On the diffeomorphism group of a smooth orbifold and its application

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§1. Introduction

Let $\mathcal{D}(M)$ denote the group of diffeomorphisms of an *n*-dimensional smooth manifold M which are istopic to the identity through compactly supported isotopies. In [TH], Thurston proved that the group $\mathcal{D}(M)$ is perfect, which means $\mathcal{D}(M)$ coincides with its commutator subgroup. There are many analogous results on the group of a smooth manifold M preserving a geometric structure of M.

In this note we shall study the case when M is a smooth orbifold. Since a smooth orbifold is locally diffeomorphic to the orbit space of a smooth G-manifold with finite group G, first we shall consider in the case of a representation space V of a finite group G. Let $\mathcal{D}_G(V)$ denote the group of equivariant smooth diffeomorphisms of V which are G-isotopic to the identity through compactly supported equivariant smooth isotopies. In general the group $\mathcal{D}_G(V)$ is not perfect. Then we calculate the first homology group $H_1(\mathcal{D}_G(V))$.

We shall prove that $\mathcal{D}_G(V)$ is perfect if dim $V^G > 0$ and $H_1(\mathcal{D}_G(V))$ is isomorphic to $H_1(Aut_G(V)_0)$ if dim $V^G = 0$. Here $Aut_G(V)_0$ is the identity component of the group of *G*-equivariant linear automorphisms of *V*, and V^G is the fixed point set of *G* on *V* ([AF5]).

Secondly we apply the above result to the case of smooth orbifold and also smooth G-manifold. Using the result by Biestone [BI1] and Schwarz [SC1], we see that $H_1(\mathcal{D}_G(V))$ is isomorphic to $H_1(\mathcal{D}(V/G))$. Combining those results and the fragmentation lemma we can determine the structure of $H_1(\mathcal{D}(N))$ of the diffeomorphism group $\mathcal{D}(N)$ for any smooth orbifold N. Then we see that $H_1(\mathcal{D}(N))$ describes a geometric structure around the isolated singularities.

Let M be a smooth G-manifold for a finite group G. Then $H_1(\mathcal{D}_G(M))$ is isomorphic to $H_1(\mathcal{D}(M/G))$, and we see that $H_1(\mathcal{D}_G(M))$ describes the properties of the isotropy representations at the isolated fixed points of M. We can also apply the above results to a smooth G-manifold when G is a compact Lie group. If M is a principal G-manifold with G a compact Lie group, then we proved that the group $\mathcal{D}_G(M)$ is perfect for dim(M/G) > 0 (Banyaga [BA1] and Abe and Fukui [AF1]). In [AF2] we calculated $H_1(\mathcal{D}_G(M))$ when M is a smooth G-manifold with codimension one orbit. We shall apply the above result to the case of a locally free U(1)-action on the 3-sphere, and calculate $H_1(\mathcal{D}_{U(1)}(S^3))$ ([AF5]).

Thirdly we shall apply the results to the modular group. Let Γ be the modular group which acts on the the upper half complex plane \mathcal{H} by the Möbius transformations. Then the orbit space \mathcal{H}/Γ is a smooth orbifold. Let \mathcal{R}_{Γ} be the compactified space of \mathcal{H}/Γ by adjoining the point * which corresponds to the Γ -equivalence class of the parabolic cusps. With the canonical smooth coordinate around *, we shall calculate the group $H_1(\mathcal{D}(\mathcal{R}_{\Gamma})))$, which describes the elliptic points and the cusp point. We can also calculate the group for the case of the congruence subgroups of Γ .

We can apply the above results to the case of foliation preserving diffeomorphism groups. We studied for the similar problem in the Lipschitz category ([AF3], [AF4], [AF6], [AF6], [AFM]).

§2. Recent results on the diffeomorphism grooups on smooth orbifolds

Let G be a finite group and let M be a smooth connected G-manifold. Let $\mathcal{D}_G(M)$ denote the group of G-equivariant smooth diffeomorphisms of M which are G-isotopic to the identity through isotopies with compact support.

First we shall calculate $\mathcal{D}_G(V)$ for a finite dimensional *G*-module *V*. Let V^G be the subspace of the fixed point set of *V*. Let $A_G(V)$ denote the set of *G*-invariant automorphisms of *V* and let $A_G(V)_0$ be the identity component of $A_G(V)$. Then we have the following.

Theorem 1

(1) If dim $V^G > 0$, then $\mathcal{D}_G(V)$ is perfect.

(2) If dim $V^G = 0$, then $H_1(\mathcal{D}_G(V)) \cong H_1(A_G(V)_0)$.

We can decompose $V = \bigoplus_{i=1}^{d} k_i V_i$, where V_i runs over the inequivalent irreducible representation space of G and k_i is a positive integer. Let $End_G(V_i)$ denote the set of G-invariant endmorphisms of V_i . Then dim $End_G(V_i) = 1, 2$ or 4.

Corollary 2 If dim $V^G = 0$, then

$$H_1(\mathcal{D}_G(V)) \cong \mathbf{R}^d \times \overbrace{U(1) \times \cdots \times U(1)}^{d_2},$$

where d_2 is the number of V_i with dim $End_G(V_i) = 2$.

Definition 3 (smooth orbifold)

A paracompact Hausdorff space M is called a smooth orbifold if there exists an open covering $\{U_i | i \in \Lambda\}$ of M, closed under finite intersections, satisfying the following. (1) There exist an open subset \tilde{U}_i in \mathbb{R}^n such that a finite group Γ_i acts effectively on \tilde{U}_i and a homeomorphism $\phi_i: \tilde{U}_i/\Gamma_i \to U_i$.

(2) Whenever $U_i \subset U_j$, there exists a smooth embedding ϕ_{ij} : $\tilde{U}_i \to \tilde{U}_j$ such that



 (U_i, ϕ_i) is called a local chart of M.

Here we define the smooth maps between smooth orbifolds (c.f. [BI1]). $f: M \to \mathbf{R}$ is said to be smooth if for any local chart (U_i, ϕ_i) of M, $\tilde{U}_i \xrightarrow{\pi_i} \tilde{U}_i / \Gamma_i \xrightarrow{\phi_i} U_i \xrightarrow{f} \mathbf{R}$ is smooth. $h: M \to M$ is said to be smooth if for any smooth function $f: M \to \mathbf{R}$, $f \circ h$ is smooth. $h: M \to M$ is called a diffeomorphism if h and h^{-1} are smooth. Let $\mathcal{D}(M)$ denote the group of diffeomorphisms of M which are isotopic to the identity through isotopies with compact support.

 $p \in M$ is said to be an isolated singular point of M if there exists a local chart (U_i, ϕ_i) around p such that \tilde{p} is the isolated fixed point of \tilde{U}_i with $\pi_i(\tilde{p}) = p$. Here $\phi_i : U_i \to \tilde{U}_i / \Gamma_i$ and $\pi_i : \tilde{U}_i \to U_i$ are the maps defined in Definition 3.

Let $(U_i, \phi_i), (U_j, \phi_j)$ be local charts of M around an isolated singular point p of M. Then we can assume that \tilde{U}_i and \tilde{U}_j are invariant open neighborhoods around the origin of linear representation spaces of Γ_i and Γ_j , respectively. By the result of Strub [ST], the groups Γ_i and Γ_j are isomorphic and the corresponding representations are equivalent. Then the isolated singular point p determines the equivalence class of the linear representation space V_p of a finite group Γ_p .

Theorem 4 If a smooth orbifold M has $\{p_1, ..., p_k\}$ as the isolated singular point set, then

$$H_1(\mathcal{D}(M)) \cong H_1(A_{\Gamma_{p_1}}(V_{p_1})_0) \times \cdots \times H_1(A_{\Gamma_{p_k}}(V_{p_k})_0).$$

We can apply Theorem 4 to the case of smooth G-manifold with finite group G.

Theorem 5 Let G be a finite group and M a smooth G-manifold. If the orbit space M/G has $\{G \cdot p_1, ..., G \cdot p_k\}$ as the isolated singular points, then

$$H_1(\mathcal{D}_G(M)) \cong H_1(A_{G_{p_1}}(T_{p_1}M)_0) \times \cdots \times H_1(A_{G_{p_k}}(T_{p_k}M)_0).$$

Corollary 6 Let $\hat{\mathbf{R}}$ be the non-trivial one dimensional representation space of \mathbf{Z}_2 . Then

$$H_1(\mathcal{D}_{\mathbf{Z}_2}(\mathbf{\tilde{R}}^n)) \cong H_1(\mathcal{D}(\mathbf{\tilde{R}}^n/\mathbf{Z}_2)) \cong \mathbf{R}.$$

We can apply Corollary 6 to a smooth U(1)-action on S^3 . Let

$$S^{3} = \{(w_{1}, w_{2}) \in \mathbf{C}^{2} | |w_{1}|^{2} + |w_{2}|^{2} = 1\}$$

with U(1)-action given by

$$z \cdot (w_1, w_2) = (zw_1, z^2w_2), \qquad z \in U(1).$$

Then it has two orbit types $\{(1), (\mathbf{Z}_2)\}$ and the orbit space $S^3/U(1)$ is homeomorphic to the space known as the tear drop which is the two dimensional sphere with one isolated singular point.

Theorem 7 $H_1(\mathcal{D}_{U(1)}(S^3)) \cong \mathbf{R} \times U(1).$

Remark 8 If we restrict the above action to \mathbb{Z}_n , then $\mathcal{D}_{\mathbb{Z}_n}(S^3)$ is perfect.

§3. Application to the modular group

In this section we shall apply the results to the modular group. Let \mathcal{H} be the upper half complex plane. Let $SL(2, \mathbf{R})$ be the group of real matrix with determinant 1. Then $SL(2, \mathbf{R})$ acts on \mathcal{H} as follows.

$$g \cdot z = \frac{az+b}{cz+d}$$
 for $g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \Gamma, \ z \in \mathcal{H}.$

Then $SL(2, \mathbf{R})$ acts transitively on \mathcal{H} and the isotropy subgroup at $i = \sqrt{-1}$ is $SL(2, \mathbf{R})_i = SO(2)$. The kernel of the action is $\mathbf{Z}_2 = \{\pm 1\}$ and $PSL(2, \mathbf{R}) = SL(2, \mathbf{R})/\{\pm 1\}$ acts effectively on $\mathcal{H} \cong SL(2, \mathbf{R})/SO(2)$.

The action can be extended to the Riemannian sphere: $\bar{\mathbf{C}} = \mathbf{C} \cup \{\infty\}$. $g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \Gamma, \ z \in \bar{\mathbf{C}},$

$$g \cdot z = \begin{cases} \frac{az+b}{cz+d} & (z \neq -\frac{d}{c}, \infty) \\ \infty & (z = -\frac{d}{c}, z = d = 0) \\ \frac{a}{c} & (z = \infty) \end{cases}$$

Set

$$R_{1} = \left\{ \pm \begin{pmatrix} a & 0 \\ 0 & a^{-1} \end{pmatrix} \mid a > 0 \right\},$$
$$R_{2} = \left\{ \pm \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \quad \pm \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \right\}$$

Then each $g \in SL(2, \mathbf{R})$ is conjugate to one of the elements of $SO(2) \cup R_1 \cup R_2$, and $g \neq \pm 1$ is called *elliptic*, hyperbolic and parabolic if g is conjugate of an element in SO(2), R_1 and R_2 , respectively.

Let $\Gamma = SL(2, \mathbb{Z})$ be the group of the integral matrices with determinant 1. Then $\overline{\Gamma} = \Gamma/\{\pm 1\}$ acts properly on \mathcal{H} (i.e. for each $z \in \mathcal{H}$, there exists open neighborhood U of z such that $\overline{\Gamma}_U = \{g \in \overline{\Gamma} | g \cdot U = U\}$ is a finite group and if $\gamma \cdot U \cap U \neq \phi$ for $\gamma \in \overline{\Gamma}$, then $\gamma \in \overline{\Gamma}_U$).

 $z \in \mathcal{H}$ is called *elliptic point* if there exits an elliptic element $g \in \Gamma$ such that $g \cdot z = z$. $x \in \mathbf{R} \cup \{\infty\}$ is called *cusp point* if there exists a parabolic element $g \in \Gamma$ such that $g \cdot z = z$.

Proposition 9 (1) If z is a elliptic point, then Γ_z is a cyclic group which is conjugate to a cyclic subgroup of SO(2).

(2) If x is a cusp point, then Γ_x is isomorphic to Z which is conjugate to the group

$$\Gamma_{\infty} = \left\{ \left(\begin{array}{cc} 1 & n \\ 0 & 1 \end{array} \right) \mid n \in \mathbf{Z} \right\}.$$

(3) Γ acts transitively on the set of cusp points which is coincides with $Q \cup \{\infty\}$, where Q is the set of rational numbers.

Set

$$\mathcal{H}^* = \mathcal{H} \cup Q, \quad \mathcal{R}_{\Gamma} = \mathcal{H}^* / \Gamma = \mathcal{H} / \Gamma \cup \{*\}.$$

We give the set

$$\{*\} \cup \cup_{c>0} \{z \in \mathcal{H} | \Im z > c\}$$

as a fundamental system of open neighborhood of the point *. Then \mathcal{R}_{Γ} is homeomorphic to S^2 .

Proposition 10 There exists a Γ_{∞} -invariant open neighborhood \tilde{U} of * satisfying the following.

(1)
$$\Gamma_{\infty} = \{ g \in \Gamma | g \cdot \tilde{U} \cap \tilde{U} \neq \phi \}.$$

(1) $\Gamma_{\infty} = \{g \in \Gamma \mid g : 0 \cap 0 \neq \varphi\}.$ (2) Let $\varphi : \tilde{U}/\Gamma_{\infty} \to \mathbb{C}$ be the map given by $\varphi(\Gamma_{\infty} \cdot z) = \exp(2\pi\sqrt{-1}z)$ for $z \in \tilde{U}$. Then φ is a homeomorphism into an open set U of \mathbb{C} .

Let $\iota: \tilde{U}/\bar{\Gamma}_{\infty} \to \mathcal{R}_{\Gamma}$ be the natural map. Put $U = \iota(\tilde{U}/\bar{\Gamma}_{\infty})$. By Proposition 10 U is an open neighborhood of * and the homeomorphism $\phi = \varphi \circ \iota^{-1}: U \to \tilde{U}/\bar{\Gamma}_{\infty}$ is regarded as a local coordinate of \mathcal{R}_{Γ} .

We call $h : \mathcal{R}_{\Gamma} \to \mathcal{R}_{\Gamma}$ to be a diffeomorphism if the following conditions (1), (2), (3) is satisfied.

(1) $h|(\mathcal{H}/\bar{\Gamma})$ is a diffeomorphism of $\mathcal{H}/\bar{\Gamma}$ as a smooth orbifold.

(2) $\phi \circ h \circ \phi^{-1}$ is a diffeomorphism of U.

(3) There exists $\overline{\Gamma}_{\infty}$ -equivariant diffeomorphism \tilde{h} of \mathcal{H} such that the induced diffeomorphism on $\mathcal{H}/\overline{\Gamma}$ coinsides with h on $U \setminus \{*\}$.

Theorem 11

(1) $H_1(\mathcal{D}_{\Gamma}(H^2)) \cong H_1(\mathcal{D}(H^2/\Gamma)) \cong \mathbf{R}^2 \times U(1).$ (2) $H_1(\mathcal{D}(\mathcal{R}_{\Gamma})) \cong U(1) \times \mathbf{R}^3.$

The orbifold H^2/Γ has two isolated singular points which correspond to the elliptic subgroups of Γ with orders 2 and 3, which induces the isomorphism in Theorem 11, (1). In addition to those singular points, \mathcal{R}_{Γ} has the singular point * corresponding to the cusp point, which induces the isomorphism in Theorem 11, (2).

Let $\Gamma(N)$ denote the principal congruence subgroup of level N. Then

$$\Gamma(N) = \left\{ \left(\begin{array}{cc} a & b \\ c & d \end{array} \right) \in \Gamma \mid a \equiv d \equiv 1, \ b \equiv c \equiv 0 \mod N\mathbf{Z} \right\}.$$

Similarly to the case of the modular group, we have the following.

Theorem 12 $H_1(\mathcal{D}(\mathcal{R}_{\Gamma}(N))) \cong \mathbf{R}^{t(N)}$, where t(N) is the number of cusps of $\mathcal{H}/\Gamma(N)$.

The number t(N) is known as:

$$t(1) = 1, \quad t(2) = 3,$$

$$t(N) = \frac{1}{2N}(N : \Gamma(N)) \quad (N \ge 3),$$
$$(N : \Gamma(N)) = N^3 \prod_{p \mid N} (1 - \frac{1}{p^2}).$$

We can also apply Theorem 1 to calculate the first homology group of the foliation preserving diffeomorphism group for a compact Hausdorff foliation.

§4. Outline of the proof of Theorem 1

First we prove Theorem 1 (1). Let G be a finite group and let V be a G-module with dim $V^G > 0$. Then there exists a G-module W with dim $W^G = 0$ such that $V = W \oplus \mathbb{R}^q$. We prove $\mathcal{D}_G(V)$ is perfect by induction of the order of G. If $G = \{1\}$, then $\mathcal{D}_G(V)$ is perfect by the result of Thurston [TH]. Assume that Theorem 1 (1) holds for any finite subgroup H with |H| < |G|.

To investigate the group structure of $\mathcal{D}_G(V)$, we give C^{∞} -topology on $\mathcal{D}_G(V)$. For the proof we need the following fragmentation lemma.

Lemma 13 (fragmentation lemma)

Let M be a smooth G-manifold and let $\{U_i\}$ be a G-invariant open covering of M. Let N be a neighborhood of the identity in $\mathcal{D}_G(M)$. Then, for any $f \in \mathcal{D}_G(M)$, there exist $\{f_j \in N | 1 \leq j \leq k\}$ such that

(1) f_j is equivariantly isotopic to the identity through G-diffeomorphisms with the support contained in U_j ,

(2) $f = f_1 \circ \cdots \circ f_k$.

Let $f \in \mathcal{D}_G(V)$. In order to prove $f \in [\mathcal{D}_G(V), \mathcal{D}_G(V)]$, by the fragmentation lemma, we can assume f is sufficiently close to the identity. Then we can find $g_1, g_2 \in \mathcal{D}_G(V)$ satisfying

(1) $g_1(x,y) = (x, \hat{g}_1(x)(y))$ with $\hat{g}_1(x) \in \mathcal{D}(\mathbf{R}^q)$,

(2)
$$g_2(x,y) = (\hat{g}_2(y)(x), y)$$
 with $\hat{g}_2(2) \in \mathcal{D}_G(W)$ for $x \in W, y \in \mathbf{R}^q$,

(3) $f = g_2 \circ g_1$.

By the result of Tsuboi [TS], we see that $g_1 \in [\mathcal{D}_G(V), \mathcal{D}_G(V)]$.

In the next we shall prove that $g_2 \in [\mathcal{D}_G(V), \mathcal{D}_G(V)]$. Let $\alpha_{g_2} : \mathbf{R}^q \to Aut_G(W)_0$ be a group homomorphism defined by $\alpha_{g_2}(y) = d\hat{g}_2(y)_0$, where $d\hat{g}_2(y)_0$ is the differential of $\hat{g}_2(y)$ at 0. Then α_{g_2} is a smooth map with compact support $\overline{\{p \in \mathbf{R}^q \mid \alpha_{g_2}(p) \neq e\}}$, where e is the unit element in $Aut_G(W)_0$.

If we take f close to the identity, then α_{g_2} is sufficiently close to the constant map e. Then applying [AF1], Lemma 4, we have

(a) $\exists \varphi_i \in \mathcal{D}(\mathbf{R}^q), \ \alpha_i \in C^{\infty}(\mathbf{R}^q, Aut_G(W)_0) \ (i = 1, ..., r = \dim Aut_G(W)_0),$ (b) $\alpha_{g_2} = (\alpha_1^{-1} \cdot (\alpha_1 \circ \varphi_1)) \cdots (\alpha_r^{-1} \cdot (\alpha_r \circ \varphi_r)).$

Let $|\cdot|$ be a G-invariant norm of W. Let $\mu: W \to [0,1]$ be a G-invariant smooth function satisfying

(i) $\mu(x) = 1$ for $|x| \le \frac{1}{2}$, (ii) $\mu(x) = 0$ for $|x| \ge 1$.

Define $h_i, F_i \in \mathcal{D}_G(V)$ (i = 1, ..., r) by

$$\begin{array}{lll} h_i(x,y) &=& (\mu(x)\alpha_i(y)(x) + (1-\mu(x))x, \ y), \\ F_i(x,y) &=& (x, \ \mu(x)\varphi_i(y) + (1-\mu(x))y) \end{array}$$

for $x \in W, y \in \mathbb{R}^q$.

Lemma 14

$$(h_i^{-1}\circ F_i^{-1}\circ h_i\circ F_i)(x,y)=((lpha_i^{-1}\cdot (lpha_i\circ arphi_i))(y)(x),\ y),$$

for $x \in W$, $y \in \mathbf{R}^q$ with $|x| \leq \frac{1}{2}$.

 Set

$$g_3 = \prod_{i=1}^r (h_i^{-1} \circ F_i^{-1} \circ h_i \circ F_i)^{-1} \circ g_2.$$

Then g_3 is written of the form $g_3(x,y) = (\hat{g}_3(x)(y), y)$ with $\hat{g}_3(x) \in \mathcal{D}_G(W)$ and $\alpha_{g_3}=e.$

For 0 < c < 1, let $\psi_c \in \mathcal{D}_G(V)$ such that, for $x \in W$, $y \in \mathbb{R}^q$,

$$\psi_c(x,y) = \begin{cases} (cx, y) & (|x| \le 1), \\ (x, y) & (|x| \ge 2). \end{cases}$$

Applying the result of Sternberg [S2], there exists $R \in \mathcal{D}(V)$ such that

(1) \tilde{R} is of the form $R(x,y) = (\hat{R}(y)(x), y)$

with $\hat{R}(y) \in \mathcal{D}(W,0)$ and $\alpha_R = e$. (2) $R \circ (g_3 \circ \psi_c) \circ R^{-1} = \psi_c$ on a neighborhood U_0 of $\{0\} \times \mathbf{R}^q$.

Set

$$\tilde{R}(x,y) = \frac{1}{|G|} \sum_{g \in G} g^{-1} \cdot R(g \cdot x, y) \quad \text{for } x \in W, \ y \in \mathbf{R}^q.$$

Then

$$\psi_c \circ \tilde{R} = \tilde{R} \circ g_3 \circ \psi_c \quad \text{on } U_0$$

Since \tilde{R} is *G*-equivariant diffeomorphic on a neighborhood of $\{0\} \times \mathbf{R}^{q}$, we can find $\tilde{R}_{1} \in \mathcal{D}_{G}(V)$ such that $\tilde{R}_{1} = \tilde{R}$ on a neighborhood $U \subset U_{0}$ of $\{0\} \times \mathbf{R}^{q}$. Put

$$g_4 = g_3 \circ (\tilde{R}_1^{-1} \circ \psi_c \circ \tilde{R}_1 \circ \psi_c^{-1})^{-1}.$$

Then $g_4 = 1$ on U.

There exist a finite point $\{p_i \in V \setminus U | 1 \le i \le k\}$ and an open disk neighborhood $U(p_i)$ at $p_i (1 \le i \le k)$ such that

(1)
$$U(p_i)$$
 is a slice at p_i ,
(2) $supp(g_4) \subset \bigcup_{i=1}^k G \cdot U(p_i)$

By the fragmentation lemma there exist $h_j \in \mathcal{D}_G(V)$ $(1 \le j \le \ell)$ such that

(a) h_j is equivariantly isotopic to the identity through G-diffeomorphisms with the support contained in $G \cdot U(p_j)$,

(b) $g_4 = h_1 \circ \cdots \circ h_\ell$.

Since $U(p_j)$ is a slice at p_j , the isotropy subgroup G_{p_j} acts on $U(p_j)$ and $G \cdot U(p_j)$ is a disjoint union of $|G/G_{p_j}|$ disks. Then from the above condition (a)

$$h_j(g \cdot U(p_j)) = g \cdot U(p_j) \text{ for } g \in G.$$

We assumed that $\mathcal{D}_H(V)$ is perfect when H is a finite group with |H| < |G|and dim $V^H > 0$. Therefore each h_j can be written as a commutator in $D_G(V)$ and Theorem 1 (1) follows.

Secondary we prove Theorem 1 (2). Let V be a G-module with dim $V^G = 0$ Let $\Phi : \mathcal{D}_G(V) \to Aut_G(V)_0$ be a group homomorphism defined by $\Phi(f) = (df)_0$. Since

$$1 \to Ker \Phi \xrightarrow{\iota} D_G(V) \xrightarrow{\Phi} Aut_G(V)_0 \to 1$$

is a short exact sequence, we have the exact sequence.

$$Ker\Phi/[Ker\Phi, \mathcal{D}_G(V)] \xrightarrow{\iota_*} H_1(\mathcal{D}_G(V)) \xrightarrow{\Phi_*} H_1(Aut_G(V)_0) \to 1$$

Then Theorem 1(2) follows from the following.

Proposition 15 $Ker\Phi = [\mathcal{D}_G(V), \mathcal{D}_G(V)]$

Proof. Let $f \in Ker\Phi$. For 0 < c < 1, let $\psi_c \in Aut_G(V)_0$ as before. Applying the result by Sternberg [S2] there exists $R \in \mathcal{D}(V,0)$ such that $(dR)_0 = 1_V$ and

 $R \circ f \circ \psi_c \circ R^{-1} = \psi_c$ on a neighborhood of 0. Set

$$\tilde{R}(x) = \frac{1}{|G|} \sum_{g \in G} g^{-1} \cdot R(g \cdot x) \quad \text{for } x \in \mathbf{R}^n,$$

where |G| is the order of G. Since \tilde{R} is equivariant diffeomorphism on a neighborhood U of 0, we can find $\hat{R} \in \mathcal{D}_G(V)$ such that $\hat{R} = \tilde{R}$ on an open neighborhood $U_1 \subset U$ of 0. Then

$$f = \hat{R}^{-1} \circ \psi_c \circ \hat{R} \circ \psi_c^{-1} \quad \text{on } U_1.$$

 Put

$$g = f \circ (\hat{R}^{-1} \circ \psi_c \circ \hat{R} \circ \psi_c^{-1})^{-1}.$$

Then g = 1 on U_1 . By the parellel way as in the proof of the case Theorem 1, (1), we can prove that g is written as a commutator in $\mathcal{D}_G(V)$.

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