

# 安定領域はレムニスケート

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## 1. Introduction

In this paper, we shall consider a periodic system with piecewise constant argument

$$\dot{x}(t) = p(t) \begin{pmatrix} \alpha & -\beta \\ \beta & \alpha \end{pmatrix} x([t]), \tag{1}$$

where  $[ \cdot ]$  denotes the greatest integer function and  $\dot{x}(t)$  means the right-hand derivative of  $x(t)$  for each integer  $t$ . In what follows, we assume the conditions:

- (i)  $p(t)$  is continuous and  $\omega$ -periodic on  $(-\infty, \infty)$ .
- (ii)  $p(t) = p(\omega/2 - t) = -p(\omega/2 + t)$  for all  $t$ .
- (iii)  $\omega = 4/k$  for some positive integer  $k$ .
- (iv)  $\alpha^2 + \beta^2 > 0$ .

Several authors ([1-3]) discussed asymptotic stability for linear delay systems with constant coefficients. For instance ([1]), the zero solution of

$$\dot{x}(t) = \rho \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} x(t - \tau)$$

is asymptotically stable if and only if

$$-(\pi/2 - |\theta|) < \rho\tau < 0.$$

However, stability region for periodic delay system

$$\dot{x}(t) = p(t) \begin{pmatrix} \alpha & -\beta \\ \beta & \alpha \end{pmatrix} x(t - \tau) \tag{2}$$

is yet unknown.

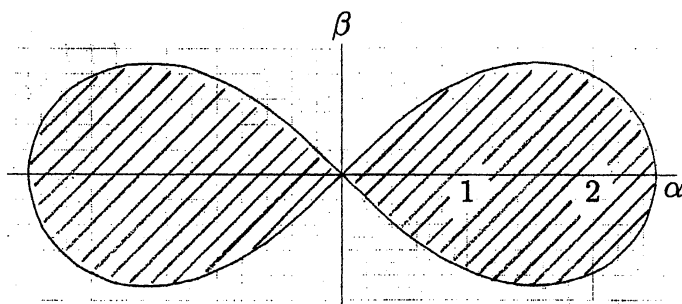
For the scalar case, we can find only one result by R. Miyazaki ([2]) which deals with the periodic delay equation

$$\dot{x}(t) = p(t)x(t - \tau), \tag{2}'$$

where  $p(t)$  satisfies the conditions (a) and (b). Roughly speaking, the zero solution of (2)' is uniformly asymptotically stable if  $\tau$  is a small positive number. We would like to

obtain the stability region for (2). However, this problem is beyond us at the present time.

Recently, using computer, we have made a simulation to find the behavior of solutions for (2). For instance, in the case of  $p(t) = \sin(\pi t)$  and  $\tau = 1/2$ , it seems that stability region for (2) is the interior of lemniscate:  $(\alpha^2 + \beta^2)^2 = 2a^2(\alpha^2 - \beta^2)$  with  $a \doteq 1.7705$ . So, we have the following conjecture.



**Conjecture.** *The system (2) is uniformly asymptotically stable if and only if the point  $(\alpha, \beta)$  is contained in the interior of some lemniscate.*

This conjecture is still open. But, for the system (1) which is similar to (2) in some sense, we can show the following result corresponding the conjecture.

**Theorem 1.** *Let  $c = \int_0^1 p(t)dt$ , and assume that  $\int_0^\omega p(t)dt = 0$  and  $k \neq 0 \pmod{4}$ . Then the system (1) is uniformly asymptotically stable if and only if*

$$0 < (\alpha^2 + \beta^2)^2 < \frac{2}{c^2} (\alpha^2 - \beta^2).$$

## 2. Main results

Let  $r = \sqrt{\alpha^2 + \beta^2}$ . Then there exists only one  $\theta \in (-\pi, \pi]$  such that

$$\begin{pmatrix} \alpha & -\beta \\ \beta & \alpha \end{pmatrix} = r \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}.$$

So, we put

$$R(\theta) = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

and  $q(t) = rp(t)$ . Then the system (1) is reduced to

$$\dot{\mathbf{x}}(t) = q(t)R(\theta)\mathbf{x}([t]), \tag{3}$$

where  $q(t)$  satisfies the same properties as  $p(t)$ :

(a)'  $q(t)$  is continuous and  $\omega$ -periodic on  $(-\infty, \infty)$ .

(b)'  $q(t) = q(\omega/2 - t) = -q(\omega/2 + t)$  for all  $t$ .

The properties (a) through (c) ensure the following lemma.

**Lemma 1.** Assume  $\int_0^\omega q(t)dt = 0$ . If  $k$  is odd, then

$$\int_0^1 q(t)dt = \int_1^2 q(t)dt = -\int_2^3 q(t)dt = -\int_3^4 q(t)dt.$$

If  $k = 4m + 2$  for some integer  $m \geq 0$ , then

$$\int_0^1 q(t)dt = -\int_1^2 q(t)dt.$$

**Proof.** Let  $k = 4m \pm 1$  for some integer  $m$ . Since  $\omega = 4/k$ , we have

$$m\omega \pm \omega/4 = 1.$$

Hence periodicity of  $q(t)$  implies

$$\int_0^1 q(t)dt = \int_0^{m\omega} q(t)dt + \int_{m\omega}^{m\omega \pm \omega/4} q(t)dt = \int_0^{\pm\omega/4} q(t)dt,$$

and also

$$\int_0^2 q(t)dt = \int_0^{\pm\omega/2} q(t)dt.$$

It follows from (b)' that

$$\int_0^{\pm\omega/2} q(t)dt = 2 \int_0^{\pm\omega/4} q(t)dt.$$

This implies

$$\int_0^2 q(t)dt = 2 \int_0^1 q(t)dt.$$

Therefore we arrive at

$$\int_0^1 q(t)dt = \int_1^2 q(t)dt.$$

On the other hand, if  $k = 4m + 2$ , then  $2 = (2m + 1)\omega$  and so

$$\int_0^2 q(t)dt = \int_0^{2(m+1)\omega} q(t)dt = 0,$$

which implies

$$\int_1^2 q(t)dt = -\int_0^1 q(t)dt.$$

We can also prove the other equalities.  $\square$

Let  $\mathbf{x}(t)$  be a solution of (3). It is convenient to denote  $\|\mathbf{x}(n)\|$  by  $\rho_n$  for each integer  $n$ . There exists only one  $\varphi \in [0, 2\pi)$  such that

$$\mathbf{x}(n) = R(\varphi) \begin{pmatrix} \rho_n \\ 0 \end{pmatrix}.$$

So, we put  $\mathbf{u}_n(t) = R(-(\theta + \varphi))\mathbf{x}(t)$  for every  $n$ . Then  $\mathbf{u}_n(t)$  satisfies

$$\dot{\mathbf{u}}_n(t) = q(t) \begin{pmatrix} \rho_n \\ 0 \end{pmatrix}, \quad \mathbf{u}_n(n) = \rho_n \begin{pmatrix} \cos \theta \\ -\sin \theta \end{pmatrix}$$

for  $t \in [n, n+1)$ . Hence it follows that

$$\mathbf{u}_n(t) = \rho_n \begin{pmatrix} \cos \theta + \int_n^t q(s) ds \\ -\sin \theta \end{pmatrix} \quad (4)$$

for  $t \in [n, n+1)$ . Now we give a result for the case  $k \neq 0 \pmod{4}$ .

**Proposition 1.** *Let  $\gamma = \int_0^1 q(t) dt$ , and assume  $\int_0^\omega q(t) dt = 0$  and  $k \neq 0 \pmod{4}$ . Then the system (3) is uniformly asymptotically stable if and only if*

$$0 < |\gamma| < \sqrt{2 \cos 2\theta}. \quad (5)$$

**Proof.** First, we consider the case of  $k = 4m \pm 1$ . It follows from (4) that

$$\rho_{n+1}^2 = \rho_n^2 \left\{ 1 + 2 \cos \theta \int_n^{n+1} q(s) ds + \left( \int_n^{n+1} q(s) ds \right)^2 \right\}.$$

Lemma 1 implies

$$\int_n^{n+1} q(s) ds = \begin{cases} \gamma & \text{if } n = 0, 1 \pmod{4} \\ -\gamma & \text{if } n = 2, 3 \pmod{4}. \end{cases}$$

Hence we have

$$\rho_{n+1}^2 = \begin{cases} \rho_n^2 (1 + 2\gamma \cos \theta + \gamma^2) & \text{if } n = 0, 1 \pmod{4} \\ \rho_n^2 (1 - 2\gamma \cos \theta + \gamma^2) & \text{if } n = 2, 3 \pmod{4}, \end{cases}$$

and so

$$\begin{aligned} \rho_{n+4}^2 &= \rho_n^2 (1 + 2\gamma \cos \theta + \gamma^2)^2 (1 - 2\gamma \cos \theta + \gamma^2)^2 \\ &= \rho_n^2 (1 - 2\gamma^2 \cos 2\theta + \gamma^4)^2 \end{aligned}$$

for each  $n$ . Thus the ratio  $\rho_{n+4}/\rho_n$  is independent of  $\mathbf{x}(t)$  and  $n$ . It is easy to see that  $\rho_{n+4}/\rho_n < 1$  if and only if

$$\gamma \neq 0 \quad \text{and} \quad \gamma^2 < 2 \cos 2\theta,$$

which is equivalent to (5). Next consider the case of  $k = 4m + 2$ . Then we have

$$\begin{aligned}\rho_{n+2}^2 &= \rho_n^2(1 + 2\gamma \cos \theta + \gamma^2)(1 - 2\gamma \cos \theta + \gamma^2) \\ &= \rho_n^2(1 - 2\gamma^2 \cos 2\theta + \gamma^4).\end{aligned}$$

This shows that  $\rho_{n+2}/\rho_n < 1$  if and only if (5) holds. Thus, if (5) holds, then  $\rho_n$  tends to 0 as  $n \rightarrow \infty$ , whenever  $k \neq 0 \pmod{4}$ . Since

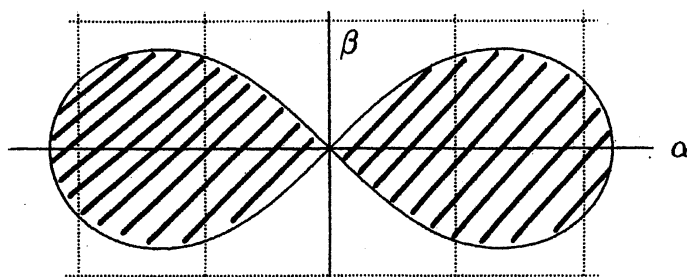
$$\sup_{t \in [n, n+1]} \|\mathbf{x}(t)\| = \sup_{t \in [n, n+1]} \|\mathbf{u}_n(t)\| \leq \max\{\rho_n, \rho_{n+1}\},$$

we can conclude that if (5) holds, then the system (3) is uniformly asymptotically stable. It is easy to show that if the system (3) is uniformly asymptotically stable then  $\rho_n$  tends to 0 as  $n \rightarrow \infty$  and hence (5) holds. Thus the proof is now completed.  $\square$

The following theorem is an immediate consequence of Proposition 1.

**Theorem 1.** *Let  $c = \int_0^1 p(t)dt$ , and assume that  $\int_0^\omega p(t)dt = 0$  and  $k \neq 0 \pmod{4}$ . Then the system (1) is uniformly asymptotically stable if and only if*

$$0 < (\alpha^2 + \beta^2)^2 < \frac{2}{c^2}(\alpha^2 - \beta^2).$$



**Proof.** Since  $q(t) = rp(t)$ , it is trivial that (5) is equivalent to

$$0 < r^2 c^2 < 2 \cos 2\theta$$

or

$$0 < r^4 < \frac{2}{c^2} r^2 \cos 2\theta.$$

Therefore we can arrive at the conclusion of this theorem.  $\square$

For the case of  $\int_0^\omega p(t)dt = 0$  but  $k = 0 \pmod{4}$ , we obtain the following result.

**Theorem 2.** *Assume that  $\int_0^\omega p(t)dt = 0$  and  $k = 4m$  for some positive integer  $m$ . Then every solution of (1) is  $\omega$ -periodic for  $t \geq N$ , where  $N$  denotes the minimal integer not less than initial time  $t_0$  of the solution.*

**Proof.** Since  $\int_0^\omega p(t) = 0$ , periodicity of  $p(t)$  implies

$$\int_t^{t+\omega} p(s) ds = 0,$$

so that  $q(t)$  also satisfies

$$\int_t^{t+\omega} q(s) ds = 0.$$

Now let  $\mathbf{x}(t)$  be a solution of (1). Then it follows from (4) that

$$\mathbf{u}_n(t + \omega) = \mathbf{u}_n(t)$$

and hence

$$\mathbf{x}(t + \omega) = \mathbf{x}(t), \quad (6)$$

whenever  $n \leq t < t + \omega \leq n + 1$ . On the other hand, since  $k = 4m$ ,  $\omega$  satisfies  $m\omega = 1$ . This, together with (6), implies

$$\mathbf{x}(n) = \mathbf{x}(N) \quad \text{or} \quad \rho_n = \rho_N$$

for any integer  $n > N$ . Hence for each  $\mathbf{u}_n(t)$ ,  $\mathbf{u}(t) = \mathbf{u}_n(n + t)$  is unique solution on  $[0, 1)$  of the initial value problem

$$\dot{\mathbf{u}}(t) = q(t) \begin{pmatrix} \rho_N \\ 0 \end{pmatrix}, \quad \mathbf{u}(0) = \rho_N \begin{pmatrix} \cos \theta \\ -\sin \theta \end{pmatrix},$$

which yields

$$\mathbf{u}_n(n + t) = \mathbf{u}_N(N + t)$$

and so

$$\mathbf{x}(n + t) = \mathbf{x}(N + t) \quad (7)$$

on  $[0, 1)$  for any integer  $n > N$ . Therefore (6) and (7) assert that

$$\mathbf{x}(t + \omega) = \mathbf{x}(t)$$

for all  $t \geq N$ . This completes the proof.  $\square$

## References

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