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On the Small Amplitude Solutions to the Derivative Nonlinear Schrödinger Equations in Multi-Space Dimensions

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1 Introduction

In this proceeding, we consider the initial value problem for the nonlinear Schrödinger equation with nonlinear term of derivative type, i.e.,

\[
\begin{align*}
\text{(NLS)}: \quad & i\partial_t u = -\Delta u + F(u, \bar{u}, \nabla u, \nabla \bar{u}) \\
u|_{t=0} = u_0,
\end{align*}
\]

where \( u \) is a complex valued unknown function of \((t, x) \in \mathbb{R}^1 \times \mathbb{R}^n (n \geq 2) \) and \( \bar{u} \) is the complex conjugate of \( u \). \( \Delta \) is the Laplacian in the \( n \) dimensional space and \( \nabla u = (\partial_1 u, \cdots, \partial_n u) \). The nonlinear term \( F \) is the polynomial on \( \mathbb{C}^{2+2n} \) of degree \( \rho = 2 \) or \( 3 \), i.e.,

\[
F(z_1, z_2, z_3, \cdots, z_{2+2n}) = \sum_{|\alpha| = \rho} C_\alpha z_1^{\alpha_1} z_2^{\alpha_2} z_3^{\alpha_3} \cdots z_{2+2n}^{\alpha_{2+2n}},
\]

where \( C_\alpha \in \mathbb{C} \) and \( \alpha = (\alpha_1, \cdots, \alpha_{2+2n}) \).

There are many results known about (NLS). Kenig-Ponce-Vega [11] showed the well-posedness for small initial data by applying the smoothing effects of linear solutions. Chihara [4] proved the problem for large initial data. His idea is based on the energy method through the pseudo differential operator technique. These results are shown by imposing large regularity on the initial data. (Recently, Chihara [3] has solved (NLS) under the condition \( u_0 \in H^{s,0}(\mathbb{R}^n) \) with \( s > n/2 + 3 \).)

Our concern in this work is to solve (NLS) for the initial data with small regularity. We obtain the following results. (One can see the notations in theorems just after the statements.)
Theorem 1.1 (the case $\rho = 3$) let $s > (n + 3)/2$. then, for $\phi \in H^{s,0}(\mathbb{R}^n)$ with $\|\phi\|_{s,0}$ sufficiently small, there exists a unique solution $u$ to (NLS) on $[0, T]$ ($T$ depends on $\|\phi\|_{s,0}$) such that

$$u \in C([0, T]; H^{s,0}(\mathbb{R}^n)).$$  \hspace{1cm} (1)

Theorem 1.2 (the case $\rho = 2$) Let $s > (n + 3)/2, s' > (n + 2)/2$ and $t' > 1/2$ satisfy $s > s' + t'$. Then, for $\phi \in H^{s,0}(\mathbb{R}^n) \cap H^{s',t'}(\mathbb{R}^n)$ with $\|\phi\|_{s',t}$ sufficiently small, there exists a unique solution $u$ to (NLS) on $[0, T]$ ($T$ depends on $\|\phi\|_{s',t}$) such that

$$u \in C([0, T]; H^{s,0}(\mathbb{R}^n) \cap H^{s',t'}(\mathbb{R}^n)).$$  \hspace{1cm} (2)

The solutions in Theorem 1.1 and 1.2 gain the regularity in the following sense.

Theorem 1.3 The solutions in Theorem 1.1 and 1.2 satisfy

$$\|\partial_j^{s+1/2}u\|_{L^2_{x_j}(L^2_{x_T})} < \infty \text{ for } 1 \leq j \leq n.$$  \hspace{1cm} (3)

Notations.

In the above theorems, the function spaces $L^p_{x_j}(L^r_{T,x_j})$ and $H^{\sigma,\tau}(\mathbb{R}^n)$ are defined by

$$L^p_{x_j}(L^r_{T,x_j}) = \{u; \|u\|^p_{L^p_{x_j}(L^r_{T,x_j})} = \int_{\mathbb{R}^n} \left(\int_0^T \int_{\mathbb{R}^n} |u(t, x)|^r dt dx_j\right)^{p/r} dx_j < \infty\},$$

where $\tilde{x}_j = (x_1, \cdots, x_{j-1}, x_{j+1}, \cdots, x_n)$.

$$H^{\sigma,\tau}(\mathbb{R}^n) = \{f \in S'; \|f\|_{\sigma,\tau} = \|\langle x\rangle^{\tau} \langle D\rangle^{\sigma} f\|_{L^2_x} < \infty\},$$

where $\langle x\rangle = (1 + |x|^2)^{1/2}$ and $\langle D\rangle^{\sigma} f = \mathcal{F}^{-1}\{\xi\}^{\sigma} \mathcal{F} f$ ($\mathcal{F}$ and $\mathcal{F}^{-1}$ stand for the Fourier and inverse Fourier transform, respectively). $\partial_j^\sigma f = \mathcal{F}^{-1}\{\xi_j^{\sigma-[\sigma]} \xi_j^{[\sigma]} \mathcal{F} f$. $[\sigma]$ is the largest integer which does not exceed $\sigma$. $U(t)\phi = \exp(it\Delta)\phi$ and $G(t)F = \int_0^t U(t-s)F(s)ds$.

We consider the initial value problem (NLS) by solving the integral equation:

$$u(t) = \Phi(u)(t)$$
$$\equiv U(t)u_0 - iG(t)F(u, \bar{u}, \nabla u, \nabla \bar{u}).$$  \hspace{1cm} (4)

Since the nonlinear term contains some derivatives, it causes, so called, the loss of derivative. Because of this difficulty, it is impossible to estimate the second term in (4) by the unitarity and Strichartz’ type estimates of $U(t)$ ([2], [17] and [19]). To overcome the loss of derivative, we make use of the smoothing properties of $U(t)$ and $G(t)$, i.e.,
Lemma 1.4 (Hayashi-Hirata [8]) Let $\phi \in L^2(\mathbb{R}^n)$ and $F \in L_{x_j}^1(L_{\tau x_j}^2)$, then, we have

\[ \| \partial_j^{1/2} U(\cdot) \phi \|_{L_{x_j}^2(L_{\tau x_j}^\infty)} \leq C \| \phi \|_{L^2} \tag{5} \]

\[ \| \partial_j^{1/2} G(\cdot) F \|_{L_{x_j}^\infty(L_{2})} \leq C \| F \|_{L_{x_j}^1(L_{2 x_j}^\infty)} \tag{6} \]

\[ \| \partial_j G(\cdot) F \|_{L_{x_j}^\infty(L_{2 x_j}^\infty)} \leq C \| F \|_{L_{x_j}^1(L_{2 x_j}^\infty)} \tag{7} \]

To introduce the maximal functions, we demonstrate the estimates of $\Phi(u)$ in (4). For simplicity, we consider the case $F(u, \bar{u}, \nabla u, \nabla \bar{u}) = \partial u \partial u \partial u$. Applying (6) in Lemma 1.4 to $\Phi(u)$, we can show that

\[ \| \partial_j \Phi(u) \|_{L_{x_j}^\infty(L_{2 x_j}^\infty)} \leq \| u_0 \|_{s,0} + C \| \partial_j^{s-1/2} (\partial u \partial u \partial_k u) \|_{L_{x_j}^1(L_{2 x_j}^\infty)} \]

\[ + \| \text{(some lower order derivatives)} \|_{L_{x_j}^1(L_{2 x_j}^\infty)} \tag{8} \]

Note that, to obtain the last inequality, we use Leibniz’ rule for fractional derivatives ([5] and [12]). Since, by Hölder’s inequality, we can show that

\[ \| \partial u \partial u \partial_j \partial_k u \|_{L_{x_j}^1(L_{2 x_j}^\infty)} \leq \| \partial u \|_{L_{x_j}^\infty(L_{\tau x_j}^\infty)} \| \partial u \|_{L_{x_j}^2(L_{\tau x_j}^\infty)} \| \partial_k \partial_j^{s-1/2} u \|_{L_{x_k}^\infty(L_{x_k}^\infty)} \tag{9} \]

we need to estimate $\| \partial \Phi(u) \|_{L_{x_j}^2(L_{\tau x_j}^\infty)}$ in order to complete the contraction mapping principle.

\[ \| \partial \Phi(u) \|_{L_{x_j}^2(L_{\tau x_j}^\infty)} \leq \| U(\cdot) \partial u_0 \|_{L_{x_j}^2(L_{\tau x_j}^\infty)} + \| G(\cdot) \partial F \|_{L_{x_j}^2(L_{\tau x_j}^\infty)} \tag{10} \]

Hence, it is important to control the $L_{x_j}^2(L_{\tau x_j}^\infty)$-norm of maximal functions for $U(t) \partial u_0$ and $G(t) \partial F$, where we call $\| U(\cdot) \phi(x) \|_{L_{x_j}^\infty(L_{\tau x_j}^\infty)}$ and $\| G(\cdot) F(x) \|_{L_{x_j}^\infty}$ the maximal functions for $U(t) \phi$ and $G(t) F$, respectively. In the proof of Theorem 1.1 and 1.2, the estimates of maximal functions play an important role to determine the regularity of $u_0$.

Remark 1.1. When the nonlinear term is quadratic, we need to estimate the weighted $L_{x_j}^2(L_{\tau x_j}^\infty)$-norm of maximal functions, i.e., $\| \langle x \rangle^\tau U(\cdot) \phi \|_{L_{x_j}^2(L_{\tau x_j}^\infty)}$ and $\| \langle x \rangle^\tau G(\cdot) \phi \|_{L_{x_j}^2(L_{\tau x_j}^\infty)}$ for $\tau > 1/2$.

Remark 1.2. We are not allowed to estimate $\| \partial_k \partial_j^{s-1/2} u \|_{L_{x_k}^\infty(L_{\tau x_k}^\infty)}$ in (9) so that

\[ \| \partial_k \partial_j^{s-1/2} u \|_{L_{x_k}^\infty(L_{\tau x_k}^\infty)} \leq C T^S \| \partial_k \partial_j^{s-1/2} u \|_{L_{x_k}^\infty(L_{\tau x_k}^\infty)} \]
for some $r > 2$, since we want to use (7) in Lemma 1.4. This is the reason we need to impose the smallness on $u_0$.

We shall introduce the statements about the estimates of maximal functions in the forthcoming section.

2 Estimates of Maximal Functions

In this section, we introduce some inequalities concerned with the maximal functions and the outline of the proofs. There has been several kinds of estimates for maximal functions (see [14], [15] and [18]). Our main result is

**Theorem 2.1** Let $n/2 < \sigma$ and $0 < T < 1$. Then, for $\phi \in H^{\sigma,0}(\mathbb{R}^n)$, we have

\[ \|U(\cdot)\phi\|_{L^2_{x_j}(T,x_j)} \leq C\|\phi\|_{\sigma,0}. \]  

(11)

In addition, let $n/2 < \sigma' < \sigma$ and $1/2 < \tau < 1$. Then, we have

\[ \|\langle x\rangle^\tau U(\cdot)\phi\|_{L^2_{x_j}(T,x_j)} \leq C\|\phi\|_{\sigma',\tau} + CT^{1/2}\|\phi\|_{\sigma+\tau,0}. \]  

(12)

As a corollary of Theorem 2.1, we obtain

**Corollary 2.2** Under the same conditions as in Theorem 2.1, we have

\[ \|G(\cdot)F\|_{L^2_{x_j}(T,x_j)} \leq C\|F\|_{L^1_{x_j}(L^\infty,T)}, \]  

(13)

\[ \|\langle x\rangle^\tau G(\cdot)F\|_{L^2_{x_j}(T,x_j)} \leq C\|F\|_{L^1_{x_j}(L^\infty,T)} + CT^{1/2}\sup_{1 \leq k \leq n}\|\delta_k^{\tau-1/2}F\|_{L^1_{x_j}(L^2_{T,x_j})}. \]  

(14)

To prove Theorem 2.1, we need several lemmas.

**Lemma 2.3** Let $\sigma > n/2$. Then, we have

\[ \|\langle D\rangle^{-2\sigma}\int_0^T U(\cdot - s)F(s)ds\|_{L^2_{x_j}(T,x_j)} \leq C\|F\|_{L^2_{x_j}(L^1_{T,x_j})}. \]  

(15)

Therefore, it follows that

\[ \|\langle D\rangle^{-\sigma}\int_0^T U(-s)F(s)ds\|_{L^2_{x_j}} \leq C\|F\|_{L^2_{x_j}(L^1_{T,x_j})}. \]  

(16)
**Proof of Lemma 2.3.** Note that the integral kernel of \( \langle D \rangle^{-2\sigma}U(t-s) \) is
\[
K(t-s, x-y) = (2\pi)^{-n} \int \langle \xi \rangle^{-2\sigma} \exp \left( -i(t-s)\xi^2 + i(x-y) \cdot \xi \right) d\xi.
\]
Since \( 2\sigma > n \), there exists no singularity at \( t=s \) and we have
\[
|K(t-s, x-y)| \leq C|x-y|^{-2\sigma}.
\]
Hence, by Young's inequality, we obtain (15).

We next prove (16). By (15), it is easy to show that
\[
\|\langle D \rangle^{-\sigma} \int_0^T U(-s)F(s)ds\|_{L^2_x}^2
= \left| \int_0^T \langle D \rangle^{-\sigma} \int_0^T U(t-s)F(s)ds dt \right|
\leq C\|F\|_{L^2_{xj}}^2.
\]
This completes the proof of Lemma 2.3. £

To prove Theorem 2.1 (12), we use the smoothing properties of \( U(t) \) and \( G(t) \). One can see the one space dimensional version of the smoothing properties in [1]. The \( n \) space dimensional version is

**Lemma 2.4** Let \( 2 \leq p < \infty \). Then, we have
\[
\|\partial_j^{1/2-1/p} U(\cdot)\phi\|_{L^2_{xj}(T,x_j)} \leq CT^{1/p}\|\phi\|_{L^2_x}, \quad (17)
\]
\[
\|\partial_j^{1-1/p} G(\cdot)F\|_{L^2_{xj}(T,x_j)} \leq CT^{1/p}\|F\|_{L^2_{xj}(T,x_j)}, \quad (18)
\]

**proof of Lemma 2.4.** The results follow from Stein’s interpolation theorem and \( L^p \)-boundedness of the Hilbert transform. £

Now we start to show the outline of the proof for Theorem 2.1.

**Proof of Theorem 2.1.** We first prove (11) by the duality argument. Applying Lemma 2.3 (16), we have
\[
\int_0^T \langle D \rangle^{-\sigma}U(s)\phi ds
= \left( \langle D \rangle^{-\sigma} \int_0^T U(-s)F(s)ds, \phi \right)
\leq \|\langle D \rangle^{-\sigma} \int_0^T U(-s)F(s)ds\|_{L^2_x}\|\phi\|_{L^2_x}
\leq C\|F\|_{L^2_{xj}(T,x_j)}\|\phi\|_{L^2_x}.
\]
Hence, we obtain (11). We next prove (12). Since

\[ \langle x \rangle^\tau U(t) \phi = U(t) \langle x \rangle^\tau \phi + iG(t)[\langle x \rangle^\tau, -\Delta]U(\cdot)\phi, \]

it follows from (11) that

\[
\|\langle x \rangle^\tau U(\cdot)\phi\|_{L^2_{\tau,x_j}(L^\infty_{\tau,x_j})} \leq C\|\phi\|_{\sigma',\tau} + CT^{1/2}\sup_k \|\langle x \rangle^{-(1-\tau)} \partial_k^{\sigma+1}U(\cdot)\phi\|_{L^2_{\tau,x}} \\
\leq C\|\phi\|_{\sigma',\tau} + CT^{1/2}\sup_k \|\langle x \rangle^{-(1-\tau)} \partial_k^{\sigma+1}U(\cdot)\phi\|_{L^2_{\tau,x}} \\
\leq C\|\phi\|_{\sigma',\tau} + CT^{1/2}\sup_k \|\partial_k^{\sigma+1}U(\cdot)\phi\|_{L^2_{\tau,x}}.
\]

where \(1/2 = 1/p + (1 - \tau - \epsilon)\) for some \(\epsilon > 0\). Applying Lemma 2.4 (17) to the second term in RHS of (19), we obtain Theorem 2.1. □

References


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