A SOLUTION FORMULA FOR THE STOKES EQUATION IN $R_{\scriptscriptstyle +}^{\rm n}$

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1. Introduction and Main Result

The Stokes equation is the linear equation obtained from the Navier-Stokes equation by ignoring the quadratic convection term. In this paper we discuss its initial boundary value problem in the half space R_+^n ($n \ge 2$);

(1.1a)
$$u_{+} - \Delta u + \nabla p = 0$$
,

$$(1.1b) \qquad \nabla \cdot \mathbf{u} = 0,$$

(1.1c)
$$\gamma u = a(t,x'),$$

(1.1d)
$$u|_{t=0} = u_0(x)$$
.

Here the unknowns are the velocity $u(t,x)=(u^1,u^2,\ldots,u^n)$ and the pressure p(t,x) where $t\geq 0$ and $x=(x_1,x_2,\ldots,x_n)=(x',x_n)\in R^{n-1}\times R_+=R_+^n$, while $v=(\partial_1,\partial_2,\ldots,\partial_n)$, $\partial_j=\partial/\partial x_j$, is the gradient, Δ the laplacian, Δ means the inner product in R^n and γ is the trace operator to the boundary $\partial R_+^n=R^{n-1}\times \{0\}$; $\gamma u=u(t,x',0)$. a(t,x') and $u_o(x)$ are the prescribed boundary and initial values, respectively. In the sequel the tangential components of vectors will be denoted with prime. Thus,

$$u=(u',u^n)$$
, $a=(a',a^n)$, $u_0=(u',u^n_0)$.

The aim of this paper is to explicitly write down the solution to (1.1) in terms of only Riesz' operators and the solution operators for the heat and Laplace's equations in R_+^n , all of which are well-

known operators. Solonikov [7] has already derived such explicit formulas to obtain various estimates of solutions to (1.1). Then his estimates have been used to evaluate solutions to (1.1) for arbitray bounded domains, see e.g. [6,8,9] (see also [4] for a different approach), which is useful to construct strong solutions to the (nonlinear) Navier-Stokes equations, [3]. The formula derived here looks more compact and seems easier to evaluate, and further, our method of derivation is quite different from and simpler than that of Solonikov [7]. Also, the formula (1.10) below which gives the solution to (1.1) for the case a=0 is not found in [7] and crucial to construct L^p -global solutions to the Navier-Stokes equation in \mathbb{R}^n_+ , see section 3.

We shall introduce two kinds of Riesz' operators, R_j , j=1,...,n, and S_j , j=1,...,n-1, which are the singular integral operators with the symbols,

$$\sigma(R_j) = i\xi_j/|\xi|, \qquad j=1,\ldots,n,$$

$$\sigma(S_j) = i\xi_j/|\xi'|, \qquad j=1,\ldots,n-1,$$

where $\xi = (\xi_1, \xi_2, \dots, \xi_n) = (\xi', \xi_n) \in \mathbb{R}^{n-1} \times \mathbb{R}$ is the dual variable to $x \in \mathbb{R}^n$. Thus R_j are defined in the space \mathbb{R}^n and given explicitly as

$$R_{j}f(x) = v.p. \int_{\mathbf{p}^{n}} R_{j}(x-y) f(y) dy,$$

where v.p. means the principal part of the integral and

$$R_{j}(x) = c_{n}x_{j}/|x|^{n+1}, c_{n} = 2^{k-n/2}\sqrt{\pi} \Gamma((n-1)/2),$$

 Γ being the gamma function, and similarly for S_j but in R^{n-1} . We note that S_j can also be considered in R_+^n as well as in R^n in a natural manner. Set

(1.2)
$$R' = (R_1, R_2, \dots, R_{n-1})$$
$$S = (S_1, S_2, \dots, S_{n-1}),$$

and define the operators V_1 and V_2 by

$$V_1 u_0 = -S \cdot u_0' + u_0^n,$$

$$(1.3) V_2 u_0 = u_0' + S u_0^n.$$

Further, let r be the restriction operator from R^n to R^n_+ , that is,

$$(1.4a)$$
 rf=f| $\mathbf{R}_{\perp}^{\mathbf{n}}$,

and e the extension operator from R_{+}^{n} over R^{n} with value 0;

(1.4b) ef=f
$$(x_n>0)$$
, =0 $(x_n<0)$.

Then we define the operator U by

(1.5) Uf =
$$rR' \cdot S(R' \cdot S + R_n)e$$
.

We shall further use the heat kernel in the whole space,

$$E_{O}(t,x) = (4\pi t)^{-n/2} \exp\{-|x|^{2}/(4t)\},$$

in order to define the operators E(t) and F respectively by

(1.6a)
$$E(t)f = \int_{\mathbb{R}^{n}_{+}} \{E_{O}(t,x-y)) - E_{O}(t,x+y)\} f(y) dy,$$

(1.6b) Fb =
$$\int_0^t \int_{\mathbb{R}^{n-1}} \partial_n E_0(t-s, x'-y', x_n) b(s, y') dsdy',$$

which are the solution operators to the heat equation in R_{+}^{n} ;

$$z_{t}-\Delta z = 0, \quad \text{in } \mathbb{R}^{n}_{+},$$

$$(1.7) \quad \gamma z = b(t,x'),$$

$$z|_{t=0} = z_{o}(x).$$

Thus $z=E(t)z_0$ solves (1.7) for the case b=0 while z=Fb does for $z_0=0$.

Also, we shall introduce the Poisson operators D and N for the Dirichlet and Neumann problems for Laplace's equation in R_+^n , respectively. Thus z=Db (resp. z=Nb) is the unique solution of

(1.8)
$$\Delta z = 0 \quad \text{in } R_{+}^{n},$$

$$\gamma z = b(x') \quad (\text{resp. } \gamma \partial_{n} z = b(x')).$$

As is well known, they are explicitly given in terms of the single and double layer potentials by

(1.9a) Db =
$$\int_{\mathbf{p}^{n-1}} \partial_n G(x'-y',x_n)b(y')dy'$$
,

(1.9b) Nb =
$$\int_{\mathbb{R}^{n-1}} G(x'-y',x_n)b(y')dy'$$
,

where

$$G(x) = C_n |x|^{-(n-2)} \quad (n \ge 3), = -(2\pi)^{-1} \log |x| \quad (n=2)$$

is the Newton potential, with $C_n = 2(n-2)^{-1} \pi^{n/2} \Gamma(n/2)$.

Now we are ready to state our solution formulas. For later convinience, they will be given separately for the case a=0 and for $u_0^{=0}$.

Theorem 1.1. Suppose a=0. Then the solution to (1.1) can be expressed as

(1.10a)
$$u^n = UE(t)V_1u_0$$
,

(1.10b)
$$u' = E(t)V_2u_0 + SUE(t)V_1u_0$$

(1.10c)
$$p = -D\gamma \partial_n E(t) V_1 u_0$$
.

Theorem 1.2. Suppose $u_0 = 0$. Then the solution to (1.1) is

$$(1.11a)$$
 $u^n = Da^n + UFV_1a$

(1.11b)
$$u' = FV_2a - S(Da^n + UFV_1a),$$

(1.11c) $p = |\nabla'|DV_1a + D\gamma \partial_n FV_1a - Na_t^n$

where $|\nabla'|$ is the pseudo differential operator having the symbol $|\xi'|$.

Remak 1.3. (i) Solonikov [7] have not given (1.10) but only (1.11), although in a slightly complex expression.

- (ii) In order that these formulas actually give smooth solutions to (1.1), u_0 and a should not only be smooth but also satisfy the compatibility conditions described in [7]. In particular, $\nabla \cdot u_0 = 0$ is required for (1.10) and $a^n(0,x) = 0$ for (1.11).
- (iii) Evidently, the sum of (1.10) and (1.11) gives the solution to (1.1) when a $\neq 0$ and $u_0 \neq 0$. However compatibility conditions are required separately for a and u_0 . More resonable is Solonikov' procedure [7]: First we solve the Cauchy problem for (1.1), with u_0 appropriatly extended over \mathbf{R}^n . Then the solution is $\mathbf{u} = \mathbf{E}_0(\mathbf{t})\mathbf{u}_0$, $\mathbf{p} = \mathbf{0}$, where

(1.12)
$$E_{o}(t)u_{o} = \int_{\mathbf{p}} E_{o}(t, x-y)u_{o}(y)dy$$

is just the solution to the Cauchy problem for the heat equation. If we set $u=E_{_{\scriptsize O}}(t)u_{_{\scriptsize O}}+v$ in (1.1), we obtain again (1.1) for v, p with $u_{_{\scriptsize O}}=0$ and a replaced by $a-\gamma E_{_{\scriptsize O}}(t)u_{_{\scriptsize O}}$, to which (1.11) applies. In this case we have compatibility conditions relating a and $u_{_{\scriptsize O}}$, see [7] for details. In case a=0, this procedure leads to a different form of the solution from (1.10).

Remark 1.4. Even if u_0 and a are not smooth nor satisfy compatibility conditions, the above formulas still give solutions to (1.1) in a certain sense. For example, suppose $u_0 \in L^p(\mathbb{R}^n_+)$ with 1 . Then we can see that for t>0, (u,p) of (1.10) is smooth and satisfies (1.1a), (1.1b) and (1.1c) with a=0, and instead of (1.1d), it holds

that as $t \downarrow 0$,

$$u(t) \rightarrow P_0 u_0$$
 strongly in $L^p(R_+^n)$,

where P_{O} is the operator defined by

$$(P_o u_o)' = V_2 u_o - SUV_1 u_o,$$

$$(P_o u_o)^n = UV_1 u_o.$$

Remark 1.5. It can be shown that if $1 , <math>P_o$ is a continuous projection from $L^p(R_+^n)$ onto the solenoidal subspace

(1.14)
$$PL^{p}(R_{+}^{n}) = \{ u_{o} \in L^{p}(R_{+}^{n}) \mid \nabla \cdot u_{o} = 0, \gamma u_{o}^{n} = 0 \}.$$

Notice, however, that P_O does not coincide with the well-known projection P associated with the Helmholtz decomposition, [2]. In particular, P is an orthogonal projection but P_O is not, in the case p=2.

2. Proof of Theorems

Since we work in the half space R_+^n , it is natural to use the Fourier transformation with respect to the tangential variable x'. Let $f(x)=f(x',x_n)$ be a function defined on R_+^n . Then its Fourier transform in x' is defined by

$$\hat{f}(\xi',x_n) = (2\pi)^{-(n-1)/2} \int_{\mathbf{p}^{n-1}} e^{ix'\cdot\xi'} f(x',x_n) dx'.$$

In the sequel we will drop \hat{f} , thus using the same symbol f for both f and its Fourier transform \hat{f} , and in accordance with this, we will freely denote the singular integral operator in x', say S in (1.2),

by its symbol, say $\sigma(S)=i\xi'/|\xi'|$. This convention will simplifies the notation greatly, not only raise no confusions.

We begin our proof by noting the equation $\Delta p=0$ which comes from (1.1a) and (1.1b). Passing to the Fourier transform in x' and recalling our convention, we get the ordinary differential equation

$$(\partial_n^2 - |\xi'|^2)p = 0$$
 in $x_n > 0$.

Now we shall solve this assuming that p is bounded. Clearly such solutions must have the form

$$p = k(\xi', x_n)\gamma p$$

where

(2.1)
$$k(\xi',s) = \exp(-|\xi'|s)$$
.

Although the trace γp is still unknown, it follows that p satisfies

$$(2.2)$$
 $(\partial_n + |\xi'|)p = 0.$

This is the key in our argument.

First, we set

(2.3)
$$z = (\partial_n + |\xi'|)u^n,$$

and apply $(\partial_n + |\xi'|)$ to the n-th equation in (1.1a) to see, by the aid of (2.2), that z_t - Δz =0 holds. Further, since (1.1b) is equivalent to

(2.4)
$$i\xi' \cdot u' + \partial_n u^n = 0$$
,

we have, together with (1.1c),

$$\gamma z = \gamma(\partial_n + |\xi'|) u^n = -i\xi' \cdot \gamma u' + |\xi'| \gamma u^n$$

= $-i\xi' \cdot a' + |\xi'| a^n = |\xi'| V_1 a,$

and similarly, with (1.1d),

$$z|_{t=0} = |\xi'| V_1 u_0$$

where V_1 is the operator defined by (1.3). This shows that z defined by (2.3) solves the heat equation (1.6) with b=| ξ '| V_1 a and z_0 =| ξ '| V_1 u₀. Accordingly, z is given in the form of

(2.5)
$$z = |\xi'|(E(t)V_1u_0 + FV_1a).$$

Note that $|\xi'| = |\nabla'|$ (pseudo differential operator) commutes with E(t) and F.

Now that z is known, u^n can be obtained if (2.3) is looked as the ordinary differential equation for u^n in $x_n>0$ and solved under the boundary condition $\gamma u^n=a^n$ which comes from (1.1c). The result is,

(2.6)
$$u^{n} = k(\xi', x_{n})a^{n} + \int_{0}^{x_{n}} k(\xi', x_{n} - y_{n})z(t, \xi', y_{n})dy_{n},$$

where k is as in (2.1).

We shall show that (2.6) coincides with the sum of (1.10a) and (1.11a). First, we note that the Poisson operator D in (1.8a) has the symbol $\sigma(D)=k(\xi',x_n)$, so the first term on the right hand side of (2.6) is Daⁿ (recall our convention). Next, define the operator \tilde{U} by

Uf =
$$|\xi'| \int_0^{x_n} k(\xi', x_n - y_n) f(\xi', y_n) dy_n$$
.

We shall show that this is nothing but U of (1.5). Set h(s) = $|\xi'|k(\xi',s)$ for s>0 and = 0 for s<0. Then we have

(2.7) Uf =
$$r \int_{-\infty}^{\infty} h(x_n - y_n) ef(y_n) dy_n$$
,

where r and e are as in (1.8). The Fourier transform $\hat{h}(\xi_n)$ of $h(x_n)$ with rerspect to x_n is

$$\hat{\mathbf{n}}(\xi_{\mathbf{n}}) = (2\pi)^{-1/2} |\xi'| \int_{0}^{\infty} e^{-(|\xi'| + i\xi_{\mathbf{n}}) x_{\mathbf{n}}} dx_{\mathbf{n}}$$
$$= (2\pi)^{-1/2} |\xi'| (|\xi'| + i\xi_{\mathbf{n}})^{-1}.$$

Hence we have, recalling (1.2),

(2.8)
$$(2\pi)^{1/2} \hat{\mathbf{n}} = |\xi'|(|\xi'| - i\xi_n)/|\xi|^2$$

$$= \sigma(\mathbf{R}) \cdot \sigma(\mathbf{S}') \{ \sigma(\mathbf{R}) \cdot \sigma(\mathbf{S}') + \sigma(\mathbf{R}_n) \}$$

$$= \sigma(\mathbf{R} \cdot \mathbf{S}' (\mathbf{R} \cdot \mathbf{S}' + \mathbf{R}_n)).$$

Since the Fourier transform of the convolution (in x_n) of h and f is $(2\pi)^{1/2}$ hf, we conclude from (2.7), (2.8) that U = U. In view of (2.5), therefore, (2.6) can be rewritten as

(2.9)
$$u^n = Da^n + U(E(t)V_1u_0 + FV_1a),$$

which is what was desired.

To obtain the tangential component u', we set

$$w = V_2 u = u' + Su^n = u' + (i\xi_n/|\xi'|)u^n$$
.

Then it follows from (1.1a) and (2.2) that

$$w_t - \Delta w = -i\xi' p - (i\xi'/|\xi'|) \partial_n p = -S(|\xi'| + \partial_n) p = 0,$$

and from (1.1c) and (1.1d) that $\gamma w=V_2a$ and $w|_{t=0}=V_2u_0$, respectively. Hence we have $w=E(t)V_2u_0+FV_2a$ or

$$u' = E(t)V_2u_0 + FV_2a - Su^n$$

which, together with (2.9), gives rise to the sum of (1.10b) and (1.11b).

It remains to derive the expression for p. This is done

upon substitution of (2.9) into the n-th equation of (1.1a);

(2.10)
$$\partial_n p = -(u_t^n - \Delta u^n) = -Da_t^n - (\partial_t - \Delta)U(E(t)V_1u_0 + FV_1a).$$

We note that $\partial_t U = U \partial_t$ and $|\xi'|^2 U = U |\xi'|^2$ while, since U = U and since $\partial k(x_n - y_n)/\partial x_n = -\partial k(x_n - y_n)/\partial y_n$ where $k(s) = k(\xi', s)$ is that of (2.1), we have by integration by parts,

$$\begin{split} \partial_{n} U f &= |\xi'| \partial_{n} \int_{0}^{x_{n}} k(x_{n} - y_{n}, \xi') f(y_{n}) dy_{n} \\ &= |\xi'| \{ f(x_{n}) - [k(x_{n} - y_{n}) f(y_{n})]_{y_{n}=0}^{x_{n}} \} + U \partial_{n} f \\ &= |\xi'| k(x_{n}) \gamma f + U \partial_{n} f. \end{split}$$

Iterating this, we get

$$\begin{split} \partial_{\mathbf{n}}^{2} \mathbf{U} \mathbf{f} &= -|\xi'|^{2} \mathbf{k}(\mathbf{x}_{\mathbf{n}}) \gamma \mathbf{f} + |\xi'| \mathbf{k}(\mathbf{x}_{\mathbf{n}}) \gamma \partial_{\mathbf{n}} \mathbf{f} + \mathbf{U} \partial_{\mathbf{n}}^{2} \mathbf{f}. \\ &= -|\xi'| (|\xi'| \mathbf{D} \gamma \mathbf{f} - \mathbf{D} \gamma \partial_{\mathbf{n}} \mathbf{f}) + \mathbf{U} \partial_{\mathbf{n}}^{2} \mathbf{f}. \end{split}$$

Recall that $\sigma(D)=k(x_n)$ for D of (1.8a). Combining these yields

$$(\partial_t - \Delta) \text{Uf} = |\xi'|(|\xi'| \text{D}\gamma f - \text{D}\gamma \partial_n f) + \text{U}(\partial_t - \Delta) f.$$

Consequently, (2.10) becomes

$$\begin{array}{lll} (2.11) & \partial_{n}p = -Da_{t}^{n} - |\xi'|(|\xi'|D\gamma - D\gamma\partial_{n})(E(t)V_{1}u_{o} + FV_{1}a) \\ \\ & = |\xi'|D\gamma\partial_{n}E(t)V_{1}u_{o} - Da_{t}^{n} - |\xi'|(|\xi'|DV_{1}a + D\gamma\partial_{n}FV_{1}a), \end{array}$$

because $z = E(t)V_1u_0 + FV_1a$ solves (1.7) for $b = V_1a$ and $z_0 = V_1u_0$. But $\partial_n p = -|\xi'|p$ by (2.2), so p is given by dividing the last expression in (2.11) by $-|\xi'|$. Noting $-\sigma(D)/|\xi'| = -k(x_n)/|\xi'| = \sigma(N)$, we have

$$p = -D\gamma \partial_n E(t) V_1 u_0 + |\nabla'| DV_1 a + D\gamma \partial_n FV_1 a - Na_t^n.$$

This completes the proof of Theorems 1.1 and 1.2.

3. L^p-L^q estimates.

The formulas derived so far provides us with an easy way to evaluate the solution of (1.1) and its derivatives in various function spaces. Here we will illustrate L^p-L^q estimates of u for the case a=0, using the formula (1.10). The case a=0 can be treated essentially in the same way. In the sequel $\|\cdot\|_p$ will denote the norm of $L^p(\mathbb{R}^n_+)$. Our main result is,

Theorem 3.1. Let $u=(u',u^n)$ be the solution to (1.1) for a=0. Then, for any p,q with $1 < q < p < \infty$, there is a constant $C \ge 0$ such that

(3.1)
$$\|u(t)\|_{p} \le Ct^{-\alpha} \|u_{0}\|_{q}$$

(3.2)
$$\|\nabla u(t)\|_{p} \le Ct^{-\alpha-1/2} \|u_{0}\|_{q}$$

hold for any $u_0 \in L^q(\mathbb{R}^n_+)$ and for all t>0, with

(3.3)
$$\alpha = (n/2)(q^{-1}-p^{-1}).$$

To prove this we need three lemmas. First, according to Calderón-Zygmund [1], Riesz' operators R_j are bounded operators on $L^p(\mathbf{R}^n)$ and S_j on $L^p(\mathbf{R}^{n-1})$, both for $1 . Further, <math>S_j$ can be also looked in a natural way as bounded operators on $L^p(\mathbf{R}^n)$. Hence we have the

Lemma 3.2. For $1 , the operators U, <math>V_1$ and V_2 are all bounded on $L^p(R_+^n)$. Moreover, V_1 and V_2 are also bounded on $L^p(R^{n-1}) = L^p(\partial R_+^n)$.

Next, we recall that U= \hat{U} where \hat{U} is defined by (2.8). Putting $k(s)=k(\xi',s)$ for (2.1) and noting that

$$k(0) = 1$$
, $\partial k(s)/\partial s = -|\xi'|k(s)$,

we readily see that

$$\partial_{\mathbf{n}} U \mathbf{f} = |\xi'| \partial_{\mathbf{n}} \int_{0}^{x_{\mathbf{n}}} k(x_{\mathbf{n}} - y_{\mathbf{n}}) f(y_{\mathbf{n}}) dy_{\mathbf{n}}$$
$$= |\xi'| \{f(x_{\mathbf{n}}) - Uf(x_{\mathbf{n}})\}.$$

Since θ_j , $1 \le j \le n-1$, commute with all R_j and S_j , we thus proved

Lemma 3.3. (i)
$$\partial_{j}U = U\partial_{j}$$
, $1 \le j \le n-1$,

(ii)
$$\partial_n U = (I-U) | \nabla' |$$
,

(iii)
$$\partial_{\mathbf{j}} V_{\mathbf{k}} = V_{\mathbf{k}} \partial_{\mathbf{j}}, \quad 1 \leq \mathbf{j} \leq \mathbf{n}, \quad \mathbf{k} = 1, 2.$$

Finally we shall prove that the solution $z(t)=E(t)z_0$ to the heat equation (1.7) with b=0 enjoys the following L^p-L^q estimates.

Lemma 3.4. For $1 \le q \le p \le \infty$, we have

(3.4)
$$\|E(t)z_0\|_p \le t^{-\alpha}\|z_0\|_q$$
,

(3.5)
$$\|\nabla E(t)z_0\|_{p} \le t^{-\alpha-1/2}\|z_0\|_{q}$$

for any $z_0 \in L^q(\mathbb{R}^n_+)$ and t>0, with α defined by (3.3).

Proof. Recall $E_{0}(t)$ of (1.14), the solution operator for the heat equation in R^{n} . Then $E(t)z_{0}$ defined by (1.6) can be written in terms of $E_{0}(t)$ as

$$(3.6) E(t)z_0 = rE_0(t)\widetilde{z}_0,$$

where $\tilde{z}_{o}(x)$ is the odd extention into $x_{n}<0$ of $z_{o}(x)$;

 $\tilde{z}_{o}(x',x_{n}) = z_{o}(x',x_{n})$ for $x_{n}>0$, and $=-z_{o}(x',-x_{n})$ for $x_{n}<0$. On the other hand, it is well-known from the properties of the heat kernel $E_{o}(t,x)$ that (3.4) and (3.5) holds for $E_{o}(t)$ if the norms are modified for R^{n} , so that the lemma immediately follows in view of (3.6).

Proof of Theorem 3.1. Since we are assuming a=0, the normal component u^n is given by (1.10a), so we have, using (3.4),

$$\begin{split} \|\mathbf{u}^{\mathbf{n}}\|_{\mathbf{p}} & \leq \|\mathbf{U}\|_{\mathbf{p}} \|\mathbf{E}(\mathbf{t}) \mathbf{V}_{1} \mathbf{u}_{0}\|_{\mathbf{p}} \\ & \leq \mathbf{t}^{-\alpha} \|\mathbf{U}\|_{\mathbf{p}} \|\mathbf{V}_{1} \mathbf{u}_{0}\|_{\mathbf{q}} \\ & \leq \mathbf{t}^{-\alpha} \|\mathbf{U}\|_{\mathbf{p}} \|\mathbf{V}_{1}\|_{\mathbf{q}} \|\mathbf{u}_{0}\|_{\mathbf{q}}, \end{split}$$

where $\|U\|_p$ is the operator norm of U on $L^p(R_+^n)$ and similarly for $\|V_1\|_q$. Since these norms are finite owing to Lemma 3.2, we have (3.1) for u^n , and also for u', proceeding similarly with (1.10b). The estimate (3.2) can be obtained essentially in the same way if one uses Lemma 3.3 and (3.5), and notices that

$$|\nabla'| = -\sum_{j=1}^{n-1} S_j \partial_j.$$

This completes the proof of Theorem 3.1.

Remark 3.5. This theorem enables us to construct local and global strong \mathbf{L}^p solutions to the Navier-Stokes equation in \mathbf{R}^n_+ ;

$$u_{t} + u \cdot \nabla u - \Delta u + \nabla p = 0,$$

$$\nabla \cdot u = 0,$$

$$\gamma u = 0,$$

$$u|_{t=0} = u_{0}.$$

In fact, Giga [3] and Kato [5] proved the existence of such L^p solutions for the whole space R^n , and also Giga [3] for arbitrary bounded domains. Their proof makes use of only the estimates (3.1) and (3.2) for the solution of the corresponding Stokes equation. In other words, their proof applies literally to the case R_+^n , by virtue of Theorem 3.1. Thus all theorems in [3,5] remain true for the half

space R_+^n . We will not reproduce them here. As for local L^p strong solutions in R_+^n , see also Weissler [10].

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