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<td>Author(s)</td>
<td>Cheng, J; Hon, Y.C.; Yamamoto, M</td>
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京都大学 学術情報リポジトリ
A CONDITIONAL STABILITY ESTIMATE FOR An INVERSE NEUMANN BOUNDARY PROBLEM

J. CHENG, Y.C. HON, AND M. YAMAMOTO

ABSTRACT. In this paper, we consider an inverse problem of determining an unknown boundary in $\mathbb{R}^2$ where a Neumann condition is imposed. A stability estimate under some a-priori assumptions on the unknown boundary and the solution of the problem is obtained. The proofs are based on using the complex extension method, an estimation of harmonic measure, and our recent stability estimation results for an inverse boundary problem of Laplace's equation on non-smooth domain.

1. INTRODUCTION

In the last decade, the technique of non-destructive testing has been developed and applied to determine the shape of a being corroded part of an unknown boundary by a suitable observation on the other part of the boundary which is accessible. This is a well known inverse boundary determination problem which arises from the engineering industry. In this paper, we consider the uniqueness and stability of an inverse problem in determining an inaccessible boundary, where a Neumann condition is imposed, from an accessible boundary, where Cauchy data in terms of electrostatic measurements can be obtained.

Let $\Omega$ be a simply connected bounded domain in $\mathbb{R}^2$ with Lipschitz continuous boundary $\partial \Omega$. Assume that $\Gamma$ and L are two distinct parts of $\partial \Omega$ which satisfy

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\( \Gamma \cap L = \emptyset \) (it is not necessary that \( \Gamma \cup L = \partial \Omega \)). Suppose that \( L \) is an accessible boundary on which we can access the boundary measurements and \( \Gamma \) is an inaccessible boundary to be determined. It is then natural to assume a Neumann condition on the unknown boundary \( \Gamma \) if it has been corroded. From [3], the model can be posed by assuming that the charge potential function \( u = u(x) \) satisfies the following Laplace's equation in \( \Omega \):

\[
\Delta u = 0, \quad x \in \Omega.
\]

On the accessible boundary \( L \), we have

\[
(1.2) \quad u = f, \quad x \in L, \\
(1.3) \quad \frac{\partial u}{\partial n} = g, \quad x \in L,
\]

where \( n \) is the outer unit normal on \( \partial \Omega \). On the inaccessible boundary \( \Gamma \), we assume

\[
(1.4) \quad \frac{\partial u}{\partial n} = 0, \quad x \in \Gamma.
\]

The inverse boundary problem is to determine \( \Gamma \) from \( f \) and \( g \).

In this paper, we will discuss the uniqueness and stability of this inverse problem. This paper is motivated by a number of recent results in the applications of non-destructive testing technique (we refer to [3], [4], [16], [21] and [22]). Particularly, an inverse problem in determining an unknown boundary was proposed in our recent work [6] where a log-type conditional stability estimate was given. The major improvement is that a zero-Dirichlet condition on the unknown boundary was imposed in [6] whereas a zero-Neumann condition was imposed in this paper. Based on the zero-Dirichlet condition, the proofs on uniqueness and conditional stability were comparatively easier to obtain by using the maximum principle for Laplace's equation without a regularity assumption placed on the domain. The zero-Neumann condition on the unknown boundary, however, is more reasonable from the view point of practical applications. This kind of inverse Neumann boundary problem was also discussed in [3] under some special assumptions. In this paper, we will discuss this inverse problem on non-smooth domain under a more general assumption. The results of uniqueness and conditional stability estimate will first be stated in the following Section 2. The detail proofs are then given in Section
3. Section 4 includes the conclusion and some remarks. It is noted here that the proofs are also extendable to three dimensional problems.

2. Main Results

Let $\Omega_1, \Omega_2$ be two simply connected bounded domains in $\mathcal{R}^2$. Assume that $0 < a < b < 1$. For arbitrarily fixed $\alpha > 0$, $\beta > 0$, $m_0 > 0$ and $m_1 > 0$, define

\[(2.1)\] $\mathcal{F} = \mathcal{F}(\alpha, \beta, m_0, m_1)$

\[= \{ F \in C[0,1] | \quad F(x) = \alpha, \quad 0 < x < a; \quad F(x) = \beta, \quad b < x < 1; \quad |F(x) - F(y)| \leq m_1|x - y|, \quad F(x) \geq m_0, \quad x, y \in [0,1] \}, \]

\[(2.2)\] $\Omega_1 = \{(x,y)| \quad 0 < x < 1, \quad 0 < y < F_1(x)\}$,

\[(2.3)\] $\Omega_2 = \{(x,y)| \quad 0 < x < 1, \quad 0 < y < F_2(x)\}$,

where $F_1, F_2 \in \mathcal{F}$. In other words, $\Gamma_j = \{(x,y) | \quad y = F_j(x), \quad a < x < b\}, j = 1, 2$ are two inaccessible boundaries given by the Lipschitz continuous functions. The a-priori information $F_1, F_2 \in \mathcal{F}$ means that the shapes of the unknown boundaries are not too complicated.

For the accessible boundary, we let

\[(2.4)\] $L = \{(x,0)| \quad a < x < b\}$.

Assume that $u_j, j = 1, 2$ satisfy

\[(2.5)\] $\Delta u_j(x,y) = 0, \quad (x,y) \in \Omega_j$,

\[(2.6)\] $\frac{\partial u_j}{\partial n}(x,y) = 0, \quad (x,y) \in \Gamma_j$,

and

\[(2.7)\] $u_j(x,0) = f_j(x), \quad \frac{\partial u_j}{\partial y}(x,0) = g_j(x), \quad c < x < d$.

The main results of this paper are stated in the following:

**Theorem 2.1.** Suppose that $g_j \neq 0, j = 1, 2$ and

\[(2.8)\] $f_1 = f_2, \quad g_1 = g_2, \quad \text{on } L$,

we then have $\Gamma_1 = \Gamma_2$. 

Remark 2.1. In [3], the assumption \( g_j \neq 0 \) was missed. However, under the zero-Neumann condition on the unknown boundary, if this assumption is not true, then the uniqueness cannot be obtained simply because \( u_j \) can be any constant.

Theorem 2.2. Let \( m_2, m_3 > 0 \), \( 0 < \alpha < 1 \) and \( M > 0 \) be arbitrarily fixed and assume that

\[
\frac{\partial f_j}{\partial x}(x_0) + |g(x_0)| \geq m_2, \quad j = 1, 2, \tag{2.9}
\]

where \( x_0 \in [a, b] \) is a fixed constant. Furthermore, assume that

\[
u_j \in C^2(\Omega_j) \cap C^1(\Omega_j), \quad ||u_j||_{C^1(\Omega_j)} \leq M, \quad j = 1, 2, \tag{2.10}
\]

and

\[
||u_j||_{C^{1+\alpha}((a,b) \times (0,m_0))} \leq m_3, \quad j = 1, 2. \tag{2.11}
\]

Then there exists constants \( C = C(m_0, m_1, m_2, m_3, \alpha, M) > 0 \) and \( 0 < \tau < 1 \) such that

\[
||F_1 - F_2||_{C[a,b]} \leq C \left[ \frac{1}{\log(\log \frac{1}{\epsilon})} \right]^\tau, \tag{2.12}
\]

where \( \epsilon = ||f_1 - f_2||_{H^1(a,b)} + ||g_1 - g_2||_{L^2(a,b)} \).

Before going to the next section on the detail proofs, we would like to give two examples to indicate that the assumptions given in Theorem 2.2 are necessary for obtaining a conditional stability estimation (2.12).

Example 2.1. Let

\[
\Omega_1 = (0, \pi) \times (0, 1),
\]

\[
u_1(x, y) = \frac{1}{n^2} [e^{-ny} + e^{-2n(1+\delta y)}] e^{nxy} \cos nx,
\]

and

\[
\Omega_2 = (0, \pi) \times (0, 1 + \delta y),
\]

\[
u_2(x, y) = \frac{1}{n^2} [e^{-ny} + e^{-2n(1+\delta y)}] e^{nxy} \cos nx.
\]

It is easy to verify that \( \nu_i(x, y) \) are harmonic functions in \( \Omega_i, i = 1, 2 \) and

\[
\frac{\partial \nu_1}{\partial x}(0, y) = \frac{\partial \nu_1}{\partial x}(\pi, y) = \frac{\partial \nu_1}{\partial y}(x, 1) = 0,
\]

\[
\frac{\partial \nu_1}{\partial x}(0, y) = \frac{\partial \nu_1}{\partial x}(\pi, y) = \frac{\partial \nu_1}{\partial y}(x, 1 + \delta y) = 0.
\]
Here the fixed boundary is \( \{(x,0)|0 < x < \pi\} \) and the remained parts are the unknown boundaries.

The distance between the two unknown boundaries is

\[
d(\Gamma_1, \Gamma_2) = \delta y,
\]

where \( \Gamma_i \) is the unknown boundary of \( \partial \Omega_i \).

The Cauchy data are

\[
\epsilon = \max_{0 < x < \pi} \{|u_1(x,0) - u_2(x,0)| + \max_{0 < x < \pi} \{|\frac{\partial u_1}{\partial y}(x,0) - \frac{\partial u_2}{\partial y}(x,0)|, \}
\]

\[
= \frac{1}{n^2}(e^{-2n} - e^{-2n(1+\delta y)}) + \frac{1}{n}(e^{-2n} - e^{-2n(1+\delta y)}).
\]

It can be shown that \( u_i \) tends to 0 when \( n \) tends to infinity. This means that \( u_i \) does not satisfy the assumption (2.9). Furthermore, if \( \delta y = \frac{1}{\ln n} \), we can obtain a double logarithmic estimation. If, however, we choose \( \delta y = \frac{1}{\ln \ln n} \), we obtain a weaker estimation.

This example indicates that the estimation can be extremely weak if the assumption in Theorem 2.2 is not imposed.

**Example 2.2.** Let \( \Omega_1 \) and \( \Omega_2 \) are the same as in Example 1. Consider the following harmonic functions

\[
u_1(x, y) = [e^{-ny} - e^{-2ny}] \cos nx,
\]

and

\[
u_2(x, y) = [e^{-ny} - e^{-2n(1+\delta y)}e^{ny}] \cos nx.
\]

The distance \( \delta y \) between the two unknown boundaries \( \Gamma_1 \) and \( \Gamma_2 \) is the same as in Example 1.

The Cauchy data are

\[
\epsilon = \max_{0 < x < \pi} \{|u_1(x,0) - u_2(x,0)| + \max_{0 < x < \pi} \{|\frac{\partial u_1}{\partial y}(x,0) - \frac{\partial u_2}{\partial y}(x,0)|, \}
\]

\[
= (e^{-2n} - e^{-2n(1+\delta y)}) + n(e^{-2n} - e^{-2n(1+\delta y)}).
\]

It is easy to check that \( ||u_i||_{C^2} \) is unbounded when \( n \) tends to infinity. Again, if \( \delta y = \frac{1}{\ln n} \), we have a double logarithmic estimation. If \( \delta y = \frac{1}{\ln \ln n} \), a weaker estimation can be obtained.
3. PROOFS OF THE MAIN RESULTS

3.1. Some Lemmata. We need the following lemmata:

Lemma 3.1. Suppose that \((x_0, F_1(x_0)) \in \overline{\Gamma}_1\). Then there exists positive constant \(C_3\) and \(0 < \beta < 1\), which are independent of \(y\), satisfying

\[
|u(x_0, y) - u_1(x_0, y)| \leq C\epsilon^\beta, \quad y \in [0, \frac{m_0}{2}].
\]

Proof. The proof follows from the results given in Payne [25].

Now, define

\[
D = \{z = x + iy \in \mathbb{C} | |z| < R, |\arg z| < \theta\},
\]

and

\[
l = \{z = x_1 | x_1 \in (\rho_1, \rho_2)\} \subset D
\]

Definition 3.1. \(\psi(z)\) is called a harmonic measure for \(D\) and \(l\) if it satisfies

\[
\Delta \psi = 0, \quad z \in D \setminus l,
\]

\[
\psi = 0, \quad z \in \partial D,
\]

\[
\psi = 1, \quad z \in l.
\]

For the existence and uniqueness of this harmonic measure, we refer to Kellog's book [17]. By using the same method in [11], we can prove that \(\psi \in C^\nu(\overline{D})\) \((0 < \nu < 1)\).

Lemma 3.2. For the harmonic measure \(\psi\) for \(D\) and \(l\), we have the following estimation

\[
\psi(x) \geq C((x_2)^{\frac{1}{5}} - \frac{\rho_2}{R}^\frac{7}{5}), \quad x \in (\rho_2, R),
\]

where \(C\) is a constant which is independent of \(x\).

Moreover, if \(\rho_1\) is sufficiently small, the constant \(C\) can be independent of \(\rho_1\) and \(\rho_2\).

Proof. The proof can be found in [9].

\[\square\]
By using the estimation for the harmonic measure, we can have the following conditional stability estimation for a holomorphic function in $D$.

**Lemma 3.3.** Suppose that $v = v(z)$ is a holomorphic function in $D$ and let $\varepsilon = \max_{x \in [\rho_1, \rho_2]} |v(x)|$. If $|v(z)| \leq M_1$, $z \in D$, then we have

$$|v(x)| \leq M_1 \left( \frac{\varepsilon}{M_1} \right)^{C \left( \frac{\rho_2^2}{\rho_1^2} - \frac{\rho_1^2}{\rho_2^2} \right)}, \quad x \in [\rho_2, R].$$

**Proof.** The proof can be found in [9].

We now state some results concerning a Neumann problem for Laplace's equation on a Lipschitz domain.

Let $D$ be a Lipschitz domain in $\mathbb{R}^2$ with boundary $\partial D$. Consider the following Neumann problem

$$\begin{align*}
\Delta w(x, y) &= 0, \quad \text{in } D, \\
\frac{\partial w}{\partial n} &= h, \quad \text{on } \partial D,
\end{align*}$$

where $\int_{\partial D} h d\sigma = 0$ and (3.4) is satisfied in a generalized sense (refer to [15]).

**Lemma 3.4.** Suppose that $h \in L^2(\partial D)$ and $\int_{\partial D} h d\sigma = 0$. There exists a unique harmonic function $w$ such that

(i) In a generalized sense, $w$ satisfies

$$\frac{\partial w}{\partial n} = h, \quad \text{on } \partial D.$$  

(ii) $w$ can be expressed as

$$w(x, y) = \int_{\partial D} \ln[(x - \xi_1)^2 + (y - \xi_2)^2]q(\xi_1, \xi_2)d\sigma(\xi),$$

where $q$ satisfies

$$\|q\|_{L^2(\partial D)} \leq C\|h\|_{L^2(\partial D)}.$$  

Here, the constant $C > 0$ depends only on the Lipschitz character of $D$.

(iii) Every solution can be expressed as

$$w(x, y) = \int_{\partial D} \ln[(x - \xi_1)^2 + (y - \xi_2)^2]q(\xi_1, \xi_2)d\sigma(\xi) + c,$$

where $c$ is a constant.

**Proof.** The proof of this lemma can be found in [15].
3.2. Proof of Theorem 2.1.

Proof. Suppose that $\Gamma_1 \neq \Gamma_2$. Without loss of generality, there is an interval $(a_1, b_1) \subset (a, b)$ such that

$$F_2(x) > F_1(x), \quad x \in (a_1, b_1),$$

and

$$F_2(a_1) = F_1(a_1), \quad F_1(b_1) = F_2(b_1).$$

Here,

$$D = \{(x, y) \in \mathbb{R}^2 | F_1(x) < y < F_2(x); \quad x \in (a_1, b_1)\}.$$

Since $f_1 = f_2$ and $g_1 = g_2$, by the uniqueness of the Cauchy problem for Laplace's equation, we have

$$u_1(x, y) = u_2(x, y), \quad (x, y) \in \Omega_1 \cap \Omega_2.$$  \hfill (3.9)

Therefore, for $x \in (a_1, b_1)$ and $0 < y < F_1(x)$, we obtain

$$\nabla u_1(x, y) = \nabla u_2(x, y).$$  \hfill (3.10)

Using the boundary condition for $u_1$ on $\Gamma_1$, we further have

$$\frac{\partial u_2}{\partial \nu} = 0, \quad \text{on} \quad \{(x, y) \in \mathbb{R}^2 | y = F_1(x), \quad x \in (a_1, b_1)\},$$  \hfill (3.11)

where $\nu$ is the unit outer normal on $D$.

By considering $u_2$ for $D$, it follows that $u_2$ is harmonic in $D$ and $\frac{\partial u_2}{\partial \nu} = 0$ for $(x, y) \in \partial D \setminus \{(a_1, F_1(a_1)), (b_1, F_2(b_1))\}$.

It can be verified that the Green's formula is also true for the non-smooth domain $D$, i.e.,

$$\int_D \Delta u_2 u_2 \, dx \, dy = - \int_D |\nabla u_2|^2 \, dx \, dy + \int_{\partial D} \frac{\partial u_2}{\partial \nu} u_2 \, d\sigma.$$  \hfill (3.12)

Therefore, we have

$$\nabla u_2(x, y) = 0, \quad (x, y) \in D.$$  \hfill (3.13)

By the unique continuation for the Laplace's equation, we have

$$\nabla u_2(x, y) = 0, \quad (x, y) \in \Omega_2,$$  \hfill (3.14)
and

\begin{equation}
(3.15) \quad g_2(x, y) = 0, \quad (x, y) \in L.
\end{equation}

This is a contradiction to the assumption \( g_j \neq 0 \). The proof is then complete. \( \square \)

3.3. Proof of Theorem 2.2.

Proof. Without loss of generality, we assume that \( |F_2(x) - F_1(x)| \) attends its maximum at \( x = x^* \in (a, b) \) and \( d = F_2(x^*) - F_1(x^*) > 0 \).

From the assumption \( F_j \in \mathcal{F} \), there is an interval \( (a_2, b_2) \subset (a, b) \) such that

\begin{equation}
(3.16) \quad F_2(x) - F_1(x) > 0, \quad x \in (a_2, b_2),
\end{equation}

and

\begin{equation}
(3.17) \quad F_2(a_2) = F_1(a_2), \quad F_2(b_2) = F_1(b_2).
\end{equation}

Let \( \eta \) be a small positive constant. Define

\begin{equation}
(3.18) \quad \mathcal{U} = \{(x, y) | F_1(x) < y < F_2(x), \ a_2 < x < b_2\},
\end{equation}

and

\begin{equation}
(3.19) \quad \mathcal{U}_\eta = \{(x, y) | F_1(x) < y < F_2(x), \ a_2 + \eta < x < b_2 - \eta\}.
\end{equation}

For \( j = 1, 2 \), denote

\begin{equation}
(3.20) \quad \gamma_j = \mathcal{U} \cap \Gamma_j,
\end{equation}

and

\begin{equation}
(3.21) \quad \gamma_j^\eta = \mathcal{U}_\eta \cap \Gamma_j.
\end{equation}

**Proposition 3.1.** The domain \( \mathcal{U}_\eta \) is a Lipschitz domain in \( \mathbb{R}^2 \) and the Lipschitz constant is less than \( \max\{1, m_1\} \).

This proposition can be obtained directly from \( \partial \mathcal{U}_\eta \) which can be expressed locally by some Lipschitz functions whose Lipschitz constants are all less than \( \max\{1, m_1\} \).

**Remark 3.1.** The domain \( \mathcal{U} \) may not be a Lipschitz domain because the points \((a_2, F_1(a_2))\) and \((b_2, F_1(b_2))\) can be cusp points.
We proceed our proof in the following three steps:

**Step 1:** Boundary value estimation for $\frac{\partial u_2}{\partial \nu}$ on $\gamma_1$. (Here $\nu$ is the unit outer normal for the domain $\mathcal{U}$ or $\mathcal{U}_\eta$).

In [10], we had proven the following results:

**Lemma 3.5.** Under the assumptions given in Theorem 2.2, there exist constants $C > 0$ and $0 < \tau_1 < 1$ which depend on $m_j$, $j = 0, 1, 2, 3$ and $M$ such that

$$|\nabla u_2 - \nabla u_1| \leq C \left(\frac{1}{\ln \frac{1}{\epsilon}}\right)^{\tau_1}.$$  

Since $\frac{\partial u_1}{\partial n} = 0$ on $\Gamma_1$, by Lemma 3.5, we have

**Lemma 3.6.** Under the assumptions given in Theorem 2.2, there exist constants $C > 0$ and $0 < \tau_1 < 1$ which depend on $m_j$, $j = 0, 1, 2, 3$ and $M$ such that

$$|\frac{\partial u_2}{\partial \nu}| \leq C \left(\frac{1}{\ln \frac{1}{\epsilon}}\right)^{\tau_1}.$$  

**Step 2:** Estimation of $d$.

Let $\delta = C \left(\frac{1}{\ln \frac{1}{\epsilon}}\right)^{\tau_1}$.

We consider the following Neumann problem for Laplace's equation in $\mathcal{U}_\eta$:

$$\Delta w = 0, \quad \text{in} \quad \mathcal{U}_\eta,$$

$$\frac{\partial w}{\partial \nu} = \frac{\partial u_2}{\partial \nu}, \quad \text{on} \quad \partial \mathcal{U}_\eta.$$  

It is obvious that $u_2$ is one the solutions for this Neumann problem.

Let $\varrho$ be a small positive parameter. Define

$$\mathcal{U}_\eta^{\varrho} = \{(x, y) \in \mathcal{U}_\eta | \text{dist}((x, y), \partial \mathcal{U}_\eta) > \varrho\}.$$  

Clearly, we have

$$|\nabla u_2(x, y)| \leq \frac{C}{\varrho} \|u_2\|_{L^2(\partial \mathcal{U}_\eta)}, \quad (x, y) \in \mathcal{U}_\eta^{\varrho},$$  

where $C > 0$ is a constant which depends on $m_1$.

Calculating $\|u_2\|_{L^2(\partial \mathcal{U}_\eta)}$, we have

$$\|u_2\|_{L^2(\partial \mathcal{U}_\eta)} \leq C_1 \delta + C_2 \eta,$$

where $C_1 > 0$ and $C_2 > 0$ are constants which depend on $m_1$ and $M$.  

From the assumptions (2.9) and (2.11), there is a positive constant $\rho$ which depends on $M$ and $m_2$ such that

\begin{equation}
|\frac{\partial u_2}{\partial x}(x_0, \rho)| + |\frac{\partial u_2}{\partial y}(x_0, \rho)| \geq \frac{m_2}{2}.
\end{equation}

We choose $\delta_1 = C_1\delta + C_2\eta$ and let $v(z) = \frac{1}{2}(\frac{\partial}{\partial x} + i\frac{\partial}{\partial y})u_2 = \partial_{\overline{z}}u_2$. It is easy to verify that $v(z)$ is a holomorphic function in $\Omega_2$ and $|v(z)| \leq M, \quad z \in \Omega_2$.

From the assumptions on $\Omega_2$, there is a positive constant $\theta$ which depends on $M$ such that

\begin{equation}
V = \{(x, y)|0 < y < r(x), a < x < b\} \subset \Omega_2,
\end{equation}

and

\begin{equation}
V_1 = \{(x, y)|r_1(x) < y < r(x), a < x < b\} \subset \mathcal{U}_\eta.
\end{equation}

Here

\begin{equation}
r(x) = \begin{cases}
tan \theta(x - x^*) + F_2(x^*) - \varrho, & x < x^*, \\
-tan \theta(x - x^*) + F_2(x^*) - \varrho, & x \geq x^*,
\end{cases}
\end{equation}

and

\begin{equation}
r_1(x) = \begin{cases}
-tan \theta(x - x^*) + F_2(x^*) - d + \varrho, & x < x^*, \\
tan \theta(x - x^*) + F_2(x^*) - d + \varrho, & x \geq x^*.
\end{cases}
\end{equation}

From Lemma 3.3, there exists a constant $\kappa$ which depends on $m_j$ and $M$ such that

\begin{equation}
|v(x, \rho)| \leq C_1\delta^{\kappa}C_2^{(d-2\rho)^\alpha} \equiv \delta_2, \quad x \in [x^* - \kappa, x^* + \kappa]
\end{equation}

where $0 < \alpha < 1$, $C_1 > 0$ and $C_2 > 0$ are constants which depend on $M$ and $m_j$.

From the results given in [10], there exist positive constants $C_3 > 0$ and $0 < \beta < 1$ which depend on $M, \kappa, \rho$ and $x_0$ such that

\begin{equation}
|v(x_0, \rho)| \leq C_3\delta^{\beta(d-2\rho)^\alpha}.
\end{equation}

From equation (3.28), we have

\begin{equation}
d \leq 2\varrho + C_4\left(\frac{1}{\ln \delta}\right)^{\tau_2},
\end{equation}

where $C_4 > 0$ and $0 < \tau_2 < 1$ are constants which depend on $m_j$ and $M$. 
Let $\eta \to 0$. It is now clear that

$$d \leq 2\rho + C_5 \left( \frac{1}{\ln[\rho \ln \frac{1}{\epsilon}]} \right)^{\tau_2}. \quad (3.36)$$

Finally, by selecting a value for $\rho$ which minimizes $2\rho + C_5 \left( \frac{1}{\ln[\rho \ln \frac{1}{\epsilon}]} \right)^{\tau_2}$, we complete the proof for the theorem. \hfill \Box

4. Conclusions

In this paper, we discuss an inverse problem in determining an unknown inaccessible boundary from given Cauchy data on the other part of the boundary. A double logarithmic conditional stability estimate is obtained. This kind of weak stability estimate is common in the studies of the ill-posedness of Cauchy problem for Laplace's equation and in particular, the highly ill-posedness in determining an unknown boundary from an incomplete boundary information of the solution. The results obtained in the paper are compatible with the results given in [1], [2], [6] and [13] except that this paper gives a most likely optimal estimate under a more general assumption.

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DEPARTMENT OF MATHEMATICS, FUDAN UNIVERSITY, SHANGHAI 200433, CHINA & DEPARTMENT OF MATHEMATICS, FACULTY OF ENGINEERING, GUNMA UNIVERSITY, KIRYU 376-8515, JAPAN

E-mail address: jcheng@math.sci.gunma-u.ac.jp & jcheng@fudan.edu.cn

DEPARTMENT OF MATHEMATICS, CITY UNIVERSITY OF HONG KONG, TAT CHEE AVENUE, KOWLOON, HONG KONG

E-mail address: maychon@cityu.edu.hk

DEPARTMENT OF MATHEMATICAL SCIENCES, UNIVERSITY OF TOKYO, 3-8-1 KOMABA, MEGURO, TOKYO 153-8914, JAPAN

E-mail address: myama@ms.u-tokyo.ac.jp