination with a uniform bound on the pressure field. Unfortunately, this approach does not seem to work if G is free to move, and therefore we defer to a future work the study of the more general case.

2 Equations of Motions and Preliminary Results

We shall describe the motion of the coupled system \mathcal{S} with respect to a frame, \mathcal{S} , attached to \mathcal{B} and with its origin at an interior point of \mathcal{B} . In this way, in particular, the domain occupied by \mathcal{L} becomes time-independent, and we will denote it by $\mathcal{D} (:= \mathbb{R}^3 \setminus \mathcal{B})$ and by Σ its boundary. We suppose \mathcal{D} of class

⁽¹⁾As a matter of fact, in [5] it is only proved $\lim_{t \rightarrow \infty} \|u(t)\|_6 = 0$. However, by elementary interpolation, for any $q \in (2, 6)$, we have $\|u(t)\|_q \leq \|u(t)\|_2 \|u(t)\|_6$, which, since $\|u(t)\|_2$ is uniformly bounded [5, Theorem 2.1], shows the claimed result.

C^2 . Thus, with the notation introduced in the previous section, the governing equations of the motion of \mathcal{S} are given by (see [4])

$$\left. \begin{aligned} \varrho \partial_t u &= \operatorname{div} \mathbb{T}(u, p) - \varrho[(u - V) \cdot \nabla u + \omega \times u] \\ \operatorname{div} u &= 0 \\ u &= V \text{ at } \Sigma \times (0, \infty) \end{aligned} \right\} \text{ in } \mathcal{D} \times (0, \infty) \quad (2.1)$$

$$\begin{aligned} \lim_{|x| \rightarrow \infty} u(x, t) &= 0, \quad t \in (0, \infty) \\ \mathbf{l} \cdot \dot{\omega} + \omega \times (\mathbf{l} \cdot \omega) + \int_{\Sigma} x \times \mathbb{T}(u, p) \cdot n &= \mathbf{M} \end{aligned} \quad (2.2)$$

endowed with initial conditions

$$u(x, 0) = u_0(x), \quad x \in \mathcal{D}, \quad \omega(0) = \omega_0. \quad (2.3)$$

In the above equations, p is the pressure field of \mathcal{L} , ϱ its (constant) density, and $V(x, t) := \omega(t) \times x$. Also, \mathbb{T} is the Cauchy stress tensor given by

$$\mathbb{T}(u, p) = 2\mu \mathbb{D}(u) - p \mathbb{I}, \quad 2\mathbb{D}(u) := \nabla u + (\nabla u)^\top,$$

with μ shear-viscosity coefficient and \mathbb{I} identity. Moreover, m is the mass of \mathcal{B} and \mathbf{l} its inertia tensor relative to G . Furthermore,

$$\mathbf{M}(t) = \mathbb{Q}^\top(t) \cdot \mathbf{M}(t), \quad (2.4)$$

with the tensor \mathbb{Q} satisfying the following equation

$$\left\{ \begin{aligned} \dot{\mathbb{Q}} &= -\mathbb{Q} \cdot \mathbb{Q}(\omega) \\ \mathbb{Q}(0) &= \mathbb{I} \end{aligned} \right. \quad \mathbb{Q}(\omega) = \begin{bmatrix} 0 & \omega_3 & -\omega_2 \\ -\omega_3 & 0 & \omega_1 \\ \omega_2 & -\omega_1 & 0 \end{bmatrix} \quad (2.5)$$

In particular, \mathbb{Q} is proper orthogonal, that is,

$$\mathbb{Q}^\top(t) \cdot \mathbb{Q}(t) = \mathbb{Q}(t) \cdot \mathbb{Q}^\top(t) = \mathbb{I}, \quad \det \mathbb{Q}(t) = 1, \quad \text{for all } t \in \mathbb{R}.$$

We wish to introduce a suitable class of functions satisfying (2.1). To this end, let ⁽²⁾

$$\mathcal{R} := \{\bar{u} \in C^\infty(\mathbb{R}^3) : \bar{u}(x) = \bar{u} \times x, \quad \bar{u} \in \mathbb{R}^3\},$$

and define

$$\mathcal{V}(\mathcal{D}) = \{u \in W^{1,2}(\mathcal{D}) : \operatorname{div} u = 0 \text{ in } \mathcal{D}, \quad u|_{\Sigma} = \bar{u}, \text{ for some } \bar{u} \in \mathcal{R}\}.$$

We also set

$$\begin{aligned} B_R &:= \{x \in \mathbb{R}^3 : |x| < R\}; \quad R_* := 2 \inf \{R \in (0, \infty) : \mathcal{B} \cap B_R \supset \mathcal{B}\}; \\ \mathcal{D}_R &:= \mathcal{D} \cap B_R, \quad \mathcal{D}^R = \mathcal{D} \setminus \overline{\mathcal{D}_R}, \quad R > R_*. \end{aligned}$$

Definition 2.1 A triple (u, p, ω) is in the class \mathcal{C} , if

$$\begin{aligned} u &\in L^\infty(0, \infty; \mathcal{V}(\mathcal{D})), \quad \nabla u \in L^2(0, \infty; W^{1,2}(\mathcal{D})) \\ \omega &\in W^{1,2}(0, \infty), \quad \nabla p \in L^2(0, \infty; L^2(\mathcal{D})), \\ u &\in C([0, \tau]; W^{1,2}(\mathcal{D}_R)), \quad \partial_t u, p \in L^2(0, \infty; L^2(\mathcal{D}_R)), \quad \text{for all } R \geq R_*, \end{aligned}$$

and, in addition, (u, p, ω) satisfies (2.1).

⁽²⁾We shall use standard notation for function spaces, see [1]. So, for instance, $L^q(\mathcal{A})$, $W^{m,q}(\mathcal{A})$, $W_0^{m,q}(\mathcal{A})$, etc., will denote the usual Lebesgue and Sobolev spaces on the domain \mathcal{A} , with norms $\|\cdot\|_{q,\mathcal{A}}$ and $\|\cdot\|_{m,q,\mathcal{A}}$, respectively. Whenever confusion will not arise, we shall omit the subscript \mathcal{A} . Occasionally, for X a Banach space, we denote by $\|\cdot\|_X$ its associated norm. Moreover $L^q(I; X)$, $C(I; X)$ I real interval, denote classical Bochner spaces.

The class \mathcal{C} is not empty, as secured by the following result, which is a particular case of [5, Theorem 2.1].

Theorem 2.1 *Let $M \in L^2(0, \infty; \mathbb{R}^3)$ and $u_0 \in \mathcal{V}(\mathcal{D})$ with $u_0|_{\Sigma} = \omega_0 \times x$. Then, there is $\delta > 0$ such that if*

$$\|u_0\|_{1,2} + |\omega_0| + \|M\|_{L^2(0,\infty)} \leq \delta, \quad (2.6)$$

there exists at least one solution $(\mathbf{u}, p, \omega, \mathbb{Q})$ to (2.1) – (2.5) with (u, p, ω) in the class \mathcal{C} .

From Definition 2.1 and Sobolev inequality, we infer that

$$p \in L^2(0, \infty; L^6(\mathcal{D})), \quad (2.7)$$

while we only have $p \in L^2(0, \infty; L^2(\mathcal{D}_R))$ for all $R > R_*$. Our first objective is to prove that the latter property holds, in fact, in the whole of \mathcal{D} . Precisely, we have the following.

Proposition 2.1 *Let $(u, p, \omega) \in \mathcal{C}$. Then,*

$$p \in L^2(0, \infty; L^2(\mathcal{D})).$$

In order to prove the proposition, we need the next two results, whose proofs are given in [5, Lemma 3.2] and [3, Lemma 3.1], respectively.

Lemma 2.1 *Let (u, p, ξ, ω, Q) be in the class \mathcal{C} . Then for a.a. $t \in (0, \infty)$*

$$\nabla p \in L^{q_1}(\mathcal{D}^{2R_*}), \quad p \in L^{q_2}(\mathcal{D}^{2R_*}), \quad \text{for all } q_1 \in (1, 6], \quad q_2 \in (\frac{3}{2}, \infty].$$

Lemma 2.2 *Let $g \in C_0^\infty(\mathcal{D})$. Then the Neumann problem*

$$\begin{aligned} \Delta \varphi &= g \quad \text{in } \mathcal{D} \\ \frac{\partial \varphi}{\partial n} &= 0 \quad \text{at } \Sigma \end{aligned} \quad (2.8)$$

with the side condition

$$\lim_{|x| \rightarrow \infty} \nabla \varphi(x) = 0. \quad (2.9)$$

has one and only one solution such that for all $s \in (1, 3)$

$$D^2 \varphi \in L^s(\mathcal{D}), \quad \nabla \varphi \in L^{3s/(3-s)}(\mathcal{D})$$

and

$$\int_{\mathcal{D}_K} \varphi = 0, \quad (2.10)$$

for a fixed $K > R_$. Moreover, $\varphi \in L^\infty(\mathcal{D})$ and*

$$\|\varphi\|_{s, \mathcal{D}_K} + \|\nabla \varphi\|_{3s/(3-s)} + \|D^2 \varphi\|_s \leq c \|g\|_s, \quad (2.11)$$

where the constant c depends only on s, K and \mathcal{D} .

Proof of Proposition 2.1. By formally applying the div operator on both sides of (2.1)₁ and observing that

$$\operatorname{div} [\rho(\partial_t u + \omega \times x \cdot \nabla u - \omega \times u) - \Delta u] = 0,$$

one easily deduces that p satisfies for a.a. $t \in (0, \infty)$ the following Neumann problem in the distributional sense

$$\begin{aligned} \Delta p &= \operatorname{div} (u \cdot \nabla u) \text{ in } \mathcal{D}, \\ \frac{\partial p}{\partial n} &= -[\rho \dot{\omega} \times x + \operatorname{curl} a] \cdot n \text{ at } \mathcal{D}, \quad a := \operatorname{curl} u. \end{aligned} \quad (2.12)$$

Let g and φ be as in Lemma 2.2. Multiplying both sides of (2.12)₁ by g , integrating by parts over \mathcal{D}_r , and taking into account (2.8) and (2.12)₂, we show

$$\int_{\mathcal{D}_r} p g = - \int_{\Sigma \cup \partial B_r} \varphi \frac{\partial p}{\partial n} + \int_{\mathcal{D}_r} \varphi \operatorname{div} (u \cdot \nabla u) = \int_{\Sigma} \varphi [\rho \dot{\omega} \times x + \operatorname{curl} a] \cdot n + \rho \int_{\mathcal{D}_r} \varphi \partial_i \partial_j (u_i u_j) + \sigma_1(r), \quad (2.13)$$

where we used the identity $\operatorname{div} (u \cdot \nabla u) = \partial_i \partial_j (u_i u_j)$, and set

$$\sigma_1(r) := - \int_{\partial B_r} (\varphi \frac{\partial p}{\partial n} - p \frac{\partial \varphi}{\partial n}).$$

By a double integration by parts, we infer

$$\begin{aligned} \int_{\mathcal{D}_r} \varphi \partial_i \partial_j (u_i u_j) &= \int_{\mathcal{D}_r} u_i u_j \partial_i \partial_j \varphi + \int_{\Sigma \cup \partial B_r} [\varphi u \cdot \nabla u \cdot n - u \cdot \nabla \varphi u \cdot n] \\ &= \int_{\mathcal{D}_r} u_i u_j \partial_i \partial_j \varphi + \int_{\Sigma} [\varphi \omega \times x \cdot \nabla u \cdot n - (\omega \times x \cdot \nabla \varphi) \omega \times x \cdot n] + \sigma_2(r), \end{aligned} \quad (2.14)$$

where

$$\sigma_2(r) := \int_{\partial B_r} [\varphi u \cdot \nabla u \cdot n - u \cdot \nabla \varphi u \cdot n].$$

By employing Hölder inequality, we deduce

$$\int_{R_*}^{\infty} |\sigma_2(r)| dr \leq \|\varphi\|_{\infty} \|u\|_2 \|\nabla u\|_2 + \|\nabla \varphi\|_2 \|u\|_4^2, \quad (2.15)$$

and, likewise, we infer

$$\int_{2R_*}^{\infty} r^{-\frac{1}{2}} |\sigma_1(r)| dr \leq \|\varphi\|_{\infty} \|r^{-\frac{1}{2}}\|_{3, (2R_*, \infty)} \|\nabla p\|_{\frac{3}{2}, \mathcal{D}^{2R_*}} + (2R_*)^{-\frac{1}{2}} \|\nabla \varphi\|_2 \|p\|_2. \quad (2.16)$$

In view of Lemma 2.1, and the fact that $u \in \mathcal{C}$, we find that the right-hand side in both equations (2.15) and (2.16) is finite. Therefore, there exists an unbounded sequence $\{r_n\}$ such that

$$\lim_{r_n \rightarrow \infty} [\sigma_1(r_n) + \sigma_2(r_n)] = 0.$$

Employing this information in (2.13), (2.14) we conclude

$$\begin{aligned} \int_{\mathcal{D}} p g &= \int_{\Sigma} \{\varphi [\rho \dot{\omega} \times x + \operatorname{curl} a] \cdot n + \rho [\varphi \omega \times x \cdot \nabla u \cdot n - (\omega \times x \cdot \nabla \varphi) \omega \times x \cdot n]\} + \rho \int_{\mathcal{D}} u_i u_j \partial_i \partial_j \varphi \\ &:= I_{\Sigma 1} + I_{\Sigma 2} + I_{\Sigma 3} + I_{\Sigma 4} + I_{\mathcal{D}}. \end{aligned} \quad (2.17)$$

In the following estimates, we shall use several times the classical trace inequality

$$\|w\|_{1, \Sigma} \leq c \|w\|_{1, 1, \mathcal{D}_K}. \quad (2.18)$$

We thus have

$$|I_{\Sigma 1}| + |I_{\Sigma 4}| \leq c (|\dot{\omega}| + |\omega|^2) \|\varphi\|_{2,2,\mathcal{D}_K}. \quad (2.19)$$

Moreover, employing (2.18) along with Schwarz inequality, we get

$$|I_{\Sigma 3}| \leq c \|\varphi\| \|\nabla u\|_{1,1,\mathcal{D}_K} \leq c (\|\varphi\|_{2,\mathcal{D}_K} \|\nabla u\|_{2,\mathcal{D}_K} + \|\varphi\|_{1,2,\mathcal{D}_K} \|\nabla u\|_{1,2,\mathcal{D}_K}),$$

which, in turn, gives

$$|I_{\Sigma 3}| \leq c \|\nabla u\|_{1,2,\mathcal{D}_K} \|\varphi\|_{2,2,\mathcal{D}_K}. \quad (2.20)$$

Also, by Schwarz inequality,

$$|I_{\mathcal{D}}| \leq \|u\|_4^2 \|D^2 \varphi\|_2. \quad (2.21)$$

The estimate for $I_{\Sigma 2}$ requires a little care. Let ζ be a function which is one in a neighborhood of Σ and zero at large distances. We have

$$I_{\Sigma 2} = - \int_{\mathcal{D}} \operatorname{div} (\varphi \operatorname{curl} (\zeta a)) = - \int_{\mathcal{D}} \nabla \varphi \cdot \operatorname{curl} (\zeta a). \quad (2.22)$$

Using the identity

$$-\operatorname{curl} A \cdot B + \operatorname{curl} B \cdot A = \operatorname{div} (A \times B)$$

with $A = \zeta a$ and $B = \nabla \varphi$, from (2.22), (2.18) and Schwarz inequality we show

$$|I_{\Sigma 2}| = \left| \int_{\Sigma} a \times \nabla \varphi \cdot n \right| \leq c \|\nabla u\| \|\nabla \varphi\|_{1,1,\mathcal{D}_K} \leq c (\|\nabla u\|_{2,\mathcal{D}_K} \|\nabla \varphi\|_{1,2,\mathcal{D}_K} + \|D^2 u\|_{2,\mathcal{D}_K} \|\nabla \varphi\|_{2,\mathcal{D}_K}),$$

which leads to

$$|I_{\Sigma 2}| \leq c \|\nabla u\|_{1,2,\mathcal{D}_K} \|\varphi\|_{2,2,\mathcal{D}_K}. \quad (2.23)$$

If we employ (2.19)–(2.23) in (2.17) and take into account (2.11), we arrive at

$$\left| \int_{\mathcal{D}} p g \right| \leq c (|\dot{\omega}| + |\omega|^2 + \|u\|_4^2 + \|\nabla u\|_2 + \|D^2 u\|_2) \|g\|_2. \quad (2.24)$$

Since g is arbitrary in $C_0^\infty(\mathcal{D})$, and, by Sobolev embedding theorem,

$$\|u\|_4^2 \leq c \|u\|_2^{\frac{1}{2}} \|\nabla u\|_2^{\frac{3}{2}}, \quad (2.25)$$

from (2.24) it follows that $p \in L^2(\mathcal{D})$ for a.a. $t \in (0, \infty)$ and

$$\|p\|_2 \leq c (|\dot{\omega}| + |\omega|^2 + \|u\|_2^{\frac{1}{2}} \|\nabla u\|_2^{\frac{3}{2}} + \|\nabla u\|_2 + \|D^2 u\|_2). \quad (2.26)$$

The proposition is then a consequence of (2.26) and the fact that (u, ω) is in the class \mathcal{C} . \square

We conclude this section with another preparatory result concerning the asymptotic behavior of functions in the class \mathcal{C} .

Lemma 2.3 *Let (u, p, ω) be in the class \mathcal{C} . Then,*

$$\lim_{t \rightarrow \infty} \|u(t)\|_6 = 0. \quad (2.27)$$

Proof. For $R \geq 2R_*$, let $\psi_R = \psi_R(r)$ be a smooth, non-increasing “cut-off” function such that $\psi_R = 1$ for $r \leq R$, $\psi_R = 0$ for $r \geq 2R$, and $|\nabla \psi_R| \leq C R^{-1}$, for some constant C independent of R . We then test (2.1)₁ by $\psi_R \operatorname{div} \mathbb{T}(u, p)$ to get

$$\int_{\mathcal{D}} \psi_R \partial_t u \cdot \operatorname{div} T = \|\sqrt{\psi_R} \operatorname{div} T\|_2^2 - \varrho \int_{\mathcal{D}} (\psi_R u \cdot \nabla u \cdot \operatorname{div} T - \psi_R \Phi \cdot \operatorname{div} T). \quad (2.28)$$

By integration by parts, we formally show the following identity that can be rigorously justified by a standard approximation procedure

$$\begin{aligned} \int_{\mathcal{D}} \psi_R \partial_t u \cdot \operatorname{div} \mathbb{T} &= \int_{\mathcal{D}} [\operatorname{div} (\psi_R \partial_t u \cdot \mathbb{T}) - 2\mu \psi_R \mathbb{D}(\partial_t u) : \mathbb{D}(u)] \\ &= \int_{\Sigma} \dot{V} \cdot \mathbb{T} \cdot n - \mu \frac{d}{dt} \|\sqrt{\psi_R} \mathbb{D}(u)\|_2^2 - \int_{\mathcal{D}} \nabla \psi_R \cdot \mathbb{T} \cdot \partial_t u. \end{aligned}$$

Set $\Phi := \omega \times x \cdot \nabla u - \omega \times u$ and recall [6, Lemma 2.4(b)]

$$\Phi \cdot n = 0 \quad \text{at } \Sigma \quad (2.29)$$

Thus, integrating by parts and with the help of (2.29) we show

$$\int_{\mathcal{D}} \psi_R \Phi \cdot \operatorname{div} \mathbb{T} = 2\mu \int_{\Sigma} \Phi \cdot \mathbb{D}(u) \cdot n - 2\mu \int_{\mathcal{D}} \psi_R \partial_i \Phi_j (\mathbb{D}(u))_{ij} - \int_{\mathcal{D}} \nabla \psi_R \cdot \mathbb{T} \cdot \Phi. \quad (2.30)$$

Next, since $\operatorname{div} u = \operatorname{div} V = 0$, we get

$$2\partial_i \Phi_j (\mathbb{D}(u))_{ij} = \operatorname{div} (\Phi \cdot \nabla u + \tfrac{1}{2} V |\nabla u|^2) + \omega \times \nabla u_i \cdot \nabla u_i - \nabla (\omega \times u) : \nabla u,$$

so that, substituting the latter in (2.30) and using Gauss theorem, we infer

$$\begin{aligned} \int_{\mathcal{D}} \psi_R \Phi \cdot \operatorname{div} \mathbb{T} &= -\mu \int_{\mathcal{D}} \psi_R (\omega \times \nabla u_i \cdot \nabla u_i - \nabla (\omega \times u) : \nabla u) + \mu \int_{\Sigma} (n \cdot \nabla u \cdot \Phi - \tfrac{1}{2} V \cdot n |\nabla u|^2) \\ &\quad + \int_{\mathcal{D}} \nabla \psi_R \cdot [2\mu (\nabla u^\top \cdot \Phi + \tfrac{1}{2} V |\nabla u|^2) - \mathbb{T} \cdot \Phi]. \end{aligned} \quad (2.31)$$

Collecting (2.28), (2.30) and (2.31) we deduce

$$\begin{aligned} \mu \frac{d}{dt} \|\sqrt{\psi_R} \mathbb{D}(u)\|_2^2 + \|\sqrt{\psi_R} \operatorname{div} \mathbb{T}\|_2^2 &= \int_{\Sigma} \left[\dot{V} \cdot \mathbb{T} \cdot n - \varrho \mu (n \cdot \nabla u \cdot \Phi - \tfrac{1}{2} V \cdot n |\nabla u|^2) \right] \\ &\quad + \varrho \int_{\mathcal{D}} \psi_R [u \cdot \nabla u \cdot \operatorname{div} \mathbb{T} + \mu (\omega \times \nabla u_i \cdot \nabla u_i - \nabla (\omega \times u) : \nabla u)] \\ &\quad - \varrho \int_{\mathcal{D}} \nabla \psi_R \cdot [\mathbb{T} \cdot \partial_t u + 2\mu (\nabla u^\top \cdot \Phi + \tfrac{1}{2} V |\nabla u|^2) - \mathbb{T} \cdot \Phi] := I_{\Sigma} + I_{\mathcal{D}} + I_R \end{aligned} \quad (2.32)$$

Arguing exactly as in the proof of [5, Eq. (3.22)] we show

$$\lim_{R \rightarrow \infty} \int_0^t I_R = 0, \quad \text{for all } t > 0. \quad (2.33)$$

Furthermore, as shown in the proof of [5, Theorem 2.1], we have

$$|I_{\mathcal{D}}| \leq c (\|\mathbb{D}(u)\|_2^3 + \|\mathbb{D}(u)\|_2^4 + \|\mathbb{D}(u)\|_2^6) + \tfrac{1}{4} \|\operatorname{div} \mathbb{T}\|_2^2 \quad (2.34)$$

Finally, using (2.18) multiple times along with the inequality [4, Lemma 4.9]

$$|\omega| \leq c \|\nabla u\|_2, \quad (2.35)$$

one can prove, in a way entirely similar to [5, Eq. (4.11)]

$$|I_\Sigma| \leq c \left[|\dot{\omega}|(\|\nabla u\|_{1,2} + \|p\|_{1,2}) + \|\mathbb{D}(u)\|_2^3 + \|\mathbb{D}(u)\|_2^4 \right] + \frac{1}{4} \|\operatorname{div} \mathbb{T}\|_2^2. \quad (2.36)$$

We now integrate both sides of (2.31) over $(0, t)$, $t \in (0, \infty)$, let $R \rightarrow \infty$ and employ (2.33), along with Lebesgue dominated convergence theorem. If we differentiate with respect to t the resulting equation, and take into account the estimates (2.34) and (2.36), we conclude, in particular,

$$\frac{d}{dt} \|\mathbb{D}(u)\|_2^2 \leq c \left[|\dot{\omega}|(\|\nabla u\|_{1,2} + \|p\|_{1,2}) + \|\mathbb{D}(u)\|_2^3 + \|\mathbb{D}(u)\|_2^4 + \|\mathbb{D}(u)\|_2^6 \right] := h(t) \quad (2.37)$$

Since $(u, p, \omega) \in \mathcal{C}$, and also in view of Proposition 2.1 we infer, on the one hand, $h \in L^1(0, \infty; \mathbb{R})$ and, on the other hand, the existence of an unbounded sequence of times $\{t_n\}$ such that

$$\lim_{t_n \rightarrow \infty} \|\mathbb{D}(u(t_n))\|_2 \rightarrow 0.$$

Thus, integrating both sides of (2.37) over the interval (t_n, t) , $t > t_n$, we get

$$\|\mathbb{D}(u(t))\|_2^2 \leq \|\mathbb{D}(u(t_n))\|_2^2 + \int_{t_n}^{\infty} h(s) \, ds$$

which implies

$$\lim_{t \rightarrow \infty} \|\mathbb{D}(u(t))\|_2 \rightarrow 0.$$

The latter furnishes the desired result after we use the inequality [4, Eq. (4.75)]

$$\|u\|_6 \leq c \|\mathbb{D}(u)\|_2, \quad u \in \mathcal{V}.$$

□

3 Main Result

In this section we will give a proof of the following result, representing the major achievement of this note.

Theorem 3.1 *Let (u, p, ω) be in the class \mathcal{C} . Suppose that*

$$\sqrt{\ln r} u_0 \in L^2(\mathcal{D}), \quad (r := \sqrt{x_i x_i}).$$

Then,

$$\lim_{t \rightarrow \infty} E(t) \equiv \frac{1}{2} \lim_{t \rightarrow \infty} (\|u(t)\|_2^2 + \omega(t) \cdot \mathbf{1} \cdot \omega(t)) = 0.$$

Proof. We begin to observe that by assumption $\omega \in W^{1,\infty}(0, \infty; \mathbb{R}^3)$ which delivers

$$\lim_{t \rightarrow \infty} |\omega(t)| = 0.$$

Therefore, we only have to show

$$\lim_{t \rightarrow \infty} \|u(t)\|_2 = 0. \quad (3.1)$$

To this end, let $\psi_R = \psi_R(r)$ be the “cut-off” function introduced in Lemma 2.3. By dot-multiplying through both sides of (2.1) by $\psi_R \ln r u$, integrating by parts over \mathcal{D} , and using the fact that $\nabla \psi_R \cdot \omega \times x =$

0, we show

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \|\psi_R \sqrt{\ln r} u(t)\|_2^2 &= \frac{1}{2} \int_{\mathcal{D}} \left(\ln r u^2 u \cdot \nabla \psi_R + \psi_R u^2 u \cdot \frac{x}{r^2} \right) - 2 \int_{\mathcal{D}} \ln r \mathbb{D}(u) : \mathbb{D}(u) \\ &\quad - 2 \int_{\mathcal{D}} (\mathbb{D}(u))_{ij} [\ln r (u_j \partial_i \psi_R + u_i \partial_j \psi_R) + \psi_R (u_j \frac{x_i}{r^2} + u_i \frac{x_j}{r^2})] \\ &\quad + \int_{\mathcal{D}} p u \cdot \left(\nabla \psi_R \ln r + \psi_R \frac{x}{r^2} \right) + \int_{\Sigma} \psi_R \ln r \omega \times x \cdot \mathbb{T}(u, p) \cdot n. \end{aligned} \quad (3.2)$$

Employing Hölder inequality multiple times, and recalling the properties of ψ_R , we get

$$\begin{aligned} \int_{\mathcal{D}} \{ \ln r u^2 u \cdot \nabla \psi_R - 2(\mathbb{D}(u))_{ij} [\ln r (u_j \partial_i \psi_R + u_i \partial_j \psi_R)] + p u \cdot \nabla \psi_R \} \\ \leq \| \ln r | \nabla \psi_R \|_{4, \mathcal{D}^R} (\|u\|_4^3 + 2\|\mathbb{D}(u)\|_2 \|u\|_4 + \|p\|_2 \|u\|_4) \\ \leq c R^{-\frac{1}{2}} \left(\|u\|_4^3 + \|\mathbb{D}(u)\|_2^{\frac{3}{2}} + \|p\|_2^{\frac{3}{2}} \right). \end{aligned}$$

On account of $(u, p) \in \mathcal{C}$ and (2.26) we thus infer

$$\lim_{R \rightarrow \infty} \int_0^t \left\{ \int_{\mathcal{D}} \{ \ln r u^2 u \cdot \nabla \psi_R - 2(\mathbb{D}(u))_{ij} [\ln r (u_j \partial_i \psi_R + u_i \partial_j \psi_R)] + p u \cdot \nabla \psi_R \} \right\} ds = 0, \quad \text{for all } t > 0. \quad (3.3)$$

Similarly, using Hardy's inequality

$$\int_{\mathcal{D}} \frac{u^2}{r^2} \leq 4 \|\nabla u\|_2^2$$

furnishes

$$\begin{aligned} \int_{\mathcal{D}} \frac{1}{r} \left| u^2 u \cdot \frac{x}{r} + p u \cdot \frac{x}{r} - 2(\mathbb{D}(u))_{ij} (u_j \frac{x_i}{r} + u_i \frac{x_j}{r}) \right| &\leq c \|r^{-1} u\|_2 (\|u\|_4^2 + \|p\|_2 + \|\mathbb{D}(u)\|_2) \\ &\leq c (\|u\|_4^4 + \|p\|_2^2 + \|\nabla u\|_2^2), \end{aligned}$$

which, in turn, since $(u, p) \in \mathcal{C}$, with the help of Proposition 2.1 and (2.25) entails

$$\int_0^\infty \left\{ \int_{\mathcal{D}} \frac{1}{r} \left| u^2 u \cdot \frac{x}{r} + p u \cdot \frac{x}{r} - 2(\mathbb{D}(u))_{ij} (u_j \frac{x_i}{r} + u_i \frac{x_j}{r}) \right| \right\} dt < \infty. \quad (3.4)$$

Finally, using (2.18) with $w = \mathbb{D}(u)$ and $w = p$, and recalling (2.35), we obtain

$$\left| \int_{\Sigma} \psi_R \ln r \omega \times x \cdot \mathbb{T}(u, p) \cdot n \right| \leq c \|\nabla u\|_2 (\|\nabla u\|_2 + \|D^2 u\|_2) + \|p\|_{1,2}$$

which, because $(u, p) \in \mathcal{C}$, with the help of Proposition 2.1 provides

$$\int_0^\infty \left| \int_{\Sigma} \psi_R \ln r \omega \times x \cdot \mathbb{T}(u, p) \cdot n \right| dt < \infty. \quad (3.5)$$

We now integrate both sides of (3.2) over $[0, t]$, arbitrary $t > 0$, and then pass to the limit $R \rightarrow \infty$. Taking into account (3.3), that $\psi_R \leq 1$, and employing Fubini's theorem, we thus receive, in particular,

$$\|\sqrt{\ln r} u(t)\|_2^2 - \|\sqrt{\ln r} u_0\|_2^2 \leq 2 \int_0^t \left\{ \int_{\mathcal{D}} \frac{1}{r} \left| u^2 u \cdot \frac{x}{r} + p u \cdot \frac{x}{r} - 2(\mathbb{D}(u))_{ij} (u_j \frac{x_i}{r} + u_i \frac{x_j}{r}) \right| \right\} ds, \quad (3.6)$$

which, by (3.4), (3.5) and the assumption, furnishes

$$\sup_{t \geq 0} \|\sqrt{\ln r} u(t)\|_2^2 \leq M < \infty. \quad (3.7)$$

For any fixed R , employing also Hölder inequality, we have

$$\|u(t)\|_2^2 = \|u(t)\|_{2,\mathcal{D}_R}^2 + \|u(t)\|_{2,\mathcal{D}^R}^2 \leq cR^2\|u(t)\|_6^2 + \frac{1}{\ln R}\|\sqrt{\ln r}u(t)\|_{2,\mathcal{D}^R}^2,$$

which, by (3.7), entails

$$\|u(t)\|_2^2 \leq cR^2\|u(t)\|_6^2 + \frac{M}{\ln R}.$$

Therefore, if we operate with $\limsup_{t \rightarrow \infty}$ on both sides of this relation, use (2.27) and then let $R \rightarrow \infty$, we arrive at (3.1), thus completing the proof of the theorem. \square

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