Title
A Note on the Chain Entanglement in Concentrated Polymer Solutions (Commemoration Issue Dedicated to Professor Waichiro Tsuji On the Occasion of his Retirement)

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A Note on the Chain Entanglement in Concentrated Polymer Solutions

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A crude form of the relaxation spectrum for concentrated polymer solutions is presented, which is compatible, though not quantitatively, with recent experimental results of the steady-shear viscosity and compliance.

INTRODUCTION

This is an English version of our old note which was published in Japanese some years ago.1) Not a few experimental results have been accumulated in our laboratory since then, and we now conceive that in the fully entangled state of polymers, the steady-shear compliance $J_0^{\infty}$ is proportional to the inverse cubic power of polymer weight concentration $c$ rather than the inverse square power.2,3) Thus, the following analysis which is based on the inverse square dependence of $J_0^{\infty}$ on $c$ has to be modified at least in this respect. Nevertheless, we decided to present this note in its original form, hoping that it still might have some value for elucidating a gross structure of the relaxation spectrum of polymer concentrates. It is one of our purposes to show that the apparently complicated dependence of $J_0^{\infty}$ on $c$ as illustrated in Fig. 2 is compatible with a very simple combination of the wedge-type and the box-type spectra for the relaxation modes.

STEADY-SHEAR VISCOSITY AND COMPLIANCE

The slow relaxation properties of polymer concentrates may be characterized in terms of two parameters, the steady-shear viscosity $\eta$ and the steady-shear compliance $J_0^{\infty}$. As for the former, it has long been recognized that***

\[ \eta = A M \quad \text{for} \quad M \leq M_e \]  
\[ \eta = B M^{3.5} \quad \text{for} \quad M > M_e \]

where $M$ is the molecular weight of the polymer, and $A$, $B$, and $M_e$ are constants determined by the polymer concentration $c$.4) The above two equations can be built in a simple two-term equation

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*** Rigorously speaking, $\eta$ should be regarded as the viscosity of the state of a constant friction coefficient $\xi$. 

(464)
\[ \eta = AM + BM^{3.5} \]  
(2)

The big difference between two exponents, 1 and 3.5, assures a sharp transition from the behavior of Eq. (1a) to that of Eq. (1b) in agreement with experimental results. We can always locate in the double logarithmic plot of \( \eta \) against \( M \) a critical molecular weight \( M_c \) at which two straight lines with slopes 1 and 3.5 intersect quite sharply. This transition has a tendency to become gradual as the polymer concentration \( c \) is decreased, but still there is no difficulty to assess \( M_c \). The values of \( M_c \) determined in this way are proportional to the reciprocal of \( c \) in most systems, and we have for example a relationship

\[ cM_c = 3.6 \times 10^4 \]  
(3)

for polystyrene solutions in Aroclor.\(^5\) Here \( c \) is expressed in gram per cubic centimeter. This equation suggests that the solvent acts merely as a diluent for the polymer.

On the other hand, the behavior of \( J_e^0 \) as function of \( M \) and \( c \) has long been in controversy. Recent experimental results obtained for narrow distribution polymers seem to support a unified view that

\[
J_e^0 = a(M/cRT) \quad \text{for small values of } M \text{ and } c \\
J_e^0 = \beta/c^\nu \quad \text{for large values of } M \text{ and } c
\]  
(4a)  
(4b)

where \( R \) is the gas constant, \( T \) is the absolute temperature, and \( a \), \( \beta \), and \( \nu \) are constants independent of \( M \) and \( c \). However, there still remains some controversy unsettled among investigators if one looks at more detailed behavior of \( J_e^0 \). For example, some investigators have shown that \( \nu \) in Eq. (4b) is approximately two, while we prefer to set it as \( \nu = 3 \), as already mentioned in the beginning of this note. But we will not go further into this problem.

Graessley and Segal have shown that their experimental data can be represented by a two term equation of the reciprocal of \( J_e^0 \):\(^6\)

\[ \log J_e^0 \]  
\[ \log M \text{ or } \log c \text{ (arbitrary unit)} \]

Fig. 1. The molecular weight- and concentration-dependences of \( J_e^0 \) as calculated from Eq.(5b). The broken lines show their asymptotes.
\[ \frac{1}{J_0} = \frac{cRT}{aM} + \frac{c^2}{\beta} \]  

(5a)

or

\[ J_0 = \left( \frac{a}{1 + a_2 cM} \right) \frac{M}{cRT}, \quad a_2 = \frac{a}{RT\beta} \]  

(5b)

For small values of the product $cM$ such that $cM < 1/a_2$, this equation reduces to Eq. (4a), while for large values of $cM$, it reduces to Eq. (4b). This equation is, in a sense, analogous to Eq. (2), but it predicts only a gradual change between two limiting types of behavior, Eqs. (4a) and (4b), as illustrated in Fig. 1. Any sharp transition can hardly be observed on neither the log $J_0$ vs. log $M$ curve nor the log $J_0$ vs. log $c$ curve, in contrast to the case of the log $\eta$ vs. log $M$ curve. Porter et al. have also reported the data which are in agreement with Eq. (5). But other groups of investigators have found that the change in the behavior of $J_0$ occurs somewhat more sharply at around a certain critical value of $cM$.

Fig. 2. The concentration dependence of $J_0$ obtained for narrow-distribution polystyrenes in Aroclor. Molecular weights of the polymers are $1.80 \times 10^6$ (open circles), $8.60 \times 10^5$ (top-filled), $4.11 \times 10^4$ (right-filled), $9.72 \times 10^4$ (left-filled, medium circles), and $8.20 \times 10^4$ (left-filled, small circles). Thin solid line corresponds to $J_0 = 0.4 M/cRT$ for each sample and the dashed line is drawn with a slope $-3$. 

(466)
molecular weight $M_J$. For example, Onogi et al. have mentioned that in the case of polystyrene, $M_J$ is approximately equal to the corresponding quantity $M_e$ for the viscosity,\textsuperscript{8} and Odani et al. have found after an extensive survey of the existing data that $M_J$ is twice or three times as large as $M_e$ is.\textsuperscript{9} This last view implies that the so-called Rouse behavior of Eq. (4a) persists beyond $M_e$ over a certain range of $M$, though not over the whole range as often assumed in the earlier view. In addition, the concentration dependence of $J_\epsilon^0$ revealed by us shows a complicated profile as illustrated in Fig. 2, which is essentially different from that given in Fig. 1.

Under these circumstances, it may be of some value to note that a set of experimental results selected from the above is compatible with a very simple form of the relaxation spectrum.

**RELAXATION SPECTRUM**

Define a parameter $M_e$ which represents an average molecular weight between entanglement coupling points along a polymer chain, and put

$$y = M/M_e$$

(6).

Since the product $cM_e$, just like $cM_e$ in Eq. (3), must be a constant characteristic of a given polymer-diluent system at least approximately, the reduced variable $y$ is proportional to $M$ when $c$ is fixed, and to $c$ when $M$ is fixed.

When $M < M_e$, each polymer chain will be free from entanglement, and the relaxation spectrum $H(\tau)$ may be expressed as

$$H(\tau) = \frac{1}{2} \left( \frac{cRT}{M} \right) \left( \frac{\tau_1}{\tau} \right)^{1/2}$$

(7)

$$\tau_1 = \left( \frac{\zeta a^2}{6\pi \eta a} \right) \left( \frac{M}{m_0} \right)^2$$

(8).

Here $\tau_1$ represents the longest relaxation time in the Rouse theory.\textsuperscript{10} Other notations in Eq. (8) have its usual meanings: $\zeta$ is the friction coefficient of a segment, $m_0$ is its molecular weight, $a$ is the average-statistical length, and $k$ is the Boltzmann constant. The viscosity $\eta$, the normal stress coefficient $\theta$, and the steady-shear compliance $J_\epsilon^0$ are related to $H(\tau)$ as

$$\eta = \int_0^{\infty} H(\tau) d\tau$$

(9)

$$\frac{\theta}{2} = \int_0^{\infty} H(\tau) \tau d\tau$$

(10)

$$J_\epsilon^0 = \frac{\theta}{2\tau_1^2}$$

(11),

respectively. Thus, substitution of Eq. (7) into Eqs. (9) to (11) yields

$$\eta = \frac{cRT}{M} \tau_1 \propto cM$$

(12)

$$J_\epsilon^0 = \frac{1}{3} \frac{M}{cRT}$$

(13).
Fig. 3. The assumed model of the relaxation spectrum \( H(\tau) \) for a system with \( M = 10M_e \). The solid line for the box corresponds to \( h = 2.0 \), and the chain line to \( h = 3.5 \).

The numerical factor \( 1/3 \) in Eq. (13) is different from the correct value 0.400 because of the use of the approximate continuous form, Eq. (7), in place of the original discontinuous spectrum. But we ignore such a difference as this.

When \( M > M_e \), the Rouse-type spectrum may be applied only to the molecular motions having \( \tau \) smaller than \( \tau_e \):

\[
\tau_e = \frac{\xi a^2}{6\pi^2 kT} \left( \frac{M_e}{m_0} \right)^2 \frac{\tau_1}{\gamma^2} \tag{14}
\]

This part of the spectrum which is of the wedge type is schematically shown in Fig. 3 by the solid line. On the other hand, the molecular motions involved in the dotted trapezoid are subjected to the entanglement coupling interactions, and they will be shifted towards longer times. Since no established theory is available for these modes of molecular motions, we simply assume the box-type spectrum for them, and put

\[
H(\tau) = \frac{1}{2} \left( \frac{cRT}{M} \right) \left( \frac{\tau_1}{\tau} \right)^{1/2} \quad 0 < \tau < \tau_e \tag{15a}
\]
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\[ H(\tau) = \frac{1}{h} \left( \frac{cRT}{M_0} \right) \]

\[ \tau_1 < \tau < \tau_m \quad (15b). \]

The maximum relaxation time \( \tau_m \) must be put

\[ \tau_m = y^{3.5} \tau_e \quad (16) \]

to recover Eq. (1b) from Eqs. (9) and (15a, b). The lower bound \( \tau_1 \) of the box spectrum may be determined with the aid of the auxiliary condition that

\[ \int_{\tau_1}^{\tau_m} H_{\text{box}} \, d \ln \tau = \int_{\tau_1}^{\tau_m} H_{\text{ent}} \, d \ln \tau \quad (17). \]

This is an analogy of the famous Debye assumption in the theory of specific heat, and represents the conservation of the degrees of freedom in molecular motions during the process of entanglement formation. Thus, we obtain

\[ \tau_1 = \tau_m \exp \left[ -h \left( 1 - \frac{1}{y} \right) \right] \]

\[ = \tau_e y^{3.5} \exp \left[ -h \left( 1 - \frac{1}{y} \right) \right] \quad (18). \]

Furthermore, \( \tau_1 \) must be larger than \( \tau_e \), otherwise some modes of molecular motions will result in the shift of wrong direction. This condition leads to the condition that

\[ h \leq 3.5 \quad (19). \]

Within this limit, we can assign any value for the parameter \( h \). Thus two possible forms of the box-type spectrum are illustrated in Fig. 3 by the solid and the chain lines, where \( y \) is put 10, and \( h \) is put 2 and 3.5.

The viscosity \( \eta \) and the steady-shear compliance \( J_e^0 \) are readily obtained by substituting Eqs. (15a, b) into Eqs. (9) to (11). The results are

\[ \eta = \frac{cRT}{M_0} \tau_e \left[ 1 + \frac{y^{3.5}}{h} \left[ 1 - \exp \left[ -h \left( 1 - \frac{1}{y} \right) \right] \right] \right] \quad (20) \]

\[ J_e^0 = \frac{M_e}{3cRT} F(y) \quad (21) \]

\[ F(y) \equiv \frac{1+(3/2h)y^7}{[1+h^{-1}y^{3.5} \left[ 1 - \exp \left[ -h(1-y^{-1}) \right] \right]^2]} \quad (22). \]

Eq. (20) is essentially a two-term equation similar to Eq. (2). On the other hand, Eq. (21) is different from Eq. (5b). The molecular weight dependence of \( J_e^0 \) is represented by \( F(y) \), while the concentration dependence by \( F(y)/y^2 \).

Figure 4 illustrates the \( M \)-dependence of \( \eta \), and the \( M \)- and \( c \)-dependences of \( J_e^0 \) calculated by Eqs. (20) and (21). The log \( \eta \) vs. log \( M \) curve shows a sharp turn at about \( M_e = 1.7 M_0 \) (\( h=3.5 \)) and \( 1.6 M_0 \) (\( h=2 \)) as expected. The log \( J_e^0 \) vs. log \( c \) curve displays a maximum qualitatively in agreement with the behavior shown in Fig. 2. But the slope of the branch for high concentrations is \( -2 \), which is not in agreement with our experimental value, \( -3 \). The log \( J_e^0 \) vs. log \( M \) curve also shows a slight maximum at the shoulder part, and it makes sharp the connection of the horizontal branch and the Rouse branch of the curve. The lower end of the horizontal branch is located around \( 2M_e \),
which is practically in agreement with \( M_e \) determined by Odani et al.\(^9\)

The so-called entanglement compliance \( J_{en}^0 \) may be obtained as

\[
J_{en}^0 = \frac{Mc}{cRT} \quad \text{independent of } h
\]

This is to be compared with

\[
\lim_{y \to \infty} J_e^0 = \frac{h}{2} \left[ \frac{\exp(2h)-1}{\exp(h-1)^2} \right] \frac{M_e}{cRT}
\]

Thus, the ratio of this limiting value of \( J_e^0 \) to \( J_{en}^0 \) is about 2 when \( h = 3.5 \). However, if we calculate the storage and loss moduli, \( G'(\omega) \) and \( G''(\omega) \), by standard procedures, the minimum appearing in the \( G''(\omega) \) vs. \( \omega \) curve is too deep in comparison with the observed results. This is undoubtedly originated from the complete removal of relaxation modes from the region lying between \( \tau_e \) and \( \tau_1 \). In real systems, there must remain a considerable number of modes in this region as a result of the distribution of the entanglement spacing. However, it may be nonsensical to embellish further a crude model as the present.

Finally, we must refer to the work of Janeschitz-Kriegl.\(^{11} \) He has also shown that \( J_e^0 cRT/M \) shows a maximum at around a critical concentration or molecular weight. His spectrum \( H(\tau) \) consists of two wedges which are separated by a distance in the time scale, and it predicts \( J_e^0 \) to be proportional to \( M \) in both regions of small \( M \) and large \( M \).
REFERENCES


