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Two-dimensional nonlinear nonequilibrium kinetic theory under steady heat conduction

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The two-dimensional steady-state Boltzmann equation for hard-disk molecules in the presence of a temperature gradient has been solved explicitly to second order in density and the temperature gradient. The two-dimensional equation of state and some physical quantities are calculated from it and compared with those for the two-dimensional steady-state Bhatnagar-Gross-Krook equation and information theory. We have found that the same kind of qualitative differences as the three-dimensional case among these theories still appear in the two-dimensional case.

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I. INTRODUCTION

The behaviors of gases in nonequilibrium states have received considerable attention from the standpoint of understanding the characteristics of nonequilibrium phenomena [1–9]. The kinetic theory has contributed not only to the understanding of nonequilibrium transport phenomena in gases but also to the development of general nonequilibrium statistical physics. It is well accepted that the Boltzmann equation is one of the most reliable kinetic models for describing nonequilibrium phenomena in gas phases. In the early stages of studies of the kinetic theory, great effort has been paid for solving kinetic model equations such as the Boltzmann equation and deriving nonequilibrium velocity distribution functions and macroscopic nonequilibrium transport equations in terms of microscopic molecular quantities. These attempts were strongly related to the development of general nonequilibrium statistical physics such as linear nonequilibrium thermodynamics, Onsager's reciprocal theorem, and the linear response theory [10,11].

Among various methods which give normal solutions of the Boltzmann equation, the Chapman-Enskog method has been widely accepted as the most reliable method. It had been believed that Burnett determined the complete second-order solution of the Boltzmann equation by the Chapman-Enskog method [1,12,13]. The physical importance of the second-order coefficients has been also demonstrated for descriptions of shock-wave profiles and sound propagation phenomena [14–16]. However, it was reported that Burnett's solution is not complete, and Schamberg derived the precise velocity distribution function of the Boltzmann equation to second order for Maxwell molecules [17]. On the other hand, because of its mathematical difficulty, the complete second-order solution of the Boltzmann equation for hard-core molecules has been derived quite recently [18]. Its validity has been also demonstrated by numerical experiments of both a molecular dynamics simulation and a direct simulation Monte Carlo method [19,20]. Other kinetic models like the Bhatnagar-Gross-Krook (BGK) equation [21–28] have been proposed mainly to avoid the mathematical difficulties in

dealing with the collision term of the Boltzmann equation. Although it was believed that its results approximately agreed with those of the Boltzmann equation, some qualitative disagreements have been found in the second-order solutions [18].

Following its success and usefulness, the Boltzmann equation is widely used in order to describe various gas-phase transport phenomena such as granular gases [29–32], plasma gases [33,34], polyatomic gases [35], relativistic gases [36], and chemically reacting gases. Chemical reactions in gas phases have been studied with the aid of gas collision theory. For the differential cross section of chemical reactions, the line-of-centers model proposed by Present has been accepted as a standard model to describe the chemical reaction in gases [37–44]. This model can be derived explicitly using a collision law of hard-core molecules, and the diameter of hard-core molecules is regarded as a distance between centers of monatomic molecules at contact [37,38,42]. In equilibrium states, experimental results including the temperature dependence can be fitted by the results from the line-of-centers model [37,40,41]. Under nonequilibrium situations such as gases under a heat flux or a shear flow, their pure nonequilibrium contributions to the rate of chemical reaction have also attracted much attention [39,43–49]. Since nonequilibrium correction terms of the chemical reaction rate are quadratic functions of nonequilibrium fluxes, the explicit nonequilibrium velocity distribution function of the Boltzmann equation for hard-core molecules to second order is needed to derive it based on the line-of-centers model [39,43,45,46]. The pure effect of a heat flux on the chemical reaction rate has been recently calculated using the second-order velocity distribution function of the Boltzmann equation for hard-core molecules [46]. In the Letter, a *thermometer* to measure a relation between a kinetic temperature of gases under a heat flux and a temperature of a heat bath has been also proposed.

It is one of the most significant subjects in modern statistical physics to construct the nonlinear nonequilibrium statistical mechanics and thermodynamics for a strongly nonequilibrium state beyond the local equilibrium state, called the local nonequilibrium state. Zubarev [50,51] has developed nonequilibrium statistical mechanics and obtained the general form of a nonequilibrium velocity distribution function with the aid of the maximum entropy principle. It is ex-

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panded to first order under some constraints to obtain the first-order nonequilibrium velocity distribution function [52] Jou and co-workers have derived the nonequilibrium velocity distribution function to second order by expanding it to second order under some constraints, which is called information theory [53,54]. Information theory has attracted interest in the development of a general framework for nonlinear nonequilibrium statistical mechanics which can describe the local nonequilibrium state. The nonequilibrium velocity distribution function from information theory has been applied to nonequilibrium systems, and some predictions were made. For example, in dilute gas systems under nonequilibrium fluxes, an anisotropic pressure and a nonequilibrium temperature which is not identical with the kinetic temperature have been predicted [55–58]. There are also several applications of information theory to chemically reacting gases [39,43]. However, some qualitative differences between information theory and the Boltzmann equation have been recently reported, and the invalidity of information theory as universal nonlinear nonequilibrium statistical mechanics has been demonstrated [59].

There have been no efforts to solve two-dimensional kinetic models to second order and discuss the two-dimensional second-order nonequilibrium phenomena, though two-dimensional transport phenomena have created great interest [60–66]. The main aims of this paper are to reconstruct all the results obtained in Refs. [18,46,59] in the case of two dimensions and to discuss properties of the two-dimensional nonlinear nonequilibrium phenomena which reflect the local nonequilibrium state. In Secs. II and III, we derive the explicit velocity distribution function of the two-dimensional steady-state Boltzmann equation for hard-disk molecules to second order by the Chapman-Enskog method. In order to achieve that, we have extended the method we developed in Ref. [18] to the two-dimensional case. We also obtain the nonequilibrium velocity distribution functions to second order for the two-dimensional steady-state BGK equation and information theory in Secs. IV A and IV B, respectively. All the nonlinear nonequilibrium velocity distribution functions are graphically compared in Sec. V. Using the two-dimensional nonequilibrium velocity distribution functions to second order, we discuss differences among those theories appearing in the two-dimensional nonlinear nonequilibrium transport phenomena in Sec. VI. In Sec. VII, we explain how to calculate the effect of steady heat flux on the rate of chemical reaction based on the line-of-centers model in the two-dimensional case and apply the two-dimensional nonequilibrium velocity distribution functions to second order to calculate it. We have also investigated the dimensional dependence appearing in the nonlinear nonequilibrium phenomena which reflect the local nonequilibrium state. Our discussion and conclusion are given in Sec. VIII.

II. CHAPMAN-ENSKOG METHOD FOR SOLVING THE TWO-DIMENSIONAL STEADY-STATE BOLTZMANN EQUATION

Let us introduce the Chapman-Enskog method to solve the two-dimensional steady-state Boltzmann equation in this

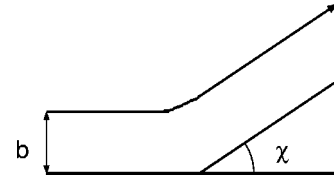


FIG. 1. Schematic description of an interaction in two dimensions.

section. Assume that we have a system of dilute gases in a steady state, with velocity distribution function $f_1=f(\mathbf{r},\mathbf{v}_1)$. The appropriate steady-state Boltzmann equation is

$$\mathbf{v}_1 \cdot \nabla f_1 = J(f_1, f_2), \quad (1)$$

where the collision integral $J(f_1, f_2)$ is expressed as

$$J(f_1, f_2) \equiv \int \int (f'_1 f'_2 - f_1 f_2) g b d\mathbf{v}_2, \quad (2)$$

with $f'_1=f(\mathbf{r},\mathbf{v}'_1)$ and $f'_2=f(\mathbf{r},\mathbf{v}'_2)$: \mathbf{v}'_1 and \mathbf{v}'_2 are postcollisional velocities of \mathbf{v}_1 and \mathbf{v}_2 , respectively. The relative velocity of two molecules before and after an interaction has the same magnitude $g=|\mathbf{v}_1-\mathbf{v}_2|$; the angle between the directions of the relative velocity before and after the interaction is represented by χ . The relative position of the two molecules is represented by b , called the impact parameter (see Fig. 1). The impact parameter b depends on kinds of the interaction between molecules, and one should specify the intermolecular interaction so as to explicitly determine the impact parameter b in the collision term $J(f_1, f_2)$. Note that χ can be expressed as a function of b for a central force.

Suppose that the velocity distribution function f_1 can be expanded as

$$f_1 = f_1^{(0)} + f_1^{(1)} + f_1^{(2)} + \cdots = f_1^{(0)}(1 + \phi_1^{(1)} + \phi_1^{(2)} + \cdots), \quad (3)$$

where the small expansion parameter will turn out the Knudsen number $K=l/L$, which means that the mean free path of molecules l should be much less than the characteristic length L for changes in macroscopic variables. $f_1^{(0)}$ is the local Maxwellian distribution function, written as

$$f_1^{(0)} = \frac{n(\mathbf{r})m}{2\pi\kappa T(\mathbf{r})} \exp\left[-\frac{m\mathbf{v}_1^2}{2\kappa T(\mathbf{r})}\right], \quad (4)$$

with m mass of the molecules and κ the Boltzmann constant. $n(\mathbf{r})$ and $T(\mathbf{r})$ will be identified later as the density and temperature at position \mathbf{r} , respectively. Substituting Eq. (3) into the two-dimensional steady-state Boltzmann equation (1), we arrive at the following set of equations which we will solve completely in this paper:

$$L[f_1^{(0)}]\phi_1^{(1)} = \mathbf{v}_1 \cdot \nabla f_1^{(0)} \quad (5)$$

to first order and

$$L[f_1^{(0)}]\phi_1^{(2)} = \mathbf{v}_1 \cdot \nabla f_1^{(1)} - J(f_1^{(1)}, f_2^{(1)}) \quad (6)$$

to second order. The linear integral operator $L[f_1^{(0)}]$ is defined as

$$L[f_1^{(0)}]X_1 \equiv \int \int f_1^{(0)} f_2^{(0)} (X'_1 - X_1 + X'_2 - X_2) g db d\mathbf{v}_2. \quad (7)$$

The solubility conditions of the integral equation (5) are given by

$$\int \Phi_i \mathbf{v}_1 \cdot \nabla f_1^{(0)} d\mathbf{v}_1 = 0, \quad (8)$$

where Φ_i are collisional invariants:

$$\Phi_1 = 1, \quad \Phi_2 = m\mathbf{v}_1, \quad \Phi_3 = \frac{1}{2}m\mathbf{v}_1^2. \quad (9)$$

Substituting Eq. (4) into the solubility conditions (8), it is seen that $n\kappa T$ is uniform in the steady state. We use this result in our calculation to second order. Similarly, the solubility conditions of the integral equation (6) are given by

$$\int \Phi_i \mathbf{v}_1 \cdot \nabla f_1^{(1)} d\mathbf{v}_1 = 0, \quad (10)$$

which will be considered in Sec. III C 2.

To construct solutions of the integral equations (5) and (6) definite, four further conditions must be specified; we identify the density

$$n(\mathbf{r}) \equiv \int f_1 d\mathbf{v}_1 = \int f_1^{(0)} d\mathbf{v}_1, \quad (11)$$

the temperature

$$n(\mathbf{r})\kappa T(\mathbf{r}) \equiv \int \frac{m\mathbf{v}_1^2}{2} f_1 d\mathbf{v}_1 = \int \frac{m\mathbf{v}_1^2}{2} f_1^{(0)} d\mathbf{v}_1, \quad (12)$$

and the mean flow

$$\mathbf{C}_0 \equiv \int m\mathbf{v}_1 f_1 d\mathbf{v}_1 = \int m\mathbf{v}_1 f_1^{(0)} d\mathbf{v}_1. \quad (13)$$

Here we assume that no mean flow—i.e., $\mathbf{C}_0=0$ —exists in the system. The introduction of these conditions distinguishes the Chapman-Enskog adopted here from the Hilbert method in which the conserved quantities are also expanded [2]. We assert that conditions (11)–(13) do not affect all our results in this paper. It should be noted that, to solve the integral equations (5) and (6), we should consider only the case in which the right-hand sides of Eqs. (5) and (6) are not zero: if the right-hand sides of Eqs. (5) and (6) are zero, the integral equations (5) and (6) become homogeneous equations which do not have any particular solutions [2].

III. METHOD FOR SOLVING THE INTEGRAL EQUATIONS

A. General form of the velocity distribution function

To solve the integral equations (5) and (6), we assume a general form of the velocity distribution function:

$$f_1 = f_1^{(0)} \left[\sum_{r=0}^{\infty} r! B_{0r} S_0^r(\mathbf{c}_1^2) + \sum_{k=1}^{\infty} \left(\frac{m}{2\kappa T} \right)^{k/2} \sum_{r=0}^{\infty} r! Y_{kr}(\mathbf{c}_1) S_k^r(\mathbf{c}_1^2) \right], \quad (14)$$

with $\mathbf{c}_1 \equiv (m/2\kappa T)^{1/2} \mathbf{v}_1$ the scaled velocity. $S_k^p(X)$ is a Sonine polynomial, defined by

$$(1-\omega)^{-k-1} e^{-X\omega/(1-\omega)} = \sum_{p=0}^{\infty} \Gamma(p+k+1) S_k^p(X) \omega^p \quad (15)$$

and

$$Y_{kr}(\mathbf{c}_1) \equiv B_{kr} Y_k(\mathbf{c}_1) + C_{kr} Z_k(\mathbf{c}_1), \quad (16)$$

where B_{kr} and C_{kr} are coefficients to be determined. Introducing the polar coordinate representation for \mathbf{c}_1 , i.e., $c_{1x} = c_1 \cos \theta$, $c_{1y} = c_1 \sin \theta$,

$$Y_k(\mathbf{c}_1) = \left(\frac{2\kappa T}{m} \right)^{k/2} c_1^k \cos k\phi \quad (17)$$

and

$$Z_k(\mathbf{c}_1) = \left(\frac{2\kappa T}{m} \right)^{k/2} c_1^k \sin k\phi. \quad (18)$$

The assumption of the velocity distribution function of Eq. (14) has some mathematical advantages in our calculation. First, it is sufficient to determine the coefficients B_{kr} , because C_{kr} can be always determined from B_{kr} by transformations of axes. Second, some important physical quantities are related to the coefficients B_{kr} and C_{kr} : e.g., the density (11), the temperature (12), and the zero mean flow (13) with f_1 in Eq. (14) lead to the four equivalent conditions

$$B_{00} = 1, \quad B_{10} = C_{10} = 0, \quad B_{01} = 0. \quad (19)$$

Similarly, the pressure tensor P_{ij} defined by

$$P_{ij} = \left(\frac{2\kappa T}{m} \right)^2 \int_{-\infty}^{\infty} d\mathbf{c}_1 m c_{1i} c_{1j} f_1, \quad (20)$$

for $i, j = x$ and y , is related to B_{20} and C_{20} .

The coefficients B_{kr} except for those in Eq. (19) can be calculated as follows. Multiplying the two-dimensional steady-state Boltzmann equation (1) by

$$Q_{kr}(\mathbf{c}_1) \equiv 4 \left(\frac{m}{2\kappa T} \right)^{k/2} \frac{Y_k(\mathbf{c}_1) S_k^r(\mathbf{c}_1^2)}{\Gamma(k+r+1)} \quad (21)$$

and then integrating over $(2\kappa T/m)^{1/2} \mathbf{c}_1$, it is found that

$$\begin{aligned} & - \left(\frac{2\kappa T}{m} \right)^{1/2} \langle \mathbf{c}_1 \cdot \nabla Q_{kr} \rangle_{av} + \nabla \cdot \left[\left(\frac{2\kappa T}{m} \right)^{1/2} \langle \mathbf{c}_1 Q_{kr} \rangle_{av} \right] \\ & = \left(\frac{2\kappa T}{m} \right)^2 \int \int \int (Q'_{kr} - Q_{kr}) f_1 f_2 g db d\mathbf{c}_2 d\mathbf{c}_1, \end{aligned} \quad (22)$$

where $\Gamma(X)$ is the gamma function, $\langle X \rangle_{av} = (2\kappa T/m) \int X f_1 d\mathbf{c}_1$, and Q'_{kr} represents the postcollisional Q_{kr} . We should calculate both sides of Eq. (22) for every k and r , because Eq. (22) leads to simultaneous equations to determine B_{kr} .

TABLE I. Numerical constants b_{1r} in Eq. (31).

r	$r \leq 1$	$r \leq 2$	$r \leq 3$	$r \leq 4$	$r \leq 5$	$r \leq 6$	$r \leq 7$
1	1	1.026	1.029	1.030	1.030	1.030	1.030
2	-	5.263×10^{-2}	5.657×10^{-2}	5.720×10^{-2}	5.734×10^{-2}	5.738×10^{-2}	5.739×10^{-2}
3	-	-	4.335×10^{-3}	4.820×10^{-3}	4.920×10^{-3}	4.946×10^{-3}	4.954×10^{-3}
4	-	-	-	3.671×10^{-4}	4.188×10^{-4}	4.313×10^{-4}	4.349×10^{-4}
5	-	-	-	-	2.966×10^{-5}	3.452×10^{-5}	3.583×10^{-5}
6	-	-	-	-	-	2.241×10^{-6}	2.651×10^{-6}
7	-	-	-	-	-	-	1.576×10^{-7}

For convenience, we introduce Ω_{kr} and Δ_{kr} as the left-hand and right-hand sides of Eq. (22), respectively:

$$\Omega_{kr} \equiv - \left(\frac{2\kappa T}{m} \right)^{1/2} \langle \mathbf{c}_1 \cdot \nabla Q_{kr} \rangle_{av} + \nabla \cdot \left[\left(\frac{2\kappa T}{m} \right)^{1/2} \langle \mathbf{c}_1 Q_{kr} \rangle_{av} \right] \quad (23)$$

and

$$\Delta_{kr} \equiv \left(\frac{2\kappa T}{m} \right)^2 \int \int \int (Q'_{kr} - Q_{kr}) f_1 f_2 g db d\mathbf{c}_2 d\mathbf{c}_1. \quad (24)$$

We will calculate Ω_{kr} and Δ_{kr} separately. From Appendix A, the result of Ω_{kr} becomes

$$\Omega_{kr} = n \left(\frac{2\kappa T}{m} \right)^{1/2} \left[\left(r + \frac{k}{2} - \frac{1}{2} \right) \left(D_{k,r} \frac{\partial_x T}{T} + E_{k,r} \frac{\partial_y T}{T} \right) - \left(D_{k,r-1} \frac{\partial_x T}{T} + E_{k,r-1} \frac{\partial_y T}{T} \right) + \partial_x D_{k,r} + \partial_y E_{k,r} \right], \quad (25)$$

where $\partial_i X$ denotes $\partial X / \partial i$ for $i=x$ and y . $D_{k,r}$ and $E_{k,r}$ are functions of B_{kr} and C_{kr} , as is written in Appendix A.

B. Collision term Δ_{kr}

Next we calculate the collision term Δ_{kr} in Eq. (24). We should specify the kind of the interaction of molecules so as to perform the calculation of the collision term Δ_{kr} . For hard-disk molecules, the impact parameter b is given by the relation

$$b = d \cos \frac{\chi}{2}, \quad (26)$$

where d is the hard-disk molecular diameter. The collision differential cross section is obtained by

$$db = -\frac{d}{2} \sin \frac{\chi}{2} d\chi. \quad (27)$$

Therefore, Δ_{kr} for hard-disk molecules, Δ_{kr}^H , becomes

$$\Delta_{kr}^H = \frac{d}{2} \int_0^{2\pi} [F_{kr}^1(\chi) - F_{kr}^1(0)] \sin \frac{\chi}{2} d\chi, \quad (28)$$

where $F_{kr}^\mu(\chi)$ is defined as

$$F_{kr}^\mu(\chi) \equiv \left(\frac{2\kappa T}{m} \right)^2 \int \int Q'_{kr} f_1 f_2 g^\mu d\mathbf{c}_2 d\mathbf{c}_1, \quad (29)$$

and we have used $F_{kr}^\mu(0) = (2\kappa T/m)^2 \int \int Q_{kr} f_1 f_2 g^\mu d\mathbf{c}_2 d\mathbf{c}_1$. Note that $\chi=0$ if $b > d$.

From Eq. (28), it is sufficient to calculate $F_{kr}^1(\chi)$ for deriving Δ_{kr}^H . The details of $F_{kr}^1(\chi)$ are written in Appendix B 1. Several explicit forms of Δ_{kr}^H are also demonstrated in Appendixes C and D. From the definitions (23) and (24), both sides of Eq. (22) for arbitrary k and r can be calculated for hard-disk molecules via

$$\Omega_{kr}^H = \Delta_{kr}^H, \quad (30)$$

which produces a set of simultaneous equations determining the coefficients B_{kr} , as is explained in Appendixes C and D. Here Ω_{kr}^H denotes Ω_{kr} for hard-disk molecules.

C. Determination of B_{kr}

We will determine the first-order coefficients B_{kr}^I and the second-order coefficients B_{kr}^{II} in accordance with the previous two subsections, which corresponds to solving the integral equations (5) and (6), respectively. Here the upper suffices I and II are introduced to specify the order of K .

1. First order

We show the results of the first-order coefficients B_{kr}^I of which the solution of the integral equation (5), $\phi_1^{(1)}$, is composed. They can be written in the form

$$B_{kr}^I = \delta_{k,1} b_{1r} \frac{2\partial_x T}{\sqrt{2\pi} dn T}. \quad (31)$$

Values of the constants b_{1r} are given in Table I. The calculation of B_{kr}^I is explained in Appendix C. It is seen that B_{kr}^I is of the order of the Knudsen number K . Though B_{kr}^I was derived only to the lowest-order approximation [62]—i.e., B_{kr}^I for $r=1$ —we have obtained B_{kr}^I for $r \leq 7$ in this paper. This ensures the convergence of all the physical quantities which will be calculated in this paper. It should be mentioned that our value of B_{kr}^I for the lowest Sonine approximation—i.e., $r=1$ —is identical with Sengers's value [62]. Once B_{kr}^I have been calculated, C_{kr}^I can be written down directly by replacing $\partial_x T$ by $\partial_y T$ by symmetry. Substituting all the first-order coefficients derived here into Eq. (16), we can finally

TABLE II. Numerical constants b_{0r} in Eq. (36).

r	$r \leq 2$	$r \leq 3$	$r \leq 4$	$r \leq 5$	$r \leq 6$
2	2.778	2.530	2.497	2.490	2.488
3	-	-3.292×10^{-1}	-3.602×10^{-1}	-3.663×10^{-1}	-3.679×10^{-1}
4	-	-	-2.676×10^{-2}	-3.038×10^{-2}	-3.125×10^{-2}
5	-	-	-	-2.294×10^{-3}	-2.670×10^{-3}
6	-	-	-	-	-1.882×10^{-4}

obtain the first-order velocity distribution function $f_1^{(1)}$.

2. Solubility conditions for $\phi_1^{(2)}$

Since the first-order velocity distribution function $f_1^{(1)}$ has been obtained, the solubility conditions for the integral equation (6) should be considered before we attempt to derive the explicit second-order solution $\phi_1^{(2)}$. The solubility conditions for $\phi_1^{(2)}$, Eqs. (10), lead to the condition

$$\nabla \cdot \mathbf{J}^{(1)} = 0, \quad (32)$$

where $\mathbf{J}^{(1)}$ —i.e., the heat flux for $f_1^{(1)}$ —can be obtained as

$$\mathbf{J}^{(1)} \equiv \left(\frac{2\kappa T}{m} \right)^{5/2} \int_{-\infty}^{\infty} d\mathbf{c}_1 \frac{m\mathbf{c}_1^2}{2} \mathbf{c}_1 f_1^{(1)} \quad (33)$$

$$= -b_{11} \left(\frac{\kappa T}{\pi m} \right)^{1/2} \frac{2\kappa}{d} \nabla T, \quad (34)$$

with the appropriate value for b_{11} listed in Table I. It must be emphasized that, since $\mathbf{J}^{(2)}$ —i.e., the heat flux for $f_1^{(2)}$ —does not appear, the solubility conditions of the two-dimensional steady-state Boltzmann equation for $\phi_1^{(2)}$ lead to the heat flux being constant to second order. This fact is in harmony with a general property that the total heat flux should be uniform in the steady state. From Eqs. (32) and (34), we also obtain an important relation between $(\nabla T)^2$ and $\nabla^2 T$,

$$\frac{(\nabla T)^2}{2T} + \nabla^2 T = 0. \quad (35)$$

Owing to the relation (35), terms of $\nabla^2 T$ can be replaced by terms of $(\nabla T)^2$.

3. Second order

We write down the results of the second-order coefficients B_{kr}^{II} of which $\phi_1^{(2)}$ is composed. Using the relation (35), we can determine the second-order coefficients B_{0r}^{II} appearing in Eq. (14) as

$$B_{0r}^{\text{II}} = \frac{b_{0r}}{\pi d^2 n^2 T^2} (\nabla T)^2. \quad (36)$$

Values for the constants b_{0r} are summarized in Table II. The calculation of B_{0r}^{II} is shown in Appendix D. We have calculated B_{0r}^{II} to the seventh approximation—i.e., B_{0r}^{II} for $r \leq 6$ in this paper.

The other second-order coefficients B_{kr}^{II} in Eq. (16) can be written in the final form

$$B_{kr}^{\text{II}} = \frac{\delta_{k,2}}{\pi d^2 n^2 T^2} \{ b_{2r}^A [(\partial_x T)^2 - (\partial_y T)^2] + b_{2r}^B T [\partial_x^2 T - \partial_y^2 T] \}. \quad (37)$$

Values for the constants b_{2r}^A and b_{2r}^B are summarized in Table III. The calculation of B_{kr}^{II} is explained in Appendix D. Owing to the properties of the trigonometrical function, C_{kr}^{II} can be obtained by replacing $(\partial_x T)^2 - (\partial_y T)^2$ and $\partial_x^2 T - \partial_y^2 T$ in Eq. (37) by $2\partial_x T \partial_y T$ and $2T \partial_x \partial_y T$, respectively, using an axis change.

One can see that both of B_{0r}^{II} and B_{kr}^{II} are of the order of K^2 . As is also found in the three-dimensional case [18], we have confirmed the fact that B_{kr}^{II} for $k=4$ and 6 do not appear. This fact strongly suggests that B_{kr}^{II} for all k greater than 2 do not appear, which was also expected in Ref. [18] and recently confirmed in Ref. [19]. We finally obtain $f_1^{(2)}$ by substituting the second-order coefficients obtained here into Eqs. (14) and (16). Finally, we note that, though we have derived all the constants b_{1r} , b_{0r} , b_{2r}^A , and b_{2r}^B in the form of fractions, we have written them in the form of four significant figures in this paper, since the forms of those fractions are too complicated.

4. Velocity distribution function to second order

The velocity distribution function for hard-disk molecules which we have derived in this subsection valid to second order is now applied to a nonequilibrium steady-state system under the temperature gradient along the x axis. In this case, the form of B_{0r}^{II} in Eq. (36) becomes

$$B_{0r}^{\text{II}} = \frac{b_{0r}}{\pi d^2 n^2 T^2} (\partial_x T)^2, \quad (38)$$

and, using the relation (35), B_{kr}^{II} in Eq. (37) can be transformed into a more simple form

$$B_{kr}^{\text{II}} = \frac{\delta_{k,2} b_{2r}}{\pi d^2 n^2 T^2} (\partial_x T)^2, \quad (39)$$

where values for the constants b_{2r} are summarized in Table IV. The other second-order term C_{kr}^{II} becomes zero.

From Eqs. (14) and (16), the velocity distribution function of the steady-state Boltzmann equation for hard-disk molecules to second order in the temperature gradient along the x axis can be written as

TABLE III. Numerical constants b_{2r}^A (upper) and b_{2r}^B (lower) in Eq. (37).

r	$r \leq 2$	$r \leq 3$	$r \leq 4$	$r \leq 5$	$r \leq 6$
0	-1.277×10^{-2}	-1.784×10^{-3}	2.073×10^{-4}	6.982×10^{-4}	8.380×10^{-4}
1	-1.007	-9.775×10^{-1}	-9.721×10^{-1}	-9.708×10^{-1}	-9.704×10^{-1}
2	3.363×10^{-1}	3.701×10^{-1}	3.758×10^{-1}	3.772×10^{-1}	3.775×10^{-1}
3	-	3.262×10^{-2}	3.643×10^{-2}	3.729×10^{-2}	3.753×10^{-2}
4	-	-	2.584×10^{-3}	2.986×10^{-3}	3.089×10^{-3}
5	-	-	-	2.091×10^{-4}	2.461×10^{-4}
6	-	-	-	-	1.557×10^{-5}
r	$r \leq 2$	$r \leq 3$	$r \leq 4$	$r \leq 5$	$r \leq 6$
0	4.052×10^{-1}	4.041×10^{-1}	4.039×10^{-1}	4.038×10^{-1}	4.038×10^{-1}
1	-4.261×10^{-1}	-4.297×10^{-1}	-4.304×10^{-1}	-4.306×10^{-1}	-4.306×10^{-1}
2	-4.452×10^{-2}	-4.886×10^{-2}	-4.968×10^{-2}	-4.987×10^{-2}	-4.993×10^{-2}
3	-	-4.594×10^{-3}	-5.174×10^{-3}	-5.304×10^{-3}	-5.340×10^{-3}
4	-	-	-4.315×10^{-4}	-4.961×10^{-4}	-5.125×10^{-4}
5	-	-	-	-3.688×10^{-5}	-4.311×10^{-5}
6	-	-	-	-	-2.881×10^{-6}

$$\begin{aligned}
f = f^{(0)} & \left\{ 1 - \frac{J_x}{b_{11} n \kappa T} \left(\frac{m}{2 \kappa T} \right)^{1/2} \sum_{r \geq 1} r! b_{1r} c_x S_1^r(\mathbf{c}^2) \right. \\
& + \frac{m J_x^2}{4 b_{11}^2 n^2 \kappa^3 T^3} \left[\sum_{r \geq 2} r! b_{0r} S_0^r(\mathbf{c}^2) \right. \\
& \left. \left. + \sum_{r \geq 0} r! b_{2r} (c_x^2 - c_y^2) S_2^r(\mathbf{c}^2) \right] \right\}, \quad (40)
\end{aligned}$$

where the specific values for b_{1r} , b_{0r} , and b_{2r} are found in Tables I, II, and IV, respectively. J_x corresponds to the x component of the heat flux in Eq. (34). Note that we have changed \mathbf{c}_1 to \mathbf{c} . As can be seen from Eq. (40), the explicit form of the velocity distribution function for hard-disk molecules becomes the sum of an infinite series of Sonine polynomials.

Figure 2 gives the $\phi^{(2)}$ in Eq. (40) scaled by $m J_x^2 / n^2 \kappa^3 T^3$ with the third, fourth, fifth, sixth, and seventh approximations b_{0r} and b_{2r} . It should be mentioned that, as Fig. 2 shows, the scaled $\phi^{(2)}$ in Eq. (40) seems to converge to the seventh approximation. Figure 3 provides the explicit form of the scaled $\phi^{(2)}$ for hard-disk molecules with seventh ap-

proximations b_{0r} and b_{2r} . It is seen that the scaled $\phi^{(2)}$ for hard-disk molecules is strained symmetrically.

IV. OTHER NONEQUILIBRIUM VELOCITY DISTRIBUTION FUNCTIONS TO SECOND ORDER

A. Chapman-Enskog solution of the two-dimensional steady-state BGK equation to second order

For comparison, we also derive the velocity distribution function for the two-dimensional steady-state BGK equation to second order by the Chapman-Enskog method. [25–28]. Suppose a nonequilibrium system subject to a temperature gradient along the x axis in a steady state whose velocity distribution function is expressed as $f = f(x, \mathbf{v})$. The steady-state BGK equation is written as

$$v_x \partial_x f = \frac{f_{LE} - f}{\tau}, \quad (41)$$

where the relaxation time τ is dependent on the position x through the density $n(x)$ and temperature $T(x)$. f_{LE} is the usual local equilibrium velocity distribution function

TABLE IV. Numerical constants b_{2r} in Eq. (39).

r	$r \leq 2$	$r \leq 3$	$r \leq 4$	$r \leq 5$	$r \leq 6$
0	-2.154×10^{-1}	-2.038×10^{-1}	-2.017×10^{-1}	-2.012×10^{-1}	-2.011×10^{-1}
1	-7.943×10^{-1}	-7.626×10^{-1}	-7.569×10^{-1}	-7.555×10^{-1}	-7.551×10^{-1}
2	3.586×10^{-1}	3.945×10^{-1}	4.006×10^{-1}	4.021×10^{-1}	4.025×10^{-1}
3	-	3.492×10^{-2}	3.902×10^{-2}	3.994×10^{-2}	4.020×10^{-2}
4	-	-	2.800×10^{-3}	3.234×10^{-3}	3.346×10^{-3}
5	-	-	-	2.276×10^{-4}	2.677×10^{-4}
6	-	-	-	-	1.701×10^{-5}

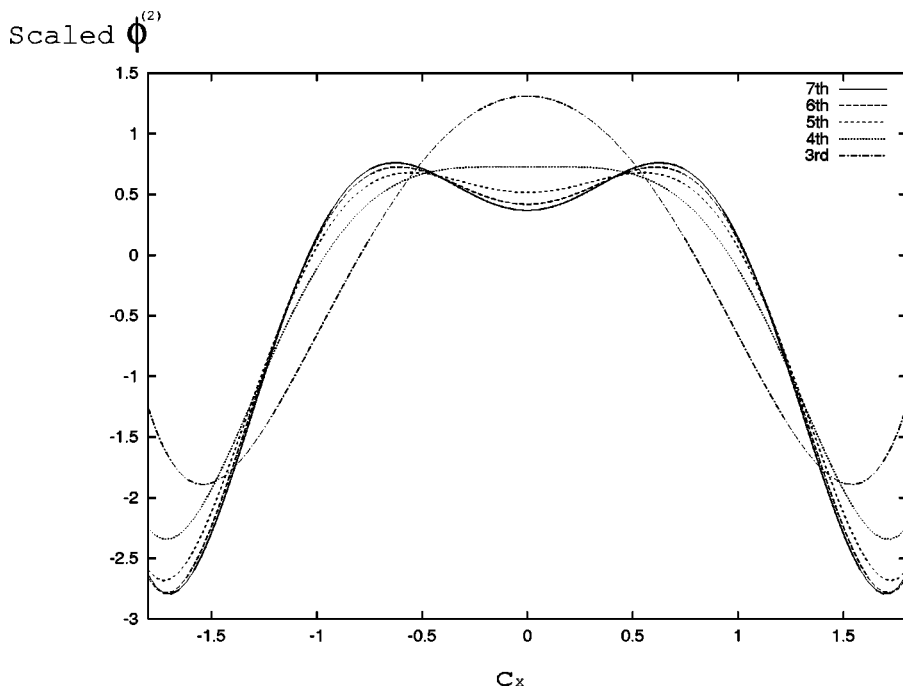


FIG. 2. The scaled $\phi^{(2)}$'s for hard-disk molecules. The dash-dotted line, the dotted line, the short-dashed line, the long-dashed line, and the solid line correspond to the scaled $\phi^{(2)}$ for hard-disk molecules with the third, fourth, fifth, sixth, and seventh approximations b_{0r} and b_{2r} , respectively. Note that we put $c_y=0$.

$f_{LE}(x, \mathbf{v}) = [mn(x)/2\pi\kappa T(x)] \exp[-m\mathbf{v}^2/2\kappa T(x)]$. It should be mentioned that, for the conservation laws, the collision term for the steady-state BGK equation, the right-hand side of Eq. (41), must satisfy

$$\int \Phi_i f_{LE} d\mathbf{v} = \int \Phi_i f d\mathbf{v}, \quad (42)$$

with the four collision invariants Φ_i introduced in Eq. (9). The velocity distribution function f can be expanded as

$$f = f^{(0)} + f^{(1)} + f^{(2)} + \dots, \quad (43)$$

with $f^{(0)} \equiv f_{LE}$. Substituting Eq. (43) into the steady-state BGK equation (41), we arrive at the following set of equations:

$$-\frac{f^{(1)}}{\tau} = v_x \partial_x f^{(0)} \quad (44)$$

to first order and

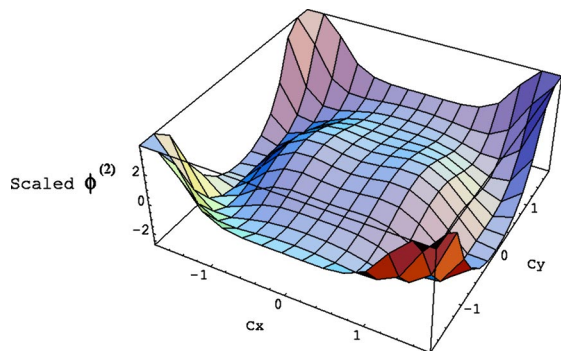


FIG. 3. The scaled $\phi^{(2)}$ for hard-disk molecules with the seventh approximations b_{0r} and b_{2r} .

$$-\frac{f^{(2)}}{\tau} = v_x \partial_x f^{(1)} \quad (45)$$

to second order. It is found that Eq. (44) with the requirement (42) leads to $n\kappa T$ being uniform and that Eq. (45) with the requirement (42) leads to heat flux J_x calculated from Eq. (33) being uniform. Using these facts, from Eqs. (44) and (45), the velocity distribution function to second order for the two-dimensional steady-state BGK equation becomes

$$f = f^{(0)} \sum_{n=0}^2 \left\{ -\frac{J_x}{n\kappa T} \left(\frac{m}{2\kappa T} \right)^{1/2} \right\}^n n! c_x^n S_1^n(\mathbf{c}^2), \quad (46)$$

with the uniform heat flux $J_x = -2n\kappa^2 T \tau \partial_x T/m$.

B. Two-dimensional information theory

Let us construct two-dimensional information theory [53,54]. The Zubarev form for the nonequilibrium velocity distribution function under a heat flux can be obtained by maximizing the nonequilibrium entropy, defined as

$$S(x) \equiv -\kappa \int f \ln f d\mathbf{v}, \quad (47)$$

under the constraints of the density

$$n(x) \equiv \int f d\mathbf{v} \quad (48)$$

and temperature

$$n(x)\kappa T(x) \equiv \int \frac{m\mathbf{v}^2}{2} f d\mathbf{v}. \quad (49)$$

We assume no mean flow:

$$\int m\mathbf{v}f d\mathbf{v} = 0, \quad (50)$$

where $\mathbf{0}$ denotes the zero vector. Furthermore, we adopt the heat flux as a constraint:

$$J_x \equiv \int \frac{m\mathbf{v}^2}{2} v_x f d\mathbf{v}. \quad (51)$$

It should be emphasized that $n\kappa T$ and the heat flux J_x are now assumed to be uniform by contrast with the case for the steady-state Boltzmann equation where its solubility conditions lead to $n\kappa T$ and J_x being constant to second order.

We have finally derived the nonequilibrium velocity distribution function to second order in the heat flux J_x by expanding the Zubarev's nonequilibrium velocity distribution function to second order as

$$f = f^{(0)} \left\{ 1 - \frac{J_x}{n\kappa T} \left(\frac{m}{2\kappa T} \right)^{1/2} c_x S_1^1(\mathbf{c}^2) + \frac{mJ_x^2}{n^2\kappa^3 T^3} \left(\frac{1}{2} - \frac{3\mathbf{c}^2}{4} \right) + \frac{mJ_x^2}{n^2\kappa^3 T^3} c_x^2 \left[1 - \mathbf{c}^2 + \frac{\mathbf{c}^2}{4} \right] \right\}. \quad (52)$$

In Eq. (52), we have expanded the *nonequilibrium temperature* which has been obtained as $\Theta = T(1 - 3mJ_x^2/4n^2\kappa^3 T^3)$ for two dimensions. Such a *modified* velocity distribution function has been also obtained and used in three dimensions [43,46]. We note that, in all the macroscopic quantities calculated in this paper, there are no differences between the results from the modified velocity distribution function and Jou's velocity distribution function where the *nonequilibrium temperature* is not expanded [53,54]. Actually, the identifications of the density, the temperature, and the mean flow in Eqs. (11)–(13) do not affect the physical properties of the velocity distribution function for the two-dimensional steady-state Boltzmann equation [18], and those identifications must be satisfied for the conservation laws in the case for the two-dimensional steady-state BGK equation [see Eq. (42)].

V. DIRECT COMPARISON OF THE SCALED $\phi^{(2)}$

Figure 4 exhibits the direct comparison of the scaled $\phi^{(2)}$'s for hard-disk molecules (40) to the seventh approximation with those for the steady-state BGK equation (46) and information theory (52). We have found that, as Fig. 4 explicitly shows, the second-order velocity distribution function for hard-disk molecules (40) definitely differs from the others. We emphasize that such a difference never appears to first order.

VI. NONLINEAR NONEQUILIBRIUM TRANSPORT PHENOMENA

We can introduce the general form of the heat flux as

$$J_x = -\varpi T^\varphi \partial_x T, \quad (53)$$

where φ indicates temperature dependence of the thermal conductivity and ϖ is a constant that depends upon micro-

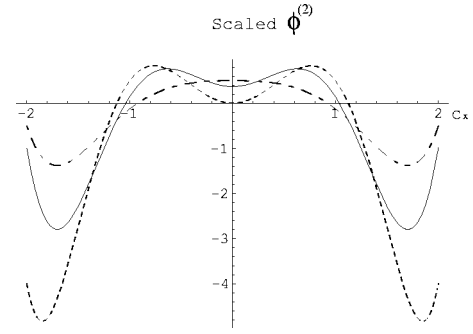


FIG. 4. Direct comparison of the scaled $\phi^{(2)}$ for hard-disk molecules with those for the steady-state BGK equation and information theory. The solid line, the dashed line, and the dash-dotted line correspond to the scaled $\phi^{(2)}$ for hard-disk molecules with the seventh approximations b_{0r} and b_{2r} , the steady-state BGK equation, and information theory, respectively. Note that we put $c_y = 0$.

scopic models. For example, φ is calculated as $1/2$ for hard-disk molecules, and ϖ is determined as $2b_{11}\kappa/d(\kappa/\pi m)^{1/2}$ with $b_{11} \approx 1.030$ for hard-disk molecules [see Eq. (34)]. Note that φ and ϖ cannot be determined explicitly from the BGK equation and information theory. From Eq. (53), the temperature profile $T(x)$ in the nonequilibrium steady state can be determined as

$$T(x) = \left[T(0)^{\varphi+1} - (\varphi+1) \frac{J_x}{\varpi} x \right]^{1/(\varphi+1)}. \quad (54)$$

It is seen that the temperature profile $T(x)$ becomes nonlinear except for $\varphi = 0$.

Using Eq. (20), the equation of state in the nonequilibrium steady state can be obtained as

$$P_{ij} = n\kappa T \left[\delta_{ij} + \lambda_p^{ij} \frac{mJ_x^2}{n^2\kappa^3 T^3} \right], \quad (55)$$

with the unit tensor δ_{ij} and the tensor components λ_p^{ij} given in Table V. The values of λ_p^{ij} for the seventh approximation b_{1r} , b_{0r} , and b_{2r} for hard-disk molecules seems to be converged to three significant figures, as can be seen from Table V. Note that the off-diagonal components of λ_p^{ij} are zero, and $\lambda_p^{xx} = -\lambda_p^{yy}$ is satisfied. Equation (55) shows that the equation

TABLE V. Numerical constants for the macroscopic quantities: the i th approximation quantities for hard-disk molecules and the exact values for the steady-state BGK equation and information theory.

i th	λ_p^{xx}	λ_s
3th	-5.085×10^{-2}	-2.549×10^{-1}
4th	-4.807×10^{-2}	-2.551×10^{-1}
5th	-4.757×10^{-2}	-2.551×10^{-1}
6th	-4.744×10^{-2}	-2.552×10^{-1}
7th	-4.741×10^{-2}	-2.552×10^{-1}
BGK equation	0	$-\frac{1}{4}$
Information	$\frac{1}{2}$	$-\frac{1}{4}$

of state in the nonequilibrium steady state is not modified to first order. We indicate that the second-order pressure tensor $P_{ij}^{(2)}$ should be uniform from the solubility conditions for the third-order solution $\phi^{(3)}$:

$$\int \Phi_i \mathbf{v}_1 \cdot \nabla f_1^{(2)} d\mathbf{v}_1 = 0. \quad (56)$$

Therefore, the pressure tensor P_{ij} in Eq. (55) becomes uniform since $n\kappa T$ is constant from the solubility conditions (8).

We find that λ_p^{ij} for hard-disk molecules differs from that for the steady-state BGK equation and information theory not only quantitatively but also qualitatively: $\lambda_p^{xx} < \lambda_p^{yy}$ for hard-disk molecules, while $\lambda_p^{xx} = \lambda_p^{yy}$ for the steady-state BGK equation and $\lambda_p^{xx} > \lambda_p^{yy}$ for information theory. This kind of difference has been also found in the three-dimensional case [18].

Each component of the kinetic temperature in the nonequilibrium steady state; i.e., T_i for $i=x$ and y is calculated as

$$\frac{n\kappa T_i}{2} \equiv \left(\frac{2\kappa T}{m} \right)^2 \int_{-\infty}^{\infty} d\mathbf{c} \frac{m\mathbf{c}_i^2}{2} f, \quad (57)$$

which leads to

$$T_i = T \left[1 + \lambda_p^{ii} \frac{mJ_x^2}{n^2 \kappa^3 T^3} \right], \quad (58)$$

for $i=x$ and y . Values for the constants in the second-order term λ_p^{ii} are the same as λ_p^{ij} for $i=j$ given in Table V. For hard-disk molecules, T_x becomes smaller than T_y regardless of the sign of J_x , which means that the motion of hard-disk molecules along the heat flux becomes dull. We note that T_i for hard-disk molecules is isotropic to first order; that is, the equipartition law of energy holds.

The Shannon entropy in the nonequilibrium steady state S is defined via

$$S \equiv - \frac{2\kappa^2 T}{m} \int_{-\infty}^{\infty} d\mathbf{c} f \ln f = -n\kappa \ln \left[\frac{nm}{2\pi\kappa T} \right] + n\kappa + \lambda_S \frac{mJ_x^2}{n\kappa^2 T^3}. \quad (59)$$

Values for the constant λ_S are given in Table V: λ_S for the seventh approximation b_{1r} , b_{0r} , and b_{2r} for hard-disk molecules seems to converge to four significant figures. It is found that λ_S for hard-disk molecules is close to that for the steady-state BGK equation and information theory. This is because the second-order correction term in the Shannon entropy is determined only by the square of the first-order solution $\phi^{(1)}$ where no important difference dependent on the kinetic equations or information theory appears. We note that the Shannon entropy in the nonequilibrium steady state is not modified to first order.

VII. CONTRIBUTION OF THE STEADY HEAT CONDUCTION TO THE RATE OF CHEMICAL REACTION

A. Calculation of the rate of chemical reaction

In the early stage of a chemical reaction between monatomic gas molecules,



the rate of chemical reaction may not be affected by the existence of products, and the reverse reaction can be neglected [67]. From the viewpoint of kinetic collision theory, the chemical reaction rate (60) can be described as

$$R = \int d\mathbf{v} \int d\mathbf{v}_1 \int d\Omega \int ff_1 g \sigma(g), \quad (61)$$

for two dimensions. Here Ω denotes the solid angle for two dimensions. For the differential cross section of chemical reaction $\sigma(g)$, we have derived the line-of-centers model for the case of two dimensions. Its form becomes

$$\sigma(g) = \begin{cases} 0, & g < \sqrt{\frac{4E^*}{m}}, \\ \frac{d}{\pi} \left(1 - \frac{4E^*}{mg^2} \right)^{1/2}, & g \geq \sqrt{\frac{4E^*}{m}}, \end{cases} \quad (62)$$

with m the mass of molecules and E^* the threshold energy of a chemical reaction.

We calculate the rate of chemical reaction (61) with the two-dimensional line-of-centers model (62) using the explicit velocity distribution function of the two-dimensional steady-state Boltzmann equation for hard-core molecules to second order (40). Substituting the expanded form of the velocity distribution function to second order in Eq. (3) into Eq. (61), we obtain

$$R = R^{(0)} + R^{(1)} + R^{(2)} \quad (63)$$

up to second order. The zeroth-order term of R ,

$$\begin{aligned} R^{(0)} &= \int d\mathbf{v} \int d\mathbf{v}_1 \int d\Omega \int f^{(0)} f_1^{(0)} g \sigma(g) \\ &= 2n^2 d \left(\frac{\pi\kappa T}{m} \right)^{1/2} e^{-E^*/\kappa T}, \end{aligned} \quad (64)$$

corresponds to the rate of chemical reaction of the equilibrium theory. Similarly, the first-order term of R is obtained as

$$R^{(1)} = \int d\mathbf{v} \int d\mathbf{v}_1 \int d\Omega \int f^{(0)} f_1^{(0)} [\phi^{(1)} + \phi_1^{(1)}] g \sigma(g), \quad (65)$$

where $R^{(1)}$ does not appear because $\phi^{(1)}$ is an odd functions of \mathbf{c} , as is shown in Eq. (40). The second-order term of R —i.e., $R^{(2)}$ —is divided into

$$R^{(2,A)} = \int d\mathbf{v} \int d\mathbf{v}_1 \int d\Omega \int f^{(0)} f_1^{(0)} \phi^{(1)} \phi_1^{(1)} g \sigma(g) \quad (66)$$

and

$$R^{(2,B)} = \int d\mathbf{v} \int d\mathbf{v}_1 \int d\Omega \int f^{(0)} f_1^{(0)} [\phi^{(2)} + \phi_1^{(2)}] g \sigma(g), \quad (67)$$

which exhibit the local nonequilibrium effect. Since the integrations (66) and (67) have the cutoff form as in Eq. (62),

TABLE VI. Numerical constants α_r in Eq. (68).

r	Boltzmann eq.	BGK eq. and information theory
0	-2.758×10^{-2}	$-\frac{3}{128}$
1	-1.761×10^{-1}	$-\frac{9}{64}$
2	4.015×10^{-1}	$\frac{9}{32}$
3	-1.310×10^{-1}	$-\frac{1}{16}$
4	1.326×10^{-2}	-
5	-1.368×10^{-3}	-
6	1.260×10^{-4}	-
7	-9.809×10^{-6}	-
8	6.290×10^{-7}	-
9	-3.249×10^{-8}	-
10	1.306×10^{-9}	-
11	-3.902×10^{-11}	-
12	8.256×10^{-13}	-
13	-1.160×10^{-14}	-
14	9.645×10^{-17}	-
15	-3.576×10^{-19}	-

the explicit forms of $\phi^{(1)}$ and $\phi^{(2)}$ of the steady-state Boltzmann equation for hard-disk molecules are required to calculate $R^{(2,A)}$ and $R^{(2,B)}$, respectively.

In Fig. 2, we have confirmed that $\phi^{(2)}$ seems to converge to the seventh Sonine approximation, so that we will show only the results calculated from $\phi^{(1)}$ and $\phi^{(2)}$ for the seventh approximation of Sonine polynomials. In order to compare the results from the steady-state Boltzmann equation with those from the steady-state BGK equation and information theory, we also use the explicit forms of $\phi^{(1)}$ and $\phi^{(2)}$ obtained in Eq. (46) for the steady-state BGK equation and in Eq. (52) for information theory.

B. Local nonequilibrium effect on the rate of chemical reaction

Inserting $\phi^{(1)}$ and $\phi^{(2)}$ of Eq. (40) for the steady-state Boltzmann equation for hard-core molecules, Eq. (46) for the steady-state BGK equation, and Eq. (52) for information theory into Eqs. (66) and (67), and performing the integrations with the chemical reaction cross section (62), we finally obtain the local nonequilibrium effect on the rate of chemical reaction based on the line-of-centers model. The expressions of $R^{(2,A)}$ and $R^{(2,B)}$ become

$$R^{(2,A)} = \frac{dmJ_x^2}{\kappa^3 T^3} \left(\frac{\pi \kappa T}{m} \right)^{1/2} e^{-E^*/\kappa T} \left\{ \sum_{r \geq 0} \alpha_r \left(\frac{E^*}{\kappa T} \right)^r \right\} \quad (68)$$

and

$$R^{(2,B)} = \frac{dmJ_x^2}{\kappa^3 T^3} \left(\frac{\pi \kappa T}{m} \right)^{1/2} e^{-E^*/\kappa T} \left\{ \sum_{r \geq 0} \beta_r \left(\frac{E^*}{\kappa T} \right)^r \right\}, \quad (69)$$

respectively. The numerical values for α_r and β_r are listed in Tables VI and VII, respectively. As well as the three-dimensional case, the two-dimensional $R^{(2,B)}$ for the steady-

TABLE VII. Numerical constants β_r in Eq. (69).

r	Boltzmann eq.	BGK eq.	Information theory
0	-1.284×10^{-1}	$-\frac{9}{64}$	$-\frac{17}{128}$
1	-4.721×10^{-1}	$-\frac{30}{64}$	$-\frac{31}{64}$
2	3.372×10^{-1}	$\frac{3}{16}$	$\frac{11}{32}$
3	7.086×10^{-2}	$\frac{1}{8}$	$\frac{1}{16}$
4	-3.874×10^{-3}	-	-
5	1.536×10^{-4}	-	-
6	-2.774×10^{-6}	-	-

state Boltzmann equation is determined only by the terms of b_{0r} in $\phi^{(2)}$ of Eq. (40). This is because $R^{(2,B)}$ of Eq. (67) has x - y symmetry, so that the terms including $(c_x^2 - c_y^2)$ in $\phi^{(2)}$ of Eq. (40) do not contribute to $R^{(2,B)}$.

The graphical results of $R^{(2)}$ compared with those of $R^{(2,A)}$ are provided in Fig. 5. Both $R^{(2)}$ and $R^{(2,A)}$ in Fig. 5 are scaled by $\pi^{1/2} dm^{1/2} J_x^2 / \kappa^{5/2} T^{5/2}$. Note that $R^{(2)}$ is the sum of $R^{(2,A)}$ and $R^{(2,B)}$ in Eqs. (68) and (69). As Fig. 5 shows, it is clear that $R^{(2,B)}$ plays an essential role for the evaluation of $R^{(2)}$. We have found that there are no qualitative differences among $R^{(2)}$ and $R^{(2,A)}$ for the steady-state Boltzmann equation and those for the steady-state BGK equation and information theory, while they exhibit slight deviations from each other. The quantitative deviation in $R^{(2,A)}$ would not be observed if we adopted $\phi^{(1)}$ of the steady-state Boltzmann equation for the lowest Sonine approximation, because that is identical with the precise $\phi^{(1)}$ of the steady-state BGK equation and information theory.

VIII. DISCUSSION AND CONCLUSION

Fushiki has recently demonstrated that our analytical three-dimensional second-order solution of the steady-state Boltzmann equation for hard-core molecules agrees well

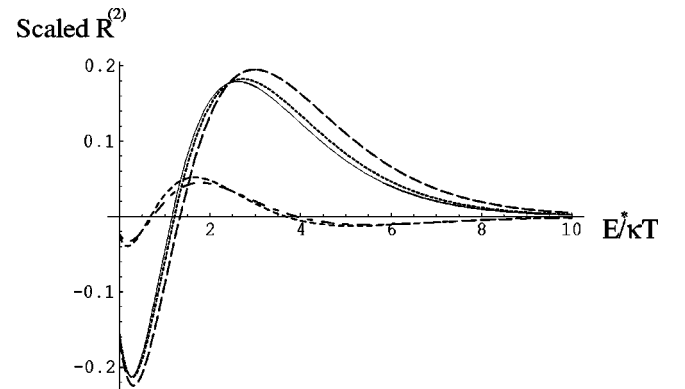


FIG. 5. Scaled $R^{(2)}$ compared to scaled $R^{(2,A)}$ as a function of $E^*/\kappa T$ for the two-dimensional case. The solid line, the long-dashed line and the dotted line show $R^{(2)}$ for hard-disk molecules, the steady-state BGK equation, and information theory, respectively. The dashed line and the dash-dotted line represent $R^{(2,A)}$ for hard-disk molecules and both the steady-state BGK equation and information theory, respectively.

with results of his numerical experiment using both a molecular dynamics simulation and a direct simulation monte carlo method [19,20]. Using the method developed in Ref. [18], we have derived the velocity distribution function of the two-dimensional steady-state Boltzmann equation for hard-disk molecules explicitly to second order in the temperature gradient, as was shown explicitly in Eq. (40) and graphically in Fig. 3. We have calculated the two-dimensional equation of state for hard-disk molecules to second order from it. We believe that the second-order solution of the steady-state Boltzmann equation is physically important in that it reflects a nonequilibrium state far from equilibrium, called the local nonequilibrium state.

We have found that there are qualitative differences between hard-disk molecules and the steady-state BGK equation in the nonlinear nonequilibrium transport phenomena based on the local nonequilibrium state: the second-order corrections appear for hard-disk molecules in the pressure tensor P_{ij} and the kinetic temperature T_i , while no corrections to these quantities appear for the steady-state BGK equation, as Table V shows. This kind of qualitative differences was detected also in the three-dimensional case [18]. This discrepancy is due to the fact that the g dependence cannot be absorbed in the single relaxation time of the BGK equation, which leads to the conclusion that the steady-state BGK equation neither captures the essence of hard-disk molecules nor possesses the characteristics of any other models of molecules which interact with a g dependence. We suggest that microscopic models which possess the property that its relaxation to the local equilibrium state is described only by a single relaxation time could not be applied to describe the nonlinear nonequilibrium transport phenomena. This suggestion may mean that the steady-state BGK equation could capture the essence of hard-disk molecules if one made the relaxation time depend on g or if one developed the steady-state BGK equation with multirelaxation times. We note that the qualitative differences mentioned above still appear no matter which boundary condition is adopted; that is, the isotropy and the anisotropy of the pressure tensor in Eq. (55) and the kinetic temperature in Eq. (58) are not affected by any kinds of boundary conditions.

We have examined information theory by the microscopic kinetic theory mentioned above and consider the possibility of the existence of a nonequilibrium universal velocity distribution function. The first-order velocity distribution function for the steady-state Boltzmann equation for hard-disk molecules—i.e., the first-order terms in Eq. (40)—is consistent with that derived by expanding Zubarev's velocity distribution function [50–52]. On the other hand, the explicit form of the second-order term in Eq. (40) definitely differs from the precise form for the steady-state BGK equation (46) or information theory (52), as Fig. 4 shows. Although information theory has been applied to nonequilibrium dilute gases [39,43,55–58], we have found that information theory contradicts the microscopic kinetic models: all the macroscopic quantities for information theory except for the Shannon entropy S in Eq. (59) are qualitatively different from those for the steady-state Boltzmann equation and the steady-state BGK equation. These results indicate that characteristics of microscopic models appear in the local non-

equilibrium state; that is, nonlinear nonequilibrium transport phenomena are sensitive to differences of kinetic models, so rather realistic models are needed when one investigates them. We can conclude that, though quite a few statistical physicists have believed in the existence of a universal velocity distribution function in the nonequilibrium steady state by maximizing the Shannon-type entropy [11,47,48,50–53], any universal nonlinear nonequilibrium velocity distribution function does not seem to exist in the two-dimensional case as well as the three-dimensional case, even when it is expressed only in terms of macroscopic quantities. We suggest that the entropy defined in Eq. (47) is not appropriate as the nonequilibrium entropy to second order, though it is appropriate to first order, and that some nonequilibrium corrections dependent on microscopic models are needed for the nonequilibrium entropy to second order.

The second-order solution of the steady-state Boltzmann equation for hard-disk molecules is indispensable for the calculation of the nonequilibrium effects on the rate of chemical reaction, since $R^{(1)}$ does not appear and $R^{(2,B)}$ is remarkably larger than $R^{(2,A)}$ as Fig. 5 shows. This indicates the significance of the second-order coefficients as terms which reflect the local nonequilibrium state.

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APPENDIX A: CALCULATION OF Ω_{kr}

From the definition of Q_{kr} , Ω_{kr} can be calculated using the mathematical properties of the trigonometrical functions and Sonine polynomials. For example, $c_{1x}Q_{kr}$ can be rewritten as

$$\left(\frac{2\kappa T}{m}\right)^{1/2} c_{1x}Q_{kr} = 2(\delta_{k,0} + 1) \left(\frac{m}{2\kappa T}\right)^{k/2} \frac{S_k^r(\mathbf{c}_1^2)}{\Gamma(k+r+1)} \times \left[Y_{k+1}(\mathbf{c}_1) + \frac{2\kappa T}{m} c_1^2 Y_{k-1}(\mathbf{c}_1) \right]. \quad (\text{A1})$$

Integrating Eq. (A1) over $(2\kappa T/m)^{1/2}\mathbf{c}_1$ with f_1 from Eq. (14) can be performed by using the following orthogonality properties. For Sonine polynomials,

$$\int_0^\infty X^k e^{-X} S_{k-1}^p(X) S_k^q(X) dX = \frac{(-1)^{p-q} \Gamma(q+k+1)}{q!}, \quad (\text{A2})$$

for $p=q$ and $p=q+1$, and is zero otherwise. For the trigonometrical functions,

$$\int_0^{2\pi} \cos n\phi \sin m\phi d\phi = 0 \quad (\text{A3})$$

and

$$\int_0^{2\pi} \cos n\phi \cos m\phi d\phi = \int_0^{2\pi} \sin n\phi \sin m\phi d\phi = \pi\delta_{nm}, \quad (\text{A4})$$

with the Kronecker delta δ_{pq} for $m \neq 0$. We can calculate $D_{k,r}$ and $E_{k,r}$ defined as

$$D_{k,r} \equiv \frac{1}{n} \frac{\partial}{\partial c_{1x}} Q_{kr}, \quad E_{k,r} \equiv \frac{1}{n} \frac{\partial}{\partial c_{1y}} Q_{kr}. \quad (\text{A5})$$

The results can be written as

$$D_{k,r} = (\delta_{k,0} + 1)[(k+r+1)B_{k+1,r} - B_{k+1,r-1} + (\delta_{k,0} + 1)B_{k-1,r} - (\delta_{k,0} + 1)(r+1)B_{k-1,r+1}] \quad (\text{A6})$$

and

$$E_{k,r} = (\delta_{k,0} + 1)[(k+r+1)C_{k+1,r} - C_{k+1,r-1} - C_{k-1,r} + (r+1)C_{k-1,r+1}]. \quad (\text{A7})$$

Additionally, $c_{1x} \partial_x Q_{kr}$ can be rewritten as

$$c_{1x} \partial_x Q_{kr} = \frac{\partial_x T}{T} c_{1x} \left[Q_{k,r-1}(\mathbf{c}_1) - \left(r + \frac{k}{2} \right) Q_{k,r} \right]. \quad (\text{A8})$$

Therefore, by integrating Eq. (A8) over $(2\kappa T/m)^{1/2} \mathbf{c}_1$, with f_1 from Eq. (14), it is found that

$$\overline{c_{1x} \partial_x Q_{kr}} = n \frac{\partial_x T}{T} \left[D_{k,r-1} - \left(r + \frac{k}{2} \right) D_{k,r} \right]. \quad (\text{A9})$$

Similarly $\overline{c_{1y} \partial_y Q_{kr}}$ is obtained by replacing the differential coefficients with respect to x by the corresponding differential coefficients with respect to y , the $D_{k,r}$'s by the corresponding $E_{k,r}$, respectively. Substituting these results into Eq. (23), Ω_{kr} finally becomes Eq. (25).

APPENDIX B: CALCULATION OF $F_{kr}^1(\chi)$

1. Details of $F_{kr}^1(\chi)$

The details of $F_{kr}^1(\chi)$ are written in this appendix. Substituting the general forms of f_1, f_2 in Eq. (14) and Q'_{kr} in Eq. (21) into $F_{kr}^1(\chi)$ in Eq. (29), $F_{kr}^1(\chi)$ can be written as

$$F_{kr}^1(\chi) = \sum_{n_1, n_2, k_1, k_2} W_{k, k_1, k_2}^{r, n_1, n_2} \{ \Xi_{k, k_1, k_2}^{Y, r, n_1, n_2}(\chi) B_{k_1 n_1} B_{k_2 n_2} + \Xi_{k, k_1, k_2}^{Z, r, n_1, n_2}(\chi) C_{k_1 n_1} C_{k_2 n_2} \}, \quad (\text{B1})$$

where $\Xi_{k, k_1, k_2}^{Y, r, n_1, n_2}(\chi)$ is the characteristic integral defined as

$$\Xi_{k, k_1, k_2}^{Y, r, n_1, n_2}(\chi) \equiv \int \int \exp[-(c_1^2 + c_2^2)] Y_k(\mathbf{c}'_1) Y_{k_1}(\mathbf{c}_1) Y_{k_2}(\mathbf{c}_2) \times S_k^r(\mathbf{c}'_1) S_{k_1}^{n_1}(\mathbf{c}_1) S_{k_2}^{n_2}(\mathbf{c}_2) g d\mathbf{c}_2 d\mathbf{c}_1 \quad (\text{B2})$$

and

$$\Xi_{k, k_1, k_2}^{Z, r, n_1, n_2}(\chi) \equiv \int \int \exp[-(c_1^2 + c_2^2)] Y_k(\mathbf{c}'_1) Z_{k_1}(\mathbf{c}_1) Z_{k_2}(\mathbf{c}_2) \times S_k^r(\mathbf{c}'_1) S_{k_1}^{n_1}(\mathbf{c}_1) S_{k_2}^{n_2}(\mathbf{c}_2) g d\mathbf{c}_2 d\mathbf{c}_1. \quad (\text{B3})$$

We note that values of the latter are obtained from those of

the former by a transformation of axes and that $\Xi_{k,0,k_2}^{Z, r, n_1, n_2}(\chi) = \Xi_{k, k_1, 0}^{Z, r, n_1, n_2}(\chi) = 0$ from Eq. (18). The integral containing $Y_{k_1}(\mathbf{c}_1) Z_{k_2}(\mathbf{c}_2) + Z_{k_1}(\mathbf{c}_1) Y_{k_2}(\mathbf{c}_2)$ becomes zero, owing to the symmetry of the trigonometrical functions. The factor $W_{k, k_1, k_2}^{r, n_1, n_2}$ in Eq. (B1) is defined as

$$W_{k, k_1, k_2}^{r, n_1, n_2} \equiv \frac{4n^2}{\pi^2 \Gamma(k+r+1)} \left(\frac{m}{2\kappa T} \right)^{(k+k_1+k_2)/2} n_1! n_2!, \quad (\text{B4})$$

which is obtained from the prefactors and the coefficients in the general form of f_1, f_2 in Eq. (14) and Q'_{kr} in Eq. (21).

We find that it is necessary only to evaluate the characteristic integral $\Xi_{k, k_1, k_2}^{Y, r, n_1, n_2}(\chi)$ in order to calculate $F_{kr}^1(\chi)$. Our calculation of $\Xi_{k, k_1, k_2}^{Y, r, n_1, n_2}(\chi)$ is written in the next subsection. Once the characteristic integral $\Xi_{k, k_1, k_2}^{Y, r, n_1, n_2}(\chi)$ has been derived, $F_{kr}^1(\chi)$ is now calculated from Eq. (B1) with $W_{k, k_1, k_2}^{r, n_1, n_2}$ in Eq. (B4).

2. Calculation of $\Xi_{k, k_1, k_2}^{Y, r, n_1, n_2}(\chi)$

We shall explain how to calculate $\Xi_{k, k_1, k_2}^{Y, r, n_1, n_2}(\chi)$ which appears in Eq. (B2). The calculation has been performed mainly based on the method developed in Ref. [18].

a. Introduction of Θ_{k, k_1, k_2}

Using Eq. (15), the characteristic integral $\Xi_{k, k_1, k_2}^{Y, r, n_1, n_2}(\chi)$ corresponds to the coefficient of $s^r t^{n_1} u^{n_2}$ in

$$\Theta_{k, k_1, k_2} \equiv \nu_{k, k_1, k_2} \int \int \tilde{Y}_k(\mathbf{c}'_1) \tilde{Y}_{k_1}(\mathbf{c}_1) \tilde{Y}_{k_2}(\mathbf{c}_2) \exp\{-\alpha c_1^2 + \beta c_2^2 + \gamma c_1'^2\} g d\mathbf{c}_2 d\mathbf{c}_1, \quad (\text{B5})$$

that is,

$$\Theta_{k, k_1, k_2} \equiv \sum_{r, n_1, n_2} \Xi_{k, k_1, k_2}^{Y, r, n_1, n_2}(\chi) s^r t^{n_1} u^{n_2}. \quad (\text{B6})$$

In Eq. (B5), α, β , and γ are defined as

$$\alpha \equiv \frac{1}{1-t}, \quad \beta \equiv \frac{1}{1-u}, \quad \gamma \equiv \frac{s}{1-s}, \quad (\text{B7})$$

and ν_{k, k_1, k_2} is given by

$$\nu_{k, k_1, k_2} \equiv (1-s)^{-k-1} (1-t)^{-k_1-1} (1-u)^{-k_2-1} \left(\frac{2\kappa T}{m} \right)^{(k+k_1+k_2)/2} \quad (\text{B8})$$

and

$$\tilde{Y}_k(\mathbf{c}'_1) = c_1'^k \cos k\phi, \quad \tilde{Y}_{k_1}(\mathbf{c}_1) = c_1^{k_1} \cos k_1\phi_1, \quad (\text{B9})$$

$$\tilde{Y}_{k_2}(\mathbf{c}_2) = c_2^{k_2} \cos k_2\phi_2.$$

Finally, we need only to evaluate the characteristic integral Θ_{k, k_1, k_2} in order to calculate $\Xi_{k, k_1, k_2}^{Y, r, n_1, n_2}(\chi)$.

b. Derivation of the inductive equation

In order to evaluate Θ_{k, k_1, k_2} in Eq. (B5), let us derive an inductive equation for $\tilde{\Theta}_{k, k_1, k_2}$, which is related to Θ_{k, k_1, k_2} by

$$\tilde{\Theta}_{k,k_1,k_2} \equiv \nu_{k,k_1,k_2}^{-1} \Theta_{k,k_1,k_2}. \quad (\text{B10})$$

By replacing c_{1x} and c_{2x} by $c_{1x}-w$ and $c_{2x}-w$, respectively, c'_{1x} and c'_{2x} will be changed to $c'_{1x}-w$ and $c'_{2x}-w$. At the same time, the relative speed g is not modified, and the value of Θ_{k,k_1,k_2} is unchanged. Therefore, Θ_{k,k_1,k_2} is independent of w and differentiation of Θ_{k,k_1,k_2} with respect to w gives zero. After this differentiation has been performed and w has been set to zero, it is found that

$$\begin{aligned} & \int \int \exp\{- (\alpha c_1^2 + \beta c_2^2 + \gamma c_1'^2)\} g d\mathbf{c}_1 d\mathbf{c}_2 \{ \alpha \tilde{Y}_k \tilde{Y}_{k_2} (\tilde{Y}_{k_1+1} \\ & + c_1^2 \tilde{Y}_{k_1-1}) (\delta_{k_1,0} + 1) + \beta \tilde{Y}_k \tilde{Y}_{k_1} (\tilde{Y}_{k_2+1} + c_2^2 \tilde{Y}_{k_2-1}) (\delta_{k_2,0} + 1) \\ & + \gamma \tilde{Y}_{k_1} \tilde{Y}_{k_2} (\tilde{Y}_{k+1} + c_1'^2 \tilde{Y}_{k-1}) (\delta_{k,0} + 1) - k_1 \tilde{Y}_k \tilde{Y}_{k_1-1} \tilde{Y}_{k_2} \\ & - k_2 \tilde{Y}_k \tilde{Y}_{k_1} \tilde{Y}_{k_2-1} - k \tilde{Y}_{k-1} \tilde{Y}_{k_1} \tilde{Y}_{k_2} \} = 0, \end{aligned} \quad (\text{B11})$$

by using the formulas

$$c_{ix} \tilde{Y}_{k_i}(\mathbf{c}_i) = \frac{(\delta_{k_i,0} + 1)}{2} \{ \tilde{Y}_{k_i+1}(\mathbf{c}_i) + c_i^2 \tilde{Y}_{k_i-1}(\mathbf{c}_i) \} \quad (\text{B12})$$

and

$$\frac{\partial \tilde{Y}_{k_i}(\mathbf{c}_i)}{\partial c_{ix}} = k_i \tilde{Y}_{k_i-1}(\mathbf{c}_i) \quad (\text{B13})$$

for $i=1$ and 2 . From Eqs. (B5) and (B10), Eq. (B11) leads to the inductive equation

$$\begin{aligned} & \alpha (\delta_{k_1,0} + 1) \tilde{\Theta}_{k,k_1+1,k_2} - \alpha (\delta_{k_1,0} + 1) \frac{\partial \tilde{\Theta}_{k,k_1-1,k_2}}{\partial \alpha} \\ & + \beta (\delta_{k_2,0} + 1) \tilde{\Theta}_{k,k_1,k_2+1} - \beta (\delta_{k_2,0} + 1) \frac{\partial \tilde{\Theta}_{k,k_1,k_2-1}}{\partial \beta} \\ & + \gamma (\delta_{k,0} + 1) \tilde{\Theta}_{k+1,k_1,k_2} - \gamma (\delta_{k,0} + 1) \frac{\partial \tilde{\Theta}_{k-1,k_1,k_2}}{\partial \gamma} \\ & - k \tilde{\Theta}_{k-1,k_1,k_2} - k_1 \tilde{\Theta}_{k,k_1-1,k_2} - k_2 \tilde{\Theta}_{k,k_1,k_2-1} = 0 \end{aligned} \quad (\text{B14})$$

for $\tilde{\Theta}_{k,k_1,k_2}$. Because of this inductive equation, once the initial value $\tilde{\Theta}_{0,k_1,k_2}$ is known for all k_1 and k_2 , then the values of the integral $\tilde{\Theta}_{k,k_1,k_2}$ for any k , k_1 , and k_2 can be obtained, and Θ_{k,k_1,k_2} is then obtained from Eq. (B10).

c. Calculation of the initial value

In principle, the initial value of the inductive equation (B14), $\tilde{\Theta}_{0,k_1,k_2}$, can be obtained and written explicitly from Eq. (B5), changing the variables \mathbf{c}_1 and \mathbf{c}_2 to $\mathbf{V}=(\mathbf{c}_1+\mathbf{c}_2)/2$ and $\mathbf{g}=\mathbf{c}_1-\mathbf{c}_2$. Though we have directly calculated $\tilde{\Theta}_{0,k_1,k_2}$ only for $k_1=k_2=0, 1, 2, 3, 4, 5, 6, 7$, and 8 , they are sufficient to get all the results shown in Appendixes C and D. We do not show the explicit expressions of the initial values in this paper because they are too complicated. We have also con-

firmed that the initial value $\tilde{\Theta}_{0,k_1,k_2}$ becomes zero for $k_1 \neq k_2$. Note that Θ_{0,k_1,k_2} is obtained by $\nu_{0,k_1,k_2} \tilde{\Theta}_{0,k_1,k_2}$ from Eq. (B10).

d. Evaluation of $\Xi_{k,k_1,k_2}^{Y,r,n_1,n_2}(\chi)$

Using the inductive equation (B14) and the initial value $\tilde{\Theta}_{0,k_1,k_1}$ calculated in Appendix B 2 c, the values of the integral $\tilde{\Theta}_{k,k_1,k_2}$ for any k , k_1 , and k_2 , can be obtained with the relation (B10). The result is that $\tilde{\Theta}_{k,k_1,k_2}$ vanishes $k=|k_1-k_2|+2q$, where q is a positive integer or zero. In order to obtain $\Xi_{k,k_1,k_2}^{Y,r,n_1,n_2}(\chi)$, it is sufficient to have $\tilde{\Theta}_{k,k_1,k_2}$ only for $k_1 \geq k_2$. This is because the value of $\Xi_{k,k_1,k_2}^{Y,r,n_1,n_2}(\chi)$, with k_1 and k_2 , n_1 and n_2 interchanged, corresponds to the value of $\Xi_{k,k_1,k_2}^{Y,r,n_1,n_2}(\chi)$ with χ replaced by $\pi-\chi$. Thus, if $k_1 \neq k_2$ or $n_1 \neq n_2$, $\Xi_{k,k_1,k_2}^{Y,r,n_1,n_2}(\chi)$ for any set of k_1 and k_2 , n_1 and n_2 corresponds to

$$\Xi_{k,k_1,k_2}^{Y,r,n_1,n_2}(\chi) = \Xi_{k,k_1,k_2}^{Y,r,n_1,n_2}(\chi) + \Xi_{k,k_1,k_2}^{Y,r,n_1,n_2}(\pi-\chi) \quad (\text{B15})$$

for $k_1 \geq k_2$; if $k_1=k_2$ and $n_1=n_2$, then $\Xi_{k,k_1,k_2}^{Y,r,n_1,n_2}(\chi)$ gives the required value at once.

APPENDIX C: CALCULATION OF THE FIRST-ORDER COEFFICIENTS B_{kr}^I

Let us explain how to obtain the first-order coefficients—that is, how to solve the integral equation (5). To begin with, we calculate Ω_{kr}^H in Eq. (25) to first order; Ω_{kr}^H for first order corresponds to the right-hand side of Eq. (5). It can be calculated only by substituting $B_{00}=1$ into the expressions of $D_{k,r}$ and $E_{k,r}$ in Eqs. (A6) and (A7): the coefficient $B_{00}=1$ corresponds to $f_1=f_1^{(0)}$, and no higher-order terms appear in Ω_{kr}^H to first order. It finally becomes

$$\Omega_{1r}^H = - \frac{2n}{T} \left(\frac{2\kappa T}{m} \right)^{1/2} \frac{\partial T}{\partial x} \delta_{1,r}. \quad (\text{C1})$$

Now Ω_{kr}^H for first order is found to vanish unless $k=1$, so that we need calculate only Δ_{1r}^H for first order; as was mentioned in the end of Sec. II, we do not need to consider the case in which the right-hand side of Eq. (5) becomes zero [2]. To derive Δ_{1r}^H in Eq. (28) for first order, we must calculate both $W_{1,k_1,k_2}^{r,n_1,n_2}$ and $\Xi_{1,k_1,k_2}^{r,n_1,n_2}$ in $F_{1,r}^I(\chi)$ of Eq. (B1) for first order, as was shown in Appendixes B 1 and B 2. The result for Δ_{1r}^H to first order can be written finally in the form

$$\Delta_{1r}^H = B_{00} \sum_{n_1} B_{1n_1}^I M_{1,1,0}^{Y,r,n_1,0}, \quad (\text{C2})$$

where the set of the coefficients $B_{1n_1}^I B_{00}$ is obtained from $W_{1,1,0}^{r,n_1,0}$ in Eq. (B4). To first order, f_1 in Eq. (29) contains only $B_{00}=1$ and the first-order coefficients $B_{k_1 n_1}^I$ and $C_{k_1 n_1}^I$; f_2 in Eq. (29) also contains $B_{00}=1$, $B_{k_2 n_2}^I$ and $C_{k_2 n_2}^I$ to first order. Thus, we obtain only the term $B_{1n_1}^I B_{00}$ from $W_{1,1,0}^{r,n_1,0}$ to first order using the fact that $F_{kr}^I(\chi)=0$ unless $k=|k_1-k_2|+2q$. Note that it is sufficient to consider only the case for $k_1 \geq k_2$ as is explained in Appendix B 2 and that we set $q=0$. The matrix $M_{1,1,0}^{Y,r,n_1,0}$ is thus obtained,

$$M_{1,1,0}^{Y,r,n_1,0} = \frac{dmn^2}{\pi^2 \kappa T \Gamma(r+2)} \frac{n_1!}{\int_0^{2\pi} [\Xi_{1,1,0}^{Y,r,n_1,0}(\chi) - \Xi_{1,1,0}^{Y,r,n_1,0}(0)] \sin \frac{\chi}{2} d\chi}, \quad (\text{C3})$$

using Eqs. (28), (B1), and (B4).

For $k=1$, Eq. (30) gives a simultaneous equation determining the first-order coefficients $B_{1n_1}^I$, i.e.,

$$\Omega_{1r}^H = \sum_{n_1 \geq 1} B_{1n_1}^I M_{1,1,0}^{Y,r,n_1,0}, \quad (\text{C4})$$

from Eqs. (C1) and (C2). Note that we need only to obtain the first-order coefficients $B_{1n_1}^I$ for $n_1 \geq 1$, because $B_{10} = 0$ from Eq. (19). We have calculated the matrix $M_{1,1,0}^{Y,r,n_1,0}$ for $1 \leq r \leq 7$ and $1 \leq n_1 \leq 7$ from Eq. (C3), and we have also confirmed that $M_{1,1,0}^{Y,0,n_1,0}$ for $1 \leq n_1 \leq 7$ calculated from Eq. (C3) vanishes. Our result for $M_{1,1,0}^{Y,r,n_1,0}$ for $1 \leq r \leq 7$ and $1 \leq n_1 \leq 7$ is given in Appendix E. At last, we can determine the first-order coefficients $B_{1n_1}^I$ by solving the simultaneous equation (C4); that is, $B_{1n_1}^I$ can be obtained as

$$B_{1n_1}^I = \sum_{r \geq 1} \Omega_{1r}^H (M_{1,1,0}^{Y,r,n_1,0})^{-1}, \quad (\text{C5})$$

where X^{-1} represents the inverse matrix of a matrix X . Finally, the results of the first-order coefficients $B_{k_1 n_1}^I$ —i.e., the first-order B_{kr} in Eq. (16)—can be calculated as in Eq. (31).

APPENDIX D: CALCULATION OF THE SECOND-ORDER COEFFICIENTS B_{kr}^H

We explain how to obtain the second-order coefficients—that is, how to solve the integral equation (6). The coefficients of first order—i.e., B_{kr}^I and C_{kr}^I —have been obtained as are given in Eq. (31), so that we can employ them to determine the second-order coefficients.

To begin with, we calculate Ω_{kr}^H in Eq. (25) for second order; Ω_{kr}^H for second order corresponds to the first term on the right-hand side of Eq. (6). It can be calculated by substituting B_{kr}^I and C_{kr}^I into the expressions of $D_{k,r}$ and $E_{k,r}$ in Eqs. (A6) and (A7); no other terms appear in Ω_{kr}^H for second order. The results of the tedious calculation of Ω_{kr}^H to second order finally become as follows. For $k=0$, Ω_{0r}^H becomes

$$\Omega_{0r}^H = 0 \quad (\text{D1})$$

for $r=0$ and 1,

$$\Omega_{02}^H = -\frac{2\pi^2}{dT^2} \left(\frac{2\kappa T}{m} \right)^{1/2} \left\{ (\nabla T)^2 \left(\frac{9}{2} b_{12} - \frac{7}{2} b_{11} \right) + T(\nabla^2 T)(3b_{12} - b_{11}) \right\} \quad (\text{D2})$$

for $r=2$, and

$$\Omega_{0r}^H = -\frac{2\pi^2}{dT^2} \left(\frac{2\kappa T}{m} \right)^{1/2} \left\{ T(\nabla^2 T)[(r+1)b_{1r} - b_{1,r-1}] + (\nabla T)^2 \left[\left(r^2 + \frac{1}{2}r - \frac{1}{2} \right) b_{1r} - \left(2r - \frac{1}{2} \right) b_{1,r-1} + b_{1,r-2} \right] \right\} \quad (\text{D3})$$

for $r \geq 3$. Note that values for the constants b_{1r} are summarized in Table I. For $k=2$, Ω_{2r}^H becomes

$$\Omega_{20}^H = \frac{\pi^2}{dT^2} \left(\frac{2\kappa T}{m} \right)^{1/2} \left\{ \frac{b_{11}}{2} [(\partial_x T)^2 - (\partial_y T)^2] + b_{11} T [\partial_x^2 T - \partial_y^2 T] \right\}, \quad (\text{D4})$$

$$\Omega_{21}^H = -\frac{\pi^2}{dT^2} \left(\frac{2\kappa T}{m} \right)^{1/2} \left\{ [(\partial_x T)^2 - (\partial_y T)^2] \left[\frac{5}{2} b_{11} - 3b_{12} \right] + T [\partial_x^2 T - \partial_y^2 T] [b_{11} - 2b_{12}] \right\}, \quad (\text{D5})$$

and

$$\Omega_{2r}^H = -\frac{\pi^2}{dT^2} \left(\frac{2\kappa T}{m} \right)^{1/2} \left\{ [(\partial_x T)^2 - (\partial_y T)^2] \left[-\left(r + \frac{1}{2} \right) \times (r+1)b_{1,r+1} + \left(2r + \frac{1}{2} \right) b_{1r} - b_{1,r-1} \right] + T [\partial_x^2 T - \partial_y^2 T] \times [-(r+1)b_{1,r+1} + b_{1r}] \right\} \quad (\text{D6})$$

for $r \geq 2$. For $k=1$ and $k \geq 3$, we find that Ω_{kr}^H for second order becomes

$$\Omega_{kr}^H = 0 \quad (\text{D7})$$

for any value of r .

Next let us calculate Δ_{kr}^H in Eq. (28) for second order. In order to derive Δ_{kr}^H for second order, we have to calculate $W_{k,k_1,k_2}^{r,n_1,n_2}$ and $\Xi_{k,k_1,k_2}^{Y,r,n_1,n_2}$ in $F_{kr}^1(\chi)$ of Eq. (B1) to second order, as was shown in Appendix B 1. For $k=0$, Δ_{kr}^H to second order results in

$$\Delta_{0r}^H = B_{00} \sum_{n_1 \geq 2} B_{0n_1}^H M_{0,0,0}^{Y,r,n_1,0} + \sum_{n_1 n_2} B_{1n_1}^I B_{1n_2}^I M_{0,1,1}^{Y,r,n_1,n_2} + \sum_{n_1 n_2} C_{1n_1}^I C_{1n_2}^I M_{0,1,1}^{Z,r,n_1,n_2}. \quad (\text{D8})$$

$B_{1n_1}^I$ from f_1 and $B_{1n_2}^I$ from f_2 of the set of the coefficients $B_{1n_1}^I B_{1n_2}^I$ are the first-order coefficients obtained in Eq. (31), so that $B_{1n_1}^I B_{1n_2}^I$ is second order. Similarly, $C_{1n_1}^I C_{1n_2}^I$ is also second order. The second and third terms on the right-hand side of Eq. (D8) correspond to $J(f_1, f_2)$ in the integral equation (6). To second order, f_i of Eq. (29) contains only $B_{00} = 1$, $B_{k_i n_i}^I$ and $C_{k_i n_i}^I$ obtained in Eq. (31), and $B_{k_i n_i}^H$ to be determined here for $i=1$ and 2. Therefore, we can only obtain the sets of the terms in Eq. (D8) for second order by using the fact that $F_{kr}^1(\chi) = 0$ unless $k = |k_1 - k_2| + 2q$. We should derive the second-order coefficients $B_{0n_1}^H$ only for $n_1 \geq 2$, because

$B_{00}=1$ and $B_{01}=0$ from Eq. (19). Note that it is sufficient to consider only the case for $k_1 \geq k_2$, as is explained in Appendix B 2, and that $B_{1n_1}^1 C_{1n_2}^1 + C_{1n_1}^1 B_{1n_2}^1$ does not appear (see Appendix B 1).

The matrix $M_{0,0,0}^{Y,r,n_1,0}$ in Eq. (D8) is obtained as

$$M_{0,0,0}^{Y,r,n_1,0} = \frac{2dn^2}{\pi^2} \int_0^{2\pi} [\Xi_{0,0,0}^{Y,r,n_1,0}(\chi) - \Xi_{0,0,0}^{Y,r,n_1,0}(0)] \sin \frac{\chi}{2} d\chi, \quad (\text{D9})$$

using Eqs. (28), (B1), and (B4). Similarly, the matrices $M_{0,1,1}^{Y,r,n_1,n_2}$ in Eq. (D8) are derived as

$$M_{0,1,1}^{Y,r,n_1,n_2} = \frac{dmn^2}{\pi^2 \kappa T} \int_0^{2\pi} [\Xi_{0,1,1}^{Y,r,n_1,n_2}(\chi) - \Xi_{0,1,1}^{Y,r,n_1,n_2}(0)] \sin \frac{\chi}{2} d\chi, \quad (\text{D10})$$

while we have confirmed $M_{0,1,1}^{Z,r,n_1,n_2} = M_{0,1,1}^{Y,r,n_1,n_2}$. Equations (D8) and (D1)–(D3) lead to a simultaneous equation to determine the second-order coefficients $B_{0n_1}^{\text{II}}$:

$$B_{0n_1}^{\text{II}} = \sum_{r \geq 2} \left\{ \Omega_{0r}^{\text{H}} - \sum_{n_1, n_2} (B_{1n_1}^1 B_{1n_2}^1 + C_{1n_1}^1 C_{1n_2}^1) M_{0,1,1}^{Y,r,n_1,n_2} \right\} \times (M_{0,0,0}^{Y,r,n_1,0})^{-1}. \quad (\text{D11})$$

We have calculated the matrix $M_{0,0,0}^{Y,r,n_1,0}$ for $2 \leq r \leq 6$ and $2 \leq n_1 \leq 6$ from Eq. (D9) and also confirmed that $M_{0,0,0}^{Y,r,n_1,0}$ vanishes for $r=0, 1$, and $2 \leq n_1 \leq 6$ or for $2 \leq r \leq 6$ and $n_1=0, 1$. We have calculated the matrix $M_{0,1,1}^{Y,r,n_1,n_2}$ for $2 \leq r \leq 6$, $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ from Eq. (D10) and confirmed $M_{0,1,1}^{Y,r,n_1,n_2}$ vanishes for $r=0, 1$, $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$. Our results for $M_{0,0,0}^{Y,r,n_1,0}$ for $2 \leq r \leq 6$ and $2 \leq n_1 \leq 6$ and $M_{0,1,1}^{Y,r,n_1,n_2}$ for $2 \leq r \leq 6$, $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ are given in Appendix E. Finally, we can determine the second-order coefficients $B_{0n_1}^{\text{II}}$ in f_1 —i.e., the second-order B_{0r} in Eq. (14) as in Eq. (36).

Similarly, for $k=2$, Δ_{kr}^{H} for second-order results in

$$\Delta_{2r}^{\text{H}} = B_{00} \sum_{n_1 \geq 0} B_{2n_1}^{\text{II}} M_{2,2,0}^{Y,r,n_1,0} + \sum_{n_1, n_2} B_{1n_1}^1 B_{1n_2}^1 M_{2,1,1}^{Y,r,n_1,n_2} + \sum_{n_1, n_2} C_{1n_1}^1 C_{1n_2}^1 M_{2,1,1}^{Z,r,n_1,n_2}, \quad (\text{D12})$$

using the fact that $F_{kr}^1(\chi)=0$ unless $k=|k_1-k_2|+2q$. Note that we have confirmed $M_{2,0,0}^{Y,r,n_1,0}$ becomes zero. The matrix $M_{2,2,0}^{Y,r,n_1,0}$ in Eq. (D12) is obtained as

$$M_{2,2,0}^{Y,r,n_1,0} = \frac{dm^2 n^2}{2\pi^2 \kappa^2 T^2} \int_0^{2\pi} [\Xi_{2,2,0}^{Y,r,n_1,0}(\chi) - \Xi_{2,2,0}^{Y,r,n_1,0}(0)] \sin \frac{\chi}{2} d\chi, \quad (\text{D13})$$

using Eqs. (28), (B1), and (B4). Similarly, the matrices $M_{2,1,1}^{Y,r,n_1,n_2}$ in Eq. (D12) are derived as

$$M_{2,1,1}^{Y,r,n_1,n_2} = \frac{dm^2 n^2}{2\pi^2 \kappa^2 T^2} \int_0^{2\pi} [\Xi_{2,1,1}^{Y,r,n_1,n_2}(\chi) - \Xi_{2,1,1}^{Y,r,n_1,n_2}(0)] \sin \frac{\chi}{2} d\chi, \quad (\text{D14})$$

while we have confirmed $M_{2,1,1}^{Z,r,n_1,n_2} = -M_{2,1,1}^{Y,r,n_1,n_2}$. Thus, Eqs. (D12) and (D4)–(D6) lead to a simultaneous equation to determine the second-order coefficients $B_{2n_1}^{\text{II}}$:

$$B_{2n_1}^{\text{II}} = \sum_{r \geq 0} \left\{ \Omega_{2r}^{\text{H}} - \sum_{n_1, n_2} (B_{1n_1}^1 B_{1n_2}^1 - C_{1n_1}^1 C_{1n_2}^1) M_{2,1,1}^{Y,r,n_1,n_2} \right\} \times (M_{2,2,0}^{Y,r,n_1,0})^{-1}. \quad (\text{D15})$$

In order to derive the second-order coefficients $B_{2n_1}^{\text{II}}$ for $n_1 \geq 0$, we have calculated the matrix $M_{2,2,0}^{Y,r,n_1,0}$ for $0 \leq r \leq 6$ and $0 \leq n_1 \leq 6$ from Eq. (D13) and also the matrices $M_{2,1,1}^{Y,r,n_1,n_2}$ for $0 \leq r \leq 6$, $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ from Eq. (D14). Those results are given in Appendix E. The second-order coefficients $B_{k_1 n_1}^{\text{II}}$ in f_1 —i.e., the second-order B_{kr} in Eq. (16)—can be written in the final form shown in Eq. (37).

We need to consider Eq. (30) only for $k=0$ and 2 for second order: it is not necessary to consider Eq. (30) for even k furthermore, which was first expected in Ref. [18] and recently confirmed in Ref. [19]. For odd k , Ω_{kr}^{H} to second order is found to be zero, and no terms corresponding to $J(f_1, f_2)$ in the integral equation (6)—i.e., the second and third terms on the right-hand side of Eq. (D11) or (D15)—appear, so that any second-order terms B_{kr}^{II} do not appear for odd k [18].

APPENDIX E: MATRIX ELEMENTS

1. $M_{1,1,0}^{Y,r,n_1,0}$ for $1 \leq r \leq 7$ and $1 \leq n_1 \leq 7$

The matrix elements $M_{1,1,0}^{Y,r,n_1,0}$ for $1 \leq r \leq 7$ and $1 \leq n_1 \leq 7$ divided by $M_{1,1,0}^{Y,1,1,0} = -2dn^2(\pi\kappa T/m)^{1/2}$ calculated from Eq. (C3) are given as follows:

$$\begin{pmatrix} 1 & -8.333 \times 10^{-2} & -2.604 \times 10^{-3} & -1.302 \times 10^{-4} & -6.782 \times 10^{-6} & -3.391 \times 10^{-7} & -1.589 \times 10^{-8} \\ -5.000 \times 10^{-1} & 1.625 & -1.185 \times 10^{-1} & -3.451 \times 10^{-3} & -1.648 \times 10^{-4} & -8.308 \times 10^{-6} & -4.053 \times 10^{-7} \\ -1.875 \times 10^{-1} & -1.422 & 2.165 & -1.327 \times 10^{-1} & -3.466 \times 10^{-3} & -1.531 \times 10^{-4} & -7.279 \times 10^{-6} \\ -1.875 \times 10^{-1} & -8.281 \times 10^{-1} & -2.654 & 2.645 & -1.383 \times 10^{-1} & -3.234 \times 10^{-3} & -1.314 \times 10^{-4} \\ -2.930 \times 10^{-1} & -1.187 & -2.079 & -4.148 & 3.081 & -1.398 \times 10^{-1} & -2.947 \times 10^{-3} \\ -6.152 \times 10^{-1} & -2.512 & -3.859 & -4.074 & -5.873 & 3.483 & -1.395 \times 10^{-1} \\ -1.615 & -6.864 & -1.027 \times 10 & -9.273 & -6.932 & -7.810 & 3.858 \end{pmatrix}.$$

2. $M_{0,0,0}^{Y,r,n_1,0}$ for $2 \leq r \leq 6$ and $2 \leq n_1 \leq 6$ and $M_{0,1,1}^{Y,r,n_1,n_2}$ for $2 \leq r \leq 6$, $1 \leq n_1 \leq 7$, and $1 \leq n_2 \leq 7$

The matrix elements $M_{0,0,0}^{Y,r,n_1,0}$ for $2 \leq r \leq 6$ and $2 \leq n_1 \leq 6$ divided by $M_{0,0,0}^{Y,2,2,0} = -4dn^2(\pi\kappa T/m)^{1/2}$ calculated from Eq. (D9) are given as

$$\begin{pmatrix} 1 & -8.333 \times 10^{-2} & -2.604 \times 10^{-3} & -1.302 \times 10^{-4} & -6.782 \times 10^{-1} \\ -7.500 \times 10^{-1} & 1.688 & -1.152 \times 10^{-1} & -3.223 \times 10^{-3} & -1.495 \times 10^{-4} \\ -3.750 \times 10^{-1} & -1.844 & 2.251 & -1.287 \times 10^{-1} & -3.204 \times 10^{-3} \\ -4.688 \times 10^{-1} & -1.289 & -3.217 & 2.741 & -1.342 \times 10^{-1} \\ -8.789 \times 10^{-1} & -2.153 & -2.883 & -4.833 & 3.182 \end{pmatrix}.$$

The matrix elements $M_{0,1,1}^{Y,2,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{0,1,1}^{Y,2,1,1} = -[\pi^4(\nabla T)^2/4dT^2](\pi\kappa T/m)^{1/2}$ calculated from Eq. (10) are given as

$$\begin{pmatrix} 1 & 5.000 \times 10^{-1} & 0.000 & -9.375 \times 10^{-1} & -4.102 & -1.661 \times 10 & -7.106 \times 10 \\ 5.000 \times 10^{-1} & 3.750 \times 10^{-1} & 9.375 \times 10^{-1} & 8.203 \times 10^{-1} & -1.846 & -2.030 \times 10 & -1.320 \times 10^2 \\ 0.000 & 9.375 \times 10^{-1} & 1.230 & 5.537 & 1.015 \times 10 & 0.000 & -1.856 \times 10^2 \\ -9.375 \times 10^{-1} & 8.203 \times 10^{-1} & 5.537 & 1.015 \times 10 & 6.598 \times 10 & 1.856 \times 10^2 & 2.629 \times 10^2 \\ -4.102 & -1.846 & 1.015 \times 10 & 6.598 \times 10 & 1.547 \times 10^2 & 1.315 \times 10^3 & 4.995 \times 10^3 \\ -1.661 \times 10 & -2.030 \times 10^1 & 0.000 & 1.856 \times 10^2 & 1.315 \times 10^3 & 3.746 \times 10^3 & 3.934 \times 10^4 \\ -7.106 \times 10 & -1.320 \times 10^2 & -1.856 \times 10^2 & 2.629 \times 10^2 & 4.995 \times 10^3 & 3.934 \times 10^4 & 1.319 \times 10^5 \end{pmatrix}.$$

The matrix elements $M_{0,1,1}^{Y,3,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{0,1,1}^{Y,2,1,1}$ are given as

$$\begin{pmatrix} -2.500 \times 10^{-1} & 1.125 & 5.000 \times 10^{-1} & -4.688 \times 10^{-2} & -2.490 & -1.482 \times 10 & -7.913 \times 10 \\ 1.125 & 2.813 \times 10^{-1} & 7.969 \times 10^{-1} & 1.436 & 2.000 & -4.153 & -7.360 \times 10 \\ 5.000 \times 10^{-1} & 7.969 \times 10^{-1} & 7.471 \times 10^{-1} & 3.845 & 1.130 \times 10^1 & 3.045 \times 10^1 & 2.990 \times 10^1 \\ -4.688 \times 10^{-2} & 1.436 & 3.845 & 5.768 & 4.187 \times 10 & 1.681 \times 10^2 & 6.534 \times 10^2 \\ -2.490 & 2.000 & 1.130 \times 10 & 4.187 \times 10 & 8.506 \times 10 & 7.926 \times 10^2 & 4.009 \times 10^3 \\ -1.482 \times 10 & -4.153 & 3.045 \times 10 & 1.681 \times 10^2 & 7.926 \times 10^2 & 2.021 \times 10^3 & 2.295 \times 10^4 \\ -7.913 \times 10 & -7.360 \times 10 & 2.990 \times 10 & 6.534 \times 10^2 & 4.009 \times 10^3 & 2.295 \times 10^4 & 7.027 \times 10^4 \end{pmatrix}.$$

The matrix elements $M_{0,1,1}^{Y,4,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{0,1,1}^{Y,2,1,1}$ are given as

$$\begin{pmatrix} -1.302 \times 10^{-2} & -2.305 \times 10^{-1} & 7.813 \times 10^{-1} & 4.946 \times 10^{-1} & -8.331 \times 10^{-2} & -4.567 & -3.443 \times 10 \\ -2.305 \times 10^{-1} & 2.295 \times 10^{-1} & 3.960 \times 10^{-1} & 7.784 \times 10^{-1} & 1.869 & 3.623 & -6.020 \\ 7.813 \times 10^{-1} & 3.960 \times 10^{-1} & 3.062 \times 10^{-1} & 1.513 & 4.918 & 1.817 \times 10 & 6.396 \times 10 \\ 4.946 \times 10^{-1} & 7.784 \times 10^{-1} & 1.513 & 2.111 & 1.527 \times 10 & 6.642 \times 10 & 3.216 \times 10^2 \\ -8.331 \times 10^{-2} & 1.869 & 4.918 & 1.527 \times 10 & 2.971 \times 10 & 2.782 \times 10^2 & 1.502 \times 10^3 \\ -4.567 & 3.623 & 1.817 \times 10 & 6.642 \times 10 & 2.782 \times 10^2 & 6.882 \times 10^2 & 7.871 \times 10^3 \\ -3.443 \times 10 & -6.020 & 6.396 \times 10^1 & 3.216 \times 10^2 & 1.502 \times 10^3 & 7.871 \times 10^3 & 2.355 \times 10^4 \end{pmatrix}.$$

The matrix elements $M_{0,1,1}^{Y,5,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{0,1,1}^{Y,2,1,1}$ are given as

$$\begin{pmatrix} -9.115 \times 10^{-4} & -1.074 \times 10^{-3} & -1.289 \times 10^{-1} & 5.948 \times 10^{-1} & 4.914 \times 10^{-1} & -1.037 \times 10^{-1} & -7.105 \\ -1.074 \times 10^{-2} & -4.272 \times 10^{-2} & 2.509 \times 10^{-1} & 3.006 \times 10^{-1} & 7.575 \times 10^{-1} & 2.279 & 5.713 \\ -1.289 \times 10^{-1} & 2.509 \times 10^{-1} & 1.104 \times 10^{-1} & 4.718 \times 10^{-1} & 1.484 & 5.886 & 2.621 \times 10 \\ 5.948 \times 10^{-1} & 3.006 \times 10^{-1} & 4.718 \times 10^{-1} & 6.042 \times 10^{-1} & 4.226 & 1.845 & 9.461 \times 10 \\ 4.914 \times 10^{-1} & 7.575 \times 10^{-1} & 1.484 & 4.226 & 7.918 & 7.326 \times 10 & 4.000 \times 10^2 \\ -1.037 \times 10^{-1} & 2.279 & 5.886 & 1.845 \times 10 & 7.326 \times 10 & 1.772 \times 10^2 & 2.017 \times 10 \\ -7.105 & 5.713 & 2.621 \times 10 & 9.461 \times 10^2 & 4.000 \times 10 & 2.017 \times 10^3 & 5.941 \times 10^3 \end{pmatrix}.$$

The matrix elements $M_{0,1,1}^{Y,6,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{0,1,1}^{Y,2,1,1}$ are given as

$$\begin{pmatrix} -6.104 \times 10^{-5} & -6.978 \times 10^{-4} & -5.046 \times 10^{-3} & -8.158 \times 10^{-2} & 4.782 \times 10^{-1} & 4.898 \times 10^{-1} & -1.087 \times 10^{-1} \\ -6.978 \times 10^{-4} & -1.976 \times 10^{-3} & -3.976 \times 10^{-2} & 1.575 \times 10^{-1} & 2.407 \times 10^{-1} & 7.397 \times 10^{-1} & 2.678 \\ -5.046 \times 10^{-3} & -3.976 \times 10^{-2} & 5.664 \times 10^{-2} & 1.387 \times 10^{-1} & 3.788 \times 10^{-1} & 1.450 & 6.802 \\ -8.158 \times 10^{-2} & 1.575 \times 10^{-1} & 1.387 \times 10^{-1} & 1.505 \times 10^{-1} & 9.806 \times 10^{-1} & 4.159 & 2.137 \times 10 \\ 4.782 \times 10^{-1} & 2.407 \times 10^{-1} & 3.788 \times 10^{-1} & 9.806 \times 10^{-1} & 1.749 & 1.579 \times 10 & 8.557 \times 10 \\ 4.898 \times 10^{-1} & 7.397 \times 10^{-1} & 1.450 & 4.159 & 1.579 \times 10 & 3.727 \times 10 & 4.194 \times 10^2 \\ -1.087 \times 10^{-1} & 2.678 & 6.802 & 2.137 \times 10 & 8.557 \times 10 & 4.194 \times 10^2 & 1.217 \times 10^3 \end{pmatrix}.$$

3. $M_{2,2,0}^{Y,r,n_1,0}$ for $0 \leq r \leq 6$ and $0 \leq n_1 \leq 6$ and $M_{2,1,1}^{Y,r,n_1,n_2}$ for $0 \leq r \leq 6$, $1 \leq n_1 \leq 7$, and $1 \leq n_2 \leq 7$

The matrix elements $M_{2,2,0}^{Y,r,n_1,0}$ for $0 \leq r \leq 6$ and $0 \leq n_1 \leq 6$ divided by $M_{2,2,0}^{Y,0,0,0} = -4dn^2(\pi\kappa T/m)^{\frac{1}{2}}$ calculated from Eq. (D13) are given as

$$\begin{pmatrix} 1 & -8.333 \times 10^{-2} & -2.604 \times 10^{-3} & -1.302 \times 10^{-4} & -6.782 \times 10^{-6} & -3.391 \times 10^{-7} & -1.589 \times 10^{-8} \\ -2.500 \times 10^{-1} & 1.063 & -8.008 \times 10^{-2} & -2.376 \times 10^{-3} & -1.149 \times 10^{-4} & -5.849 \times 10^{-6} & -2.874 \times 10^{-7} \\ -6.250 \times 10^{-2} & -6.406 \times 10^{-1} & 1.232 & -7.939 \times 10^{-2} & -2.143 \times 10^{-3} & -9.707 \times 10^{-5} & -4.706 \times 10^{-6} \\ -4.688 \times 10^{-2} & -2.852 \times 10^{-1} & -1.191 & 1.420 & -7.825 \times 10^{-2} & -1.900 \times 10^{-3} & -7.953 \times 10^{-5} \\ -5.859 \times 10^{-2} & -3.311 \times 10^{-1} & -7.713 \times 10^{-1} & -1.878 & 1.607 & -7.676 \times 10^{-2} & -1.680 \times 10^{-3} \\ -1.025 \times 10^{-1} & -5.896 \times 10^{-1} & -1.223 & -1.596 & -2.687 & 1.787 & -7.510 \times 10^{-2} \\ -2.307 \times 10^{-1} & -1.391 & -2.846 & -3.207 & -2.822 & -3.605 & 1.961 \end{pmatrix}.$$

The matrix elements $M_{2,1,1}^{Y,0,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{2,1,1}^{Y,0,1,1} = -(\pi^4/16dT^2)(\pi\kappa T/m)^{\frac{1}{2}}\{(\partial_x T)^2 - (\partial_y T)^2\}$ calculated from Eq. (D14) are given as

$$\begin{pmatrix} 1 & 1.500 & 1.875 & 3.281 & 7.383 & 2.030 \times 10 & 6.598 \times 10 \\ 1.500 & 9.375 \times 10^{-1} & 3.281 & 7.383 & 2.030 \times 10 & 6.598 \times 10 & 2.474 \times 10^2 \\ 1.875 & 3.281 & 3.691 & 2.030 \times 10 & 6.598 \times 10 & 2.474 \times 10^2 & 1.052 \times 10^3 \\ 3.281 & 7.383 & 2.030 \times 10^1 & 3.299 \times 10^1 & 2.474 \times 10^2 & 1.052 \times 10^3 & 4.995 \times 10^3 \\ 7.383 & 2.030 \times 10 & 6.598 \times 10 & 2.474 \times 10^2 & 5.258 \times 10^2 & 4.995 \times 10^3 & 2.622 \times 10^4 \\ 2.030 \times 10 & 6.598 \times 10 & 2.474 \times 10^2 & 1.052 \times 10^3 & 4.995 \times 10^3 & 1.311 \times 10^4 & 1.508 \times 10^5 \\ 6.598 \times 10 & 2.474 \times 10^2 & 1.052 \times 10^3 & 4.995 \times 10^3 & 2.622 \times 10^4 & 1.508 \times 10^5 & 4.712 \times 10^5 \end{pmatrix}.$$

The matrix elements $M_{2,1,1}^{Y,1,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{2,1,1}^{Y,0,1,1}$ are given as

$$\begin{pmatrix} 2.250 & 2.125 & 3.094 & 6.680 & 1.825 \times 10 & 5.952 \times 10 & 2.246 \times 10^2 \\ 2.125 & 7.969 \times 10^{-1} & 2.930 & 8.408 & 2.999 \times 10 & 1.231 \times 10^2 & 5.650 \times 10^2 \\ 3.094 & 2.930 & 2.563 & 1.523 \times 10 & 6.218 \times 10 & 3.011 \times 10^2 & 1.624 \times 10^2 \\ 6.680 & 8.408 & 15.23 \times 10 & 2.094 \times 10 & 1.691 \times 10^2 & 8.815 \times 10^2 & 5.324 \times 10^3 \\ 1.825 \times 10 & 2.999 \times 10 & 6.218 \times 10 & 1.691 \times 10^2 & 3.170 \times 10^2 & 3.221 \times 10^3 & 2.029 \times 10^3 \\ 5.952 \times 10^1 & 1.231 \times 10^2 & 3.011 \times 10^2 & 8.815 \times 10^2 & 3.221 \times 10^3 & 7.649 \times 10^3 & 9.343 \times 10^4 \\ 2.246 \times 10^2 & 5.650 \times 10^2 & 1.624 \times 10^3 & 5.324 \times 10^3 & 2.029 \times 10^4 & 9.343 \times 10^4 & 2.686 \times 10^5 \end{pmatrix}.$$

The matrix elements $M_{2,1,1}^{Y,2,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{2,1,1}^{Y,0,1,1}$ are given as

$$\begin{pmatrix} -3.211 & 3.855 & 2.370 & 4.590 & 1.368 \times 10 & 5.090 \times 10 & 2.199 \times 10^2 \\ 3.855 & 8.413 \times 10^{-1} & 2.059 & 4.478 & 1.522 \times 10 & 6.873 \times 10 & 3.660 \times 10^2 \\ 2.370 & 2.059 & 1.799 & 8.862 & 2.974 \times 10 & 1.351 \times 10^2 & 7.762 \times 10^2 \\ 4.590 & 4.478 & 8.862 & 1.268 \times 10 & 9.068 \times 10 & 4.030 \times 10^2 & 2.253 \times 10^3 \\ 1.368 \times 10 & 1.522 \times 10 & 2.974 \times 10 & 9.068 \times 10 & 1.778 \times 10^2 & 1.650 \times 10^3 & 9.068 \times 10^3 \\ 5.090 \times 10 & 6.873 \times 10 & 1.351 \times 10^2 & 4.030 \times 10^2 & 1.650 \times 10^3 & 4.090 \times 10^3 & 4.651 \times 10^4 \\ 2.199 \times 10^2 & 3.660 \times 10^2 & 7.762 \times 10^2 & 2.253 \times 10^3 & 9.068 \times 10^3 & 4.651 \times 10^4 & 1.391 \times 10^5 \end{pmatrix}.$$

The matrix elements $M_{2,1,1}^{Y,3,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{2,1,1}^{Y,0,1,1}$ are given as

$$\begin{pmatrix} 2.493 \times 10^{-1} & -3.585 & 3.119 & 2.456 & 5.985 & 2.271 \times 10 & 1.070 \times 10^2 \\ -3.585 & 1.265 & 1.474 & 2.290 & 5.928 & 2.340 \times 10 & 1.257 \times 10^2 \\ 3.119 & 1.474 & 9.898 \times 10^{-1} & 4.274 & 1.257 \times 10 & 4.831 \times 10 & 2.443 \times 10^2 \\ 2.456 & 2.290 & 4.274 & 5.626 & 3.800 \times 10 & 1.565 \times 10^2 & 7.774 \times 10^2 \\ 5.985 & 5.928 & 1.257 \times 10 & 3.800 \times 10 & 7.156 \times 10 & 6.429 \times 10^2 & 3.357 \times 10^3 \\ 2.271 \times 10 & 2.340 \times 10 & 4.831 \times 10 & 1.565 \times 10^2 & 6.429 \times 10^2 & 1.557 \times 10^3 & 1.733 \times 10^4 \\ 1.070 \times 10^2 & 1.257 \times 10^2 & 2.443 \times 10^2 & 7.774 \times 10^2 & 3.357 \times 10^3 & 1.733 \times 10^4 & 5.108 \times 10^4 \end{pmatrix}.$$

The matrix elements $M_{2,1,1}^{Y,4,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{2,1,1}^{Y,0,1,1}$ are given as

$$\begin{pmatrix} 7.719 \times 10^{-3} & 2.301 \times 10^{-1} & -2.277 & 2.579 & 2.484 & 7.307 & 3.369 \times 10 \\ 2.301 \times 10^{-1} & -8.267 \times 10^{-1} & 1.678 & 1.262 & 2.404 & 7.292 & 3.285 \times 10 \\ -2.277 & 1.678 & 5.255 \times 10^{-1} & 1.778 & 4.645 & 1.607 \times 10 & 7.049 \times 10 \\ 2.579 & 1.262 & 1.778 & 2.037 & 1.276 \times 10 & 5.015 \times 10 & 2.363 \times 10^2 \\ 2.484 & 2.404 & 4.645 & 1.276 \times 10 & 2.262 \times 10 & 1.960 \times 10^2 & 9.990 \times 10^2 \\ 7.307 & 7.2919 & 1.607 \times 10 & 5.015 \times 10 & 1.960 \times 10^2 & 4.589 \times 10^2 & 5.000 \times 10^3 \\ 3.369 \times 10 & 3.285 \times 10 & 7.049 \times 10 & 2.363 \times 10^2 & 9.990 \times 10^2 & 5.000 \times 10^3 & 1.442 \times 10^4 \end{pmatrix}.$$

The matrix elements $M_{2,1,1}^{Y,5,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{2,1,1}^{Y,0,1,1}$ are given as

$$\begin{pmatrix} 3.858 \times 10^{-4} & 6.369 \times 10^{-3} & 1.235 \times 10^{-1} & -1.567 & 2.185 & 2.488 & 8.576 \\ 6.369 \times 10^{-3} & 4.532 \times 10^{-2} & -8.947 \times 10^{-1} & 1.178 & 1.088 & 2.463 & 8.595 \\ 1.235 \times 10^{-1} & -8.947 \times 10^{-1} & 4.736 \times 10^{-1} & 7.623 \times 10^{-1} & 1.573 & 4.855 & 1.940 \times 10 \\ -1.567 & 1.178 & 7.623 \times 10^{-1} & 6.743 \times 10^{-1} & 3.723 & 1.366 \times 10 & 6.171 \times 10 \\ 2.185 & 1.088 & 1.573 & 3.723 & 6.063 & 4.991 \times 10 & 2.467 \times 10^2 \\ 2.488 & 2.463 & 4.855 & 1.366 \times 10 & 4.991 \times 10 & 1.119 \times 10^2 & 1.186 \times 10^3 \\ 8.576 & 8.595 & 1.940 \times 10 & 6.171 \times 10 & 2.467 \times 10^2 & 1.186 \times 10^3 & 3.331 \times 10^3 \end{pmatrix}.$$

The matrix elements $M_{2,1,1}^{Y,6,n_1,n_2}$ for $1 \leq n_1 \leq 7$ and $1 \leq n_2 \leq 7$ divided by $M_{2,1,1}^{Y,0,1,1}$ are given as

$$\begin{pmatrix} 2.012 \times 10^{-5} & 2.953 \times 10^{-4} & 2.997 \times 10^{-3} & 7.361 \times 10^{-2} & -1.141 & 1.888 & 2.482 \\ 2.953 \times 10^{-4} & 1.169 \times 10^{-3} & 4.239 \times 10^{-2} & -5.364 \times 10^{-1} & 8.671 \times 10^{-1} & 9.507 \times 10^{-1} & 2.494 \\ 2.997 \times 10^{-3} & 4.239 \times 10^{-2} & -2.109 \times 10^{-1} & 5.791 \times 10^{-1} & 5.711 \times 10^{-1} & 1.395 & 4.977 \\ 7.361 \times 10^{-2} & -5.364 \times 10^{-1} & 5.791 \times 10^{-1} & 2.404 \times 10^{-1} & 1.035 & 3.364 & 1.422 \times 10 \\ -1.141 & 8.671 \times 10^{-1} & 5.711 \times 10^{-1} & 1.035 & 1.473 & 1.122 \times 10 & 5.291 \times 10 \\ 1.888 & 9.507 \times 10^{-1} & 1.395 & 3.364 & 1.122 \times 10 & 2.374 \times 10 & 2.425 \times 10^2 \\ 2.482 & 2.494 & 4.977 & 1.422 \times 10 & 5.291 \times 10 & 2.425 \times 10^2 & 6.591 \times 10^2 \end{pmatrix}.$$

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