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<th>Title</th>
<th>On Replacement of Petri Nets and Some Applications (Semigroups, Formal Languages and Computer Systems)</th>
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<tr>
<td>Author(s)</td>
<td>TIPBLE, Ferucio Laurentiu; KATSURA, Masashi; ITO, Masami</td>
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<tr>
<td>Citation</td>
<td>数理解析研究所講究録, 1996, 960: 178-190</td>
</tr>
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<td>Issue Date</td>
<td>1996-08</td>
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<td>URL</td>
<td><a href="http://hdl.handle.net/2433/60494">http://hdl.handle.net/2433/60494</a></td>
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<tr>
<td>Type</td>
<td>Departmental Bulletin Paper</td>
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On Replacement of Petri Nets and Some Applications

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Abstract

Refinement and abstraction are complementary techniques in system design and analysis; both of them are generally referred to as replacements. In this paper we consider a general enough technique of replacement of Petri nets. It may be simply described by "replace the subnet $\gamma_1$ of $\gamma$ by the net $\gamma_2$; denote the result by $\gamma[\gamma_1 \leftarrow \gamma_2]$". The subnet $\gamma_1$ will always be generated by a subset of transitions of $\gamma$, and this is the only restriction imposed in our replacement operation. Moreover, this operation is expressed in terms of difference and catenation of nets. A commutative monoid of nets with respect to catenation and two congruences, $\approx_{mP}$ and $\approx_{mPW}$, on this monoid are given. It is shown that from $\gamma_1 \approx_{mP} \gamma_2$ (or $\gamma_1 \approx_{mPW} \gamma_2$, resp.) one can infer $\gamma \approx_{P} \gamma[\gamma_1 \leftarrow \gamma_2]$ (or $\gamma \approx_{PW} \gamma[\gamma_1 \leftarrow \gamma_2]$, resp.), where $\approx_{P}$ and $\approx_{PW}$ are the process and respectively partial word equivalence on nets. A particular case when the equivalences $\approx_{mP}$ and $\approx_{mPW}$ may be easier decided is highlighted. Some applications on normalization of Petri nets are then presented. They consist in establishing the correctness of four transformations ([10], [19]) in a much simpler way.

1 Introduction and Preliminaries

Many transformations of Petri nets may be simply described by "replace the subnet $\Sigma_1$ of $\Sigma$ by the net $\Sigma_2"; that means the subnet $\Sigma_1$ will be removed from $\Sigma$ and the net $\Sigma_2$ is inserted in its place. Clearly, some fitting conditions must be satisfied and if one wants to preserve some properties of the original net, some more conditions are needed. If $\Sigma_2$ is more "detailed" than $\Sigma_1$ this operation is called refinement, otherwise it is an abstraction; both of them are particular cases of replacement. In literature mostly refinement was studied and various techniques was proposed ([1], [2], [5], [6], [8], [9], [16], [20], [23], [24]). A large number of behaviour and equivalence notions preserving refinements have also been considered.

1A complete final version of this paper will be published elsewhere
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In this paper we propose a technique of replacement preserving the processes and partial words of the original net (Section 2). Using this technique we give shorter and elegant proofs to the correctness of some transformations of Petri nets (Section 3). In the remainder of this section we recall the basic definitions and notations in Petri net theory (for further details the reader is referred to [3], [4], [12], [13], [14]). The empty set is denoted by $\emptyset$, and $|A|$ denotes the cardinality of the finite set $A$. $A \subseteq B$ denotes the inclusion of the set $A$ into the set $B$. The set of nonnegative integers is denoted by $\mathbb{N}$. If $f_i : A_i \rightarrow \mathbb{N}$, $i = 1, 2$, $f_1 + f_2$ is the function from $A_1 \cup A_2$ into $\mathbb{N}$ given by $(f_1 + f_2)(a) = f_1(a)$ for all $a \in A_1 - A_2$, $(f_1 + f_2)(a) = f_2(a)$ for all $a \in A_2 - A_1$, and $(f_1 + f_2)(a) = f_1(a) + f_2(a)$ for all $a \in A_1 \cap A_2$. The restriction of a function $f : A \rightarrow B$ to the set $C \subseteq A$ is denoted by $f|_C$; $f^{-1}$ is the function from $B$ into the powerset of $A$ given by $f^{-1}(b) = \{a \in A | f(a) = b\}$ for all $b \in B$.

A (finite) $P/T$-net, abbreviated $PTN$, is a 4-tuple $\Sigma = (S, T, F, W)$ where $S$ and $T$ are two finite non-empty sets (of places and transitions, resp.), $S \cap T = \emptyset$, $F \subseteq (S \times T) \cup (T \times S)$ is the flow relation and $W : (S \times T) \cup (T \times S) \rightarrow \mathbb{N}$ is the weight function of $\Sigma$ verifying $W(x, y) = 0$ iff $(x, y) \notin F$ (we suppose that all our nets do not have isolated transitions). A marking of $\Sigma$ is any function $M : S \rightarrow \mathbb{N}$; it will sometimes be identified with a vector $M \in \mathbb{N}^{|S|}$. The operations and relations on vectors are componentwise defined. For $x \in S \cup T$ we set $*x = \{y|(y, x) \in F\}$, $x^* = \{y|(x, y) \in F\}$, $*x^* = *x \cup x^*$, and usually extend these notations to subsets $X \subseteq S \cup T$.

A marked $PTN$, abbreviated $mPTN$, is a pair $\gamma = (\Sigma, M_0)$, where $\Sigma$ is a $PTN$ and $M_0$, the initial marking of $\gamma$, is a marking of $\Sigma$. A $\lambda$-labelled $mPTN$, abbreviated $l^\lambda mPTN$, is a 3-tuple $\gamma = (\Sigma, M_0, l)$, where the first two components form an $mPTN$ and $l$, the $\lambda$-labelling function of $\gamma$, assigns to each transition either a letter or the empty word $\lambda$. When $\lambda$ is not in the range of $l$ we will refer to such triples as labelled $mPTN$ and to $l$ as labelling function; the notation will be modified correspondingly to $lmPTN$.

In the sequel we shall often use the term "Petri net" or "net" whenever we refer to a structure $\gamma$ as defined above. In all the above definitions $\Sigma$ is called the underlying net of $\gamma$. A marking (place, transition, arc, weight, resp.) of a net $\gamma$ is any marking (place, transition, arc, weight, resp.) of the underlying net of $\gamma$. Pictorially, a net $\gamma$ is represented by a graph. Then the places are denoted by circles and transitions by boxes; the flow relation is represented by arcs. The arc $f \in F$ is labelled by $W(f)$ whenever $W(f) > 1$. The initial marking $M_0$ is presented by putting $M_0(s)$ tokens into the circle representing the place $s$ and the labelling function is denoted by placing letters into the boxes representing transitions.

Let $\gamma$ be a net and $M$ a marking of it. The transition rule states that a transition $t$ is enabled at $M$, denoted $M[t]_\gamma$, if $M(s) \geq W(s, t)$ for all $s \in S$. If $t$ is enabled at $M$ then $t$ may occur yielding a new marking $M'$, abbreviated $M[t]_\gamma M'$, given by $M'(s) = M(s) - W(s, t) + W(t, s)$ for all $s \in S$. The transition rule is extended to sequences of transition $w \in T^*$ in the usual way. If $M_0[w]_\gamma M$ then $M$ is called reachable; $[M_0]_\gamma$ denotes the set of all reachable markings. The notation "$[\cdot]$$_\gamma$" will be simplified to "$[\cdot]$" whenever $\gamma$ is understood from context.

The concurrent behaviour of Petri nets is well-expressed by the notion of a process. Generally speaking, processes of Petri nets are obtained by running the nets and solving
conflicts in an arbitrary fashion as and when they arise. A process of a net is also a net; these nets are called occurrence nets and they are classical nets $N = (B, E, R)$ ($R$ is the flow relation and the weights of the arcs are 1) satisfying:

(i) $|b| \leq 1$ and $|b^*| \leq 1$, for all $b \in B$;
(ii) $R^+$ is acyclic, i.e. for all $x, y \in B \cup E$ if $(x, y) \in R^+$ then $(y, x) \not\in R^+$.

Usually the elements of $B$ are called conditions whereas the elements of $E$ are called events. The partially ordered set induced by $N$ is $(B \cup E, \prec_N)$, where $\prec_N = R^+$. A $B$-cut of $N$ is any maximal subset $C \subseteq B$ of incomparable elements according with the relation $\prec_N$. As we will only use $B$-cuts we shortly call them cuts (see [4] for more details). The initial (final, resp.) cut of $N$ is $^0N = \{b \in B | ^*b| = 0\}$ ($N^o = \{b \in B | |b^*| = 0\}$, resp. In defining processes we will use labelled occurrence nets which are couples $\pi = (N, p)$, where $N$ is a occurrence net and $p$ is a total function from $B \cup E$ into an alphabet $V$. The above definitions (partial order, cut, initial and final cut) are transferred to labelled occurrence nets $\pi$ by means of $N$; the notations are obtained by changing "$N$" into "$\pi$" (e.g. $\prec_{\pi}$, $^0\pi$, $\pi^*$).

Let $\Sigma = (S, T, F, W)$ be a Petri net, $\pi = (N, p)$ a labelled occurrence net such that $p$ is a function from $B \cup E$ into $S \cup T$ satisfying $p(B) \subseteq S$ and $p(E) \subseteq T$, and $C$ a subset of conditions of $\pi$. Define the marking induced by $C$ in $\Sigma$ as being $M_C(s) = |p^{-1}(s) \cap C|$, for all $s \in S$. There are two alternative definitions of a process, axiomatic and inductive, and it is well-known that for Petri nets of finite synchronization they yields exactly the same objects ([4]). We adopt here the axiomatic definition. A process of $\gamma = (\Sigma, M_0)$ is any couple $\pi = (N, \varphi)$, where $N$ is an occurrence net and $\varphi : B \cup E \rightarrow S \cup T$ is a mapping satisfying:

(i) $\varphi(B) \subseteq S$, $\varphi(E) \subseteq T$;
(ii) $M_0(s) = |\varphi^{-1}(s) \cap S\pi|$ for all $s \in S$;
(iii) $W(s, \varphi(e)) = |\varphi^{-1}(s) \cap e\pi|$ and $W(\varphi(e), s) = |\varphi^{-1}(s) \cap e^\pi|$ for all $e \in E$ and $s \in S$ (as we can see we allow events without pre-conditions or post-conditions). In order to obtain processes of $\lambda$-labelled nets $\gamma = (\Sigma, M_0, l)$ what we have to do is to consider each process $\pi = (N, p)$ of $\Sigma, M_0$, and to replace the function $p$ by $p'$, where $p'(x) = p(x)$ for all the conditions $x$, and $p'(x) = (l \circ p)(x)$ for all the events $x$; that is, the events will be labelled by $l \circ p$; we will sometimes use $l \circ p$ instead of $p'$ with the above meaning.

Finally, to compare processes we consider the notions of isomorphism of processes and partial word. Let $\pi_1 = (N_1, p_1)$ and $\pi_2 = (N_2, p_2)$ be processes (not necessary of the same net). $\pi_1$ and $\pi_2$ are said isomorphic, abbreviated $\pi_1 \cong \pi_2$, if there is a bijection $\varphi : B_1 \cup E_1 \rightarrow B_2 \cup E_2$ such that

1. $p_1(x) = p_2(\varphi(x))$ for all $x \in E_1$, and $p_1(x) = p_2(\varphi(x))$ whenever $x \in B_1$ and $p_1(x) \in S_1 \cap S_2$ or $p_2(\varphi(x)) \in S_1 \cap S_2$;
2. $x \prec_{\pi_1} y$ iff $\varphi(x) \prec_{\pi_2} \varphi(y)$ for all $x, y \in B_1 \cup E_1$.

(1) says that $\varphi$ is a label-preserving bijection between $E_1 \cup p_1^{-1}(S_1 \cap S_2)$ and $E_2 \cup p_2^{-1}(S_1 \cap S_2)$, while (2) says that $\varphi$ is order preserving in both directions.

In order to define the partial word associated to a process we have to derive from processes another structure by recording only the events which are not labelled by $\lambda$. Let $\pi = (N, p)$ be a process of a net $\gamma$. An abstraction of $\pi$ is any labelled partially ordered set $(E', A, p')$, where:

- $E' = \{e \in E | p(e) \neq \lambda\}$ and $p' = p|_{E'}$;
- $(e, e') \in A$ iff there is a path in $\pi$ leading from $e$ to $e'$.

The equivalence class with respect to isomorphism induced by $(E', A, p')$, denoted $PW(\pi)$, is called the partial word associated to $\pi$. The set of all partial words of $\gamma$ is denoted by $PW(\gamma)$.

Let $\gamma_1$ and $\gamma_2$ be two nets. We say that $\gamma_1$ and $\gamma_2$ are process equivalent, abbreviated $\gamma_1 \approx_P \gamma_2$, if for any process $\pi_1$ of $\gamma_1$ there is a process $\pi_2$ of $\gamma_2$ such that $\pi_1 \cong \pi_2$, and vice versa. We say that $\gamma_1$ and $\gamma_2$ are partial word equivalent, abbreviated $\gamma_1 \approx_{PW} \gamma_2$, if $PW(\gamma_1) = PW(\gamma_2)$. Thus we have obtained two equivalence relations on nets: $\approx_P$ (process equivalence) and $\approx_{PW}$ (partial word equivalence).

2 Replacements of Petri Nets

The operation that we will consider in this section has its roots in various transformations of Petri nets. These transformations may be simply described by "replace the subnet $\Sigma_1$ of $\Sigma$ by the net $\Sigma_2"$, that means the subnet $\Sigma_1$ will be removed from $\Sigma$ and the net $\Sigma_2$ is inserted in its place. Clearly, some fitting conditions must be satisfied and if one wants to preserve the behaviour of the original net, some more conditions are needed, and this is what we want to discuss in the next two subsections.

2.1 Subnets, Connecting Places, and Replacements

In our paper the subnets that are considered will always be generated by subsets of transitions. That is, if $\Sigma = (S, T, F, W)$ is a net and $T_1 \subseteq T$ then the subnet generated by $T_1$ is $\Sigma_1 = (S_1, T_1, F_1, W_1)$, where $S_1 = \star T_1$ and $F_1$ and $W_1$ are the restrictions of $F$ and $W$ to $S_1$ and $T_1$. Let $\Sigma_1$ be such a subnet of $\Sigma$. The set of places $S_1$ can be partitioned in two disjoint subsets (not necessary both of them non-empty) $S_1 = S_1^1 \cup S_1^2$, where

$$S_1^1 = \{s \in S| \exists t \in T - T_1, \exists t_1 \in T_1 : s \in \star t \cap \star t_1\}.$$

We will call the places in $S_1^1$ (resp. $S_1^2$, resp.) connecting (internal, resp.) places of $\Sigma_1$. The terminology is clear, the connecting places assure the connection of $\Sigma_1$ to $\Sigma$ and the internal places are specific only for $\Sigma_1$, that is no transition in $T - T_1$ is connected to any place in $S_1^1$.

**Definition 2.1.1** Let $\Sigma$ be a net and $\Sigma_1$ a subnet of $\Sigma$. We say that $\Sigma'$ is the difference of $\Sigma$ and $\Sigma_1$, abbreviated $\Sigma' = \Sigma - \Sigma_1$, if $S' = S - S_1^1$, $T' = T - T_1$ and the flow relation and the weight function of $\Sigma'$ are the corresponding restrictions of $F$ and $W$ to $S'$ and $T'$.

Specifying $\Sigma_1$ the set $S_1^1$ is implicitly specified. Our intention is to replace $\Sigma_1$ by a new net $\Sigma_2 = (S_2, T_2, F_2, W_2)$ (suppose $(S \cup T) \cap (S_2 \cup T_2) = \emptyset$). To do that we have first to specify a set of connecting places of $\Sigma_2$, $S_2^1$, and an one-to-one correspondence between $S_1^1$ and $S_2^1$. Therefore we consider an one-to-one mapping $h$ from $S_1^1$ into $S_2$ and denote $S_2^1 = h(S_1^1)$ and $S_2^1 = S_2 - S_2^1$. This one-to-one mapping says us how to connect $\Sigma_2$ to $\Sigma - \Sigma_1$. Now the replacement of $\Sigma_1$ by $\Sigma_2$ can be described as follows: connect the nets $\Sigma - \Sigma_1$ and $\Sigma_2$ by identifying the places $s \in S_1^1$ and $h(s) \in S_2$; the resulting net is denoted $\Sigma[\Sigma_1 \xleftarrow{h} \Sigma_2]$. 

---

$\Sigma_{1}=(s_{1}, \tau_{1}, F_{1}, W_{1})$

$\Sigma'=(s_{1}, \tau_{1}, F_{1}, W_{1})$

$\Sigma_{1}^{c}=(s_{1}, \tau_{1}, F_{1}, W_{1})$

$\Sigma_{1}$

$\Sigma_{2}$

$\Sigma_{1}^{c}=(s_{1}, \tau_{1}, F_{1}, W_{1})$

$\Sigma_{1}^{c}=(s_{1}, \tau_{1}, F_{1}, W_{1})$

$\Sigma_{1}^{c}=(s_{1}, \tau_{1}, F_{1}, W_{1})$

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**Definition 2.1.2** Let $\Sigma_1$ and $\Sigma_2$ be nets, $S_i^c \subseteq S_1$, and $h$ an one-to-one mapping from $S_i^c$ into $S_2$ (suppose $(S_1 \cup T_1) \cap (S_2 \cup T_2) = \emptyset$). We say that the net $\Sigma'$ is obtained by \textit{h-catenation} of $\Sigma_1$ and $\Sigma_2$, abbreviated $\Sigma' = \Sigma_1 \circ_h \Sigma_2$, if the following properties hold:
- $S' = S_1 \cup (S_2 - h(S_i^c))$;
- $T' = T_1 \cup T_2$;
- $(x, y) \in F'$ iff $((x, y) \in F_1 \land W'(x, y) = W_1(x, y))$ or $((h(x), y) \in F_2 \land W'(x, y) = W_2(h(x), y))$ or $((x, y) \in F_2 \land W'(x, y) = W_2(x, h(y)))$ (this defines both $F'$ and $W'$).

We allow the case $S_i^c = \emptyset$ as well: the net $\Sigma'$ consists of two disjoint subnets, $\Sigma_1$ and $\Sigma_2$.

**Definition 2.1.3** Let $\Sigma$ and $\Sigma_2$ be nets, $\Sigma_1$ a subnet of $\Sigma$ and $h$ an one-to-one mapping from $S_i^c$ into $S_2$ (suppose $(\Sigma \cup T) \cap (S_2 \cup T_2) = \emptyset$). We say that the net $\Sigma'$ is obtained by \textit{h-replacement} of $\Sigma_1$ by $\Sigma_2$ in $\Sigma$, abbreviated $\Sigma' = \Sigma[\Sigma_1 \circ_h \Sigma_2]$, if $\Sigma' = (\Sigma - \Sigma_1) \circ_h \Sigma_2$.

The above definitions are naturally extended to nets $\gamma = (\Sigma, M_0, I)$. For instance, the difference $\gamma - \gamma_1$ is simply defined by restricting the components of $\gamma$ to $\Sigma - \Sigma_1$ ($\gamma_1$ is a subnet of $\gamma$). If $\gamma_1$ and $\gamma_2$ are nets such that $M_0^1(s) = M_0^2(h(s))$ for all $s \in S_i^c$ ($S_i^c \subseteq S_1$ and $h$ is an one-to-one mapping from $S_i^c$ into $S_2$) then the $h$-catenation of $\gamma_1$ and $\gamma_2$ is the net $\gamma'$ given by:
- $\Sigma' = \Sigma_1 \circ_h \Sigma_2$;
- $M_0' = M_0^1\mid S_1^c + M_0^1\mid S_2^c + M_0^2\mid S_2^c$;
- $T' = T_1 \cup T_2$.

The $h$-catenation of processes (labelled occurrence nets) needs a supplementary condition: the function $h$ should preserve the labels of places, that is $p_1(s) = p_2(h(s))$ for all $s \in S_i^c$ ($p_1$ and $p_2$ are the corresponding labelling functions). Now, the extension of the $h$-replacement to $\gamma_1$ by $\gamma_2$ follows from the above extensions of the difference and $h$-catenation.

**Example 2.1.1** In Figure 2.1.1(a) is pictorially represented a net $\gamma$ and a subnet $\gamma_1$ of it; the net $\gamma - \gamma_1$ is given in Figure 2.1.1(b). Consider the net $\gamma_2$ in Figure 2.1.1(c) and the mapping $h(s_i) = s_i'$, $i = 2, 3$. The net $\gamma[\gamma_1 \circ_h \gamma_2]$ is given in Figure 2.1.1(d).

As we have seen the replacement operation on $\gamma = (\Sigma, M_0, I)$ requires the specification of a subnet $\Sigma_1$ of $\Sigma$ and an one-to-one mapping $h$. The subnet $\Sigma_1$ will be the subnet generated by a non-empty set of transitions $T_1 \subset T$, and therefore to specify $\Sigma_1$ is to specify $T_1$. The mapping $h$ will be specified considering $S_i^c = S_2^c$ (is the identity, $S \cap S_2 = S_1^c$, and $T \cap T_2 = \emptyset$). Then we will simply write $\gamma[\gamma_1 \circ_h \gamma_2]$ (resp.) instead of $\gamma[\gamma_1 \circ_h \gamma_2]$ (com). Let $\mathit{PN}(S^c)$ denote the class of Petri nets having in common only the set $S^c$ of places and

$$\mathit{PN}(S^c, M_0^c) = \{ \gamma \in \mathit{PN}(S^c) | M_0\mid S^c = M_0^c \}$$

($M_0^c \in \mathbb{N}^{S^c}$). Then, we have:

**Proposition 2.1** $(\mathit{PN}(S^c, M_0^c), o)$ is a commutative monoid.

**Proof** The associativity and commutativity directly follow from definitions; the net $((S^c, \emptyset, \emptyset, \emptyset), M_0^c, \emptyset)$ is the unity of this monoid. \qed
2.2 Concurrent Behaviour and Replacements

Our interest is to find some equivalence relations on nets, ≈, such that from γ₁ ≈ γ₂ one can infer γ ≈ₚ γ₁ ← γ₂ or γ ≈ₚₛ γ₁ ← γ₂. In what follows we will give two such equivalence relations; as we shall see they are very close to the relations ≈ₚ and ≈ₛₚ, the difference consisting in the interaction with the environment.

Let γ be a net, S² ⊆ S, and π a process of γ. An S²-abstraction of π is any labelled partially ordered set (B' ∪ E', A, p'), where:

- B' = \{b ∈ B|p(b) ∈ S² ∧ (|b| = 0 ∨ \|b\| = 0)\}, E' = \{ e ∈ E|p(e) ≠ λ\}, and p' = p|_{E \cup E'};
- (x, y) ∈ A iff there is a path in π leading from x to y.

The equivalence class with respect to isomorphism induced by (B' ∪ E', A, p'), denoted S²-PW(π), is called the S²-partial word associated to π. The class of all S²-partial words of γ is denoted by S²-PW(γ).

Let γ ∈ PN(S², M₀) and M ∈ N². By (γ + M) we denote the net (Σ, M₀ + M, l) ∈ PN(S², M₀ + M). For any γ₁, γ₂ ∈ PN(S², M₀) and M ∈ N² we have (γ₁ o (γ₂ + M)) = (γ₁ o (γ₂ + M)).

**Definition 2.2.1** Let γ₁, γ₂ ∈ PN(S², M₀). We say that γ₁ and γ₂ are m-process equivalent (m-partial word equivalent, resp.), abbreviated γ₁ ≈ₚ γ₂ (γ₁ ≈ₚₛ γ₂, resp.), if for any M ∈ N² we have (γ₁ o (γ₂ + M)) ≈ₚ (γ₁ + M) (S²-PW(γ₁ + M) = S²-PW(γ₂ + M), resp.).

This definition says that no matter how the initial marking on S² is increased that two nets have the same processes (up to an isomorphism) or the same S²-partial words. It is easy to see that ≈ₚ and ≈ₛₚ are equivalence relations on nets (in order to simplify the writing we will use, in what follows, the next notations and conventions: ≈ₚₚ denotes one of the relations ≈ₚ or ≈ₛₚ, while ≈ denotes ≈ₚ or ≈ₛₚ. Moreover, when we use both ≈ₚ and ≈ and ≈ₚ denotes ≈ₚ then ≈ will denote ≈ₚ, and similar for the other case). Let ≈ₚₚ be the binary relation

\[
S² = \{s₁, s₂, s₃, s₄\}
\]

\[
S₃ = \{s₁, s₂, s₃\}
\]

\[
S₄ = \{s₁, s₂, s₃, s₄\}
\]

\[
S₅ = \{s₁, s₂, s₃\}
\]
\[ \gamma_1 M_1 \approx_m \gamma_2 \iff (\gamma_1 + M) \approx_m (\gamma_2 + M), \]
where \( M \in \text{N}^{S^c} \). That is, \( \gamma_1 M_1 \approx_m \gamma_2 \iff (\gamma_1 + M') \approx (\gamma_2 + M') \) for all \( M' \geq M \) \( (M' \in \text{N}^{S^c}) \).

We have:

**Proposition 2.2.1** (1) \( \approx_m \subseteq \approx \);
(2) \( \approx_m \subseteq M \approx_m \subseteq \approx_m \) for all \( M, M' \in \text{N}^{S^c} \) with \( M \leq M' \).

The next theorem represents the main result of this section.

**Theorem 2.2.1** Let \( \gamma_1, \gamma_2 \in PN(S^c, M_0^c) \). If \( \gamma_1 \approx_m \gamma_2 \) then \( \gamma_0 \circ \gamma_1 \approx \gamma_0 \circ \gamma_2 \) for all \( \gamma_0 \in PN(S^c, M_0^c) \).

**Corollary 2.2.1** Let \( \gamma_1, \gamma_2 \in PN(S^c, M_0^c) \). If \( \gamma_1 \approx_m \gamma_2 \) then \( \gamma_0 \circ \gamma_1 \approx \gamma_0 \circ \gamma_2 \) for all \( \gamma_0 \in PN(S^c, M_0^c) \). Therefore, \( \approx_{mF} \) and \( \approx_{mFW} \) are congruences on \( (PN(S^c, M_0^c), o) \).

**Corollary 2.2.2** Let \( \gamma_1 \) be a subnet of \( \gamma \) generated by a subset \( T_1 \) of transitions, and \( \gamma_2 \in PN(S^c, M_0^c) \), where \( M_0^c = M_0|_{S_1} \). If \( \gamma_1 \approx_m \gamma_2 \) then \( \gamma \approx \gamma_1 \cap \gamma_2 \).

From practical point of view we are interested in Corollary 2.2.2. The difficulty in using this corollary consists in the fact that we have to decide whether or not \( \gamma_1 \approx_m \gamma_2 \), that is we have to decide whether or not \( (\gamma_1 + M) \approx (\gamma_2 + M) \) for all \( M \in \text{N}^{S^c} \). A favourable particular case would be when there is a marking \( M \in \text{N}^{S^c} \) such that the processes of nets \( (\gamma + M') \), where \( M' \in \text{N}^{S^c} \) and \( \neg(M' \leq M) \), can be reduced to processes of \( (\gamma + M) \).

Let us introduce first a few notations. Let \( \pi = (N, p) \) be a labelled occurrence net and \( A \) a subset of the range of \( p \). If \( C \subseteq p^{-1}(A) \cap o_\pi \), where \( o_\pi = o_\pi \cap o_\pi \), then we will denote by \( (\pi - C) \) the labelled occurrence net obtained from \( \pi \) by removing all the conditions in \( C \).

**Definition 2.2.2** Let \( \gamma \in PN(S^c, M_0^c), M_1, M_2 \in \text{N}^{S^c}, \pi_1 \in \Pi(\gamma + M_1), \) and \( \pi_2 \in \Pi(\gamma + M_2) \). We say that \( \pi_1 \) and \( \pi_2 \) are almost isomorphic, abbreviated \( \pi_1 \cong_a \pi_2 \), if there are \( C_1 \subseteq p_1^{-1}(S^c) \cap o_\pi_1 \) and \( C_2 \subseteq p_2^{-1}(S^c) \cap o_\pi_2 \) such that \( (\pi_1 - C_1) \cong (\pi_2 - C_2) \).

This definition wants to say that if we remove from \( \pi_1 \) and \( \pi_2 \) some conditions without predecessors and successors and labelled by places in \( S^c \) we get two isomorphic labelled occurrence nets.

**Lemma 2.2.1** Let \( \gamma \in PN(S^c, M_0^c), M_1, M_2 \in \text{N}^{S^c}, \pi_1 \in \Pi(\gamma + M_1), \) and \( \pi_2 \in \Pi(\gamma + M_2) \). Then, \( \pi_1 \cong_a \pi_2 \iff (\pi_1 - (p_1^{-1}(S^c) \cap o_\pi_1)) \cong (\pi_2 - (p_2^{-1}(S^c) \cap o_\pi_2)) \).

**Definition 2.2.3** Let \( \gamma \in PN(S^c, M_0^c) \) and \( M \in \text{N}^{S^c} \). We say that \( \gamma \) is process stable w.r.t. \( M \) if for any marking \( M' \in \text{N}^{S^c} \) with \( \neg(M' \leq M) \) we have:
- for any process \( \pi' \) of \( (\gamma + M') \) there is a process \( \pi \) of \( (\gamma + M) \) such that \( \pi \cong_a \pi' \); versa.

As an example, the nets in Figure 3.2(a)(b) are process stable w.r.t. \( M = (0, \ldots, 0) \). We have:

**Proposition 2.2.2** Let \( \gamma_1, \gamma_2 \in PN(S^c, M_0^c) \) be two process stable nets w.r.t. \( M \). If \( (\gamma_1 + M) \approx (\gamma_2 + M) \) then \( \gamma_1 \approx_m \gamma_2 \).
3 Applications

The Corollary and Proposition 2.2.2 may be used to prove the correctness of some transformations of Petri nets. Their efficiency directly depends on the easiness of deciding the equivalences $\approx_{mP}$ and $\approx_{mPW}$. Intuitively, the simpler are $\gamma_1$ and $\gamma_2$ the easier we can test $\gamma_1 \approx_{mP} \gamma_2$ and $\gamma_1 \approx_{mPW} \gamma_2$ and therefore the more efficient we can apply Corollary 2.2.2 and Proposition 2.2.2. In what follows will exemplify our discussion by some applications. First we recall the inductive definition of processes in terms of catenation of nets. Let $\gamma = (\Sigma, M_0)$ be a net and $t$ a transition of it. An elementary occurrence net associated to $t$ is any labelled occurrence net $\pi = (N, p)$ with the properties: $\pi$ contains only an event $e$ labelled by $t$, $W(s, t)$ preconditions and $W(t, s)$ postconditions of $e$ labelled by $s$, for all $s \in S$ ($\pi$ does not contain other elements than those already specified). An initial occurrence net of $\gamma$ is any occurrence net $(N, p)$ which does not contain any event and for each $s \in S$ it contains exactly $M_0(s)$ conditions labelled by $s$ (it does not contain other elements than those already specified). Define $\Pi(\gamma)$ as being the smallest set with the properties:

1. $\Pi(\gamma)$ contains all the initial occurrence nets associated to $\gamma$;
2. if $\pi_1 \in \Pi(\gamma)$ and $\pi_2$ is an elementary occurrence net such that $\pi_1$ and $\pi_2$ are disjoint, and $h : B'_1 \rightarrow \sigma \pi_2$ is a bijection $(B'_1 \subseteq B_1)$ such that $p_1(b) = p_2(h(b))$ for all $b \in B'_1$, then $\pi_1 \circ h \pi_2 \in \Pi(\gamma)$.

Processes of $\lambda$-labelled nets may be defined as in the first section.

According to [10], a labelled marked Petri net is called normalized if the weight function and the initial marking take values into $\{0, 1\}$. E. Pelz ([10]) showed that any Petri net is process equivalent with a normalized one. Moreover an algorithm to transform a Petri net into an equivalent normalized one was given. The Pelz's algorithm works in two main steps, denoted Transformation-A and Transformation-B. In the first one the weight function, and in the second the initial marking, is processed. Also the initial marking is needed to be processed in the first step. The Pelz's solution for processing the initial marking was to add new places and transitions in order to "simulate" it. This fact led to an increasing almost double of the complexity of construction. In [18] another solution was proposed. It consists of a distribution of the initial marking in the old places. No place and transition is needed more. The complexity of Transformation-A is to the half reduced. Therefore, we will describe the Pelz's algorithm as in [18]. First, a few notations and definitions are needed.

Let $\gamma = (\Sigma, M_0, l)$ be a net, $S_1 \subseteq S$, and $M$ a marking of $\gamma$. We say that $M$ is uniformly distributed over $S_1$ if $|M(s_1) - M(s_2)| \leq 1$ for all $s_1, s_2 \in S_1$. Let $s \in S$ and $\gamma'$ be a net obtained from $\gamma$ replacing the place $s$ by a set of new places, $S'$, and connecting the places of $S'$ to transitions of $\gamma$ in an arbitrary but fixed way. Let $M$ and $M'$ be markings of $\gamma$ and respectively $\gamma'$. We say that $M$ and $M'$ are $s$-compatible if $M'(x) = M(x)$ for all $x \in S - \{s\}$, and $M(s) = \sum_{s' \in S'} M'(s')$.

Now, using the replacement operation we can describe the Pelz's algorithm as follows.

Transformation-A: Let $\gamma = (\Sigma, M_0, l)$ be a net and $n_s = \max\{W(s, t), W(t, s) | t \in T\}$ for all $s \in S$. For each $s$ with $n_s > 1$ replace the subnet $\gamma_s$ generated by $T_s = \{t \in T | t \in *s*\}$, by the net $\gamma'_s$ defined as follows:
- $\gamma'_s = (\Sigma'_s, M'_s, l'_s)$, $\Sigma'_s = (S'_s, T'_s, F'_s, W'_s)$;
- $S'_s = (S_s - \{s\}) \cup C(s)$, where $S_s$ is the set of places of $\gamma_s$ and $C(s) = \{s^1, \ldots, s^{m_s}\}$ is a set of $n_s$ new places (copies of $s$);
- $T'_s := \cup_{t \in \star s} C(t)$, where for each $t \in \star s$, $C(t) = \{t_{A,B}|A, B \subseteq C(s) \wedge |A| = W(s, t) \wedge |B| = W(t, s)\}$ is a set of new transitions (copies of $t$);
- $F'_s := F_1 \cup F_2$, where:
  \begin{align*}
  F_1 &= \{(s', t_{A,B})|t_{A,B} \in C(\star s^s), (s', t) \in F\} \cup \\
  \quad &\{(t_{A,B}, s')|t_{A,B} \in C(\star s^s), (t, s') \in F\}, \\
  F_2 &= \{(s', t_{A,B})|t_{A,B} \in C(\star s^s), s' \in A\} \cup \\
  \quad &\{(t_{A,B}, s')|t_{A,B} \in C(\star s^s), s' \in B\},
  \end{align*}
and $C(\star s^s)$ is the union-extension of $C(\cdot)$ to the set $\star s^s$;
- $W'_s$ is given by:
  \begin{align*}
  W'_s(s', t_{A,B}) &= W(s', t) \text{ for all } (s', t_{A,B}) \in F_1, \\
  W'_s(t_{A,B}, s') &= W(t, s') \text{ for all } (t_{A,B}, s') \in F_1, \\
  W'_s(f) &= 1 \text{ for all } f \in F_2;
  \end{align*}
- $M'_{s}|_{C(s)}$ is an arbitrary but fixed uniformly distributed marking over $C(s)$ and $s$-compatible with $M_0|_{s}$; $M'_s(s') := M_0(s')$ for all $s' \in S_s - \{s\}$;
- $l'_s(t_{A,B}) = l(t)$ for all $t_{A,B} \in T'_s$.

This transformation is exemplified in Example 2.1.1. It is clear that the arcs of the net yielded by it have the weight 0 or 1.

Theorem 3.1 ([10], [18])

The net $\gamma'$ yielded by Transformation-A on the input $\gamma$ satisfies $\gamma \approx P \gamma'$.

Proof In the view of Corollary 2.2.2 we have to prove that $\gamma_s \approx_{mP} \gamma'_s$, for all $s$ with $n_s > 1$. To prove this it is enough to show that:
- any initial occurrence net of $(\gamma_s + M)$ is isomorphic with any initial occurrence net of $(\gamma'_s + M)$,
- any elementary occurrence net of $(\gamma_s + M)$ associated to a transition $t$ is isomorphic with any elementary occurrence net of $(\gamma'_s + M)$ associated to any copy of $t$, where $M$ is an arbitrary marking on the connecting places. But these facts follows directly from the definition of $\gamma'_s$. □

Transformation-B: Let $\gamma = (\Sigma, M_0, l)$ be a net such that $W(f) = 1$ for all $f \in F$. Let $m_s = M_0(s)$ for all $s \in S$. For each $s$ with $m_s > 1$ replace the subnet $\gamma_s$ of $\gamma$ generated by $T_s = \{t \in T|\star s^s\}$, by the net $\gamma'_s$ defined as follows:
- $\gamma'_s = (\Sigma'_s, M'_s, l'_s)$, $\Sigma'_s = (S'_s, T'_s, F'_s, W'_s)$;
- $S'_s = (S_s - \{s\}) \cup C(s)$, where $S_s$ is the set of places of $\gamma_s$ and $C(s) = \{s^1, \ldots, s^{m_s}\}$ is a set of new places (copies of $s$);
- $T'_s := \cup_{t \in T_s} C(t)$, where for each $t \in T_s$, $C(t) = \{t^1, \ldots, t^{m_s}\}$ is a set of new transitions (copies of $t$);
- $F'_s := F_1 \cup F_2$, where:
  \begin{align*}
  F_1 &= \{(s', t^i)|t^i \in T'_s, s' \in S_s - \{s\}, (s', t) \in F\} \cup \\
  \quad &\{(t^i, s')|t^i \in T'_s, s' \in S_s - \{s\}, (t, s') \in F\}, \\
  F_2 &= \{(s', t')|t^i \in T'_s, s' \in C(s), (s, t) \in F\} \cup \\
  \quad &\{(t^i, s')|t^i \in T'_s, s' \in C(s), (t, s) \in F\};
  \end{align*}
- $W'_{s}(f) = 1$ for all $f \in F_{s}$;
- $M'_{s}(s^{i}) = 1$ for all $1 \leq i \leq m_{s}$; $M'_{s}(s') := M_{0}(s')$ for all $s' \in S_{s} - \{s\}$;
- $l'_{s}(t^{i}) = l(t)$ for all $t^{i} \in T'_{s}$.

This transformation is exemplified in Example 3.1 for the case of the place $s_{1}$. Clearly, the net yielded by Transformation-B is normalized.

\begin{figure}[h]
\centering
\includegraphics[width=0.8\textwidth]{figure3_1.png}
\caption{Figure 3.1}
\end{figure}

**Theorem 3.2 ([10])**

The net $\gamma'$ yielded by Transformation-B on the input $\gamma$ satisfies $\gamma \approx_{P} \gamma'$.

**Proof** A similar argument as in the proof of the above theorem works in this case too: any elementary occurrence net of $\gamma_{s}$ whose event is labelled by $a$ is isomorphic to any elementary occurrence net of $\gamma'_{s}$ whose event is labelled by $a$ too. \(\square\)

The above two theorems assure the correctness of the Pelz’s algorithm.

In [15] a systematic investigation of graph theoretic properties of Petri nets within the framework of language theory was initiated. In other words, various subclasses of Petri nets were introduced by imposing various restrictions on the in- and out-degree of nodes in the graph of the underlying net structure. Further these restrictions were refined in [17] by considering $(n, m)$-transition restricted Petri nets as being Petri nets for which the weight function takes values in $\{0, 1\}$ and $1 \leq |t| \leq n$ and $1 \leq |t^{*}| \leq m$ for all transitions $t$. Thus, interesting hierarchies of Petri net languages was obtained, and in the case of $\lambda$-labelled Petri nets, the above normal form was improved with respect to the finite transition sequence behaviour. More precisely, it was shown that every $\lambda$-labelled Petri net is equivalent to a $(2, 2)$-transition restricted net (with respect to the finite transition sequence behaviour). This result was extended in [19] by showing that this new normal form, called the **super-normal form**, preserves the partial words but not the processes of Petri nets. We will give here short proofs of these results. Let us recall first the basic transformations.

Let $\gamma$ be a $\lambda$-labelled net. In the view of the Pelz’s theorem we may assume that $\gamma$ is normalized. Now we have to do two basic transformations on $\gamma$.

**Transformation-C:** Let $\gamma$ be a normalized net. For each transition $t$ of $\gamma$ such that $|t| = 0$ or $|t^{*}| = 0$ replace the subnet $\gamma_{t}$ (generated by $t$) by the net $\gamma'_{t} = (\Sigma_{t}', M'_{t}, l'_{t})$ as follows:
- if $\Sigma_t$ is the net in Figure 3.2(a) then $\Sigma'_t$ is the net in Figure 3.2(b);
- if $\Sigma_t$ is the net in Figure 3.2(c) then $\Sigma'_t$ is the net in Figure 3.2(d);
- the initial marking of $\gamma'_t$ on the places $s_1, \ldots, s_k$ is the same as the initial marking of $\gamma$ on these places;
- the labeling is that specified in diagrams.

![Diagram](a)

![Diagram](b)

![Diagram](c)

![Diagram](d)

**Figure 3.2**

It is clear that the net $\gamma'$ yielded by Transformation-C is normalized and satisfies $|t| \geq 1$ and $|t^*| \geq 1$ for all transitions $t$.

**Theorem 3.3** ([19])
The net $\gamma'$ yielded by Transformation-C on the input $\gamma$ satisfies $\gamma \approx_{PW} \gamma'$.

**Proof** In the view of Corollary 2.2.2 we have to prove that $\gamma_t \approx_{mPW} \gamma'_t$ for all $t$ with the property $|t| = 0$ or $|t^*| = 0$. But this job is as simple as minute it is, and therefore it is omitted (for the nets in Figure 3.2(a)(b) we may use Proposition 2.2.2).

**Transformation-D:** Let $\gamma$ be a normalized net $\gamma$ satisfying $|t| \geq 1$ and $|t^*| \geq 1$ for all $t \in T$. For each transition $t \in T$ such that $|t| \geq 3$ or $|t^*| \geq 3$ replace the subnet $\Sigma_t$ by the net $\Sigma'_t$ as given in Figure 3.3, but with the next remarks:
- in the case $n = 1$ or $n = 2$ the places $s_1$ or $s_1$ and $s_2$ respectively are directly connected to $t^n$;
- in the case $m = 1$ or $m = 2$ the only successors of $t^n$ are $s_{n+1}$ or $s_{n+1}$ and $s_{n+2}$ respectively

(in Figure 3.3 it was assumed that $t = \{s_1, \ldots, s_n\}$, $t^* = \{s_{n+1}, \ldots, s_{n+m}\}$, $s'_1, \ldots, s'_{n+m-3}$ are new places, and $t^1, \ldots, t^{n+m-2}$ are new transitions. Moreover, it was assumed that $t \cap t^* = \emptyset$; the case $t \cap t^* \neq \emptyset$ case can be easily imagined).

![Diagram](a')

![Diagram](b')

![Diagram](c')

![Diagram](d')

**Figure 3.3**
It is clear that the net $\gamma'$ yielded by Transformation-D is normalized and $(2, 2)$-transition restricted, and the proof of the next theorem can be easily completed.

**Theorem 3.4 ([19])**

The net $\gamma'$ yielded by Transformation-D on the input $\gamma$ satisfies $\gamma \approx_{PW} \gamma'$.

**Conclusions**

We have proposed a replacement technique of Petri nets and some congruences preserving the process and partial word equivalence between the original net and the net yielded by replacement. The "power" of these congruences have been proved by reporting them to different transformations of Petri nets known from literature.

**References**


