



Searching for Supernova Bursts in Super-Kamiokande IV

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Abstract

Super-Kamiokande has been searching for neutrino bursts characteristic of core-collapse supernovae continuously, in real time, since the start of operations in 1996. The present work focuses on detecting more distant supernovae whose event rate may be too small to trigger in real time, but may be identified using an offline approach. The analysis of data collected from 2008 to 2018 found no evidence of distant supernovae bursts. This establishes an upper limit of 0.29 yr^{-1} on the rate of core-collapse supernovae out to 100 kpc at 90% C.L. For supernovae that fail to explode and collapse directly to black holes the limit reaches to 300 kpc.

Unified Astronomy Thesaurus concepts: Core-collapse supernovae (304); Supernova neutrinos (1666); Particle astrophysics (96)

1. Introduction

The observation of neutrinos from SN1987A (Hirata et al. 1987; Bionta et al. 1987; Alexeyev et al. 1988; Aglietta et al. 1988) established the basic mechanism of core-collapse supernovae⁶⁰ featuring neutrino production during the initial matter infall, the subsequent shock revival, and at later times as the remnant proto-neutron star cools (Sato & Suzuki 1987). This production is expected to last several tens of seconds and to carry detailed information on the mechanisms and dynamics of the collapse process.

Since that first observation, several experiments have searched in real time for other galactic supernovae using liquid scintillator (Asakura et al. 2016; Bruno et al. 2017; Monzani 2006), plastic scintillator (Ambrosio et al. 1998), lead (Zuber 2015), heavy-water (Aharmim et al. 2011), and

water-based (Abe et al. 2016a; Köpke 2018) detectors. These have yielded only null results. Such searches focus on the intense burst of neutrinos expected for a canonical explosion at the galactic center (about 10 kpc) in order to overcome intrinsic backgrounds and trigger the detector, as in Ikeda et al. (2007). More distant supernovae likely only produce a weak signal incapable of being detected by such searches. However, this signal has the characteristic distributions of neutrino interactions in space and time that may be used to extract a viable signal from the backgrounds. Such events are the target of the present search.

Although distant supernovae produce only a few neutrino interactions in a terrestrial detector and provide limited information about the collapse mechanism, their observation has other advantages. For example, the accumulation of stars and dust along the galactic plane as viewed from Earth obfuscates optical observations of supernova occurring opposite our position from the galactic center but is no barrier to the neutrino signal. Also, some stars may collapse as so-called “failed supernova,” emitting neutrinos without a corresponding optical counterpart (Nakazato et al. 2013) due to the formation of a black hole.

Offline searches have the potential to uncover hitherto unseen supernovae or to constrain their rate. Indeed, present estimates of the rate of supernovae from observational data are $O(1)$ per 100 yr per galaxy and are accompanied by large uncertainties (Rozwadowska et al. 2021). Note that based on

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⁶⁰ Note that there are Type Ia supernovae that are driven by other mechanisms and do not emit many neutrinos (Wright et al. 2016). In this paper we use the term “supernova” to mean core-collapse supernova.



optical searches (Ando et al. 2005), the supernova rate out to 60 kpc is estimated to be about 0.035 yr^{-1} . As there are few known stars between 60 kpc and 100 kpc, there is no rate expected in this region. However, a neutrino search allows for constraints on the opposite side of the galaxy where optical searches are limited and the detection of a positive signal with only a few neutrino interactions would nevertheless allow for comparison against models. Indeed, the detection of only two dozen neutrinos from SN1987A yielded useful gross variables such as the total neutrino luminosity and the average neutrino energy. Since then distant supernovae searches with neutrinos have been performed at other experiments, including the 1 kiloton (kt) liquid scintillator detector LVD (Agafonova et al. 2015; Vigorito et al. 2020) and at Super-Kamiokande (SK) using earlier data (Ikeda et al. 2007).

This paper describes the search for distant supernova in SK data from the period 2008 to 2018, using an updated analysis technique and newer supernovae neutrino emission models. Sections 2 and 3 present the detector and the search methodology, respectively. A description of the analysis sensitivity is presented in Section 5 before the search results are described in Section 6. Discussion of the result is described in Section 7. Finally, concluding remarks are made in Section 8.

2. The Super-Kamiokande Experiment

Super-Kamiokande is a water Cherenkov detector located ~ 1000 m deep under Mount Ikeno in the Gifu prefecture, Japan. Its 50 kt of ultra pure water are held in a cylindrical stainless steel tank that is optically separated into two regions (Fukuda et al. 2003). The inner detector (ID) forms the main target volume. For the data period in this work it was instrumented with 11,129 twenty inch photomultiplier tubes (PMTs) that observe Cherenkov light from charged particles traversing its 32 kt water volume. The outer detector (OD) serves primarily as a veto of external radiation in the 18 kt water volume surrounding the ID and is instrumented with 8 inch PMTs connected to wavelength-shifting plates. Due to radioactive backgrounds emitted from detector materials in the PMT support structure, most analyses use a 22.5 kt “fiducial” subvolume of the ID (or smaller volumes at low energies; Abe et al. 2016b). However, in the event of a nearby galactic supernova, the neutrino event rate is expected to overwhelm those backgrounds such that the entire ID volume can be used. As discussed below, the present analysis will make use of both the fiducial and full ID volumes in a staged approach to identifying and verifying a distant supernova signal.

Super-Kamiokande has been in operation since 1996 April and has spanned six run periods to date, labeled SK-I through SK-VI. During the SK-I period the detector was operated with 40% photocathode coverage until 2001 July, when it was stopped for maintenance. Following a subsequent accident that destroyed half of the PMTs, SK-II took data with 19% coverage from 2002 until 2005. After recovering the full complement of PMTs in 2006 the SK-III period continued until 2008 when it was stopped for 1 week to upgrade the front-end electronics (Yamada et al. 2010). During this upgrade the electronics were replaced in sections so as to minimize the number of inactive channels at any give time and to minimize the dead time for supernovae detection. The subsequent period, SK-IV, ran for the next 10 yr. In the summer of 2018 the detector was again stopped for maintenance and repairs in

preparation for the addition of gadolinium sulfate to the detector water (Abe et al. 2022). The final pure-water phase, SK-V, was operated from 2019 until the summer of 2020, when the gadolinium compound was added for the first time, marking the start of the SK-Gd project and SK-VI.

This analysis uses the full SK-IV data set, corresponding to 3381.41 live-days. In contrast to earlier phases and the previous distant supernova search, the SK-IV period is characterized by dead-time-free electronics using a low-noise charge-to-time converter (QTC) design (Nishino et al. 2009) that has enabled a lower energy threshold. The event trigger used in this analysis is formed when at least 47 PMTs register hits within any 200 ns time period. This corresponds to efficiency of 54% for positron kinetic energies greater than 5.5 MeV and 99% for energies greater than 8.5 MeV. Although lower-energy triggers are available, the majority of supernova neutrino candidates are expected to be above 5 MeV. In this paper, the term “event” refers to an interaction within the detector satisfying this criterion.

3. Search Methodology

Neutrinos from supernovae are expected to produce a collection of interactions (a “cluster”) in a short time interval with a uniform spatial distribution in a terrestrial detector. For a supernova near the galactic center (10 kpc) such a cluster would contain $O(1000)$ events in SK distributed over 100 s, with the majority occurring in the first 10 s. The number of events in a cluster decreases with the inverse square of the distance.

In order to search for these distant supernovae, this new analysis expands the methods in a previous search (Ikeda et al. 2007) and the methods used in the SK real-time supernova monitor system, “SNWatch” (Abe et al. 2016a). The new method first searches for clusters of events in the 22.5 kt fiducial volume using three different combinations of energy thresholds and time windows, the longest of which is 10 s (described below). Clusters are then subject to additional selection cuts to remove backgrounds stemming from cosmic-muon-induced spallation or electronic noise. These cuts have been optimized using recent supernova neutrino models, described in Section 3.1. If a cluster survives the cuts, the search for additional cluster events will be expanded to include the whole ID volume near that cluster’s time to either bolster confidence in the signal or reject rare backgrounds that have a signal-like topology.

3.1. Supernova Models

Since supernovae producing a high-intensity neutrino burst in the detector are likely to have been identified by the real-time supernova monitor, this search focuses on clusters with a small number of events produced within up to 10 s. While many supernova models offer predictions of neutrino emission for only the first second of the burst, the Livermore model (Totani et al. 1998) provides predictions up to 20 s. Until recently the Livermore model was the only simulation with predictions out to such long times. This late-time property of the model was used in the previous search using earlier SK data (Ikeda et al. 2007). However, the present analysis adopts three newer models: the Mori model (Mori et al. 2020), the Nakazato model (Nakazato et al. 2013), and a model of failed

SN (Nakazato et al. 2013). Each model has more advanced treatments of relativity, neutrino transport, and neutrino interactions during the burst. The former two models are spherically symmetric supernova simulations that explode successfully. The latter model is also one-dimensional, but the star fails to explode and instead produces a black hole. These models address other known issues in the Livermore model, such as the rise in the average neutrino energy at late times. In this study, the Mori model is adopted as the benchmark, while the other two are used for comparison purposes. Figure 1 shows the time evolution of the luminosity and average neutrino energy predictions of the Mori, Nakazato, and failed SN models. The dominant reaction (about 90% of all events) of supernova neutrinos with water is inverse beta decay (IBD), in which a proton and an electron antineutrino react to produce a positron and a neutron ($p^+ + \bar{\nu}_e \rightarrow n + e^+$). We therefore consider only IBD when determining the cut criteria in Section 4. Neutrino oscillations have a small impact on the expected number of observed events (see Mori et al. 2020) and are included in the analysis below assuming both the normal and inverted mass orderings.

3.2. Backgrounds

For this search the most serious source of background comes from muon-induced spallation: the decay products of radioactive nuclei produced in the dissociation of oxygen nuclei following the passage of cosmic-ray muons. A variety of spallation isotopes are formed in muon-oxygen interactions with different half-lives and daughter particle energies (see Li & Beacom 2014, 2015; Zhang et al. 2016). The resulting isotopes from a single muon or from multiple muons may conspire to produce a cluster of events that appear in the search window described below. Fortunately these events are highly correlated with the timing and path of their preceding muon and can be removed efficiently using existing algorithms, referred to as the “spallation cut” below. These are described in Hosaka et al. (2006) and Zhang et al. (2016). This cut rejects about 90% of spallation events between 4 and 20 MeV, while rejecting only 20% of simulated supernova events across all energies.

Other, less frequent, spurious event clusters may be produced by problems in the front-end electronics, discharges at the PMT dynode, or data acquisition troubles that repeat over short intervals and become background to the analysis. Data known to include such problematic events are removed in the present search, although transient incidents falling in an otherwise normal data set are possible. The event selection process automatically removes most of those problematic events, but others must be removed manually at the end of the analysis by visual scanning.

4. Event Selection

At the first stage of the analysis, events are required to have a reconstructed vertex within the 22.5 kt fiducial volume defined as the region of the ID more than 2 m from any of its walls. At a later stage of the analysis, following the cluster search described below, we also use events outside of this volume to potentially augment the signal from a supernova candidate. Events passing the initial fiducial volume cut are then subject to a test on their reconstructed quality. The cut uses a goodness parameter based on the width of the PMT residual timing

distribution to the reconstructed vertex, g_t in Cravens et al. (2008), and a second goodness parameter testing the azimuthal symmetry of the reconstructed hit pattern, g_p in Abe et al. (2016b). See Appendix A for their definitions.

The total fit quality is formulated as $g_t^2 - g_p^2$ and ranges from 0 to 1, where 1 represents better fit quality. Simulated supernova neutrinos have an average fit quality of 0.45, whereas for spallation events the average fit quality is near 0.25. Based on this, events are required to have a fit quality greater than 0.25. See Appendix B for more detail. Finally, since some spallation isotopes have very short lifetimes, the search requires a time difference of more than 50 μ s between all events. This cut predominantly removes most Michel electrons from untaged muons with minimal impact on the supernova burst search.

Figure 2 shows simulated energy spectra from different models integrated over the first 20 s and an “estimated background,” consisting of data from a single 24 hr run in 2011 that is assumed to contain no supernova events. The figure shows events after selection inside (left) and outside (right) of the fiducial volume. These show that most of the background events accumulate at energies below 15 MeV. The bottom panel of the figure shows the events inside the fiducial volume after applying the spallation cut. Remaining events in the background can be attributed to spallation events that passed the selection as well as other types of events, such as solar neutrinos or electronics noise. Note that the spallation cut has not been tuned for the region outside of the fiducial volume so will not be used there in this analysis. The figure shows the non-supernova event rate is less than 10^{-2} events over 20 s above 5.5 MeV inside the fiducial volume. Similarly, outside the fiducial volume and above 15 MeV the event rate is also less than 10^{-2} . These energies are chosen as additional cuts applied to these two regions. The cuts for this stage of the event selection are summarized in Table 1.

4.1. Cluster Search

Events surviving the preselection above are passed to a search algorithm that identifies clusters of events occurring within any of three specified time windows. The limits of these time windows are chosen based on the evolution of the neutrino flux during a supernova using criteria from the previous study (Ikeda et al. 2007). The 0.5 s window corresponds to the time between the initial collapse and subsequent bounce. The 2 s window covers the time until the shock is revived. The 10 s window corresponds to the neutron star cooling phase. In order to enhance the analysis efficiency, the event thresholds for these time windows are roughly half those used in the previous study, requiring at least 2, 2, and 4 events per cluster, respectively. The time windows are shown in Table 2. These criteria were analyzed to ensure they increased sensitivity without increasing the rate of background clusters. The number of events forming a cluster identified by the selection criteria is referred to as the cluster’s multiplicity. See Section 5.1 for details.

4.2. Spatial Classification and Cluster Cuts

For supernova, the spatial distribution of events in the detector is expected to be uniform within its volume. In contrast, spallation background events are expected to be distributed along their parent muon’s track. When the event

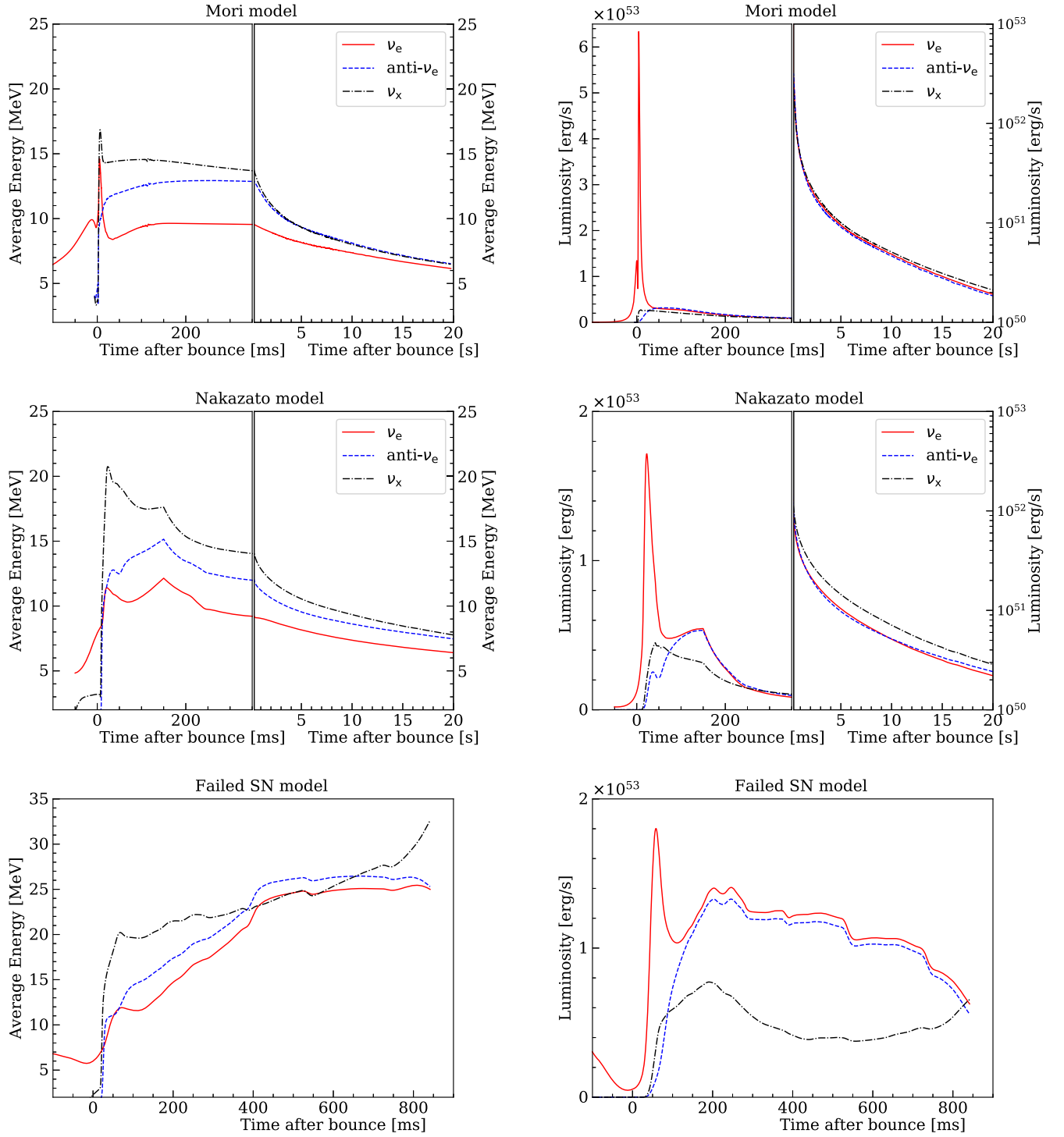


Figure 1. Average energy and luminosity of neutrinos in the Mori (top), Nakazato (middle), and failed SN (bottom) models. The left panels show the average energy, and the right panels show the luminosity. The horizontal axis shows the time relative to the supernova bounce, where the figures are divided into the region -100 ms to 350 ms and 350 ms to 20 s for the Mori and Nakazato models. The horizontal axis for the failed SN model ranges up to 800 ms after the bounce. Red lines denote electron neutrinos, blue lines their antineutrinos, and the black lines represent all other neutrino species.

multiplicity in a cluster is low the observed event distribution may deviate from these ideals. To account for this, clusters are separated into four spatial classifications—volume-like, plane-like, linelike, and pointlike—based on the vertex distribution of their events. The algorithm uses the eigenvalues of the correlation matrix of vertices, $\langle (x_i - \langle x_i \rangle)(x_j - \langle x_j \rangle) \rangle$, where i and j label axes of the vertices, to determine which of the

geometries is most consistent with the vertex distribution. More details can be found in Abe et al. (2016a).

Clusters are then subject to different cuts depending upon their spatial classification. Three variables are introduced for this purpose: the average kinetic energy of its reconstructed positron candidates, $\langle E_{\text{kin}} \rangle$, the average pairwise distance between event vertexes in a cluster, $\langle D \rangle$, and the average

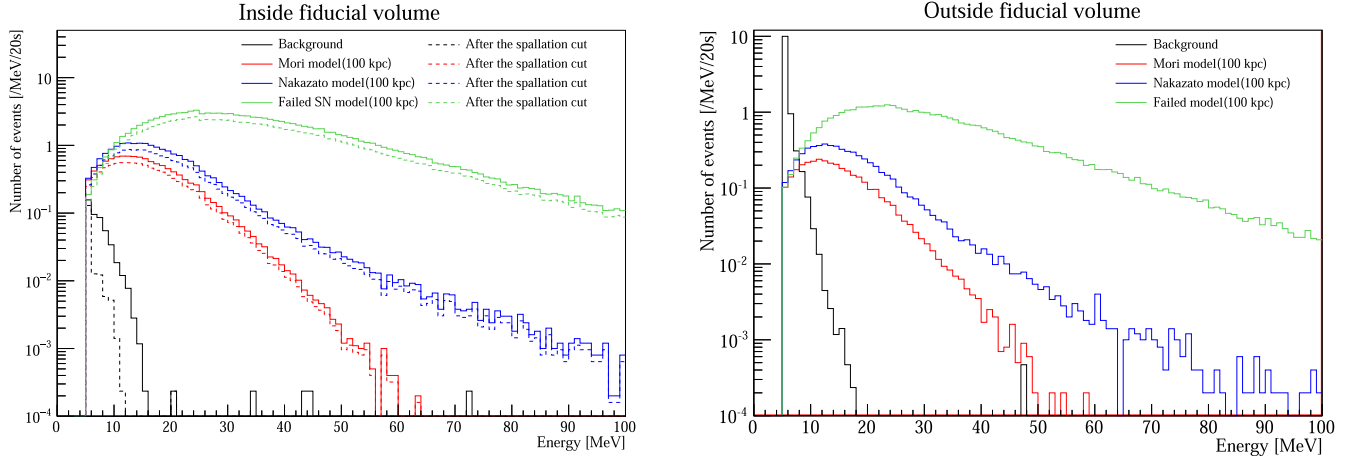


Figure 2. The spectra of background and supernovae MC at 100 kpc for the Mori and Nakazato models inside and outside the fiducial volume after the event selection in Table 1. Here data from a single 24 hr run from 2011 August is used for the background and we use only IBD interactions in the signal models (black lines). The solid lines show the result before the spallation cut, and the dashed lines show the result after the spallation cut. At present there is no spallation cut for the region outside the fiducial volume. Red lines show the Mori model and blue lines show the Nakazato model. Red lines show the Mori model, blue lines show the Nakazato model, and green lines show the failed SN model. All histograms have been normalized to the expected number of events in 20 s from an SN at 100 kpc.

Table 1
Event Selection Criteria for the Input to the Cluster Search

	Inside Fiducial Volume	Outside Fiducial Volume
Vertex distance to ID wall	>200(cm)	$0 < d < 200(\text{cm})$
Time difference to previous event	>50 [μs]	>50 [μs]
Energy	>5.5 [MeV]	>15 [MeV]
Fit quality	>0.25	>0.25

Note. The fiducial volume is defined as the region 200 cm inside of the ID wall. Here the energy cut refers to the total energy of positron candidates.

residual distance of event vertexes to the cluster centroid, $\langle \Gamma \rangle$. They are defined as

$$\langle E_{\text{kin}} \rangle = \frac{\sum_{i=1}^M E_i}{M}, \quad (1)$$

$$\langle D \rangle = \frac{\sum_{i < j}^M |d_i - d_j|}{M C_2}, \quad (2)$$

$$\langle \Gamma \rangle = \sqrt{\frac{1}{3(M-1)} \sum_{i=1}^M (d_i - d_0)^2}, \quad (3)$$

where M is the number of events included in a cluster (the multiplicity), E_i is the total positron candidate energy of the i th event in a cluster, d_i is the vertex of that event, $M C_2$ is the number of combinations of M taken two at a time, and $d_0 = 1/M \times \sum_{i=1}^M d_i$ is the centroid of the cluster.

Clusters from spallation events are expected to have lower $\langle E_{\text{kin}} \rangle$ and smaller $\langle D \rangle$ than supernova clusters. Spallation clusters typically have $\langle D \rangle$ less than 1000 cm and $\langle E_{\text{kin}} \rangle$ less than 10 MeV, while supernova clusters have larger values. However, spallation clusters can have $\langle D \rangle$ larger than 2000 cm for muon tracks traversing the entire length of the SK ID and producing multiple spallation isotopes. Similarly, a group of muons from a single cosmic-ray shower bundle can produce several spallation events across the detector resulting in large values of $\langle D \rangle$.

Table 2
Time Window Settings

Time window 1	≥ 2 events in 0.5 [s]
Time window 2	≥ 2 events in 2 [s]
Time window 3	≥ 4 events in 10 [s]

Clusters are divided into six types, based on their spatial classification and the number of events they contain, as summarized in Table 3. Low-multiplicity linelike and pointlike clusters were found to have sufficiently different distributions in the variables above to warrant separate cuts from their higher-multiplicity counterparts. In particular, for pointlike clusters with only three events, signal and background can be efficiently separated without using $\langle E_{\text{kin}} \rangle$, thereby reducing the dependence of cut tuning on the choice of supernova model.

Cuts on the variables in each of the six types have been optimized using machine learning (ML) methods provided by the “Scikit-learn” Python package (Pedregosa et al. 2011). The logistic regression (LR) and support vector machine (SVM) methods were used because they provide the highest accuracy (score) for correctly identifying signal and background clusters (Bishop 2006). When performing the optimization, a sample of clusters from 200 days of data (tagged as spallation-like by the spallation likelihood) serves as the background model. The signal simulation uses 30,000 supernova clusters generated using the Mori model assuming distances between around 100 kpc and 500 kpc and including neutrino oscillation effects for the normal mass hierarchy calculated according to Dighe & Smirnov (2000). These signal clusters typically have multiplicities of between three and seven events. During training, the background and supernova samples were balanced for each cluster category with background events having a weight of 20 compared to a weight of 1 for signal events.

In order to account for systematic errors in the reconstruction during cut optimization, the number of signal and background clusters is artificially increased by a factor of 10. Each cluster was used to generate nine additional clusters, drawn from a random Gaussian distribution centered at the parent cluster’s $\langle E_{\text{kin}} \rangle$ and $\langle D \rangle$ with widths corresponding to the expected resolution in these variables, 1.5 MeV and 30 cm, respectively.

Table 3
The Six Cluster Categories and Their Additional Cut Criteria

Category	Volume-like	Planelike	Linelike Low Multiplicity	Linelike High Multiplicity	Pointlike Low Multiplicity	Pointlike High Multiplicity
Cut Variables	$\langle D \rangle$ vs. $\langle E_{\text{kin}} \rangle$	$\langle D \rangle$ vs. $\langle E_{\text{kin}} \rangle$	$\langle D \rangle$ vs. $\langle E_{\text{kin}} \rangle$	$\langle D \rangle$ vs. $\langle E_{\text{kin}} \rangle$	$\langle D \rangle$ vs. $\langle E_{\text{kin}} \rangle$	$\langle D \rangle$ vs. $\langle \Gamma \rangle$
M	...	...	≤ 3	≥ 4	≤ 3	≥ 4
$\langle D \rangle$	...	...	...	...	≥ 500 cm for $M \geq 3$	or ≤ 500 cm for $M \leq 3$

Table 4
Machine Learning Models for Each Cluster Category and Resulting Scores

Category	Volume-like	Planelike	Linelike Low Multiplicity	Linelike High Multiplicity	Pointlike Low Multiplicity	Pointlike High Multiplicity	Weighted Average
ML model	LR	LR	SVM	SVM	SVM	SVM	...
Signal score	0.951	0.935	0.911	0.878	0.879	0.984	0.919
Fraction	0.119	0.501	0.070	0.257	0.043	0.010	1.0
Background score	0.971	0.993	0.994	0.939	0.950	0.999	0.994
Fraction	0.004	0.412	0.027	0.028	0.002	0.527	1.0

Note. Fraction denotes the fraction of the corresponding sample in each category. The Weighted Average column is the sum of scores weighted by those fractions.

Training samples for the optimization were formed from 80% of the resulting distributions, with 20% used for validating the optimized cuts (called the “test” sample).

Table 4 shows the background and signal classification scores after cut optimization for the six cluster types. The score represents the fraction of events of a given category, signal, or background that were correctly classified. When selecting a model for each category, preference was given to that with the highest background score. If multiple models had the same background score then the one with the highest signal score was chosen. Using this method the LR was adopted for the volume-like and planelike categories and SVM for the others. The “weighted average” column of the table represents the sum of scores across the signal (background) row weighted by the relative fraction of signal (background) clusters in each column of that row. These weights are shown in the rows labeled as “Fraction.” The corresponding signal and background scores are 0.994 and 0.919, respectively. However, we note that this information is simply added for reference and was not used in the selection of ML models. Figure 3 shows the results of the cut optimization overlaid with the test signal and background samples. The black cluster in the signal region in the bottom right panel of Figure 3 is due to spallation events produced by multiple muons. As seen in the figure such pointlike clusters are rare and are easily removed with the spallation cut (see Figure 5).

Clusters that are classified as signal-like by the ML method for their type are then passed to the spallation cut.⁶¹ The spallation cut is applied on an event-by-event basis meaning that some clusters may contain both spallation-like events and other events. In these cases the spallation-like events are removed from the cluster, the input variables for the ML cut are recomputed, and the ML cut is reapplied. Any signal-like clusters remaining are then subject to further cross checks to reduce backgrounds from transient instabilities in the front-end electronics. The search is then expanded to the outer fiducial volume around the time of any clusters remaining to determine

if there are other events that should be associated with that cluster.

5. Analysis Performance

The effect of the event-by-event selection (discussed in Section 4) on the “background” from 1 day of the SK data and simulated supernovae for the Mori and Nakazato models is shown in Table 5. A supernova distance of 1 kpc was assumed to give large data sets. The numbers in brackets show the efficiency relative to the previous cut. The total efficiency, including all cuts, is 72.9% (27.5%) for the Mori model and 75.1% (34.4%) for the Nakazato model and background rejection is 99.3% (99.9%) inside (outside) the fiducial volume. Inside the fiducial volume the fit quality cut is the most effective at reducing backgrounds, whereas the energy cut dominates the reduction outside of the fiducial volume.

5.1. Monte Carlo Simulation of Observation

In order to estimate the expected event rate and analysis efficiency as a function of the supernova distance, several simulated supernovae were generated from the Mori and Nakazato models assuming oscillations under both the normal and inverted mass hierarchies (Dighe & Smirnov 2000).⁶² The failed supernova model from Nakazato, in which the star collapses directly to a black hole, and the Livermore model were also simulated. Here 1000 supernovae were simulated at each assumed distance. Figure 4 shows the detection probability P_{detect} .

$$P_{\text{detect}} = \frac{N_{\text{detected}}}{N_{\text{sim}}}, \quad (4)$$

where N_{detected} is the number of detected simulations and N_{sim} is the total number of simulations. Here “detected” means a simulation that includes at least one event cluster satisfying the cluster criteria described in Section 4.2.

⁶¹ Since this cut is computationally expensive it is only applied to passing signal-like clusters.

⁶² Note that this model of oscillations assumes adiabatic flavor conversions, though other transitions are also possible.

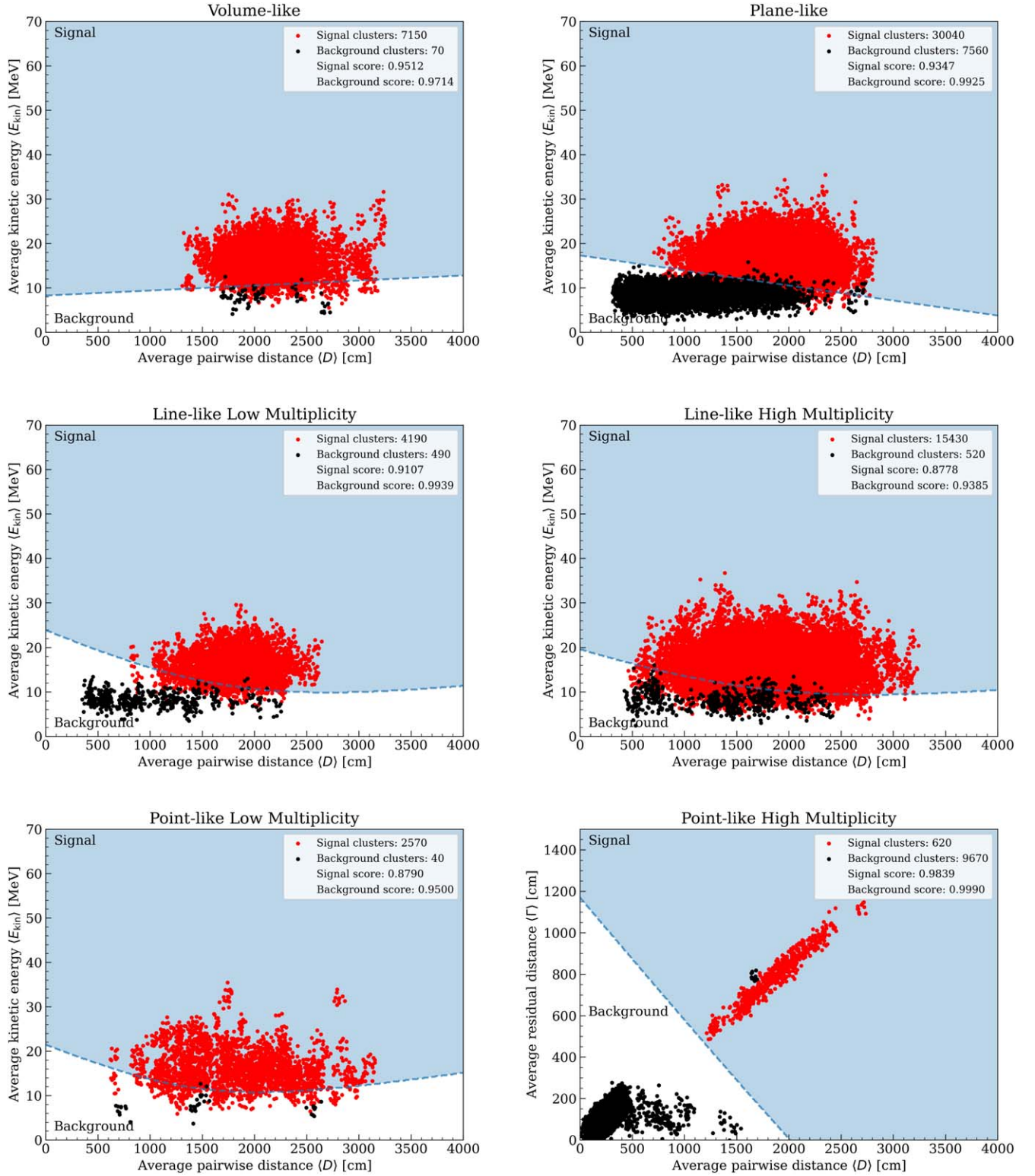


Figure 3. Optimized ML classification curves for the six cluster types and classification results for the test sample. Red points denote the supernova signal, and black points are background taken from 204 days of data. The blue regions are classified as signal-like while the white regions are background-like. Note that the spallation cut has not been applied.

The left panel of Figure 4 shows that the detection probability for all models is 1.0 up to at least 100 kpc. Further, in the present study the nonzero detection probability extends to larger distances than that of the previous analysis, which was based on the Livermore model, with a similar energy threshold. For the Mori and Nakazato

models the detection probability drops to a few percent at around 500 kpc, representing the limit of the present search's sensitivity. Detection probabilities for all models are also presented in Table 6.

The right panel of Figure 4 shows the average number of events detected in a cluster as a function of distance to the

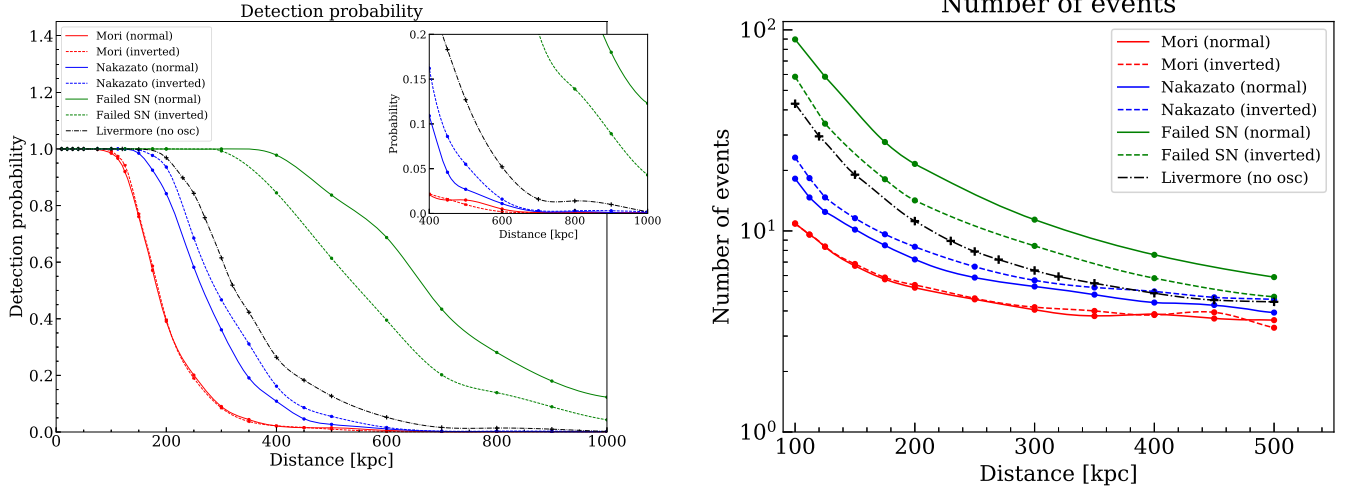


Figure 4. Predicted detection probability and number of detected events as a function of distance for several models.

Table 5

Reduction Summary Using 1 Day of Data and Simulated SN Events at 1 kpc
Using the Mori and Nakazato Models

Background Data		
	Inside Fiducial Volume	Outside Fiducial Volume
Reconstructed events	40215	166680
Energy cut	16018 (39.8%)	12 (0.01%)
Time difference cut	40192 (99.9%)	166585 (99.9%)
Fitting quality cut	2005 (5.0%)	49178 (29.5%)
Spallation cut	17621 (43.8%)	...
All cuts	297 (0.74%)	12(0.01%)
Mori Model at 1 kpc		
	Inside Fiducial Volume	Outside Fiducial Volume
True events	126067	55987
Reconstructed events	123995 (98.4%)	39044 (69.7%)
Energy cut	116287 (92.2%)	15505 (27.7%)
Time difference cut	...	...
Fitting quality cut	119521 (94.8%)	37336 (66.7%)
Spallation cut	99196 (78.7%)	...
All cuts	91864 (72.9%)	15396 (27.5%)
Nakazato Model at 1 kpc		
	Inside Fiducial Volume	Outside Fiducial Volume
True events	177847	78738
Reconstructed events	175197 (98.5%)	55396 (70.4%)
Energy cut	168769 (94.9%)	27293 (34.7%)
Time difference cut	...	...
Fitting quality cut	170772 (96.0%)	53520 (62.5%)
Spallation cut	140157 (78.8%)	...
All cuts	133553 (75.1%)	27113 (34.4%)

Note. Cut criteria are shown in Table 1.

supernova for several models and oscillation assumptions. On average 10 events are expected for the Mori model at 100 kpc and 15 events for the Nakazato model. This average does not follow an inverse square law with distance since at least two events are required to define a cluster (see Table 2). The predicted number of events for each model is summarized in Table 7.

6. Data Analysis and Result

All SK data from the SK-IV period, representing 3318.41 days of livetime, were used in the analysis. There were 151,923 clusters found by the cluster search, 362 of which were classified as volume-like and 60,972 of which were planelike. Further, 4857 and 4759 clusters were classified as linelike low multiplicity and high multiplicity, with 186 pointlike low-multiplicity and 80,787 high-multiplicity clusters as shown in Table 8.

Figure 5 shows the final remaining clusters before and after application of the spallation cut. One cluster remains after all of the event selections and is classified as a linelike high-multiplicity cluster. This cluster is discussed in detail in the next section.

7. Discussion

After all analysis cuts one supernova-like cluster remains. A visual scan of the events in the cluster found that they are consistent with particle interactions and cannot be attributed to noise in the detector or its electronics. The three events in the remaining cluster have an $\langle E_{\text{kin}} \rangle$ of 19.97 MeV and their individual times and vertexes are summarized Table 9.⁶³ We define the average residual distance $\langle \Gamma^{\text{Line}} \rangle_{\text{min}}$, which is the average distance of events from the best-fit line through the cluster:

$$\langle \Gamma^{\text{Line}} \rangle_{\text{min}} = \min_{\mathbf{x}(\alpha)} \left\{ \sqrt{\frac{M}{2(M-2)} \sum_{i=1}^M (\mathbf{d}_i - \mathbf{x}(\alpha))^2} \right\}, \quad (5)$$

where $\mathbf{x}(\alpha) = \mathbf{d}_0 + \alpha \mathbf{n}$, with α a real number and $\mathbf{n}$ a unit vector, specifies a line that passes through the centroid ($\mathbf{d}_0$) of the cluster. Figure 6 shows the distribution of this parameter for linelike clusters. The last two events are separated spatially by only 74 cm, while the first is separated from those two by ~ 3500 cm giving $\langle D \rangle = 2361$ cm. Note that if this cluster is attributed to a supernova, the p -value for observing an event with an energy larger than that of the largest energy event in the cluster is 0.3% for the Mori model. Even the most energetic

⁶³ The detector coordinates have the origin at the center of the tank with the x - and y -axes parallel to its top and bottom surfaces. The z -axis is along the central axis of the detector. Further details can be found in Nakahata et al. (1999).

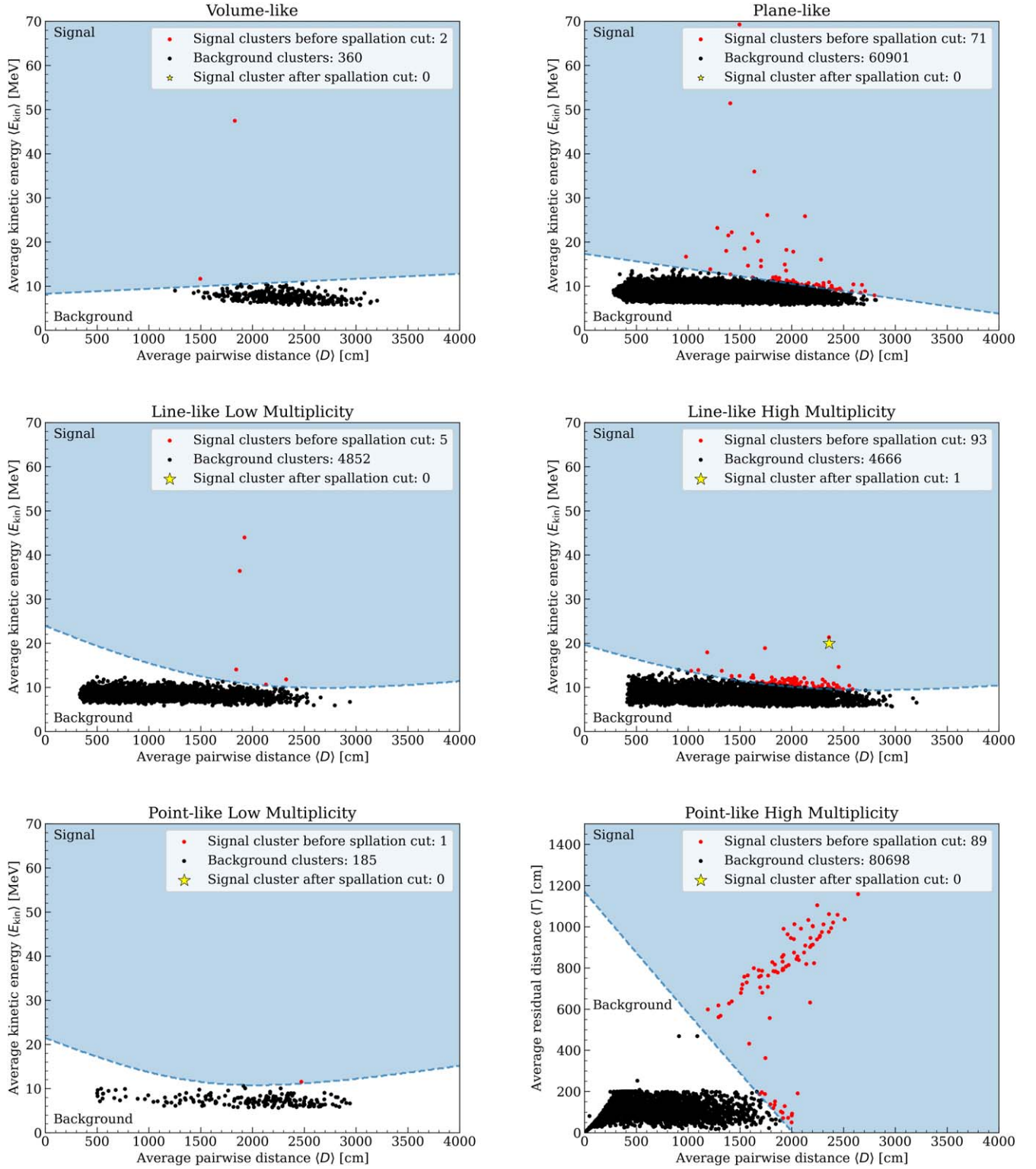


Figure 5. Results of the cluster search on the full SK-IV data set before and after application of the spallation cut. Red (black) points denote clusters falling into the blue (white) signal-like (background-like) regions before application of the spallation cut. The star denotes the lone remaining signal-like cluster after application of the spallation cut.

photons from spallation nuclei are below 20 MeV, indicating that this event is more consistent with the expected energy of a Michel electron from a decayed muon. However, looking at all muons preceding these events none are found with a stopping point consistent with the position of this event.

Another possibility is that light from particles produced in interactions of the form $\nu_\mu + [16]O \rightarrow \mu^- + [16]F$ or $\bar{\nu}_\mu + [16]O \rightarrow \mu^+ + [16]N$ in coincidence with a 5.79 MeV background event could explain this cluster. In the case of the latter, the 44.77 MeV and 9.35 MeV events could be explained by the

Table 6
Detection Probability for Each Model as a Function of Distance for Several Models and Oscillation Assumptions

Model	100 kpc	200 kpc	300 kpc	400 kpc	500 kpc	600 kpc	700 kpc	800 kpc	900 kpc	1000 kpc
Mori (Normal)	0.985	0.391	0.090	0.021	0.015	0.005	0.001	0.001	0.001	0.001
Mori (Inverted)	0.993	0.397	0.085	0.022	0.010	0.002	0.001	0.001	0.001	0.001
Nakazato (Normal)	1.000	0.842	0.361	0.109	0.027	0.011	0.002	0.002	0.001	0.001
Nakazato (Inverted)	1.000	0.936	0.467	0.162	0.055	0.016	0.003	0.003	0.003	0.002
Failed SN (Normal)	1.000	1.000	1.000	0.978	0.837	0.687	0.434	0.281	0.180	0.123
Failed SN (Inverted)	1.000	1.000	0.993	0.845	0.614	0.395	0.202	0.139	0.089	0.043
Livermore (No osc)	1.000	0.969	0.615	0.264	0.127	0.052	0.016	0.014	0.010	0.002

Note. These numbers are used in the left panel of Figure 4.

Table 7
Prediction of the Number of Events as a Function of Distance for Several Models and Oscillation Assumptions

Model	100 kpc	200 kpc	300 kpc	400 kpc	500 kpc
Mori (Normal)	10.9	5.2	4.1	3.9	3.6
Mori (Inverted)	10.9	5.4	4.2	3.8	3.3
Nakazato (Normal)	18.2	7.2	5.3	4.4	3.9
Nakazato (Inverted)	23.2	8.3	5.7	5.0	4.6
Failed SN (Normal)	89.7	21.5	11.4	7.6	5.9
Failed SN (Inverted)	58.5	14.2	8.4	5.8	4.7
Livermore (No osc)	42.9	11.2	6.4	4.9	4.4

Note. These numbers are used in the right panel of Figure 4.

Table 8
Summary of Clusters before the Spallation Cut

Category	Signal Region	Background Region	Total
Volume-like	2	360	362
Planelike	71	60901	60972
Lineline Low Multiplicity	5	4852	4857
Lineline High Multiplicity	93	4666	4759
Pointlike Low Multiplicity	1	185	186
Pointlike High Multiplicity	89	80698	80787
Total	261	151662	151923

Table 9
Event Information of the Remaining Cluster, where Time Is Measured from the First Event and x , y , and z are Vertexes in the Tank

Time [s]	x [cm]	y [cm]	z [cm]	Kinetic Energy [MeV]
0.0	414	1363	-1261	5.79
0.83	-869	-909	1101	44.77
0.95	-842	-845	1126	9.35

Note. The first event was recorded at 19:50:11 on 2008 July 7 UTC.

Michel electron of a below-Cherenkov-threshold μ^+ followed by a photon from the $[16]\text{N}$ decay ($\tau = 7.13$ s), respectively. For the former, an above-threshold μ^- and its subsequent capture on ^{16}O to produce ^{16}N would provide the mechanism.

Calculating the average residual distance of these events to the best-fit line returned by the lineline fit yields a distance of 32 cm. Figure 6 shows the average residual distance from the

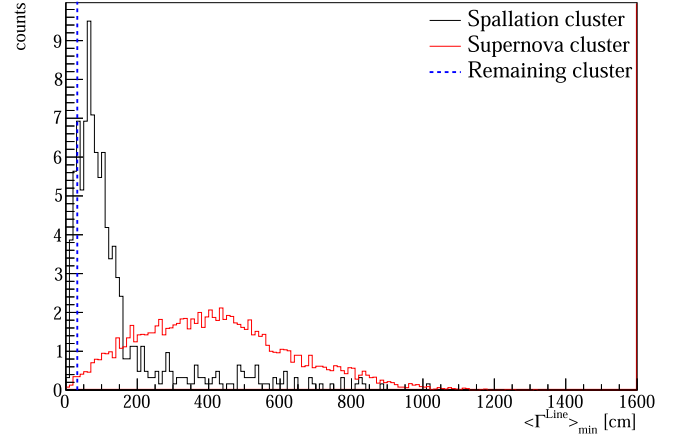


Figure 6. The average residual distance from the best-fit line for lineline clusters. The red histogram shows the distribution for supernova clusters and the black is for spallation clusters. The average residual distance of the candidate cluster is 32 cm.

best-fit line for lineline clusters. Supernova clusters peak at around 450 cm, while the peak for spallation clusters is around 70 cm. In this metric only 0.59% (12.4%) of supernova (spallation) clusters have a residual distance smaller than 32 cm, indicating this cluster is more consistent with spallation. Despite the tight residual distance to a line no muons were found passing in the vicinity of the line found by the lineline fit in the 60 s of data prior to the start of this cluster. For these reasons this cluster of events is not easily explained as either supernova neutrino interactions nor as the decays of spallation products. As a result, two limit calculations are presented in Equations (8) and (9), one of which considers this candidate representative of an unknown background source that occurs once in the current data set and one that does not. Note that the candidate cluster is not removed from the observation when computing either limit.

7.1. Upper Limit

Since no clear candidate supernova clusters were found in the analysis, an upper limit on the rate of supernovae out to 100 kpc is calculated. This limit is valid for all models and hierarchies considered, except that for the failed supernovae. For that case the limit can be extended to 400 kpc assuming the normal mass hierarchy since the detection probability is 1.0 at this distance, and similarly out to 300 kpc for the inverted hierarchy (see Figure 4). We have one background cluster and

the upper limit at 90% confidence level is calculated using

$$0.9 = \frac{e^{bT_{\text{live}}}}{bT_{\text{live}} + 1} \int_0^{\lambda_{\text{lim}}} e^{-(\lambda + bT_{\text{live}})} (\lambda + bT_{\text{live}}) d\lambda, \quad (6)$$

where b is background rate and T_{live} is the livetime.

The upper limit on the supernova rate is then given by

$$R_{\text{SN}} = \frac{\lambda_{\text{lim}}}{T_{\text{live}} p_{\text{detect}}}, \quad (7)$$

where p_{detect} is the detection probability at 100 kpc. The background rate b is estimated from 204.8 days of data taken at random from normal runs in SK-IV after applying the spallation cut. We increase the effective statistics by generating 100 additional clusters for each passing cluster in the same manner as used in the ML training described above. As a result, 27 clusters are found across all signal regions. The background rate is therefore

$$b = \frac{27}{204.8 \text{ days} \times 100} = 0.4812 \text{ yr}^{-1}. \quad (8)$$

Tests with larger numbers of additional clusters yielded nearly identical background estimations. However, this estimation may not account for the type of cluster responsible for the remaining candidate in Figure 5. To account for this possibility, we additionally consider a modified background rate, where this candidate is considered to represent an unmodeled background:

$$b' = 0.4812 + \frac{1}{3318.41 \text{ days}} \times 365 = 0.5911 \text{ yr}^{-1}. \quad (9)$$

Using either background estimate the resulting upper limit at 90% C.L. is unchanged in the first two decimal places. The resulting upper limit from this analysis is 0.29 supernovae per year out to 100 kpc.

8. Summary

This analysis presents a search for neutrinos from distant supernovae carried out using roughly 10 yr of SK data. Relative to the previous analysis from SK, the present work adopts modern supernova simulations and event selections optimized with machine learning tools. For the Mori model the detection probability is 98.5% at 100 kpc and 39.1% at 200 kpc assuming the normal mass hierarchy. Using the Nakazato model the probabilities are 100% and 84.2%, respectively. No significant signal excess was found in the search, resulting in a 90% confidence level limit on the rate of supernovae of 0.29 per year out to 100 kpc for these models and out to 300 kpc for the failed supernova model. These may be compared with recent result from LVD of 0.09 per year out to 25 kpc (Vigorito et al. 2020) and to 0.32 per year from our

previous search (Ikeda et al. 2007). Despite the decreased event rate expected from modern models relative to that in the latter, the present work slightly improves on its limit at the same distances.

Appendix A Definition of the Goodness Parameter

The definition of g_i combines two timing residuals for the vertex $\mathbf{v}$ as

$$g_i = \sum w_i e^{-\frac{1}{2} \left(\left(\frac{t_i - \tau_i(\mathbf{v}) - t_0}{\omega} \right)^2 + \left(\frac{t_i - \tau_i(\mathbf{v}) - t_0}{\sigma} \right)^2 \right)}, \quad (A1)$$

with

$$w_i = \frac{1}{e^{-\frac{1}{2} \left(\frac{t_i - \tau_i(\mathbf{v}) - t_0}{\omega} \right)^2}}, \quad (A2)$$

where $\omega = 60$ ns and $\sigma = 5$ ns. Here t_i is the time of the hit, $\tau_i(\mathbf{v})$ is the time-of-flight-corrected hit time assuming direct travel from the vertex to the i th PMT, and t_0 is the light emission time. See Cravens et al. (2008) for details. Super-Kamiokande observes Cherenkov light from charged particles as rings projected on its wall. A goodness parameter is used to study the uniformity of the PMT hit pattern around this ring. This parameter, g_p , is defined as

$$g_p = \frac{\max_i \{ \angle_{\text{uni}}(i) - \angle_{\text{data}}(i) \} - \min_i \{ \angle_{\text{uni}}(i) - \angle_{\text{data}}(i) \}}{2\pi}, \quad (A3)$$

where $\angle_{\text{data}}(i)$ is the azimuthal angle of the i th hit PMT included in a moving 50 ns time window and $\angle_{\text{uni}}(i)$ is the angle when a uniform PMT hit distribution is assumed. The origin of this angle is taken to be along the perpendicular line connecting the reconstructed direction with the earliest hit PMT in the ring.

Appendix B Performance of the Goodness Parameter

This appendix details the performance of the goodness parameter $g_i^2 - g_p^2$ discussed in Section 4 for supernova neutrino events and background events. Figure 7 shows the goodness distribution of events both inside and outside of the fiducial volume. The background distribution in either case largely populates the region below 0.25, whereas signal events are mainly above this threshold. As a result, the present analysis uses events with goodness greater than 0.25. Table 10 summarizes the fraction of events above this threshold for the background and signal models.

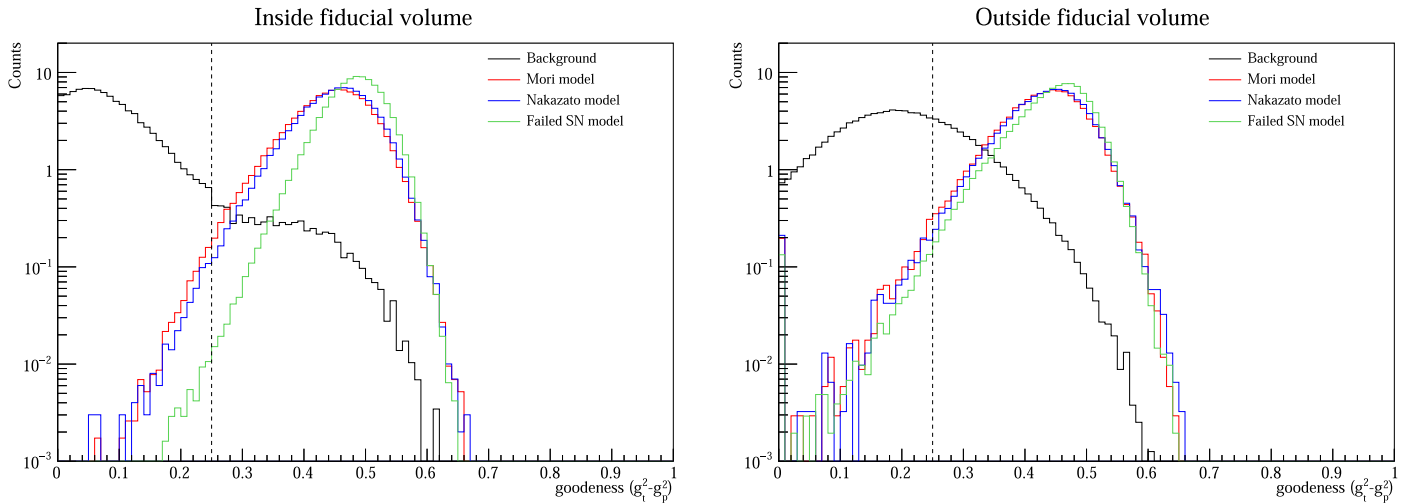


Figure 7. Goodness distribution of background and supernova events. The left panel shows events reconstructed inside of the fiducial volume, and the right panel shows those outside of the fiducial volume. The dashed lines indicate the cut position, $g_t^2 - g_p^2 = 0.25$. All histograms are normalized to an area of 100 events, and events are required to have energies greater than 5.0 MeV.

Table 10

Fraction of Events Passing the Goodness Threshold of 0.25 for Events Reconstructed Inside and Outside of the Fiducial Volume

	Background	Mori	Nakazato	Failed SN
Inside	5.0%	94.8%	94.9%	96.0%
Outside	29.5%	66.7%	62.5%	64.5%

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