# Generalization of geometry－induced effect noted by Takagi and Tanzawa 

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The formulation on a particle motion in n－demensional curved manifold $\mathbf{M}_{\boldsymbol{n}}$ embed－ ded in p －dimensional Euclidean space $\mathrm{R}_{p}$ is summarized，and the geometry－induced gauge structure is explained．Next we examine the scalar field theory with a soliton solution，and point out that in spite of the infinite degrees of freedom such a field theory has the same mathematical structure as a particle motion in $\mathbf{M}_{n} \subset \mathbf{R}_{p}$ ，and our formalism affords a clearer view of understanding physical contents of such a field theory．

1．Introduction：Quantum theory on a curved manifold has been investigated from various points of view $[1,2,3]$ ．Quantum treatment of soliton such as Skyrmion provides a typical example of quantum theory on a curved manifold［4］．We consider the motion of a particle on an $n$－dimensional curved manifold $\mathbf{M}_{n}$ embedded in a p－dimensional Euclidean space $\mathbf{R}_{p}$ ，and the particle motion is thought to be confined by some confining potential． Then a correction term with the order $\hbar^{2}$ in the effective Hamiltonian on $\mathbf{M}_{n}$ appears as a quantum effect due to a particle motion in the directions perpendicular to $\mathbf{M}_{n}$［2］．Such an effect is dropped from the beginning when we apply simply Dirac method for constrainted dynamical systems．

Two years ago，Takagi and Tanzawa［5］have pointed out that，for a particle motion
in a thin tube（in $\mathbf{R}_{3}$ ）forming a closed loop，in the effective Hamiltonian on $\mathbf{M}_{\mathbf{1}}$ there appears an effective vector potential，which depends on the geometry of $M_{1}$ ，and that there exists a complete analogy with Aharonov－Bohm effect，called a geometry－induced AB effect． One of the present authors（K．F．）and N．Ogawa［6］genaralized this result to the case of a particle motion in a thin neighborhood of $\mathrm{M}_{n}$ embedded in $\mathbf{R}_{\boldsymbol{p}}$ ．The aim of the present report is to apply this formalism to a scalar field theory which allows a classical solution， and to examine the correspondence to the field theory of the extended object given by Sakita and others［7］．

In the following，we first summarize the formalism in case of a particle motion on $\mathbf{M}_{n} \subset \mathbf{R}_{p}$（in Sec．2），and extend it to the case of a scalar field theory with a classical solution（in Sec．3）．The last section is devoted to discussions and summary of remaining tasks．

2．Particle motion in a thin layer along $M_{n}$ embedded in $R_{n}$
2－1．Basic relations As in［6］，a set of coordinates $\left\{X^{A} ; A=1, \cdots, p\right\}$ of a point in a thin－layer neighbourhood of $M_{n}$ is expressed as

$$
\begin{equation*}
X^{A}\left(q^{\beta}\right)=x^{A}\left(q^{b}\right)+\sum_{U=n+1}^{p} q^{U} N_{U}^{A}\left(q^{b}\right), \quad s=1, \cdots, p \tag{2.1}
\end{equation*}
$$

$\left\{q^{\beta}, \beta=1, \cdots, n, n+1, \cdots, p\right\}$ consists of two parts；the first part $\left\{q^{b}, b=1, \cdots, n\right\}$ is a set of curvilinear coordinates on $\mathbf{M}_{n}$ and the remaining part is $\left\{q^{U}, U=n+1, \cdots, p\right\}$ ．
$N_{U}^{A}\left(q^{b}\right)$ is a unit normal vector to $\mathrm{M}_{n}$ at a point $x^{A}\left(q^{b}\right)$ ．For simplicity we omit $\sum_{U=n+1}^{p}$ for a dummy index U and write e．g．$x^{A}\left(q^{b}\right)$ as $x^{A}(q)$ ．The metric tensor in $\mathbf{R}_{n}$ ，written as $\tilde{G}_{\alpha \beta}\left(q, q^{U}\right)$ is given by

$$
\begin{equation*}
\tilde{G}_{\alpha \beta}=\tilde{B}_{\alpha}^{A} \eta_{A D} \tilde{B}_{\beta}^{A} \quad \text { with } \quad \tilde{B}_{\beta}^{A}\left(q, q^{U}\right)=\frac{\partial X^{A}\left(q, q^{U}\right)}{\partial q^{\beta}} \tag{2.2a}
\end{equation*}
$$

and the metric tensor on $\mathrm{M}_{\boldsymbol{n}}$ as

$$
\begin{equation*}
g_{a b}(q)=B_{a}^{A} \eta_{A D} B_{b}^{D} \quad \text { with } \quad B_{b}^{A}(q)=\frac{\partial x^{A}(q)}{\partial q^{b}} \tag{2.2b}
\end{equation*}
$$

Since $B_{b}{ }^{A}$ is tangent to $\mathrm{M}_{n}$ ，we have $B_{b}{ }^{A} \eta_{A D} N_{V}{ }^{D}=0$ ．Note that we have $\tilde{B}_{\beta}{ }^{A}=$ $\left(\tilde{B}_{b}{ }^{A}, \tilde{B}_{V}{ }^{A}\right)=\left(B_{b}{ }^{A}+\partial_{b} N_{W}{ }^{A} \cdot q^{W}, N_{V}{ }^{A}\right)$.

The fundamental equations for $B_{b}{ }^{A}$ and $N_{V}{ }^{A}$ are

$$
\begin{align*}
\partial_{a} B_{b}{ }^{A} & =\Gamma_{a b}^{d} B_{d}{ }^{A}+H_{W a b} \eta^{W U} N_{U}{ }^{A},  \tag{2.3a}\\
\partial_{a} N_{V}{ }^{A} & =-H_{V a}{ }^{d} B_{d}{ }^{A}-T_{V W, a} \eta^{W U} N_{U}{ }^{A} \tag{2.3b}
\end{align*}
$$

where $\Gamma^{d}{ }_{a b}$ is Christoffel symbol constructed in terms of $g_{b d}$ and $H_{W a b}=H_{W b a}=H_{W b}{ }^{e} g_{e a}$ ， $T_{V W, a}=-T_{W V, a}$.

Concrete forms of $\tilde{G}_{\alpha \beta}$ and its inverse $\tilde{G}^{\alpha \beta}$ are given as follows：

$$
\left[\tilde{G}_{\alpha \beta}\right]=\left[\begin{array}{cc}
\tilde{G}_{a b} & \tilde{G}_{a U}  \tag{2.4a}\\
\tilde{G}_{V b} & \tilde{G}_{V U}
\end{array}\right]
$$

with

$$
\begin{gather*}
\tilde{G}_{a b}=\lambda_{a b}+\tilde{G}_{a X} \eta^{X Y} \tilde{G}_{b Y}, \quad \lambda_{a b}=g_{a b}-2 H_{W a b} q^{W}+q^{X} q^{Y} H_{X a}{ }^{e} H_{Y e b}, \\
\tilde{G}_{a U}=\tilde{G}_{U a}=T_{U X, a} q^{X}, \quad \tilde{G}_{V U}=\eta_{V U} ; \\
{\left[\tilde{G}^{\alpha \beta}\right]=\left[\begin{array}{cc}
\tilde{G}^{a b} & \tilde{G}^{a U} \\
\tilde{G}^{V b} & \tilde{G}^{V U}
\end{array}\right]} \tag{2.4b}
\end{gather*}
$$

with $\quad \tilde{G}^{a b}=\lambda^{a b}, \quad \lambda^{a b} \lambda_{b d}=\delta^{a}{ }_{d}, \quad \tilde{G}^{a U}=\tilde{G}^{U a}=-\lambda^{a d} T_{X W, d} q^{W} \eta^{X U}$,

$$
\tilde{G}^{V U}=\eta^{V U}+\eta^{V X} T_{X W, b} q^{W} \lambda^{b d} T_{Y Z, d} q^{Z} \eta^{Y U}
$$

From the condition $\partial_{a} B_{b}{ }^{A}=\partial_{b} B_{a}{ }^{A}$ ，one obtains the curvature tensor on $\mathbf{M}_{n}$ given as

$$
\begin{equation*}
R_{a b, c d}=\eta_{A B}\left(H_{a c}^{A} H_{b d}^{B}-H_{a d}^{A} H_{b c}^{B}\right) \tag{2.5a}
\end{equation*}
$$

with $H_{a b}^{A}=H_{V a b} \eta^{V W} N_{W} A$（Euler－Schouten tensor）； hence，the tensor $R_{b c}=g^{a d} R_{a b, c d}=\eta_{A B}\left(H_{b}{ }^{d} H^{B}{ }_{d c}-H^{A}{ }_{a}{ }^{a} H^{B}{ }_{b c}\right)$ ，and scalar curvature

$$
\begin{equation*}
R=g^{b c} R_{b c}=\eta_{A B}\left(H_{b}^{A^{d}} H_{d}^{B}-H_{a}^{A^{a}} H_{b}^{B_{b}^{b}}\right) . \tag{2.5b}
\end{equation*}
$$

From $\partial_{a} \partial_{b} N_{V}{ }^{A}-\partial_{b} \partial_{a} N_{V}{ }^{A}=0$ ，one obtains

$$
\begin{equation*}
R_{d a, V W} \eta^{V W}=\eta^{V W}\left(-H_{V d}^{b} H_{W b a}+H_{V a}^{b} H_{W b d}\right) \tag{2.5c}
\end{equation*}
$$

where $\quad R_{d a, V W} \equiv-\partial_{d} T_{V W, a}+\partial_{a} T_{V W, d}+T_{X V, d} \eta^{X Y} T_{Y W, a}-T_{X V, a} \eta^{X Y} T_{Y W, d}$.


$$
\begin{equation*}
R=H_{b}^{A_{b}^{d} \eta_{A B} H_{d}^{B}-n^{2} H^{2} . . . . .} \tag{2.6}
\end{equation*}
$$

2－2．Canonical quantization and form of kinetic energy
We examine the form of
kinetic energy

$$
\begin{equation*}
\tilde{K}=\frac{1}{2} \dot{X^{A}} \eta_{A B} \dot{X^{B}}, \quad \dot{X^{A}}=\frac{d X^{A}}{d \tau} \tag{2.7}
\end{equation*}
$$

expressed in terms of $q^{\beta}$－variables．In order to perform the quantum－mechanical calculations from the outset，we adopt the procedure which is consistent for the transformation from Euclidean coordinates to curvilinear ones as in the present case．We assume

$$
\begin{equation*}
\left[q^{\beta}, \dot{q}^{\delta}\right]=i \hbar f^{\beta \delta}\left(q^{\gamma}\right), \quad\left[q^{\beta}, q^{\delta}\right]=0 \tag{2.8a}
\end{equation*}
$$

where $f^{\beta \delta}$ is a function of only $\left(q^{\gamma}\right)$ ．When we require the cannonical commutation relations

$$
\begin{gather*}
{\left[q^{\alpha}, p_{\beta}\right]=i \hbar \delta^{\alpha}{ }_{\beta}, \quad\left[p_{\alpha}, p_{\beta}\right]=0}  \tag{2.8b}\\
\text { for } \quad p_{\beta} \equiv \frac{\partial \tilde{K}}{\partial \dot{q}^{\beta}}=\frac{1}{2}\left\{\tilde{G}_{\beta \delta}, \dot{q}^{\delta}\right\} \equiv<\tilde{G}_{\beta \delta}, \dot{q}^{\delta}> \tag{2.8c}
\end{gather*}
$$

we obtain $f^{\alpha \beta} \tilde{G}_{\beta \delta}=\delta^{\alpha}{ }_{\delta}$ ，i．e．$f^{\alpha \beta}$ is the inverse of $\tilde{G}_{\beta \delta}$ ．
Now we rewrite $\tilde{K}(2.7)$ in the covariant form

$$
\begin{equation*}
\tilde{K}=\frac{1}{2} \tilde{G}^{-1 / 4} p_{\alpha} \tilde{G}^{-1 / 2} \tilde{G}^{\alpha \beta} p_{\beta} \tilde{G}^{-1 / 4}, \quad \tilde{G}=\left|\operatorname{det} \tilde{G}_{\alpha \beta}\right| \tag{2.9a}
\end{equation*}
$$

We obtain by noting $\tilde{G}=\left|\operatorname{det} \lambda_{a b} \cdot \operatorname{det} \eta_{V W}\right|=\left|\operatorname{det} \lambda_{a b}\right| \equiv \lambda$ ，

$$
\begin{equation*}
\tilde{K}=\frac{1}{2} \lambda^{-1 / 4} \Pi_{a} \lambda^{1 / 2} \lambda^{a b} \Pi_{b} \lambda^{-1 / 4}+\frac{1}{2} \lambda^{-1 / 4} p_{V} \lambda^{1 / 2} \eta^{V W} p_{W} \lambda^{-1 / 4} \tag{2.9b}
\end{equation*}
$$

Here，$\Pi_{a}$ is defined by

$$
\begin{align*}
\Pi_{a} & \equiv p_{a}+\frac{1}{2} T_{V W, a} L^{V W}  \tag{2.9c}\\
L^{W X} & \equiv q^{W} \eta^{X V} p_{V}-q^{X} \eta^{W V} p_{V}=\eta^{X V} p_{V} q^{W}-\eta^{W V} p_{V} q^{X} \tag{2.9d}
\end{align*}
$$

$L^{W X}$ satisfies the commutation relation

$$
\begin{equation*}
\left[L^{V X}, L^{W Y}\right]=i \hbar\left(\eta^{V W} L^{X Y}+\eta^{X Y} L^{V W}-\eta^{V Y} L^{X W}-\eta^{X W} L^{V Y}\right) \tag{2.9e}
\end{equation*}
$$

In the thin layer approximation $\left|H_{U a b} q^{U}\right| \ll 1$ and $\left|T_{U V, b} q^{U}\right| \ll 1[5,6]$ ，one obtains

$$
\begin{equation*}
\tilde{K} \xrightarrow{\text { thin layer }} \quad K^{*}=K+\frac{1}{2} p_{V} \eta^{V W} p_{W}+\Delta V^{*}, \tag{2.10a}
\end{equation*}
$$

where $\quad K=\frac{1}{2} g^{-1 / 4} \Pi_{a} g^{1 / 2} g^{a b} \Pi_{b} g^{-1 / 4}, \quad \Delta V^{*}=\frac{\hbar^{2}}{2}\left[-\frac{R}{2}-\frac{1}{4} n^{2} H^{2}\right]$.
$\Delta V^{*}$ comes from the last term in（2．9b）．It may be worthy of noting that we have

$$
\begin{equation*}
\Delta V^{*}=-\left.\frac{1}{2}\left[\tilde{Y}\left(q, q^{V}\right)-Y(q)\right]\right|_{t h i n ~ l a y e r} \tag{2.11a}
\end{equation*}
$$

where $-\frac{1}{2} \tilde{\mathrm{Y}}\left(\mathrm{q}, \mathrm{q}^{\mathrm{V}}\right)=\hbar^{2}\left[\frac{1}{4} \partial_{\delta}\left(\tilde{\mathrm{G}}^{\delta \beta} \tilde{\Gamma}_{\beta}+\frac{1}{8} \tilde{\mathrm{G}}^{\delta \beta} \tilde{\Gamma}_{\delta} \tilde{\Gamma}_{\beta}\right)\right], \tilde{\Gamma}_{\alpha} \equiv \tilde{\Gamma}_{\alpha \beta}^{\beta}=\tilde{\mathrm{G}}^{\gamma \beta} \partial_{\alpha} \tilde{\mathrm{G}}_{\gamma \beta} / 2$.
$\mathrm{Y}(\mathrm{q})$ is the quantity constructed in terms of $g_{a b}$ corresponding to $\tilde{Y}$ ；

$$
\begin{equation*}
-\frac{1}{2} Y / \hbar^{2}=\frac{1}{4} \partial_{b}\left(g^{b d} \Gamma_{d}\right)+\frac{1}{8} g^{b d} \Gamma_{b} \Gamma_{d}=\frac{1}{8}\left[R+g^{a b} \Gamma_{a}^{e}{ }_{d} \Gamma^{d}{ }_{b e}\right] . \tag{2.11b}
\end{equation*}
$$

Using（2．11b），we can rewrite（2．10b）as

$$
\begin{equation*}
K(2.10 b)=\frac{1}{2} \Pi_{a} g^{a b} \Pi_{b}-\frac{1}{2} Y(q) \tag{2.11c}
\end{equation*}
$$

2－3．Commutator $\left[\Pi_{a}, \Pi_{b}\right]$
Utilizing some relations given in 2－1，we obtain

$$
\begin{equation*}
\left[\Pi_{b}, \Pi_{d}\right]=\frac{i \hbar}{2} R_{b d, V W} L^{V W} \tag{2.12a}
\end{equation*}
$$

This is analogous to a charged particle moving in magnetic field $\vec{H}$ ，in which we have

$$
\begin{equation*}
\left[\Pi_{j}, \Pi_{k}\right]=i \hbar \frac{e}{c} F_{j k} ; \quad \Pi_{j}=p_{j}-\frac{e}{c} A_{j} ; \quad j, k=1,2,3 ; \quad F_{j k}=\frac{1}{2} \epsilon_{j k l} H^{l} \tag{2.12b}
\end{equation*}
$$

We see that the field $T_{V W, a}=N_{V}{ }^{A} \partial_{a} N_{W}^{B} \eta_{A B}$ plays a role of gauge potential．The gauge property including the non－Abelian one is seen as follows：When the total Hamiltonian $\tilde{H}=\tilde{K}(2.9 b)+V$ has the part of potential which confines the particle motion to $\mathbf{M}_{n}$ ，and is invariant under rotation of the set of $\left\{N_{U}{ }^{A}, U=n+1, \cdots, p\right\}$ such as

$$
\begin{equation*}
N_{V}^{\prime}(q)=N_{W}^{A}(q) \Lambda_{V}^{W}(q), \quad \quad \eta_{X Y} \Lambda_{W}^{X} \Lambda_{V}^{Y}=\eta_{W V} \tag{2.13a}
\end{equation*}
$$

we obtain

$$
\begin{equation*}
T_{W V, b} \longrightarrow T_{W V, b}^{\prime}=\left(\Lambda^{-1}\right)_{W}^{X} T_{X Y, b} \Lambda_{V}^{Y}+\left(\Lambda^{-1}\right){ }_{W X} \partial_{b} \Lambda_{V}^{X} \tag{2.13b}
\end{equation*}
$$

$T_{W V, b}$ cannot be eliminated globally．In case of a tube embedded in $\mathbf{R}_{3}[5], \Pi_{b}$ reduces to

$$
\begin{equation*}
\Pi_{1}=p_{1}+T_{23} L^{23} \equiv p-\omega L \tag{2.14a}
\end{equation*}
$$

It is pointed out in Ref．［5］due to multivaluedness of triangular function

$$
\begin{equation*}
\int_{0}^{l} \omega(q) d q=\int_{0}^{l} \tau(q) d q \quad(\bmod 2 \pi) \tag{2.14b}
\end{equation*}
$$

is obtained，where $l$ is the length of center line of the tube；$\tau$ is the torsion appearing in Frenet－Seret equation in $\mathbf{R}_{\mathbf{3}}$ ．

## 3．Application to field theory of extended object

3－1．Purpose In this section we extend the formalism given in Secion 2 to field theory．For simplicity，we examine the scalar filed theory which allows a soliton solution． We consider the Lagrangian expressed as

$$
\begin{equation*}
L=-\frac{1}{2} \partial_{\mu} \phi^{A}(x) \eta_{A B} \partial^{\mu} \phi^{B}(x)-V(\phi(x)) \tag{3.1}
\end{equation*}
$$

where $\left(x^{\mu}\right)$ is a space－time coordinate；its metric is $\eta_{\mu \nu}$ with $\operatorname{diag}\left(\eta_{\mu \nu}\right)=(-++\cdots)$ ；the upper index A of $\phi^{A}$ denotes the internal degrees of freedom．

The field operator $\phi^{A}\left(\vec{x}, x^{0}\right)$ is assumed to be expanded as［7］

$$
\begin{equation*}
\phi^{B}\left(\vec{x}, x^{0}\right)=\phi_{0}^{B}\left(\vec{x}, q^{b}\right)+\sum_{U} \phi_{U}^{B}\left(\vec{x}, q^{b}\right) q^{U} \tag{3.2a}
\end{equation*}
$$

where $\left\{q^{b}, b=1, \cdots, n\right\}$ denotes a set of collective coordinates representing the center of mass coordinates of the classical soliton，the orientation on the internal space and so on；$\phi_{0}^{B}$ is the soliton solution satisfying

$$
\begin{equation*}
-\frac{\partial}{\partial \vec{x}} \frac{\partial}{\partial \vec{x}} \phi_{0}^{B}\left(\vec{x}, q^{b}\right)+\frac{\partial V}{\partial \phi_{0}^{A}\left(\vec{x}, q^{b}\right)} \eta^{A B}=0 \tag{3.2b}
\end{equation*}
$$

$\partial \phi_{0}^{B}(\vec{x}, q) / \partial q^{b}$ satisfies

$$
\begin{equation*}
\left[-\vec{\nabla}^{2} \delta_{D}^{B}+\frac{\partial^{2} V}{\partial \phi_{0}^{D}(\vec{x}, q) \partial \phi_{0}^{A}(\vec{x}, q)} \eta^{A B}\right] \partial_{b} \phi_{0}^{D}(\vec{x}, q)=0 \tag{3.2c}
\end{equation*}
$$

$\phi_{U}{ }^{D}(\vec{x}, q)$＇s are non－zero－mode solutions corresponding to（3．2b），and are normalized to

$$
\begin{equation*}
\int d \vec{x} \phi_{V}^{B}(\vec{x}, q) \eta_{B D} \phi_{W}^{D}(\vec{x}, q)=\eta_{V W}, \quad \int d \vec{x} \partial_{b} \phi_{0}^{B}(\vec{x}, q) \eta_{B D} \phi_{W}^{D}(\vec{x}, q)=0 \tag{3.2d}
\end{equation*}
$$

（Hereafter we write a function of $q^{b}$ ，,$f\left(q^{b}\right)$ ，as $\mathrm{f}(\mathrm{q})$ for simplicity．）
The expression（3．2a）with the properties（3．2d）is completely analogous with（2．1）． With the aim of making clear the analogy，we write（3．2a）and（3．2d）as

$$
\begin{align*}
\phi^{B x}\left(x^{0}\right) & =\phi_{0}^{B x}(q)+N_{U}^{B x}(q) \cdot q^{U}  \tag{3.3a}\\
N_{V}^{B x}(q) \eta_{B x, D y} N_{U}^{D y}(q) & =\eta_{V W}, \quad \dot{B}_{b}^{B x}(q) \eta_{B x, D y} N_{U}^{D x}(q)=0, \tag{3.3b}
\end{align*}
$$

where $\eta_{B x, D y}=\eta_{B D} \delta(\vec{x}-\vec{y}) ; B_{b}^{B x}(q)=\partial_{b} \phi_{0}^{B x}(q)$ ．The following subsections is devoted to investigate the role of this analogy in constructing the field theory of extended object．

3－2．Fundamental relations and the metric
Various relations given in the previous section remain to hold if the index A （representing the vector property in $\mathbf{R}_{p}$ ）is changed to $A x$ ；from（2．3a）and（2．3b）one obtains

$$
\begin{align*}
\partial_{a} B_{b}{ }^{A x}(q) & =\Gamma_{a b}^{d} B_{d}^{A x}+H_{W a b} \eta^{W U} N_{U}^{A x},  \tag{3.4a}\\
\partial_{a} N_{V}^{A x}(q) & =-B_{b}^{A x} H_{V a}^{b}-T_{V W, a} \eta^{W U} N_{U} A x . \tag{3.4b}
\end{align*}
$$

As to $\tilde{B}_{\beta}^{A x} \equiv \partial \phi^{A x} / \partial q^{\beta}$ ，we have

$$
\begin{equation*}
\tilde{B}_{b}^{A x}(q)=B_{b}^{A x}(q)+\partial_{b} N_{V}^{A x} \cdot q^{V}, \quad \tilde{B}_{V}^{A x}(q)=N_{V}^{A x}(q) ; \tag{3.5a}
\end{equation*}
$$

and the small interval

$$
\begin{equation*}
d s^{2}=d \phi^{B x} \eta_{B x, D y} d \phi^{D y}=\tilde{G}_{\alpha \beta}\left(q, q^{V}\right) d q^{\alpha} d q^{\beta} \quad \text { with } \quad \tilde{G}_{\alpha \beta}=\tilde{B}_{\alpha}^{A} \eta_{A B} \tilde{B}_{\beta}^{B} \tag{3.5b}
\end{equation*}
$$

3－3．Canonical quantization and Hamiltonian form From Lagrangian（3．1），one ob－ tains the momentum operator $p_{A x}$ ，conjugate to $\phi^{A x}$ ，defined by

$$
\begin{equation*}
p_{A x} \equiv \frac{\partial L}{\partial \partial \phi^{A x} / \partial x^{0}}=\frac{\partial \phi^{D y}}{\partial x^{0}} \eta_{D y, A x} \equiv \dot{\phi}^{D y} \eta_{D y, A x} . \tag{3.6a}
\end{equation*}
$$

Utilizing

$$
\begin{equation*}
\dot{\phi}^{B x}=\left(\tilde{B}_{\beta}^{B x} \cdot \dot{q}^{\beta}+\dot{q}^{\beta} \cdot \tilde{B}_{\beta}^{B x}\right) / 2 \equiv<\tilde{B}_{\beta}^{B x}, \dot{q}^{\beta}> \tag{3.6b}
\end{equation*}
$$

and following the quantization procedure described in 2－2，one obtains

$$
\begin{align*}
p_{\beta} & \equiv \frac{\partial L}{\partial \dot{q}^{\beta}}=<\tilde{G}_{\beta \alpha}, \dot{q}^{\alpha}>  \tag{3.6c}\\
p_{A x} & =<\eta_{A x, B y} \tilde{B}_{\beta}^{B y}, \dot{q}^{\beta}>=<\eta_{A x, B y} \tilde{B}_{\beta}^{B y} \tilde{G}^{\beta \delta}, p_{\delta}> \tag{3.6d}
\end{align*}
$$

From the commutation relations（2．8b），we obtain the equal－time ones as

$$
\begin{equation*}
\left[\phi^{B x}, \phi^{D y}\right]=0, \quad\left[\phi^{B x}, p_{D y}\right]=i \hbar \delta^{B x} D y, \quad\left[p_{B x}, p_{D y}\right]=0 \tag{3.6e}
\end{equation*}
$$

Hamiltonian $H[\phi, p]$ is defined by

$$
\begin{equation*}
H[\phi, p] \equiv \frac{1}{2}\left\{p_{A x}, \dot{\phi}^{A x}\right\}-\int d \vec{x} L \tag{3.7a}
\end{equation*}
$$

which is expressed as

$$
\begin{equation*}
H[\phi, p]=\frac{1}{2} p_{A x} \eta^{A x, B y} p_{B y}+\frac{1}{2}(\vec{\nabla} \phi)^{A x} \eta_{A x, B y}(\vec{\nabla} \phi)^{B y}+\int V(\phi) d \vec{x} . \tag{3.7b}
\end{equation*}
$$

This is expressed in terms of $\left(q^{\alpha}, p_{\beta}\right)$ variables as

$$
\begin{equation*}
H[\phi, p]=\tilde{K}(2.9 b)+\int V(\phi) d \vec{x} \tag{3.7c}
\end{equation*}
$$

$$
\begin{equation*}
\tilde{K}(2.9 b)=\frac{1}{2} \Pi_{a} \lambda^{a b} \Pi_{b}+1 / 2 p_{V} \eta^{V W} p_{W}-\frac{1}{2} \tilde{Y}\left(q, q^{U}\right) . \tag{3.7d}
\end{equation*}
$$

Here，the last term $-\frac{1}{2} \tilde{Y}$ is given by（2．11a）and can be rewritten as

$$
\begin{equation*}
-\frac{1}{2} \tilde{Y}=\frac{\hbar^{2}}{8}\left[\tilde{R}+\tilde{\Gamma}_{\alpha \gamma}^{\delta} \tilde{G}^{\alpha \beta} \tilde{\Gamma}_{\beta \delta}^{\gamma}\right] ; \tag{3.7e}
\end{equation*}
$$

in the present case，$\tilde{R}=0$ ．We will examine the correspondence of the above expressions to those derived by Gervais and others［7］in the next subsection．

3－4．Momentum operators From（3．6c）and（3．6d），one obtains

$$
\begin{equation*}
p_{\beta}=<\tilde{B}_{\beta}^{A x}, p_{A x}>, \quad \text { i.e. } \quad p_{U}=<N_{U}^{A x}, p_{A x}>, \quad p_{b}=<\tilde{B}_{b}^{B x}, p_{B x}>. \tag{3.8}
\end{equation*}
$$

We define

$$
\begin{equation*}
\Pi_{B x} \equiv \eta_{B x, D y} N_{V}{ }^{D y} \eta^{V W} p_{W} \tag{3.9a}
\end{equation*}
$$

By employing the second relation of（3．8），one obtains

$$
\begin{equation*}
\Pi_{B x}=<\eta_{B x, D y} N_{V}^{D y} \eta^{V W} N_{W}^{E z}, p_{E z}>. \tag{3.9b}
\end{equation*}
$$

When we define $p_{0, B x} \equiv p_{B x}-\Pi_{B x}$ ，we obtain

$$
\begin{gather*}
p_{0, B x}=<\delta_{B x}^{E z}-\eta_{B x, D y} N_{V}^{D y} \eta^{V W} N_{W}^{E z}, p_{E z}>=<\eta_{B x, D y} B_{b}^{D y} g^{b d} B_{d}^{E z}, p_{E z}>;  \tag{3.9c}\\
N_{V}^{B x} \cdot \Pi_{B x}=p_{V}, \quad B_{b}^{B x} \cdot \Pi_{B x}=0  \tag{3.9d}\\
<N_{V}^{B x}, p_{0, B x}>=0, \quad<B_{b}^{B x}, p_{0, B x}>=<B_{b}^{B x}, p_{B x}>. \tag{3.9e}
\end{gather*}
$$

Therefore，we write $\phi^{B x}$ and $p_{B x}$ as

$$
\begin{equation*}
\phi^{B x}=\phi_{0}^{B x}+\chi^{B x}, \quad p_{B x}=p_{0, B x}+\Pi_{B x}, \tag{3.10a}
\end{equation*}
$$

with $\chi^{B x}=N_{V}{ }^{B x} q^{V}, \quad \Pi_{B x}=(3.9 a)$ ，from which we have

$$
\begin{equation*}
<\Pi_{B x}, \partial_{b} \phi^{B x}>=-\frac{1}{2} T_{W V, b} L^{W V} . \tag{3.10b}
\end{equation*}
$$

Thus we see $\Pi_{a}$ in（3．7d）is expressed as

$$
\begin{equation*}
\Pi_{a}=p_{a}-<\Pi_{B x}, \partial_{a} \phi^{B x}> \tag{3.10c}
\end{equation*}
$$

which is the same as given by Gervais and others［7］．

Next we examine the form of

$$
\begin{equation*}
<p_{B x}, \dot{\phi}^{B x}>=\int d \vec{x} L-H[\phi, p](3.7 c) \tag{3.11a}
\end{equation*}
$$

in the c－number theory．We obtain

$$
\begin{align*}
p_{B x} \dot{\phi}^{B x} & =p_{\beta} \dot{q}^{\beta}=p_{0, B x} \dot{\phi}^{B x}+\Pi_{B x} \dot{\chi}^{B x}  \tag{3.11b}\\
p_{0, B x} \dot{\phi}^{B x} & =p_{d} \dot{q}^{d}-p_{V} T_{X W, d} q^{W} \eta^{X V} \dot{q}^{d}=\Pi_{d} \dot{q}^{d} \tag{3.11c}
\end{align*}
$$

4．Discussions and conclusion
In sec．3，we examine the scalar field theory which allows a soliton solution with the aim of establishing the correspondence between such a field theory and the formalism of one－particle motion on a curved manifold $\mathbf{M}_{\boldsymbol{n}}$ embedded in $\mathbf{R}_{p}$ ．Our formulation seems helpful to see general mathematical structure of the field theory with soliton and fluctuation around it．A noteworthy point in the present formalism is that there appears a geometry－induced gauge structure which corresponds to that giving rise to the geometry－induced Aharonov－Bohm effect for a particle moving in a thin－tube in $\mathbf{R}_{3}$ ．

One of the future tasks is to investigate about what physical effects such a geometry－ induced structure brings．It may be interesting to examine the possiblity of inducing the gauge field as an independent dynamical degree of freedom after compactifying $q^{U}$－space． From such a point of view，the recent works presented by Kikkawa and others［8］seems interesting，on which we shall discuss elsewhere．
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