

K.OKUBO: CONNECTION PROBLEMS FOR EQUATIONS OF FUCHSIAN CLASS AND FOR THEIR LAPLACE ADJOINT.

Differential Equations:

$$(1) \quad L[y] = t(dy/dt) + (A + tB)y = 0$$

$$(2) \quad M[x] = (t-B)dx/dt - (A-I)x = 0$$

$$(3) \quad N[z] = (t-B)dz/dt - Az = 0$$

Assumptions. x, y, z n -vectors: A, B n by n matrices.

(A-1) $B = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$ $\lambda_1 = \lambda_2 = \dots = \lambda_p$, otherwise $|\lambda_j - \lambda_k| > |\lambda_k| > 0$.

(A-2) $A = (a_{j,k})$. The initial block $A' = (a_{j,k})$ $1 \leq j, k \leq p$ is diagonal matrix.

(A-3) All the diagonal elements a_{kk} ($k=1, 2, \dots, n$) are non-integral.

(A-4) The eigenvalues $\rho_1, \rho_2, \dots, \rho_n$ of the matrix A ; $\det(\rho_j I - A) = 0$ satisfy:

$$\rho_j - \rho_k \neq 0 \pmod{1}$$

except for one set of q eigenvalues. But the system (1) at $t=0$, the systems

(2.), (3) at $t = \infty$ have no logarithmic solution.

(A-5) All the quantities $\rho_j - a_{kk}$ ($j, k=1, 2, \dots, n$) are non-integral.

(A-6) At least one of ρ_j 's is zero. (Just for the sake of simplicity).

Theorem 1. The system (3) has an independent set of solutions:

$$z_k(t) = \sum_{m=0}^{\infty} g_k(m) (t - \lambda_k)^{a_{kk} + m} \quad (k=1, 2, \dots, n)$$

and we have:

$$\det(z_1(t), z_2(t), \dots, z_n(t)) = \prod_{k=1}^n [(t - \lambda_k)^{a_{kk}} \Gamma(a_{kk} + 1) / \Gamma(\rho_k + 1)]$$

in a simply connected compact domain containing the origin $t=0$.

Theorem 2. The monodromy group of the system (3) with respect to the above set of solutions is a free group generated from:

$M_1 = T_1^{-1} \text{diag}[e_1, e_2, \dots, e_p, 1, \dots, 1] T_1$, $T_1 - I$ contains non-zero elements in the p by $n-p$ block at the upper right corner.

$M_j = T_j^{-1} \text{diag}(1, \dots, e_j, \dots, 1) T_j$, $T_j - I$ contains non-zero elements only for j -th row vector whose j -th element is zero.

The group is completely determined if

$$p(p-1) = (n-q-1)(2-n-q) \quad 1 \leq p, q \leq n-1.$$

Theorem 3. The system (3) has a constant vector solution $z(t)=g$, which is the eigenvector for the matrix A corresponding to the eigenvalue 0. In case, we can determine the group completely, we can write down g as a linear combination of the solutions $z_1(t), \dots, z_n(t)$. The coefficient of this linear combination is the eigenvector for the eigenvalue $\exp(2\pi i)=1$ of the matrix $M_1 \dots M_m$ and explicitly computable up to a constant multiplier.

By the Laplace transform

$$(4) \quad y(t) = \int_C \exp(-t\sigma) x(\sigma) d\sigma$$

of a solution $x(\sigma)$ of (2), we have:

$$L[y] = [\exp(-t\sigma)(\sigma - B)x(\sigma)]_C + \int_C \exp(-t\sigma) M_\sigma[x(\sigma)] d\sigma$$

Theorem 4. Let $x(t)$ be the solution near $t = \infty$ corresponding to the eigenvalue -1 of $(A-I)$, then $y(t)$ defined by (4) is the solution of the system (1) corresponding to the characteristic exponent 0 at $t=0$, when C is a circle of sufficiently large radius.

Theorem 5. Let $x_k(t)$ be the solution at $t=\lambda_k$ of the form:

$$x_k(t) = \sum_{m=0}^{\infty} h_k(m) (t-\lambda_k)^{a_{kk}+m-1} \quad (h_k(0) = \varepsilon_k)$$

Let us define $y_k(t)$ by:

$$y_k(t) = \int_0^{(\lambda_k)} \exp(-t\sigma) x_k(\sigma) d\sigma.$$

Then we have:

$$L[y_k] = (1 - e_k)(-B)x_k(0), \quad y_k(0) = (1 - e_k) a_{kk}^{-1} z_k(0).$$

Theorem 6.
$$y(t) = \sum_{k=1}^n \int_0^{(\lambda_k)} \exp(-t\sigma) (a_{kk}-1)(1-e_k)^{-1} S_k x_k(\sigma) d\sigma$$

$$\left(\sum_{k=1}^n S_k z_k(t) = g \right).$$