<table>
<thead>
<tr>
<th>項目</th>
<th>内容</th>
</tr>
</thead>
<tbody>
<tr>
<td>タイトル</td>
<td>CECH-COMPLETENESS IN FIBREWISE TOPOLOGY (General Topology, Geometric Topology and Their Applications)</td>
</tr>
<tr>
<td>作者</td>
<td>Bai, Yun-Feng; Miwa, Takuo</td>
</tr>
<tr>
<td>引用</td>
<td>数理解析研究所講究録 2007, 1531: 49-54</td>
</tr>
<tr>
<td>発行日</td>
<td>2007-02</td>
</tr>
<tr>
<td>URL</td>
<td><a href="http://hdl.handle.net/2433/58940">http://hdl.handle.net/2433/58940</a></td>
</tr>
<tr>
<td>タイプ</td>
<td>Departmental Bulletin Paper</td>
</tr>
<tr>
<td>テキストバージョン</td>
<td>publisher</td>
</tr>
</tbody>
</table>

京都大学
ČECH-COMPLETENESS IN FIBREWISE TOPOLOGY

Yun-Feng Bai
Department of Mathematics, Shimane Univ. (Capital Normal Univ.)

Takuo Miwa
Department of Mathematics, Shimane University

1. INTRODUCTION

We introduce a new notion "Čech-complete map", and investigate some basic properties, invariance under perfect maps, relationships between (locally) compact map, Čech-complete map and k-map, and characterizations by compactifications of Čech-complete maps.

Motivation and significance of Čech-complete maps are:

(1): The notion of Čech-complete maps in the fibrewise category $TOP_B$ is corresponding to the notion of Čech-complete spaces in the topological category TOP. In fact, we can prove the following:

Compact map $\Rightarrow$ Locally compact map $\Rightarrow$ Čech-complete map $\Rightarrow$ k-map.

(2): The notion of Čech-complete maps is a new idea in General Topology. So, General Topology becomes plentifully by this notion.

For an arbitrary topological space $B$ one considers the category $TOP_B$, the objects of which are continuous maps into the space $B$, and for the objects $p : X \to B$ and $q : Y \to B$, a morphism from $p$ into $q$ is a continuous map $\lambda : X \to Y$ with the property $p = q \circ \lambda$. This is denoted by $\lambda : p \to q$. A morphism $\lambda : p \to q$ is said to be onto, closed, perfect, etc., if respectively, such is the map $\lambda : X \to Y$. A continuous map $p : X \to B$ is called by a projection, and $X$ is called by a fibrewise space over $B$ or $(X, p)$ is called by a fibrewise space. Further we call $\lambda : X \to Y$ a morphism when we write $\lambda : p \to q$, and we also call it a fibrewise map when we write $\lambda : (X, p) \to (Y, q)$.

Throughout this paper, we assume that all spaces are topological spaces, and all maps and projections are continuous. For other terminology and notations undefined in this paper, one can consult [3] about TOP, and [5] and [8] about $TOP_B$. 
2. Preliminaries

In this section, we refer to the notions and notations in Fibrewise Topology.

Let \((B, \tau)\) be a fixed topological space \(B\) with a fixed topology \(\tau\). Throughout this paper, we will use the abbreviation \(\text{nbd}(s)\) for \(\text{neighborhood}(s)\). We also use that for \(b \in B\), \(N(b)\) is the set of all open nbds of \(b\), and \(N, Q\) and \(R\) are the sets of all natural numbers, all rational numbers and all real numbers, respectively. Note that regularity of \((B, \tau)\) is assumed in Theorems 3.7 and 3.10, further first countability of \((B, \tau)\) is assumed in Theorem 3.10.

For a projection \(p : X \to B\) and each point \(b \in B\), the fibre over \(b\) is the subset \(X_b = p^{-1}(b)\) of \(X\). Also for each subset \(B'\) of \(B\) we regard \(X_{B'} = p^{-1}(B')\) as a fibrewise space over \(B'\) with the projection determined by \(p\). For a filter (base) \(\mathcal{F}\) in \(X\), we denote that \(p_*(\mathcal{F})\) is the filter generated by the family \(\{p(F) | F \in \mathcal{F}\}\).

First, we begin with defining some separation axioms on maps.

**Definition 2.1.** A projection \(p : X \to B\) is called a \(T_i\)-map, \(i = 0, 1, 2\), if for all \(x, x' \in X\) such that \(x \neq x'\), \(p(x) = p(x')\) the following condition is respectively satisfied:

1. \(i = 0\): at least one of the points \(x, x'\) has a nbd in \(X\) not containing the other point;
2. \(i = 1\): each of the points \(x, x'\) has a nbd in \(X\) not containing the other point;
3. \(i = 2\): the points \(x\) and \(x'\) have disjoint nbds in \(X\).

**Definition 2.2.** The subsets \(F\) and \(H\) of the space \(X\) are said to be respectively:

1. \(\text{nbd separated}\) in \(U \subset X\),
2. \(\text{functionally separated}\) in \(U \subset X\),

if the sets \(F \cap U\) and \(H \cap U\)

1. have disjoint nbds in \(U\),
2. are functionally separated in \(U\) (i.e. there exists a map \(\phi : U \to [0, 1]\) such that \(F \cap U \subset \phi^{-1}(0)\) and \(H \cap U \subset \phi^{-1}(1)\)).

**Definition 2.3.** A projection \(p : X \to B\) is called \(\text{completely regular}\) (resp. \(\text{regular}\)), if for every point \(x \in X\) and every closed set \(F\) in \(X\) such that \(x \notin F\), there exists a nbd \(W \in N(p(x))\), such that the sets \(\{x\}\) and \(F\) are functionally separated (resp. nbd separated) in \(X_W\). A completely regular (resp. regular) \(T_0\)-map is called \(\text{Tychonoff}\) or \(T_{3\frac{1}{2}}\)- (resp. \(T_3\)-) map.

It can be easily verified that every \(T_j\)-map is a \(T_i\)-map for \(j, i = 0, 1, 2, 3, 3\frac{1}{2}\) and \(i \leq j\).

**Definition 2.4.** Let \(p : X \to B\) be a projection.

1. The map \(p\) is called a \(\text{functionally} \ T_2\text{-map}\) if for all \(x, x' \in X\) such that \(x \neq x'\), \(p(x) = p(x')\) there exists \(W \in N(b)\) such that the sets \(\{x\}\) and \(\{x'\}\) are functionally separated in \(X_W\).
(2) The map $p$ is called functionally normal (resp. normal) if for every $b \in B$ and every two disjoint, closed sets $F$ and $H$ in $X$, there exists $W \in N(b)$ such that $F$ and $H$ are functionally separated (resp. nbd separated) in $X_W$. A functionally normal (resp. normal) $T_3$-map is called a functionally $T_4$-map (resp. $T_4$-map).

It can be easily verified that (1) every $T_4$-map is a $T_3$-map, (2) every functionally $T_4$-map is a $T_{3\frac{1}{2}}$-map and every $T_{3\frac{3}{4}}$-map is a functionally $T_2$-map. However, note that every $T_4$-map is not necessarily a $T_{3\frac{1}{2}}$-map. For this, see the remark in this section.

We now give the definitions of submaps, compact maps [9] and locally compact maps [7].

**Definition 2.5.** The restriction of the projection $p : X \to B$ on a closed (resp. open, type $G_\delta$, etc.) subset of the space $X$ is called a closed (resp. open, type $G_\delta$, etc.) *submap* of the map $p$.

**Definition 2.6.** (1) A projection $p : X \to B$ is called a compact map if it is perfect (i.e. it is closed and all its fibres $p^{-1}(b)$ are compact).

(2) A projection $p : X \to B$ is said to be a locally compact map if for each $x \in X_b$, where $b \in B$, there exists a nbd $W \in N(b)$ and a nbd $U \subset X_W$ of $x$ such that $p' : X_W \cap \overline{U} \to W$ is a compact map, where $p'$ is the restriction of $p$ and $X_W \cap \overline{U}$ is the closure of $U$ in $X_W$.

Note that a closed submap of a (resp. locally) compact map is (resp. locally) compact, and for a (resp. locally) compact map $p : X \to B$ and every $B' \subset B$ the restriction $p|_{X_{B'}} : X_{B'} \to B'$ is (resp. locally) compact.

**Definition 2.7.** (1) For a map $p : X \to B$, a map $c(p) : c_pX \to B$ is called a compactification of $p$ if $c(p)$ is compact, $X$ is dense in $c_pX$ and $c(p)|X = p$.

(2) A map $p : X \to B$ is called a $T_2$-compactifiable map (resp. $T_{3\frac{1}{2}}$-compactifiable map) if $p$ has a compactification $c(p) : c_pX \to B$ and $c(p)$ is a $T_2$-map (resp. $T_{3\frac{1}{2}}$-map).

**Remark:** (1) The compactification of a map was studied by Pasynkov [7]. In James [5] Section 8, there are some basic study of compactifiable maps, but note that in [5] he uses a terminology “fibrewise compactification”. For other study of compactifiable maps, see [1] and [6].

(2) Note that we must consider both $T_2$- and $T_{3\frac{1}{2}}$-compactifiable maps because, unlike the case of spaces, there exist $T_2$-compact maps which are not $T_{3\frac{1}{2}}$-maps ([4] 4.2 or [2] Example 3.4).

**Definition 2.8.** For the collection of fibrewise spaces $\{(X_\alpha, p_\alpha) | \alpha \in \Lambda \}$, the subspace $X = \{t = \{t_\alpha\} \in \prod\{X_\alpha : \alpha \in \Lambda : p_\alpha t_\alpha = p_\beta t_\beta \forall \alpha, \beta \in \Lambda\}$ of the Tychonoff product $\prod = \prod\{X_\alpha : \alpha \in \Lambda\}$ is called the fan product of the spaces $X_\alpha$ with respect to the maps $p_\alpha$, $\alpha \in \Lambda$. 


For the projection $p_{\alpha} : \prod \rightarrow X_{\alpha}$ of the product $\prod$ onto the factor $X_{\alpha}$, the restriction $\pi_{\alpha}$ on $X$ will be called the projection of the fan product onto the factor $X_{\alpha}, \alpha \in \Lambda$. From the definition of fan product we have that, $p_{\alpha} \circ \pi_{\alpha} = p_{\beta} \circ \pi_{\beta}$ for every $\alpha$ and $\beta$ in $\Lambda$. Thus one can define a map $p : X \rightarrow B$, called the product of the maps $p_{\alpha}, \alpha \in \Lambda$, by $p = p_{\alpha} \circ \pi_{\alpha}, \alpha \in \Lambda$, and $(X, p)$ is called the fibrewise product space of $\{(X_{\alpha}, p_{\alpha})|\alpha \in \Lambda\}$.

Obviously, the projections $p$ and $\pi_{\alpha}, \alpha \in \Lambda$, are continuous.

**Proposition 2.9.** Let $\{(X_{\alpha}, p_{\alpha})|\alpha \in \Lambda\}$ be a collection of fibrewise spaces.
(1) If each $p_{\alpha}$ is $T_{i}$ ($i = 0, 1, 2$) (resp. functionally $T_{2}$), then the product $p$ is also $T_{i}$ ($i = 0, 1, 2$) (resp. functionally $T_{2}$).
(2) If each $p_{\alpha}$ is a surjective $T_{3}^{-}$ (resp. $T_{3\frac{1}{2}}^{-}$)-map, then the product $p$ is also a $T_{3}^{-}$ (resp. $T_{3\frac{1}{2}}^{-}$)-map.
(3) If each $p_{\alpha}$ is a compact map, then the product $p$ is a compact map.
(4) If each $p_{\alpha}$ is a $T_{2}$-compactifiable map, then the product $p$ is a $T_{2}$-compactifiable map.

We shall conclude this section by defining the concept of $b$-filters (or tied filters) which plays an important role in this report.

**Definition 2.10.** ([5] Section 4.) For a fibrewise space $X$ over $B$, by a $b$-filter (or tied filter) on $X$ we mean a pair $(b, F)$, where $b \in B$ and $F$ is a filter on $X$ such that $b$ is a limit point of the filter $p_{\ast}(F)$ on $B$. By an adherence point of a $b$-filter $F$ ($b \in B$) on $X$, we mean a point of the fibre $X_{b}$ which is an adherence point of $F$ as a filter on $X$.

### 3. SOME PROPERTIES

**Definition 3.1.** Let $X$ be a topological space, and $A$ a subset of $X$. We say that the **diameter** of $A$ of the space $X$ is less than a family $A = \{A_{s}\}_{s \in S}$ of subsets of the space $X$, and we shall write $\delta(A) < A$, provided that there exists an $s \in S$ such that $A \subset A_{s}$.

**Definition 3.2.** A $T_{2}$-compactifiable map $p : X \rightarrow B$ is Čech-complete if for every $b \in B$, there exists a countable family $\{A_{n}\}_{n \in \mathbb{N}}$ of open (in $X$) covers of $X_{b}$ with the property that every b-filter $F$ which contains sets of diameter less than $A_{n}$ for every $n \in \mathbb{N}$ has an adherence point.

Since the real line $\mathbb{R}$ with the usual topology is Čech-complete, $p : \mathbb{R} \rightarrow B$ is Čech-complete where $B$ is a one-point space. All rational numbers $\mathbb{Q}$, as a subset of $\mathbb{R}$, is not Čech-complete, thus $p|\mathbb{Q}$ is not Čech-complete though $p|\mathbb{Q}$ is open and closed. But we have the following results.

**Theorem 3.3.** For a Čech-complete map $p : X \rightarrow B$, if $F$ is closed subset of $X$, then $p|F : F \rightarrow B$ is Čech-complete.
Theorem 3.4. For a Čech-complete map $p : X \to B$, if $G$ is a $G_\delta$-subset of $X$ and $X$ is regular, then $p|G : G \to B$ is Čech-complete.

Theorem 3.5. Let $\{(X_n, p_n)|n \in N\}$ be a countable family of fibrewise spaces and $(\prod_B X_n, p)$ be the fibrewise product space. If every $p_n$ is surjective Čech-complete, then $p$ is Čech-complete.

Theorem 3.6. Let a fibrewise map $\lambda : (X, p) \to (Y, q)$ be a perfect map, and $p$ and $q$ be $T_2$-compactifiable maps. Then $p$ is Čech-complete if and only if $q$ is Čech-complete.

Theorem 3.7. Suppose that $B$ is regular. For a $T_2$-compactifiable map $p : X \to B$, the following are equivalent:
1. $p : X \to B$ is Čech-complete.
2. For every $T_2$-compactification $p' : X' \to B$ of $p$ and each $b \in B$, $X_b$ is a $G_\delta$-subset of $X'_b$.
3. There exists a $T_2$-compactification $p' : X' \to B$ of $p$ such that $X_b$ is a $G_\delta$-subset of $X'_b$ for each $b \in B$.

Theorem 3.8. Every locally compact map, $T_2$-map is Čech-complete.

Definition 3.9. (James [5], Definitions 10.1 and 10.3) (1) Let $(X, p)$ be a fibrewise space. The subset $H$ of $X$ is quasi-open (resp. quasi-closed) if the following condition is satisfied: for each $b \in B$ and $V \in N(b)$ there exists a nbd $W \in N(b)$ with $W \subset V$ such that whenever $p|K : K \to W$ is compact then $H \cap K$ is open (resp. closed) in $K$.
(2) Let a projection $p : X \to B$ be a $T_2$ map. The map $p$ is a $k$-map if every quasi-closed subset of $X$ is closed in $X$ or, equivalently, if every quasi-open subset of $X$ is open in $X$.

Theorem 3.10. Suppose that $B$ is first countable and regular. Then a Čech-complete map $p : X \to B$ is a $k$-map.

References
